



# Team 3

## Maze Buster



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— Mechanical Engineering  
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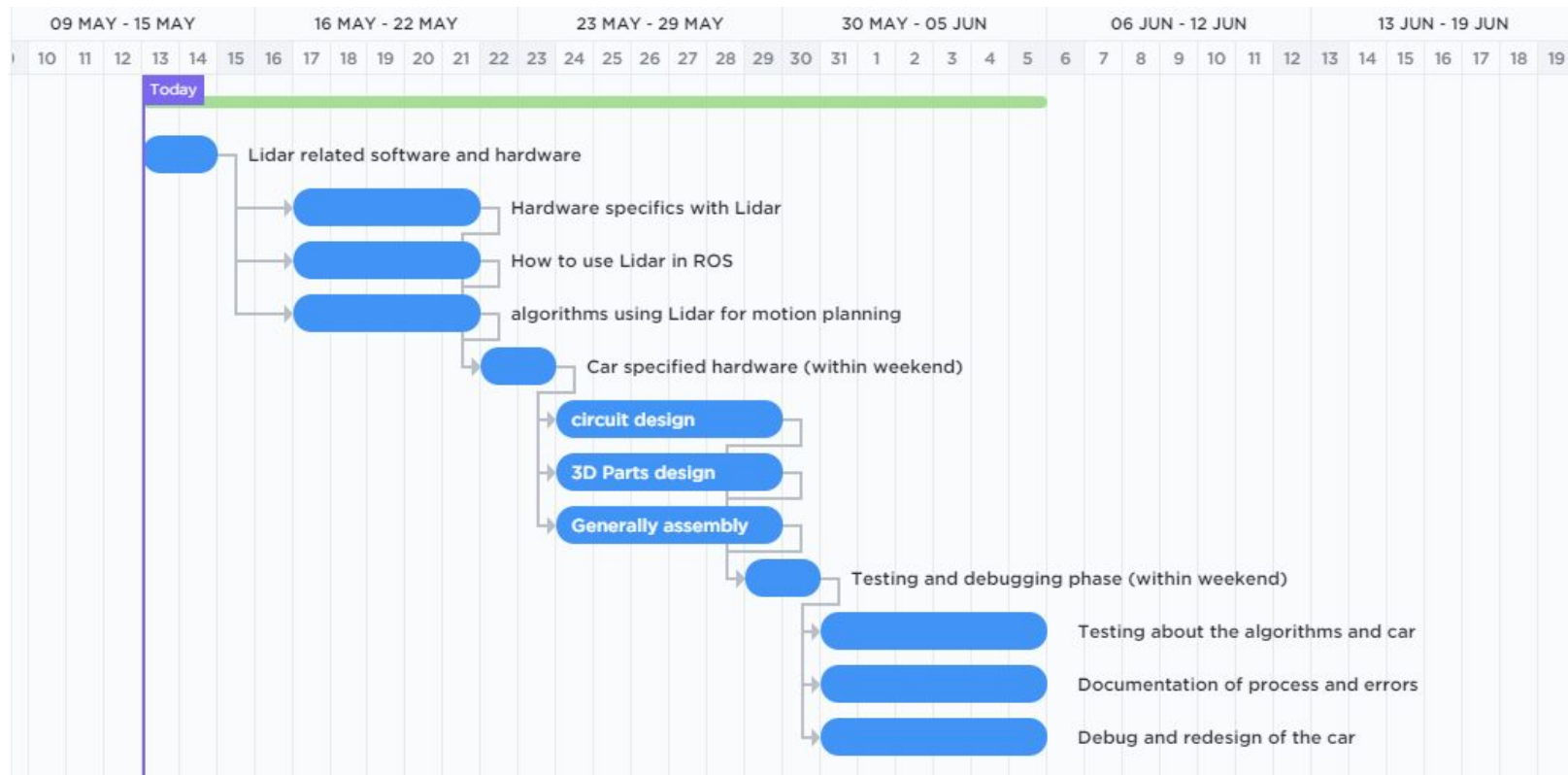


### Proposition

Using LiDAR to guide autonomous vehicles to go out from maze.

- MUST have
  - We will be using lidar to guide the car
  - It will navigate itself automatically through a unknown environment
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- NICE to have
  - It will give a 2D mapping after
  - It will find a way out







# Progress

- The jetbot is moving by loading python code
- All drivers installed on the SDcard for the JTN Nano to be able to drive the jetbot
- Started making the maze
- Learned how to use lidar