Graph Algorithms Intro

- Problems on Graphs
- Cycle Checking
- Connected Components
- Hamiltonian Path and Circuit
- Euler Path and Circuit

Problems on Graphs

What kind of problems do we want to solve on/via graphs?

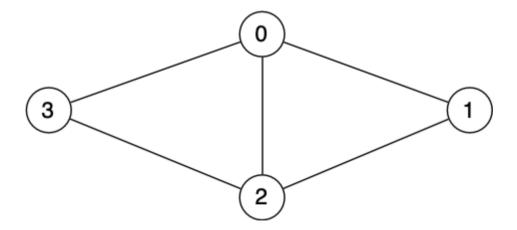
- how many connected components in the graph?
- is one vertex reachable from some other vertex? (path finding)
- what is the cheapest cost path from v to w?
- which vertices are reachable from *v*? (transitive closure)
- is there a cycle somewhere in the graph?
- is there a cycle that passes through all vertices? (circuit)
- is there a tree that links all vertices? (spanning tree)
- what is the minimum spanning tree?
- can a graph be drawn in a plane with no crossing edges? (planar graphs)
- are two graphs "equivalent"? (isomorphism)

Cycle Checking

A graph has a cycle if

- it has a path of length > 2
- with start vertex *src* = end vertex *dest*
- and without using any edge more than once

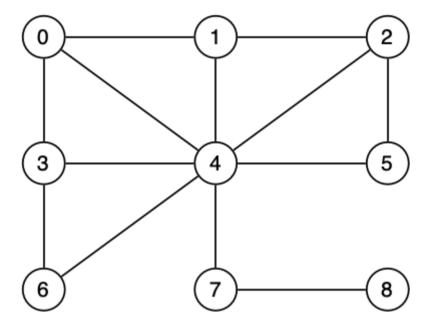
This graph has 3 distinct cycles: 0-1-2-0, 2-3-0-2, 0-1-2-3-0



("distinct" means the *set* of vertices on the path, not the order)

❖ ... Cycle Checking

Consider this graph:



This graph has many cycles e.g. 0-4-3-0, 2-4-5-2, 0-1-2-5-4-6-3-0, ...

... Cycle Checking

First attempt at checking for a cycle

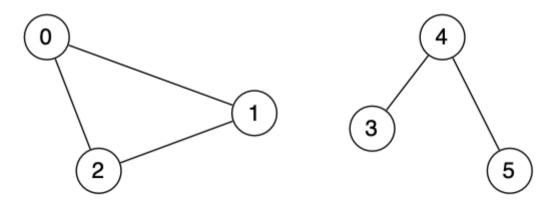
```
hasCycle(G):
   Input graph G
   Output true if G has a cycle, false otherwise
   choose any vertex v \in G
   return dfsCycleCheck(G,v)
dfsCycleCheck(G,v):
   mark v as visited
   for each (v,w) \in edges(G) do
      if w has been visited then // found cycle
         return true
      else if dfsCycleCheck(G,w) then
         return true
   end for
   return false // no cycle at v
```

... Cycle Checking

The above algorithm has two bugs ...

- only one connected component is checked
- the loop **for each (v,w)** \in **edges(G) do** should exclude the neighbour of v from which you just came, so as to prevent a single edge w-v being classified as a cycle.

If we start from vertex 5 in the following graph, we don't find the cycle:



Connected Component #1

Connected Component #2

... Cycle Checking

Version of cycle checking (in C) for one connected component:

```
bool dfsCycleCheck(Graph g, Vertex v, Vertex u) {
   visited[v] = true;
   for (Vertex w = 0; w < g > nV; w++) {
      if (adjacent(g, v, w)) {
         if (!visited[w]) {
            if (dfsCycleCheck(g, w, v))
               return true;
         else if (w != u)
            return true;
   return false;
```



Wrapper to ensure that all connected components are checked:

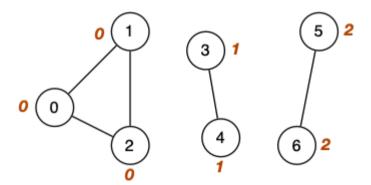
```
Vertex *visited;
bool hasCycle(Graph g, Vertex s) {
   bool result = false;
   visited = calloc(g->nV,sizeof(int));
   for (int v = 0; v < g > nV; v++) {
      for (int i = 0; i < g->nV; i++)
         visited[i] = -1;
      if dfsCycleCheck(g, v, v)) {
         result = true;
         break;
   free(visited);
   return result;
```

Consider these problems:

- how many connected subgraphs are there?
- are two vertices in the same connected subgraph?

