



Blue tracker, poor lighting



Blue tracker, good lighting



Color detector

BGR = [50,100,90]

upper = np.array([10,50,50])

lower = np.array([10,50,50])

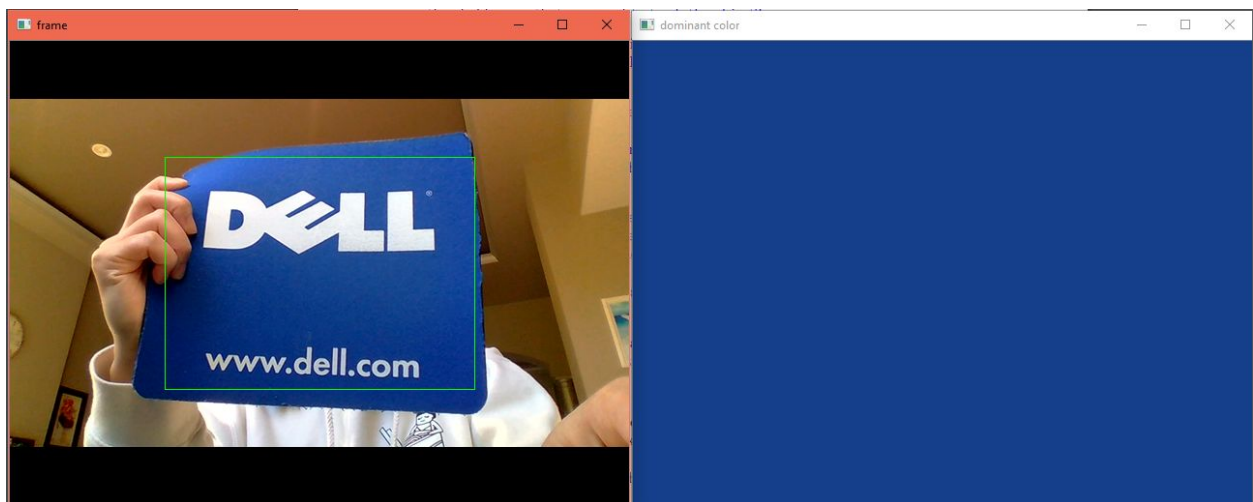


Color detector

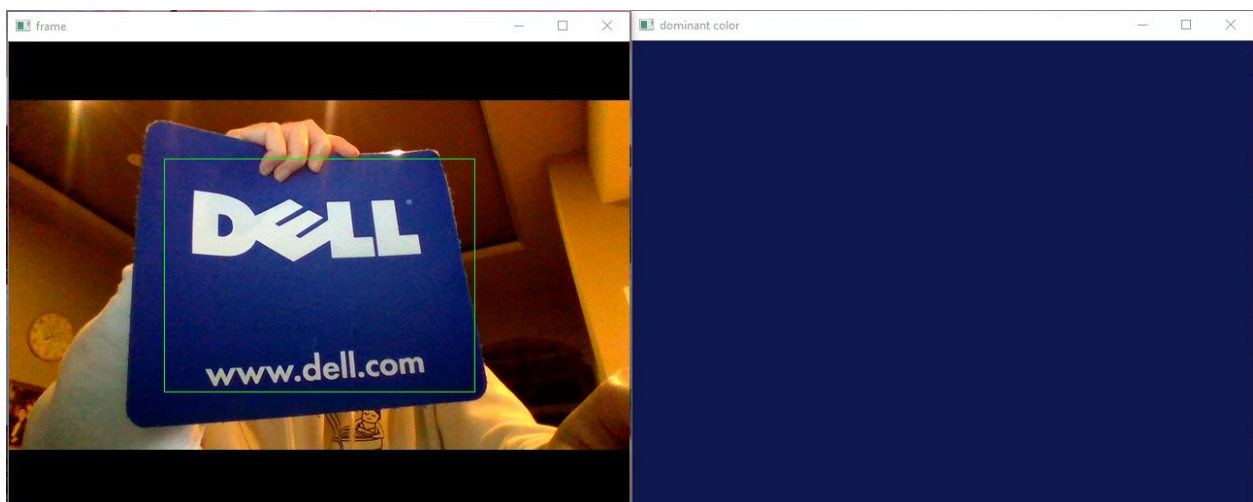
BGR = [50,50,255]

upper = np.array([0,50,50])

