

Bayesian Recurrent Neural Networks for Monitoring Rotorcraft Icing from Aeroacoustics Time-Series Data

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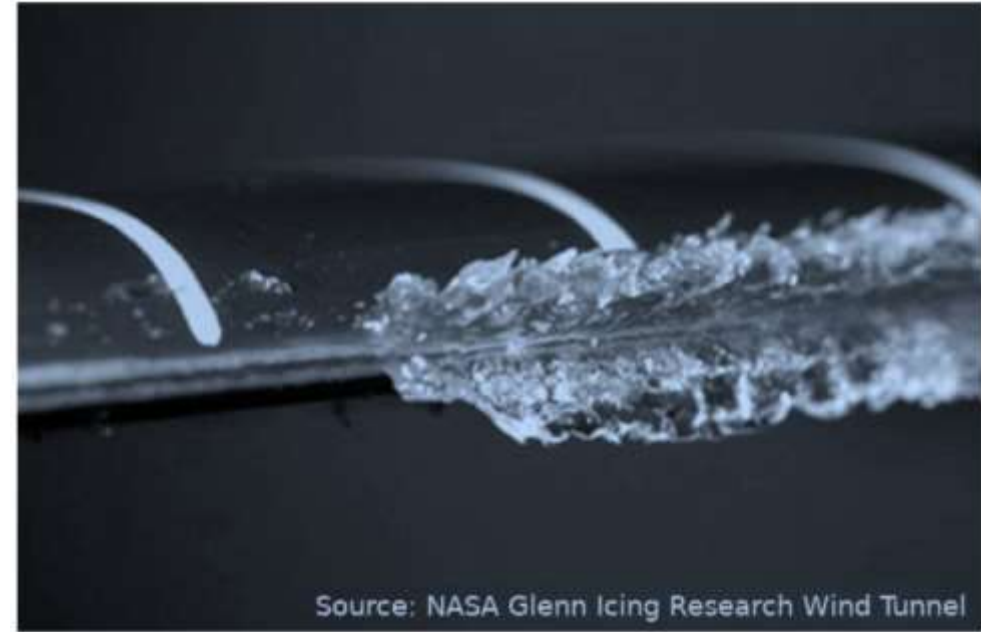
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In-flight rotorcraft icing is extremely dangerous:

- alters leading-edge shape of rotor blades
- severely degrades aerodynamic performance
- is difficult to escape from/recover

Many icing-induced fatal accidents in recent years

Real-time in-flight ice detection system is of paramount importance

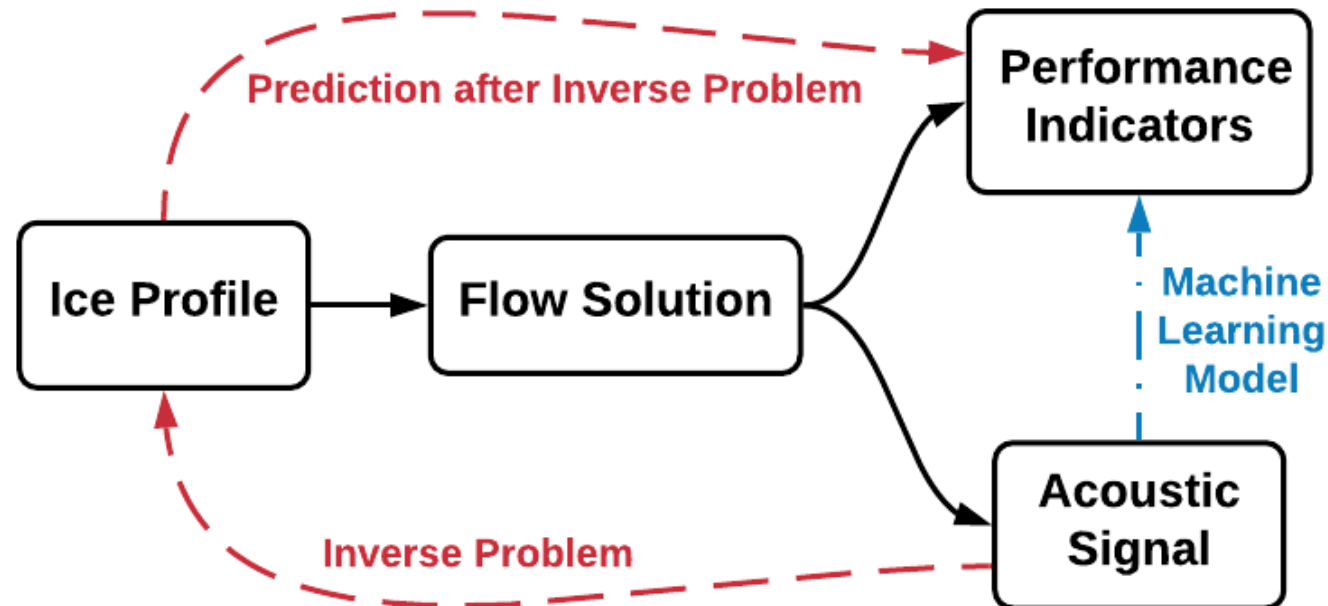
In-flight visual inspection nearly impossible due to high rotor RPM

