

Heapsort

- HeapSort
- Cost Analysis

❖ HeapSort

Heapsort uses a priority queue (PQ) implemented as a heap.

Reminder: **heap** is a top-to-bottom ordered tree

- that has a simple implementation as an array of **Items**

Reminder: priority queues ...

- implement a key-ordered queue structure
- items added to queue in arrival order
- items removed from queue in max-first order

❖ ... HeapSort

Heapsort (really PQ-sort) approach:

- insert all array items into priority queue
- one-by-one, remove all items from priority queue
- inserting each into successive array element

Priority queue operations ...

```
PQueue newPQueue();  
void PQJoin(PQueue q, Item it);  
Item PQLeave(PQueue q); // remove max Item  
int  PQIsEmpty(PQueue q);
```

❖ ... HeapSort

Implementation of HeapSort:

```
void HeapSort(Item a[], int lo, int hi)
{
    PQueue pq = newPQueue();
    int i;
    for (i = lo; i <= hi; i++) {
        PQJoin(pq, a[i]);
    }
    for (i = hi; i >= lo; i--) {
        Item it = PQLeave(pq);
        a[i] = it;
    }
}
```

❖ ... HeapSort

Problem: requires an additional data structure ($O(N)$ space)

Recall that earlier we defined **fixDown()**

- forces value at $a[k]$ into correct position in heap

Allowed us to work with arrays as heap structures, hence as PQs.

Can we use these ideas to build an in-array PQ-sort?

❖ ... HeapSort

Reminder: **fixDown()** function

```
// force value at a[i] into correct position in a[1..N]
// note that N gives max index *and* number of items
void fixDown(Item a[], int i, int N)
{
    while (2*i <= N) {
        // compute address of left child
        int j = 2*i;
        // choose larger of two children
        if (j < N && less(a[j], a[j+1])) j++;
        if (!less(a[i], a[j])) break;
        swap(a, i, j);
        // move one level down the heap
        i = j;
    }
}
```

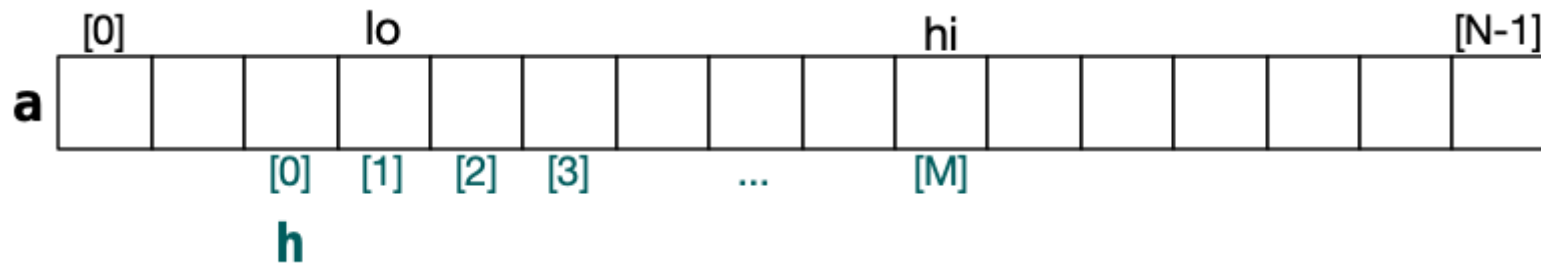
❖ ... HeapSort

Heapsort: multiple iterations over a shrinking heap

- initially use whole array as a heap
- uses **fixDown** to set max value at end
- reduce size of heap, and repeat

One minor complication: $a[lo..hi]$ vs $h[1..M]$ (where $M=hi-lo+1$)

To solve: pretend that heap starts one location earlier.