Both of the above can be solved if we can

- build componentOf[] array, one element for each vertex v
- indicating which connected component *v* is in



```
componentOf[1] = 0
componentOf[5] = 2
sameComponent(3,4) = true
```

nComponents(q) = 3

Algorithm to assign vertices to connected components:

```
components(G):
   Input graph G
   Output componentOf[] filled for all V
   for all vertices v \in G do
      componentOf[v]=-1
   end for
   compID=0 // component ID
   for all vertices v \in G do
      if componentOf[v]=-1 then
         dfsComponent(G, v, compID)
         compID=compID+1
      end if
   end for
```



DFS scan of one connected component

Consider an application where connectivity is critical

- we frequently ask questions of the kind above
- but we cannot afford to run **components()** each time

Add a new fields to the **GraphRep** structure:

```
typedef struct GraphRep *Graph;

struct GraphRep {
    ...
    int nC; // # connected components
    int *cc; // which component each vertex is contained in
    ... // i.e. array [0..nV-1] of 0..nC-1
}
```

With this structure, the above tasks become trivial:

```
// How many connected subgraphs are there?
int nConnected(Graph g) {
    return g->nC;
}
// Are two vertices in the same connected subgraph?
bool inSameComponent(Graph g, Vertex v, Vertex w) {
    return (g->cc[v] == g->cc[w]);
}
```

But ... introduces overheads ... maintaining cc[], nC

Consider maintenance of such a graph representation:

- initially, **nC** = **nV** (because no edges)
- adding an edge may reduce nC
 (adding edge between v and w in different components)
- removing an edge may increase nC
 (removing edge between v and w in same component)
- cc[] can simplify path checking (ensure v, w are in same component before starting search)

Additional cost amortised by lower cost for nConnected() and inSameComponent()

Is it simpler to run components () after each edge change?

Hamiltonian path problem:

- find a simple path connecting two vertices v,w in graph G
- such that the path includes each vertex exactly once

If v = w, then we have a Hamiltonian circuit

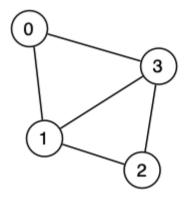
Simple to state, but difficult to solve (*NP*-complete)

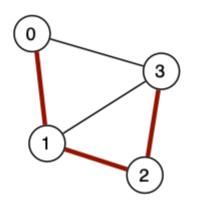
Many real-world applications require you to visit all vertices of a graph:

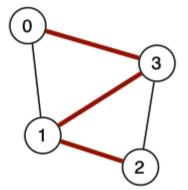
- Travelling salesman
- Bus routes
- ...

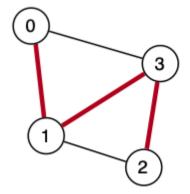
Named after Irish mathematician/physicist/astronomer Sir William Hamilton (1805-1865)

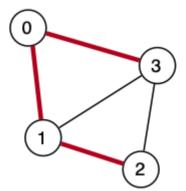
Graph and some possible Hamiltonian paths:

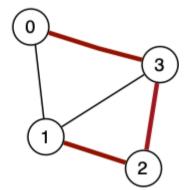












Approach:

- generate all possible simple paths (using e.g. DFS)
- keep a counter of vertices visited in current path
- stop when find a path containing *V* vertices

Can be expressed via a recursive DFS algorithm

- similar to simple path finding approach, except
 - keeps track of path length; succeeds if length = v
 - resets "visited" marker after unsuccessful path

Algorithm for finding Hamiltonian path:

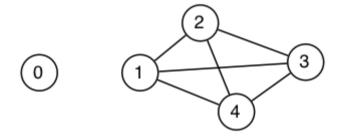


Recursive component:

```
hamiltonR(G,v,dest,d):
   Input G graph
         v current vertex considered
         dest destination vertex
              distance "remaining" until path found
   if v=dest then
      if d=0 then return true else return false
   else
      visited[v]=true
      for each (v,w) \in edges(G) where not visited[w] do
         if hamiltonR(G,w,dest,d-1) then
            return true
         end if
      end for
   end if
   visited[v]=false
                             // reset visited mark
   return false
```

Analysis: worst case requires (V-1)! paths to be examined

Consider a graph with isolated vertex and the rest fully-connected



Checking hasHamiltonianPath(g, x, 0) for any x

- requires us to consider every possible path
- e.g 1-2-3-4, 1-2-4-3, 1-3-2-4, 1-3-4-2, 1-4-2-3, ...
- starting from any x, there are 3! paths \Rightarrow 4! total paths
- there is no path of length 5 in these (V-1)! possibilities

There is no known simpler algorithm for this task \Rightarrow *NP*-hard.