Promising route: detection using **acoustic signals** enabled by simulations

- computational fluid dynamics (CFD)
- computational aeroacoustics (CAA)

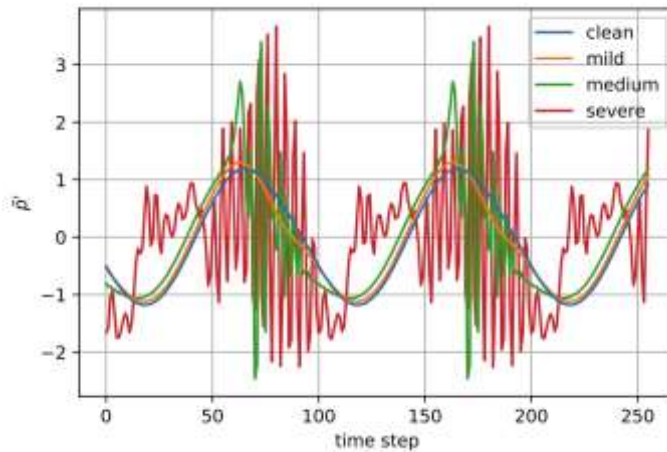
But: physics-based solutions very expensive (min/hours)

⇒ accelerate via **machine-learning (ML)** models

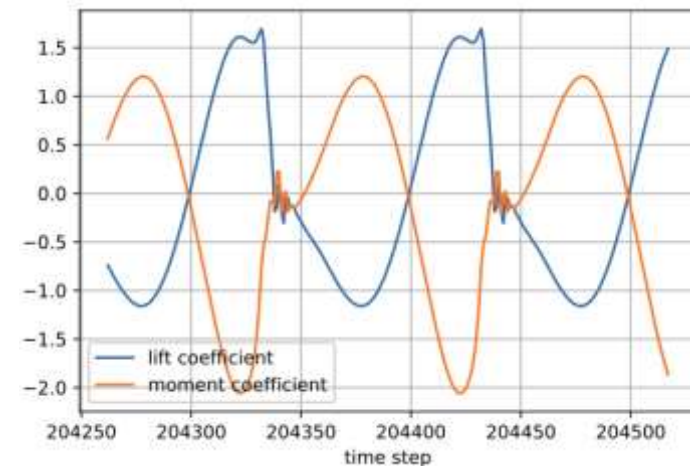
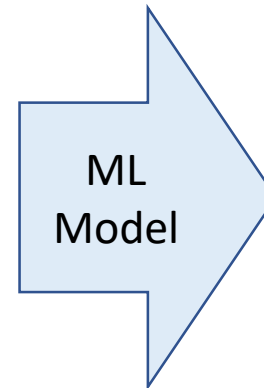


Key components:

- PoliDrop, PoliMIce—ice seeding and accretion
- URANS/DES—turbulent flow solve for near field
- FW-H (Ffowcs Williams-Hawking)—acoustics solver propagate signals to far field
- Coupled through open-source software SU2



Input feature
(acoustic signal time-series)