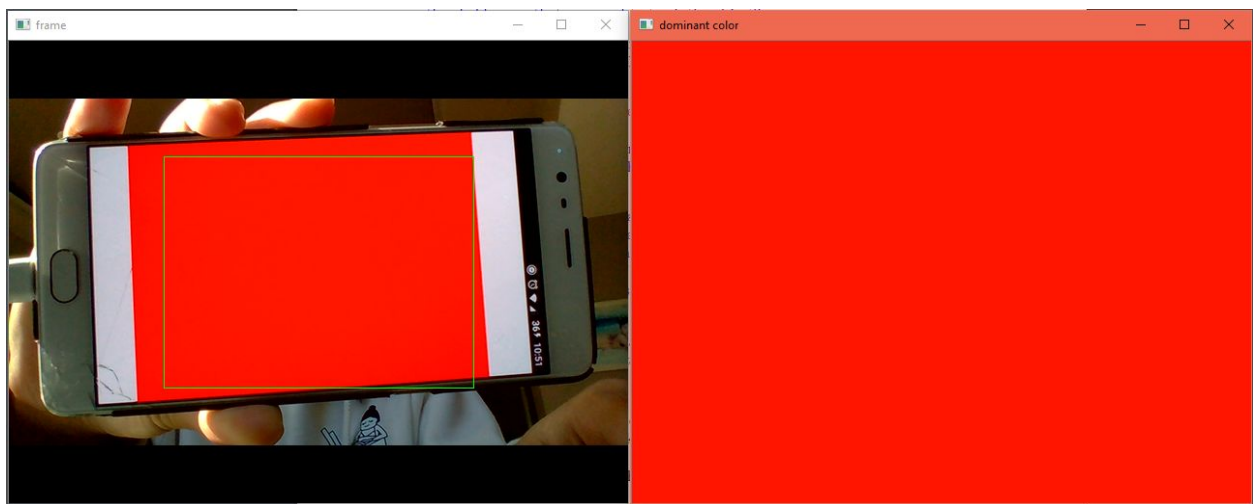
lower = np.array([50,50,50])



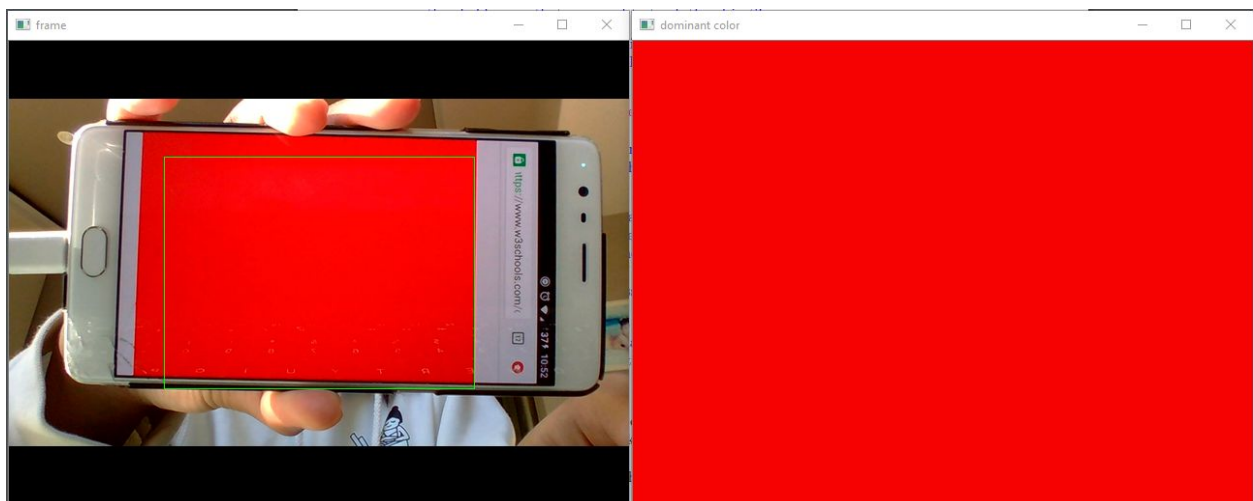
Dominant color, good lighting



Dominant color, poor lighting



Dominant color, full brightness



Dominant color, low brightness