

- read problem-specific [boundary conditions as algebraic expressions](#)

```
sigma = 5.670374419e-8 # W m^2 / K^4 as in wikipedia
e = 0.98 # non-dimensional
T0 = 1000 # K
Tinf = 300 # K
```

```
BC left T=T0
BC right q=sigma*e*(Tinf^4-T(x,y,z)^4)
```

- access shape functions and its derivatives evaluated either at Gauss points or at arbitrary locations for computing elementary contributions to
 - [stiffness matrix](#)
 - [mass matrix](#)
 - [right-hand side vector](#)

For example, this snippet would build the elemental stiffness matrix for the [Laplace problem](#):

```
int build_laplace_Ki(element_t *e, unsigned int q) {
    double wdet = feenox_fem_compute_w_det_at_gauss(e, q);
    gsl_matrix *B = feenox_fem_compute_B_at_gauss(e, q);
    feenox_call(feenox_blas_BtB_accum(B, wdet, feenox.fem.Ki));
    return FEENOX_OK;
}
```

The calls for computing the weights and the matrices with the shape functions and/or their derivatives currently support first and second-order iso-geometric elements, but other element types can be added as well. More complex cases involving non-uniform material properties, volumetric sources, etc. can be found in the [examples](#), [tutorials](#) and [tests](#).

- solve the discretized equations using the appropriate PETSc ([Balay et al., 1997, 2023](#)) or SLEPc ([Hernandez et al., 2005](#); [Roman et al., 2023](#)) objects, i.e.
 - KSP for [linear static problems](#)
 - SNES for [non-linear static problems](#)
 - TS for [transient problems](#)
 - EPS for [eigenvalue problems](#)

The particular functions that implement each problem type are located in subdirectories [src/pdes](#), namely

- [laplace](#)
- [thermal](#)
- [mechanical](#)
- [modal](#)
- [neutron_diffusion](#)
- [neutron_sn](#)

Researchers with both knowledge of mathematical theory of finite elements and programming skills might, with the aid of [the community](#), add support for other PDEs. They might do that by using one of these directories (say [laplace](#)) as a template and

1. replace every occurrence of `laplace` in symbol names with the name of the new PDE
2. modify the initialization functions in `init.c` and set
 - the names of the unknowns
 - the names of the material properties
 - the mathematical type and characteristics of problem
 - etc.