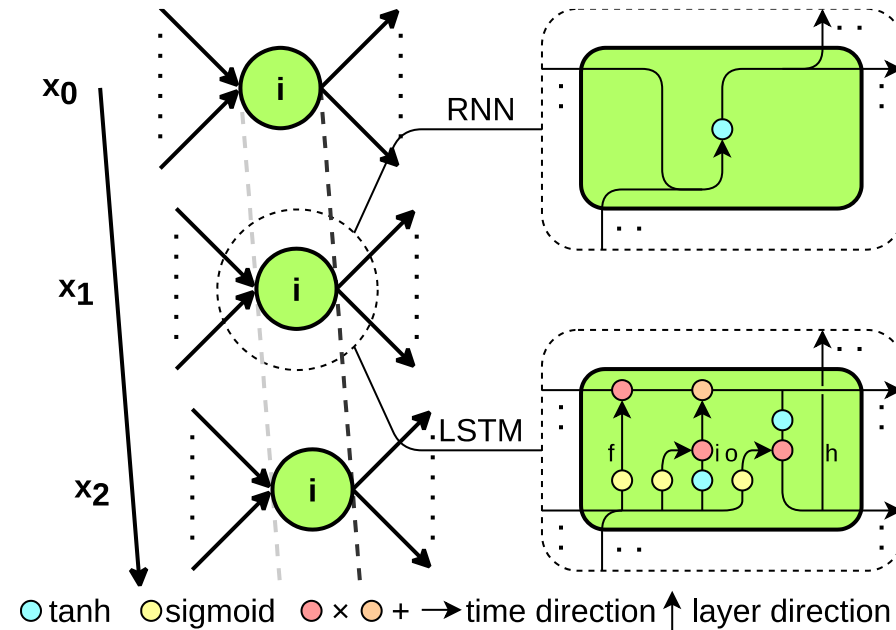
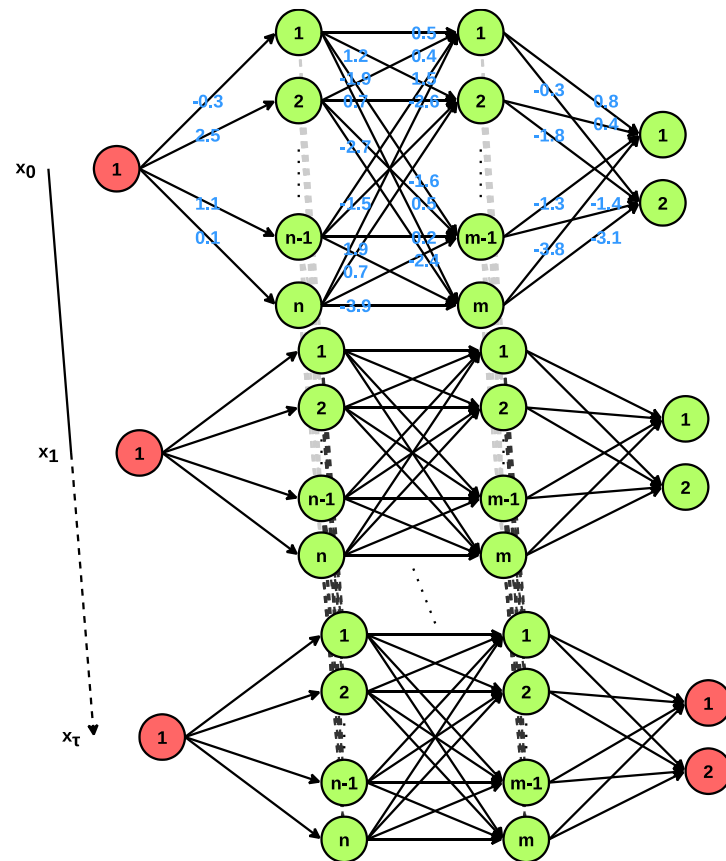
Output prediction
(C_L , C_M time-series)

