## **RESEARCH** Computer Vision – Machine Learning – Robotics

#### **EDUCATION**

University of Oxford, 2017 - May 2021

PhD Student in Engineering Science (Robotics & Computer Vision), Advisor: Dr. Maurice Fallon

University of Edinburgh, 2015 - 2016

MSc in Artificial Intelligence (Merit), Advisor: Dr. Maurice Fallon

University of Aberdeen, 2011 - 2015

BSc Computing Science (First class), Advisors: Dr. Martin J. Kollingbaum, Prof. Wamberto Vasconcelos

## SELECTED

**X**Resolution Correspondence Networks

## PUBLICATIONS (full list on page 2)

British Machine Vision Conference (BMVC), 2021.

Georgi Tinchev, Shuda Li, Kai Han, David Mitchell, Rigas Kouskouridas

SKD: Keypoint Detection for Point Clouds Using Saliency Estimation

IEEE International Conference on Robotics and Automation (RAL+ICRA), 2021.

Georgi Tinchev, Adrian Penate-Sanchez, M. Fallon

Learning to See the Wood for the Trees: Laser Localization in Urban and Natural Environments on a CPU

IEEE International Conference on Robotics and Automation (RAL+ICRA), 2019.

Georgi Tinchev, Adrian Penate-Sanchez, M. Fallon

# PROFESSIONAL EXPERIENCE

**Applied Scientist** 

Amazon, London, United Kingdom; October 2021 - present

Leading a team to develop text-to-speech (TTS) models using **generative machine learning** - **normalizing flows, diffusion models, VAEs**.

**Computer Vision Scientist Intern** 

XYZ Reality, London, United Kingdom; October 2020 - May 2021

Developed state-of-the-art models for correspondence networks in image data in PyTorch.

Evaluated SfM methods on numerous datasets, such as HPatches, InLoc, Aachen Day-Night.

#### **Applied Scientist Intern**

Amazon Research, Cambridge, United Kingdom; November 2019 - August 2020

Conducted statistically relevant experiments while analyzing state-of-the-art TTS models.

Improved the computational efficiency of deep learning models.

Part of a team to help design, develop, and run large scale models from proof of concept into production.

Experimented with generative models for speech generation.

#### **Software Developer**

Ikiji Ltd, Aberdeen, United Kingdom; June 2013 – November 2018

Designed solutions satisfying clients' needs, building them with PHP frameworks like Laravel.

Configured and maintained multiple AWS instances and backup solutions.

### **TECHNICAL SKILLS**

## **Computer Vision**

Evaluated state-of-the-art 6DoF registration algorithms.

Designed and optimized architectures for real-time operation of a global localization system.

Analyzed keypoint detection and segmentation methods on both images and point clouds.

Led a project to evaluate and improve rotation invariance of point cloud-based networks.

#### **Robotics**

Implemented scalable deep learning models with TensorFlow on both Python and C++.

Led the development of C++ real-time **SLAM** application in challenging environments.

Developed a dataset of aligned LiDAR by fusing sensor information from GPS, VO & loop closures.

Conducted experiments in close loop operation on NASA Valkyrie, Clearpath Husky, ANYmal robots.

Implemented multirobot communication with LCM, ROS, and MOOS frameworks.

Engineered visualization software for perception applications using OpenCV, Eigen, Boost libraries.

## **Machine Learning**

Developed statistical methods for predictive analysis decreasing the computation time for localizing. Conducted statistical analysis and implemented visualization tools to illustrate experimental results.

**PATENTS** 

Localization of a Mobile Apparatus (Application No. GB1902493.4, Publication Date: 10/04/2019)

Configuration method for the display of a building information model (Application No. 2104720.4, Filed Date: 01/04/2021)

**INTERESTS** 

Sports: Captain of the national and blues (1st) volleyball teams at the University of Oxford; Oxford, UK

2nd place at a 3\* UK Beach Tour, England, UK, 2019

5th place at student beach volleyball championships at BUCS; UK, 2018

Reading: I enjoy reading fantasy novels, such as The Kingkiller Chronicle, The Witcher.

Interests: Skiing, Mechanical Keyboards, Hiking

Reviewer: CVPR, ICCV, RAL+ICRA, TRO, IROS, ICRA, ITSC

PUBLICATIONS (chronological order)

**X**Resolution Correspondence Networks

British Machine Vision Conference (BMVC), 2021.

Georgi Tinchev, Shuda Li, Kai Han, David Mitchell, Rigas Kouskouridas

**Universal Neural Vocoding with Parallel WaveNet** 

IEEE International Conference on Acoustics, Speech and Signal Processing (ICASSP), 2021.

Yunlong Jiao, Adam Gabrys, Georgi Tinchev, Bartosz Putrycz, Daniel Korzekwa, Viacheslav Klimkov

SKD: Keypoint Detection for Point Clouds Using Saliency Estimation

IEEE International Conference on Robotics and Automation (RAL+ICRA), 2021.

Georgi Tinchev, Adrian Penate-Sanchez, Maurice Fallon

Online LiDAR-SLAM for Legged Robots with Robust Registration and Deep-Learned Loop Closure *IEEE International Conference on Robotics and Automation (ICRA)*, 2020.

Milad Ramezani, Georgi Tinchev, Egor luganov, Maurice Fallon

Seeing the Wood for the Trees: Reliable Localization in Urban and Natural Environments

IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), 2018.

Georgi Tinchev, Simona Nobili, Maurice Fallon

**Predicting Alignment Risk to Prevent Localization Failure** 

IEEE International Conference on Robotics and Automation (ICRA), 2018.

Simona Nobili, Georgi Tinchev, Maurice Fallon