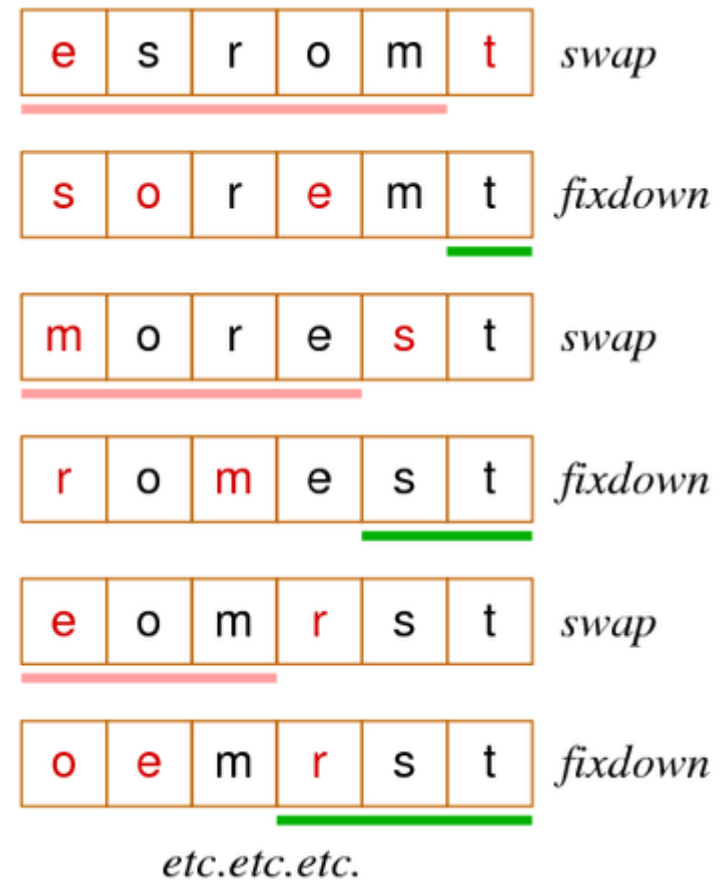
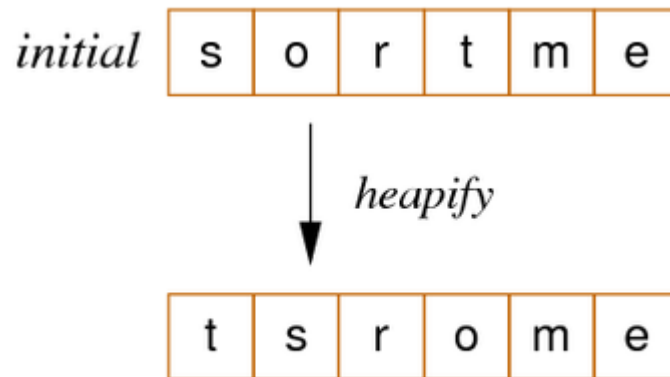
❖ ... HeapSort

Heapsort algorithm:

```
void heapsort(Item a[], int lo, int hi)
{
    int i, N = hi-lo+1;
    Item *h = a+lo-1; //start addr of heap
    // construct heap in a[0..N-1]
    for (i = N/2; i > 0; i--)
        fixDown(h, i, N);
    // use heap to build sorted array
    while (N > 1) {
        // put largest value at end of array
        swap(h, 1, N);
        // heap size reduced by one
        N--;
        // restore heap property after swap
        fixDown(h, 1, N);
    }
}
```


❖ ... HeapSort

Trace of heapsort:



❖ Cost Analysis

Heapsort involves two stages

- build a heap in the array
 - iterates $N/2$ times, each time doing **fixDown()**
 - each **fixDown()** is $O(\log N)$, so overall $O(N \log N)$
 - note: can write *heapify* more efficiently than we did $O(N)$
 - note: each **fixDown()** involves at most $\log_2(2C + S)$
- use heap to build sorted array
 - iterates N times, each time doing **swap()** and **fixDown()**
 - **swap()** is $O(1)$, **fixDown()** is $O(\log N)$, so overall $O(N \log N)$

Cost of heapsort = $O(N \log N)$