Long short-term memory (LSTM) recurrent neural network



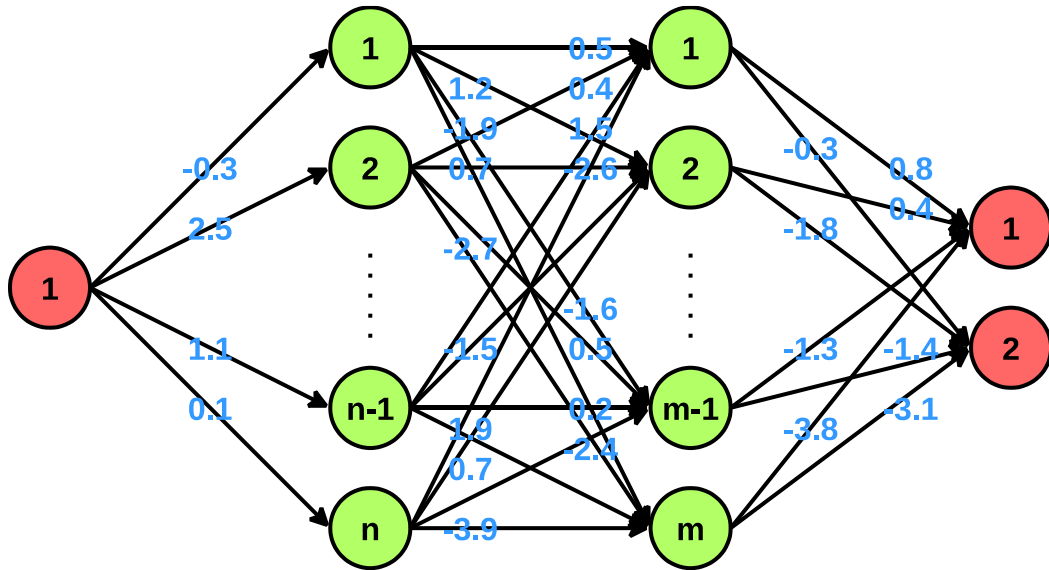
Recurrent neural networks (RNNs)

- Similar to dense DNNs, also use information from previous time steps
- LSTM adds a cell chain to memorize long-term information

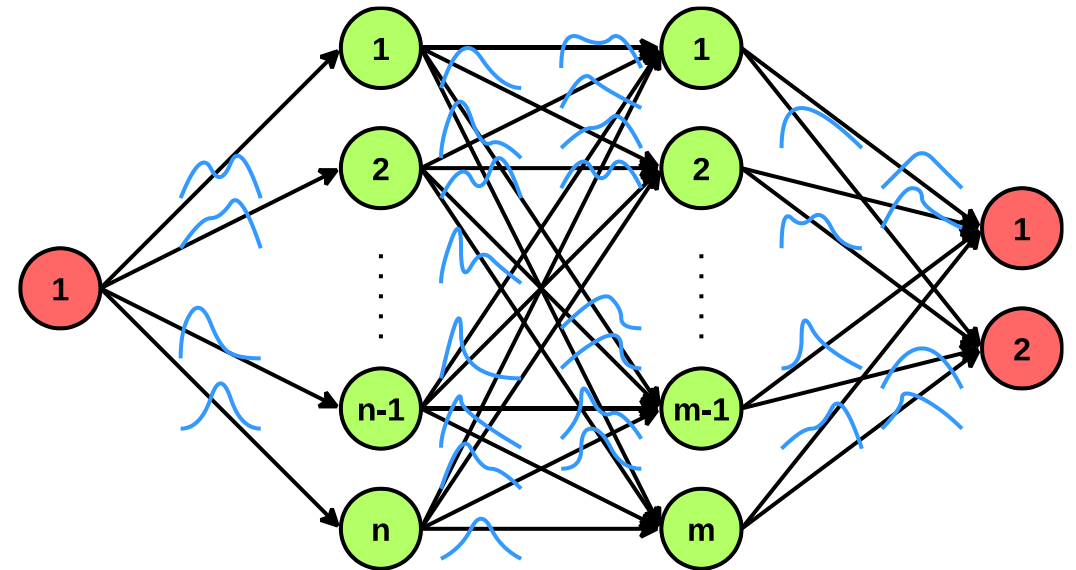


A Bayesian treatment

- computes *distribution* of weights
- captures **uncertainty** of weight parameters