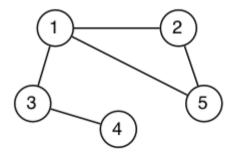
Note, however, that the above case could be solved in constant time if we had a fast check for 0 and x being in the same connected component

COMP2521 20T2 \$\rightarrow\$ Graph Algorithms [19/26]

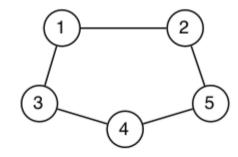
Euler path problem:

- find a path connecting two vertices *v,w* in graph *G*
- such that the path includes each edge exactly once
 (note: the path does not have to be simple ⇒ can visit vertices more than once)

If v = w, the we have an Euler circuit



Euler Path: 4-3-1-5-2-1



Euler Circuit: 1-2-5-4-3-1

Many real-world applications require you to visit all edges of a graph:

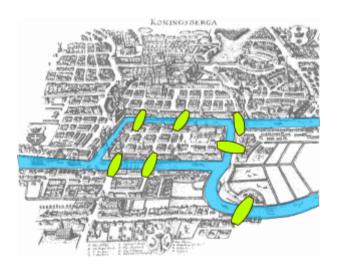
- Postman
- Garbage pickup

• ...

COMP2521 20T2 ♦ Graph Algorithms [20/26]

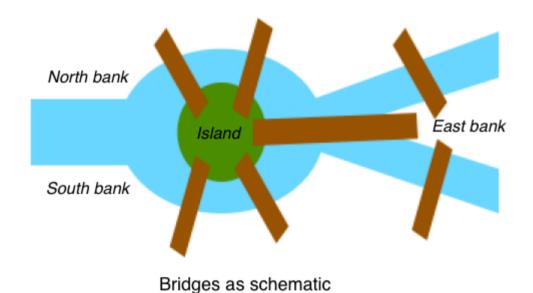
Problem named after Swiss mathematician, physicist, astronomer, logician and engineer Leonhard Euler (1707 - 1783)

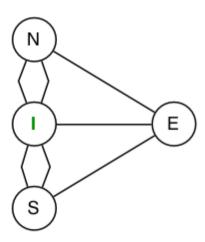
Based on a circuitous route via bridges in Konigsberg



Is there a way to cross all the bridges of Konigsberg exactly once on a walk through the town?

• treat land as nodes; bridges as edges





Bridges as graph

One possible "brute-force" approach:

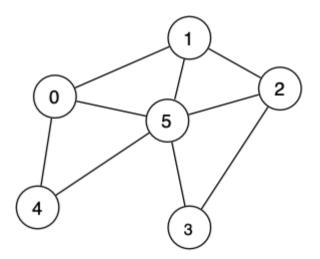
- check for each path if it's an Euler path
- would result in factorial time performance

Can develop a better algorithm by exploiting:

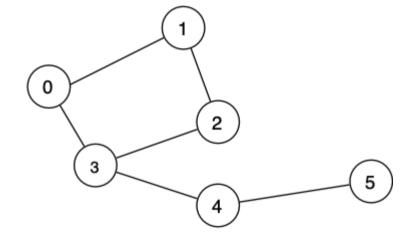
Theorem. A graph has an Euler circuit if and only if it is connected and all vertices have even degree

Theorem. A graph has a non-circuitous Euler path if and only if it is connected and exactly two vertices have odd degree

Graphs with an Euler path are often called Eulerian Graphs



Has neither Eulerian path or circuit



Has no Eulerian circuit, but does have path



Assume the existence of degree(g,v)

Algorithm to check whether a graph has an Euler path:

```
hasEulerPath(G,src,dest):
   Input graph G, vertices src,dest
   Output true if G has Euler path from src to dest
          false otherwise
   if src≠dest then
      if degree(G,src) is even V degree(G,dest) is even then
         return false
      end if
   end if
   for all vertices v \in G do
      if v≠src ∧ v≠dest ∧ degree(G,v) is odd then
         return false
      end if
   end for
   return true
```

Analysis of **hasEulerPath** algorithm:

- assume that connectivity is already checked
- assume that **degree()** is available via O(1) lookup
- single loop over all vertices $\Rightarrow O(V)$

If degree requires iteration over vertices

- cost to compute degree of a single vertex is O(V)
- overall cost is $O(V^2)$
- ⇒ problem tractable, even for large graphs (unlike Hamiltonian path problem)

For the keen, a linear-time (in the number of edges, *E*) algorithm to compute an Euler path is described in [Sedgewick] Ch.17.7.

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