

Big Data Computing

Master's Degree in Computer Science
2025-2026



SAPIENZA
UNIVERSITÀ DI ROMA

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- Each metric may be suitable for specific task(s) in a particular domain
- **Clustering** is one of these tasks!

CLUSTERING

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- A standard problem in many (big) data applications:
 - Categorizing documents by their topics
 - Grouping customers by their behaviors
 - ...

What is Clustering?

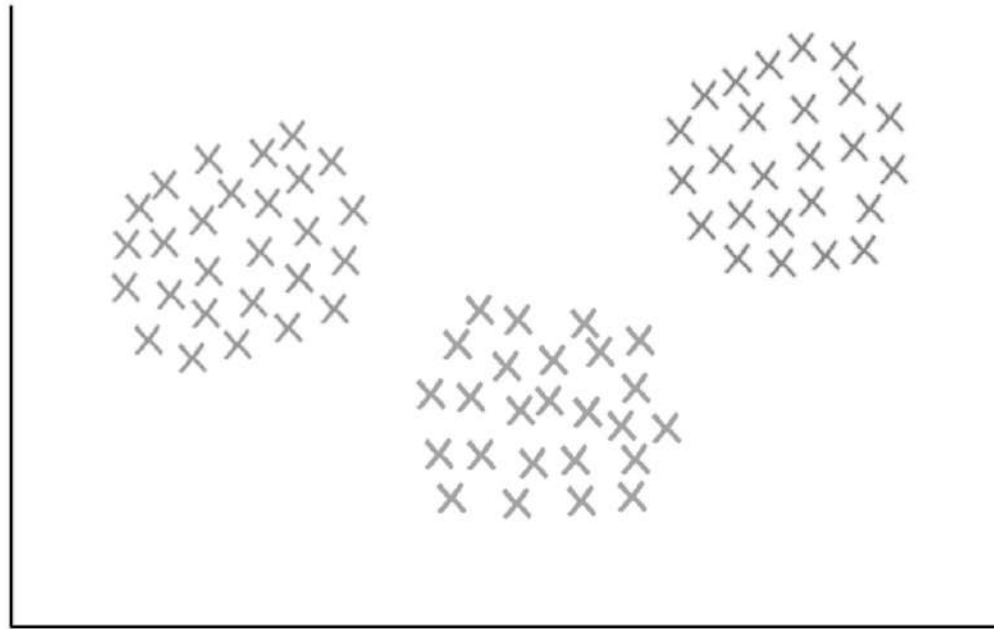
- A typical example of **unsupervised learning** technique

What is Clustering?

- A typical example of **unsupervised learning** technique
- A method of **data exploration**, i.e., a way of looking for patterns of interest in data

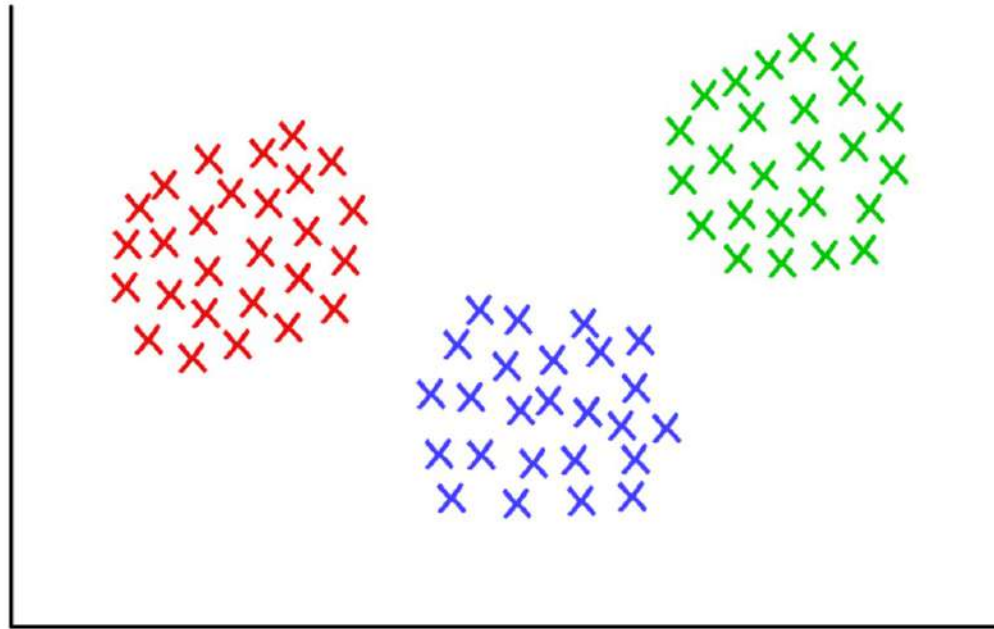
Clustering: Intuition

Given a set of 2-dimensional data points



Clustering: Intuition

We'd like to understand their "structure" to find groups of data points



Clustering: Formal Definition

- Given a set of data points and a notion of **distance** between those

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 - Members of different clusters are dissimilar (i.e., **low inter-cluster similarity**)