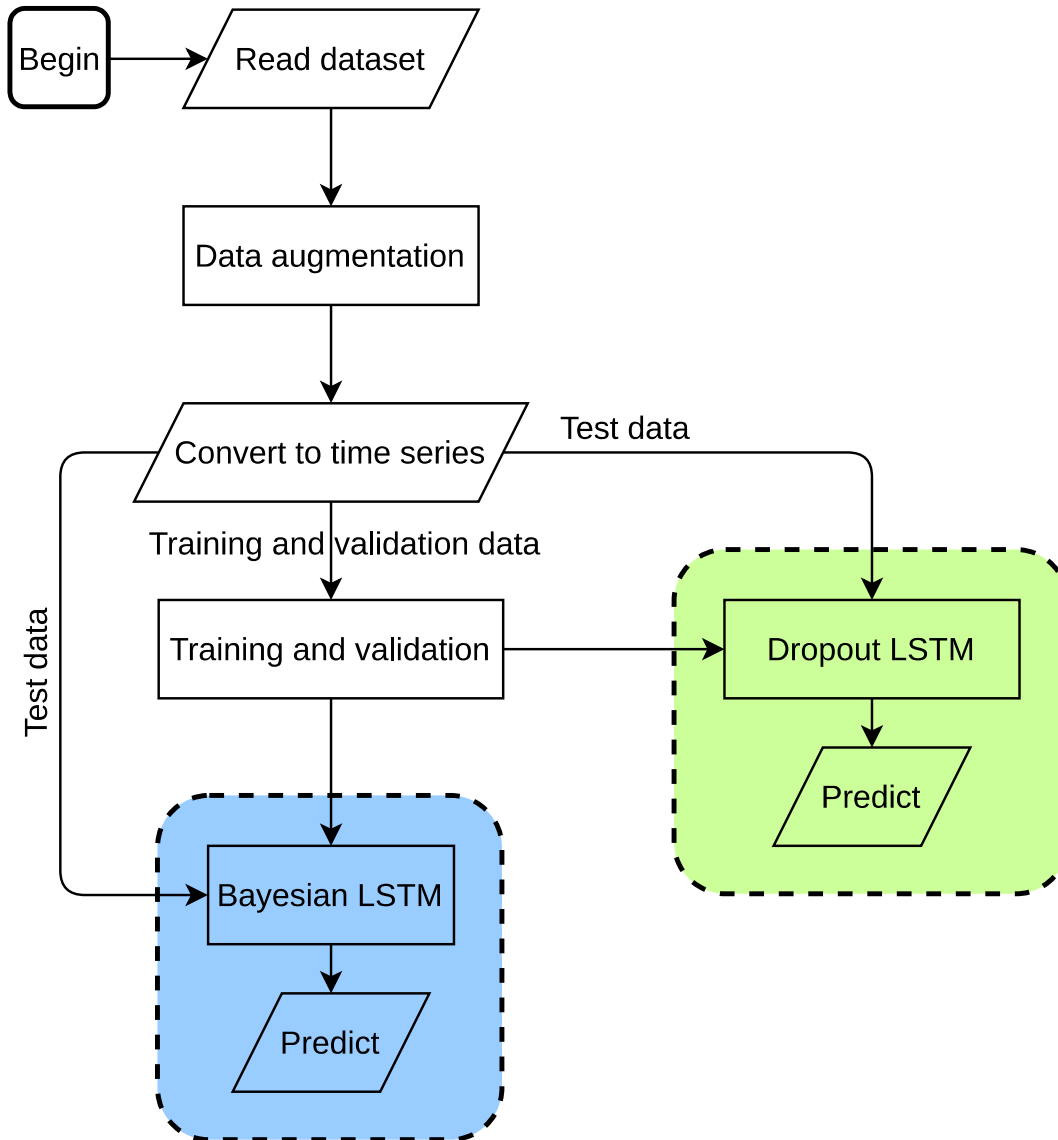


$$w^* = \operatorname{argmin}_w \mathcal{L} [f(x_T; w), y_T]$$



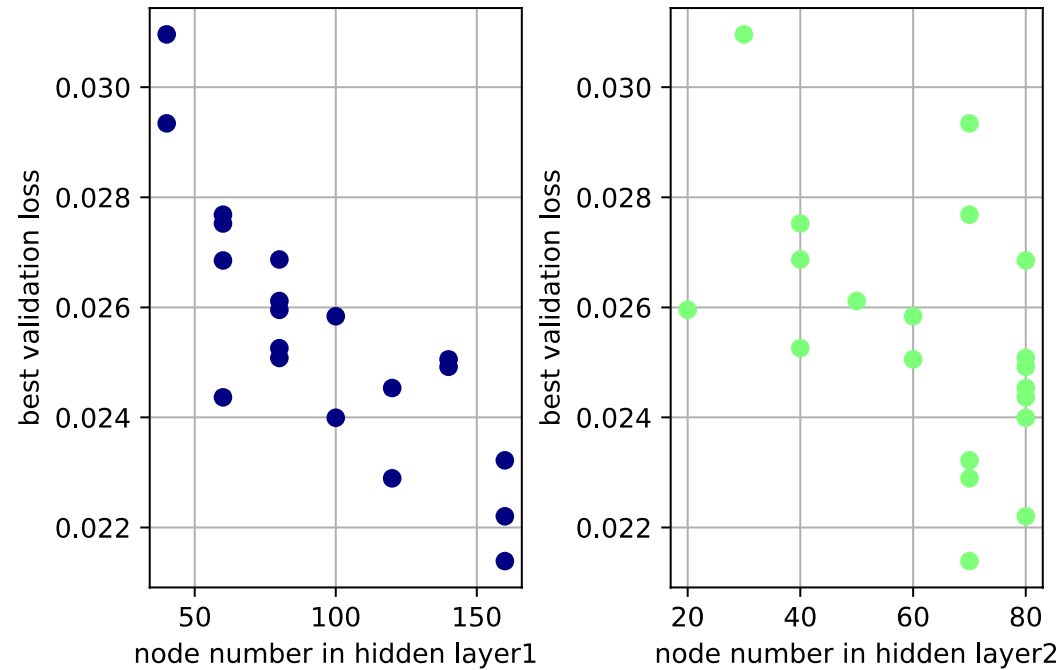
$$p(w|x_T, y_T) = \frac{p(y_T|x_T, w)p(w|x_T)}{p(y_T|x_T)}$$

Overall procedure workflow



- **Data augmentation:** added noise to clean data to simulate real-life measurement error
- **Validation:** hyperparameter optimization for # neurons
- **Comparison:** dropout Monte Carlo LSTM

Hyperparameter optimization, test predictions

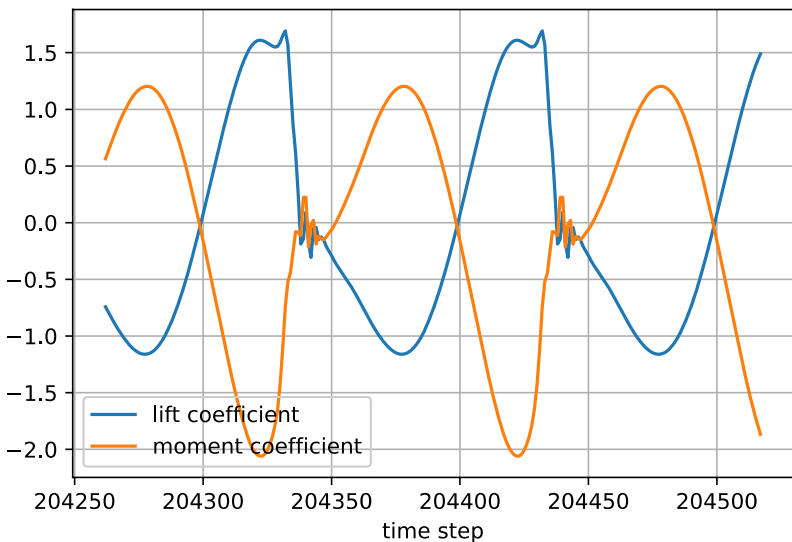
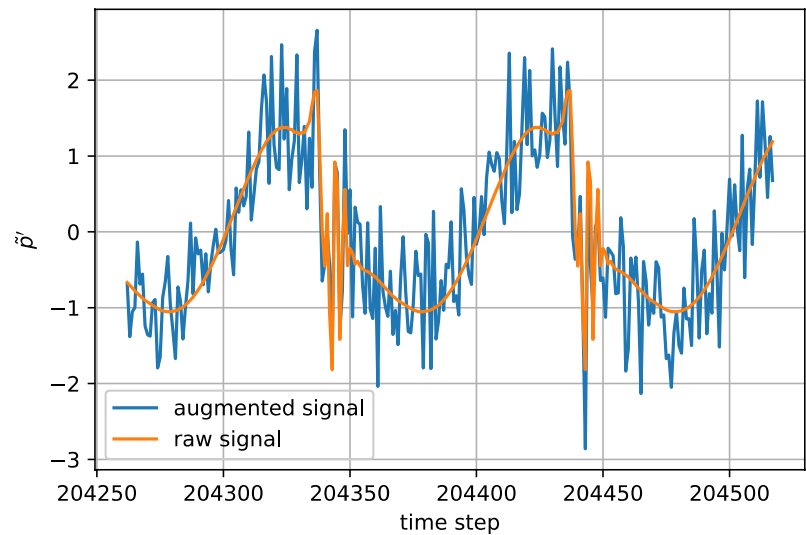