Clustering: Practical Issues

- Object **representation**
 - Data points may be in very high-dimensional spaces

Clustering: Practical Issues

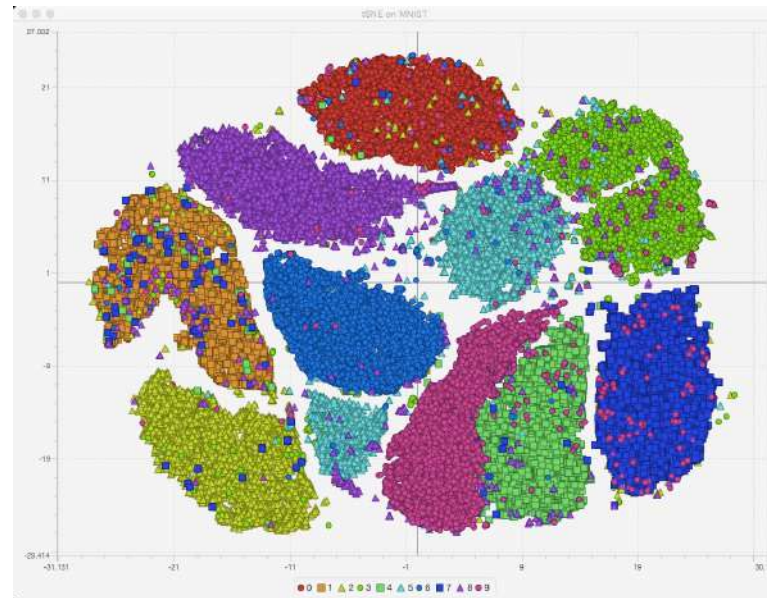
- Object **representation**
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- Notion of **similarity** between objects using a distance measure
 - Euclidean distance, Cosine similarity, Jaccard coefficient, etc.

Clustering: Practical Issues

- Object **representation**
 - Data points may be in very high-dimensional spaces
- Notion of **similarity** between objects using a distance measure
 - Euclidean distance, Cosine similarity, Jaccard coefficient, etc.
- Number of **output clusters**
 - Fixed apriori? Data-driven?

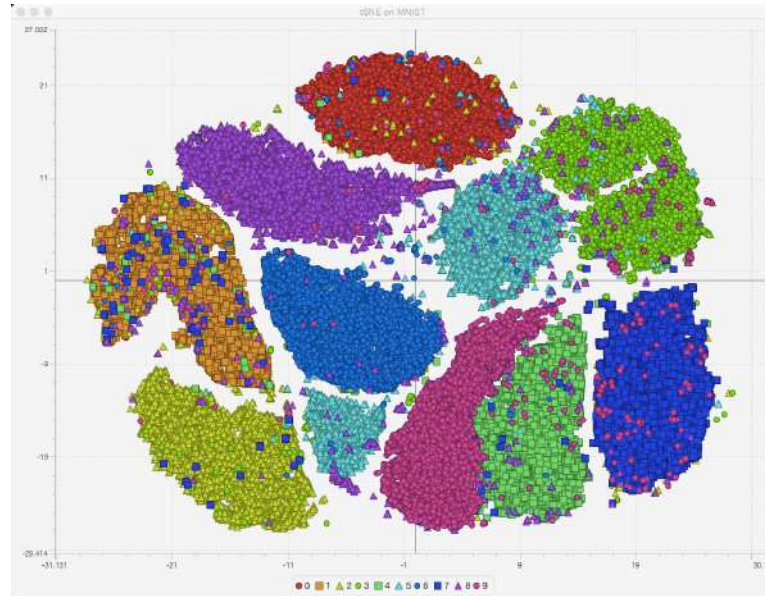
Clustering: A Hard Problem

Data points are not always easily and clearly separable



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Finding a clear boundary between clusters may be hard in the real world

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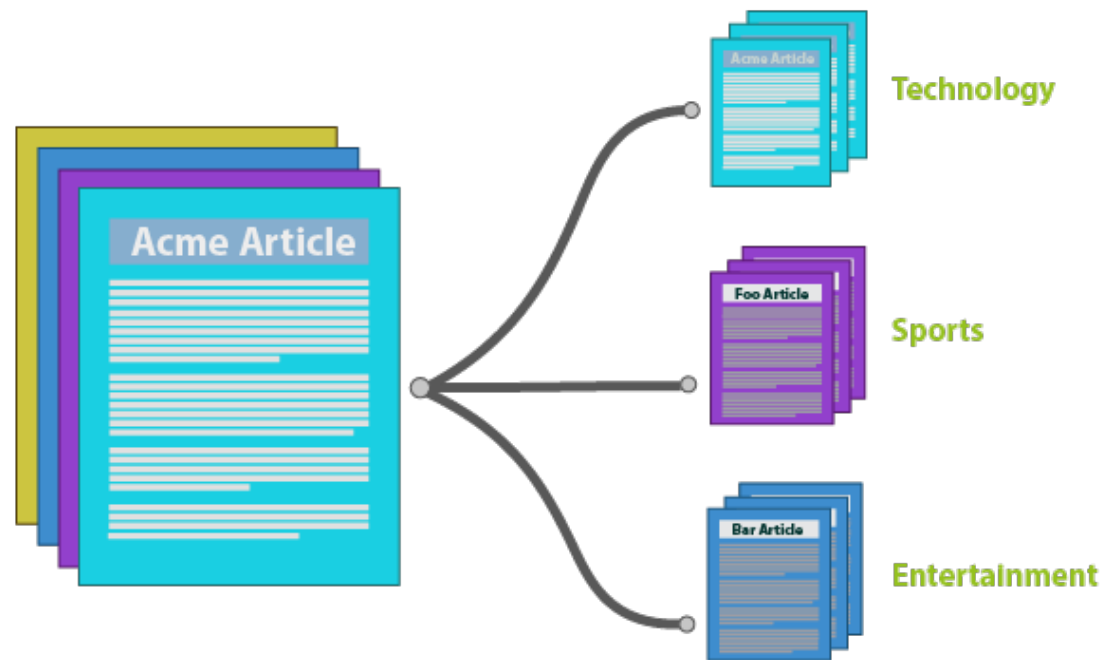
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- **What does make things hard, then?**

Many real-world applications involve 10s, 100s, or 1,000s of dimensions



In high-dimensional spaces almost all pairs of points are at the same (large) distance

Example: Text Document Clustering



source: <https://towardsdatascience.com/applying-machine-learning-to-classify-an-unsupervised-text-document-e7bb6265f52>

Example: Text Document Clustering

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Example: Text Document Clustering

- **Problem:** Group together documents on the same **topic**
- Documents with similar sets of words may be about the same topic
- **Key Issues:**
 - Representing documents (in the space of words)
 - Measuring document similarity (in the space of words)

Document Representation

- Different ways of representing documents (in the space of words)

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 - More advanced representations derived from (Large) Neural Language Models (e.g., word2vec, BERT, Transformers)
- The choice of document representation affects the similarity measure

Document Representation: Set of Words

doc 1

John likes to
watch movies.
Mary likes
movies too.

doc 2

Mary also likes
to watch
football games.

Document Representation: Set of Words

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John likes to
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{John, likes, to, watch, movies, Mary, too}

{Mary, also, likes, to, watch, football, games}

Document Representation: Bag-of-Words

We keep **multiplicity**

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Document Representation: Bag-of-Words