Model	C_L MSE Loss	C_M MSE Loss	Prediction time [s]
Bayesian LSTM	0.001516	0.0001307	721
Monte-Carlo Dropout LSTM	0.01168	0.001152	560

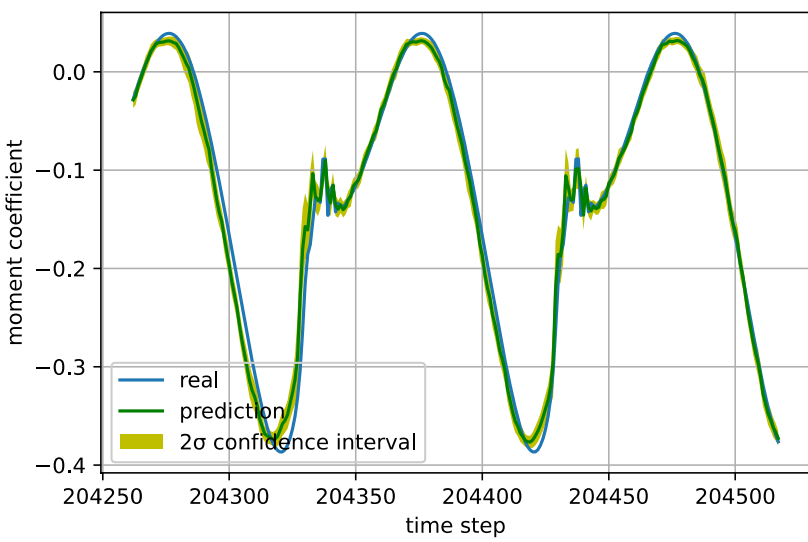
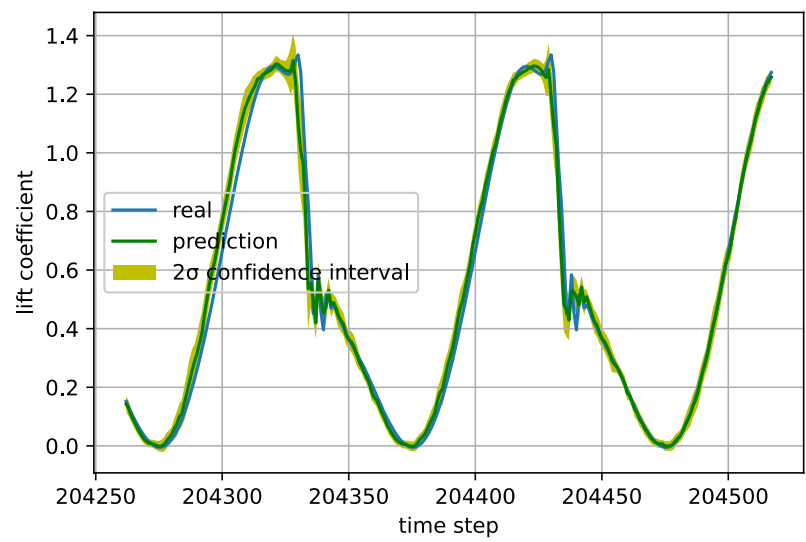
Sample model predictions from Bayesian LSTM



Simulation input
and output



Bayesian LSTM
prediction of
 C_L and C_M



Summary:

- Presented a Bayesian LSTM model
- Enabled time-series inputs and prediction quantities
- Employed Bayesian formulation for quantified uncertainty
- Illustrated promising preliminary performance

Future work:

- More simulation data with high-fidelity models
- Improve robustness under additional icing and flight conditions

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