We keep **multiplicity**

doc 1

John likes to
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```
{  
John:1, likes:2, to:1,  
watch:1,  
movies:2, Mary:1, too:1  
}
```

doc 2

Mary also likes
to watch
football games.

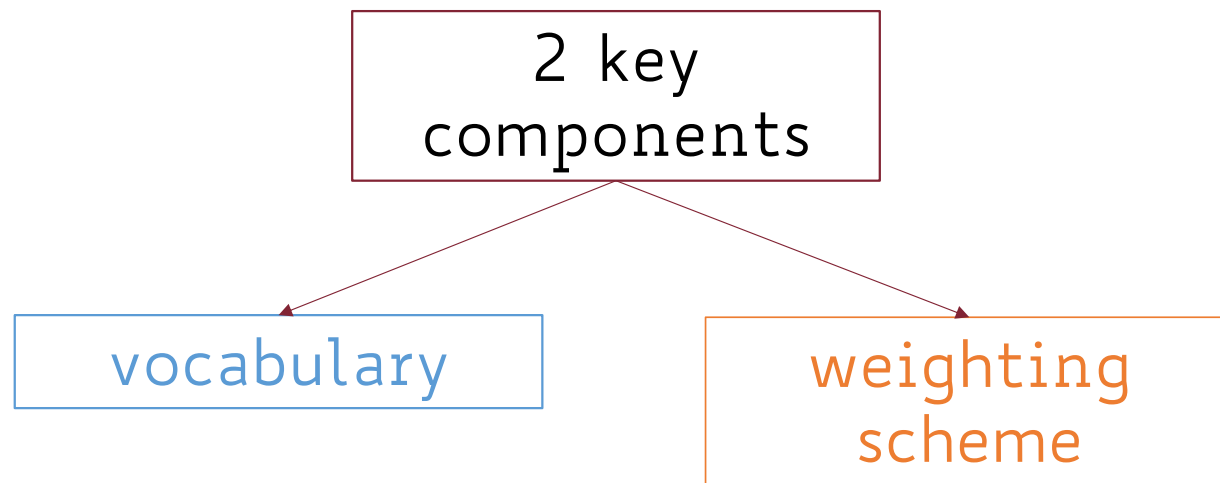
```
{  
Mary:1, also:1, likes:1, to:1,  
watch:1, football:1, games:1  
}
```

Document Representation: Bag-of-Words

Bag-of-Words (BoW) model is just a preliminary step for more complex document representations

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Bag-of-Words: Vocabulary

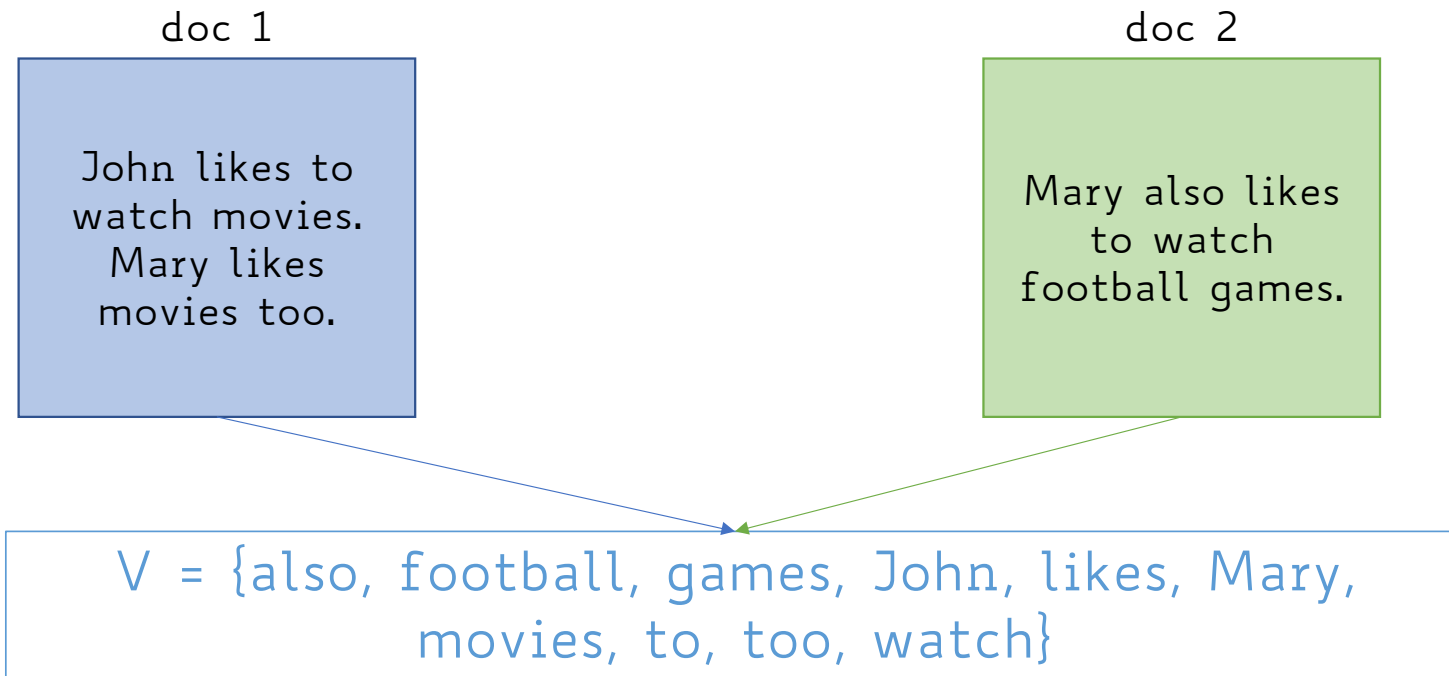
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Bag-of-Words: Vocabulary



Bag-of-Words: Weighting Scheme

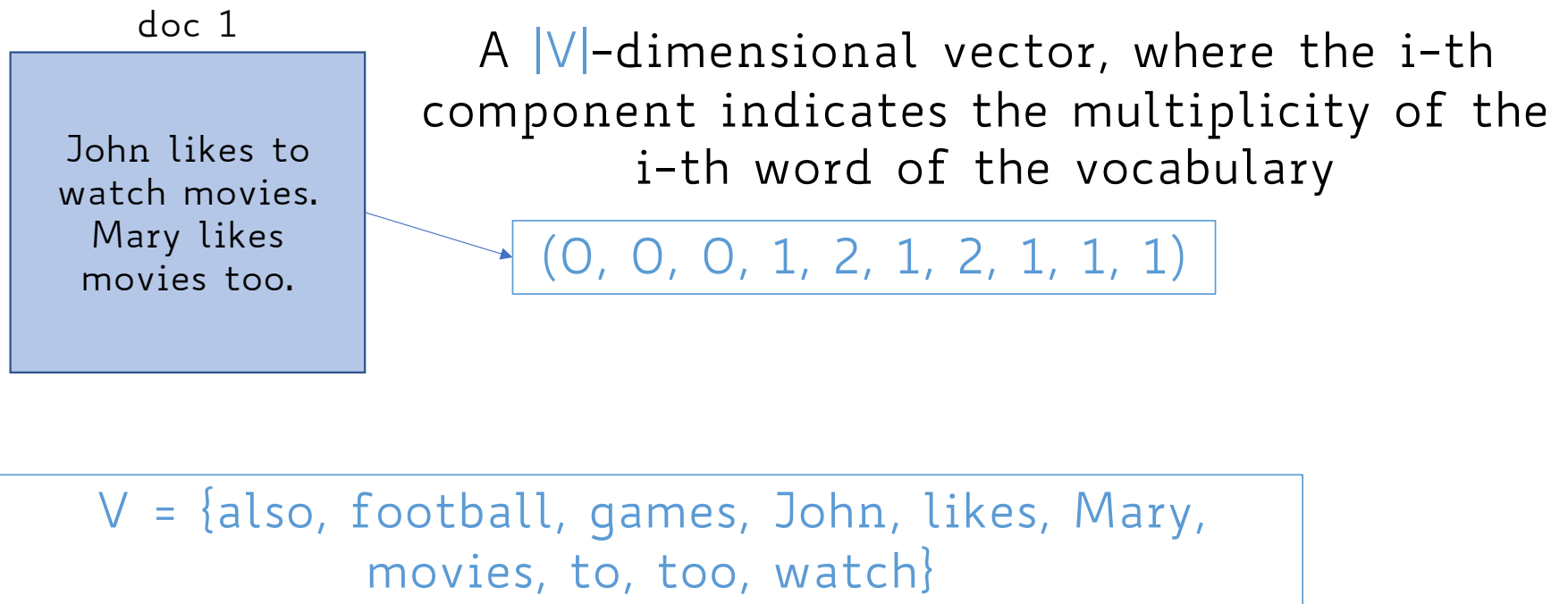
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A $|V|$ -dimensional vector, where the i -th component indicates the multiplicity of the i -th word of the vocabulary

$V = \{\text{also, football, games, John, likes, Mary, movies, to, too, watch}\}$

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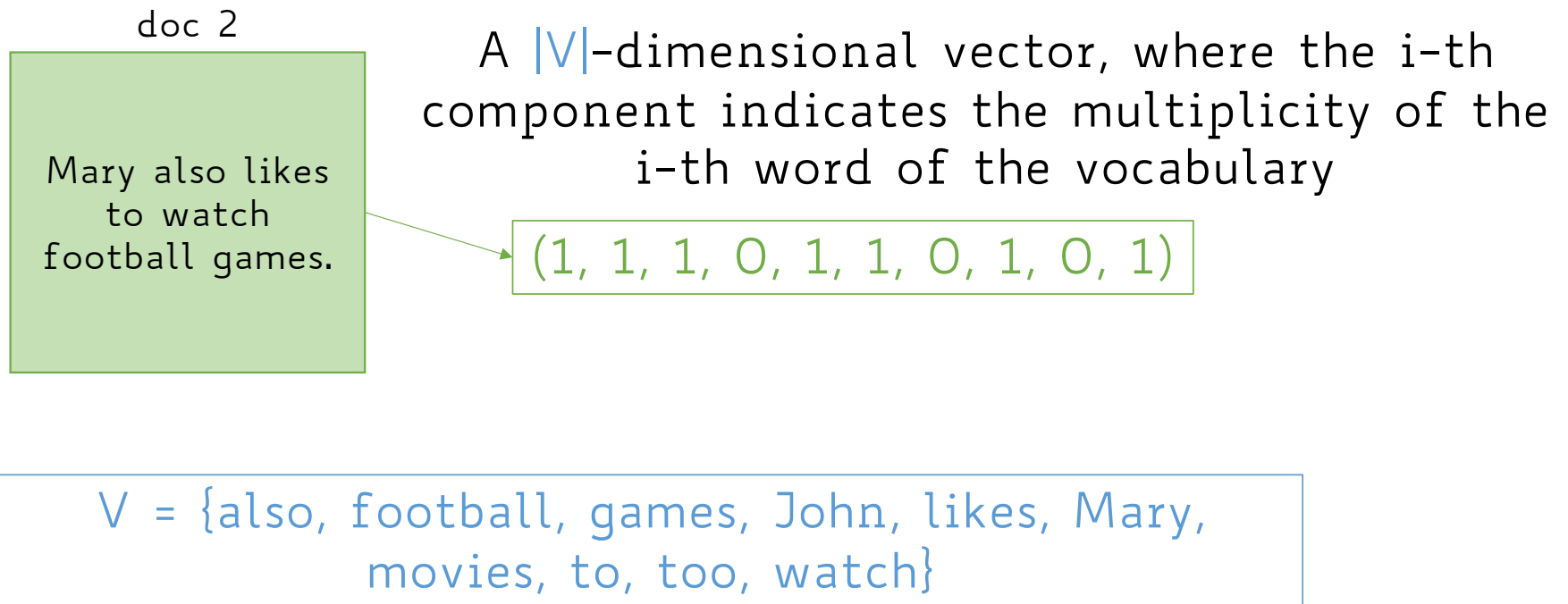
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Bag-of-Words: Weighting Scheme



Bag-of-Words: A Formal Perspective

$D = \{d_1, \dots, d_N\}$ = collection of N documents

$V = \{w_1, \dots, w_{|V|}\}$ = **vocabulary** of $|V|$ words extracted from D

$\mathbf{d}_i = (f(w_1, i), \dots, f(w_{|V|}, i))$ = $|V|$ -dimensional vector representing d_i

$f : V \times D \mapsto \mathbb{R}$ is a function that maps each word of a document to a real value (**weighting scheme**)

Bag-of-Words: A Formal Perspective

One-Hot (binary) weighting scheme

$$f(w_j, i) = \begin{cases} 1 & \text{if } w_j \text{ appears in } d_i \\ 0 & \text{otherwise} \end{cases}$$

Bag-of-Words: A Formal Perspective

Term-Frequency weighting scheme

$$f(w_j, i) = tf(w_j, i)$$

tf computes the number of times word w_j occurs in document d_i

Bag-of-Words: A Formal Perspective

TF-IDF weighting scheme

$$f(w_j, i) = tf(w_j, i) * idf(w_j)$$

$$idf(w_j) = \log \left(\frac{N}{n_j} \right)$$

n_j is the number of documents in D containing the word w_j

Bag-of-Words: A Formal Perspective

TF-IDF weighting scheme

$$f(w_j, i) = tf(w_j, i) * idf(w_j)$$

$$idf(w_j) = \log \left(\frac{N + 1}{n_j + 1} \right)$$

Any idea
why?

n_j is the number of documents in D containing the word w_j

BoW: Limitations and Improvements

- **2 main limitations** of BoW model:
 - High dimensionality → sparseness
 - No sequential information nor semantics included → unigram model

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- **2 main limitations** of BoW model:
 - High dimensionality → sparseness
 - No sequential information nor semantics included → unigram model
- Possible improvements:
 - Use n -grams rather than unigrams to capture sequentiality between consecutive words (i.e., context)
 - Even better, use so-called Neural Language Models like word2vec, BERT, and, more recently, Transformers (LLMs)

Bag-of- n -grams

Example: bigrams ($n=2$)

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{"John likes", "likes to", "to
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{"Mary also", "also likes", "likes to",
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Document Similarity

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- Depending on those, several similarity measures can be used
- For example, if documents are represented as:
 - set of words → Jaccard coefficient
 - one-hot bag-of-words → Euclidean distance
 - tf or tf-idf bag-of-words → Cosine similarity

High-Dimensional Spaces

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- In the word space, the size of the vocabulary can be very high!
- Moreover, only few dimensions are non-zero
- Other domains like images, audio, etc. suffer from the same issue

High-Dimensional Spaces

- Data in a high-dimensional space tends to be **sparser** than in lower dimensions

High-Dimensional Spaces

- Data in a high-dimensional space tends to be **sparser** than in lower dimensions
- Data points are **more dissimilar** to each other

High-Dimensional Spaces

- In Euclidean space, the distance between two points is large as long as they are far apart along **at least one** dimension

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- In Euclidean space, the distance between two points is large as long as they are far apart along **at least one** dimension
- The higher the number of dimensions the higher the chance this happens

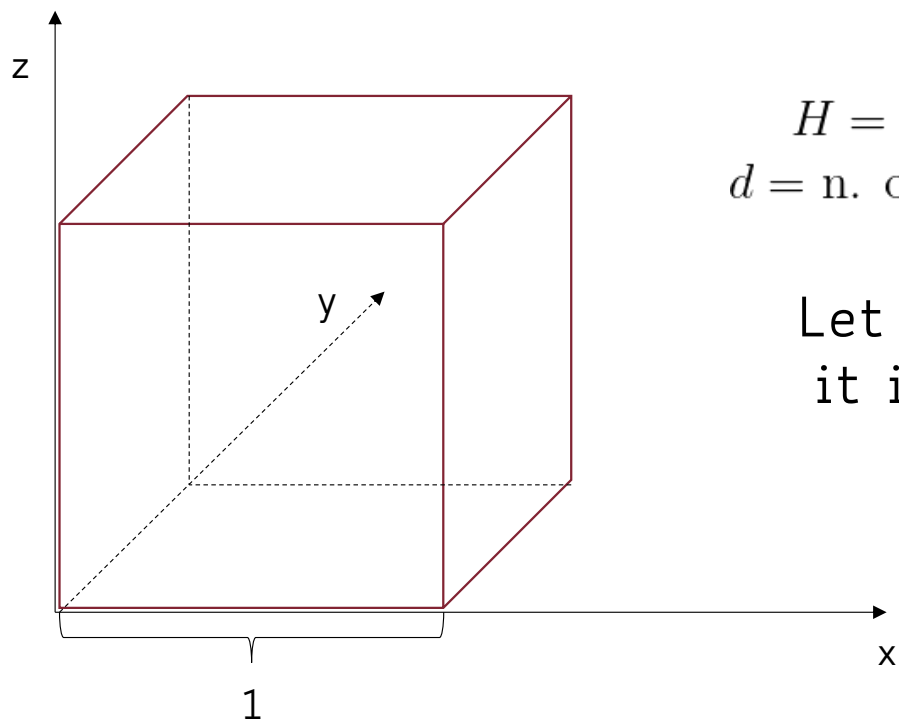
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The Curse of Dimensionality

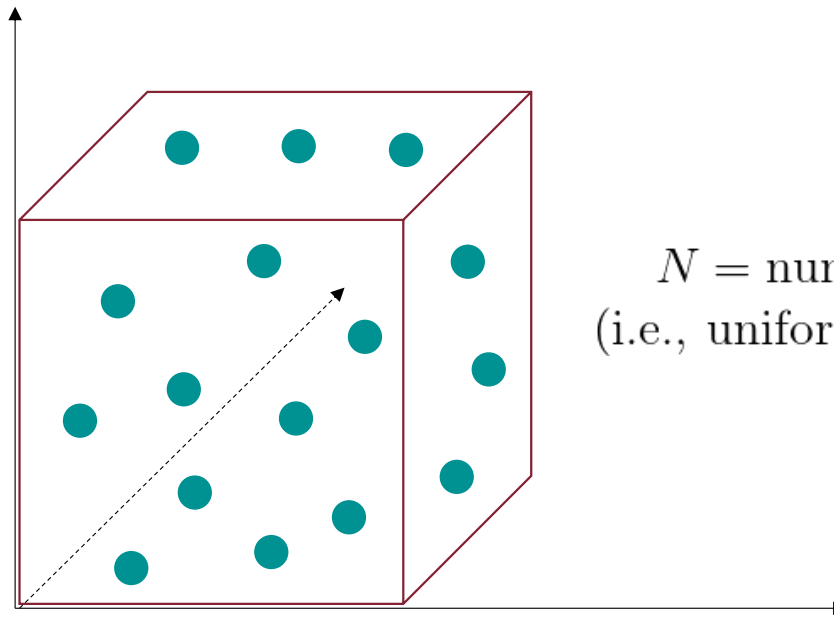
The Curse of Dimensionality



H = unit-length hypercube in \mathbb{R}^d
 d = n. of space dimensions

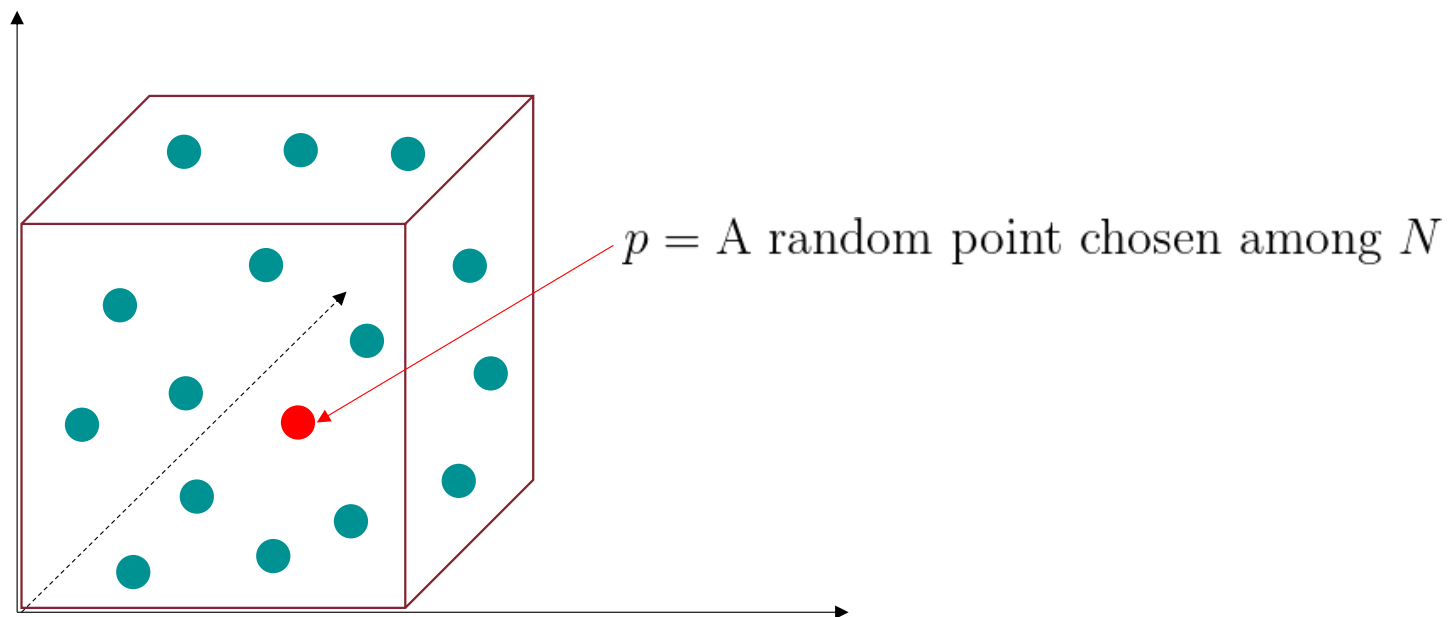
Let $d=3$ as beyond that
it is hard to visualize
the space

The Curse of Dimensionality

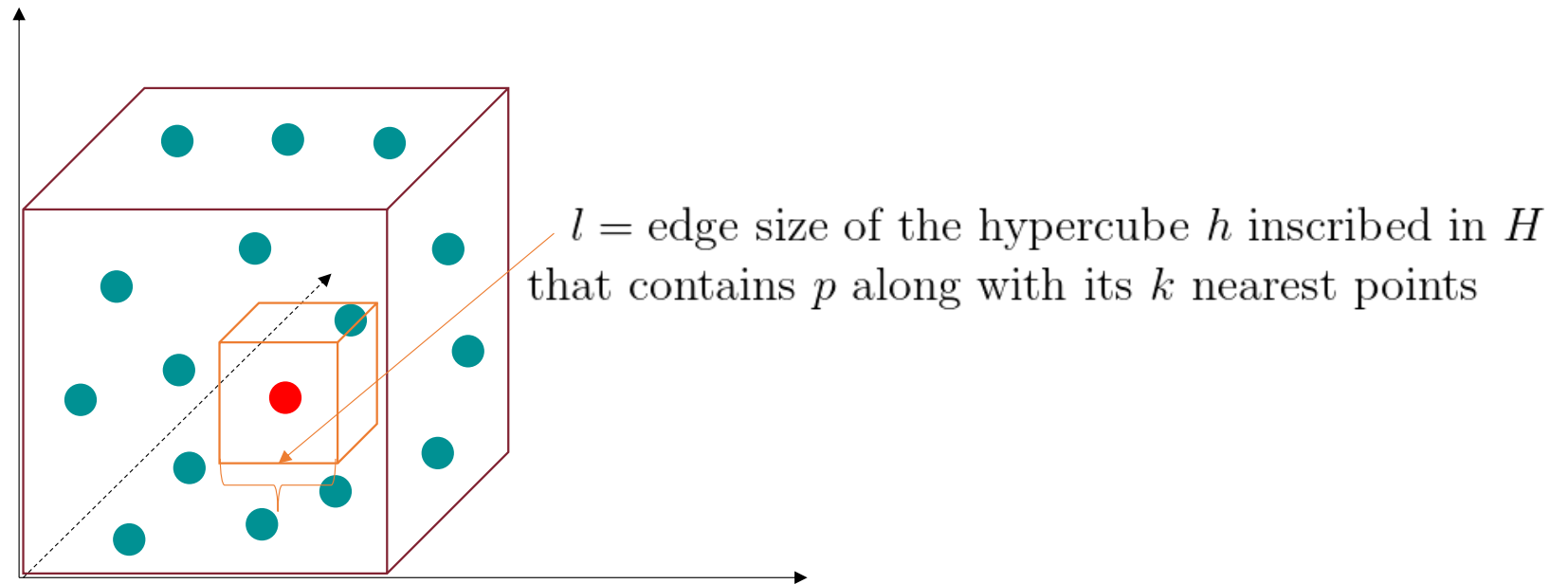


N = number of data points randomly
(i.e., uniformly) distributed in H

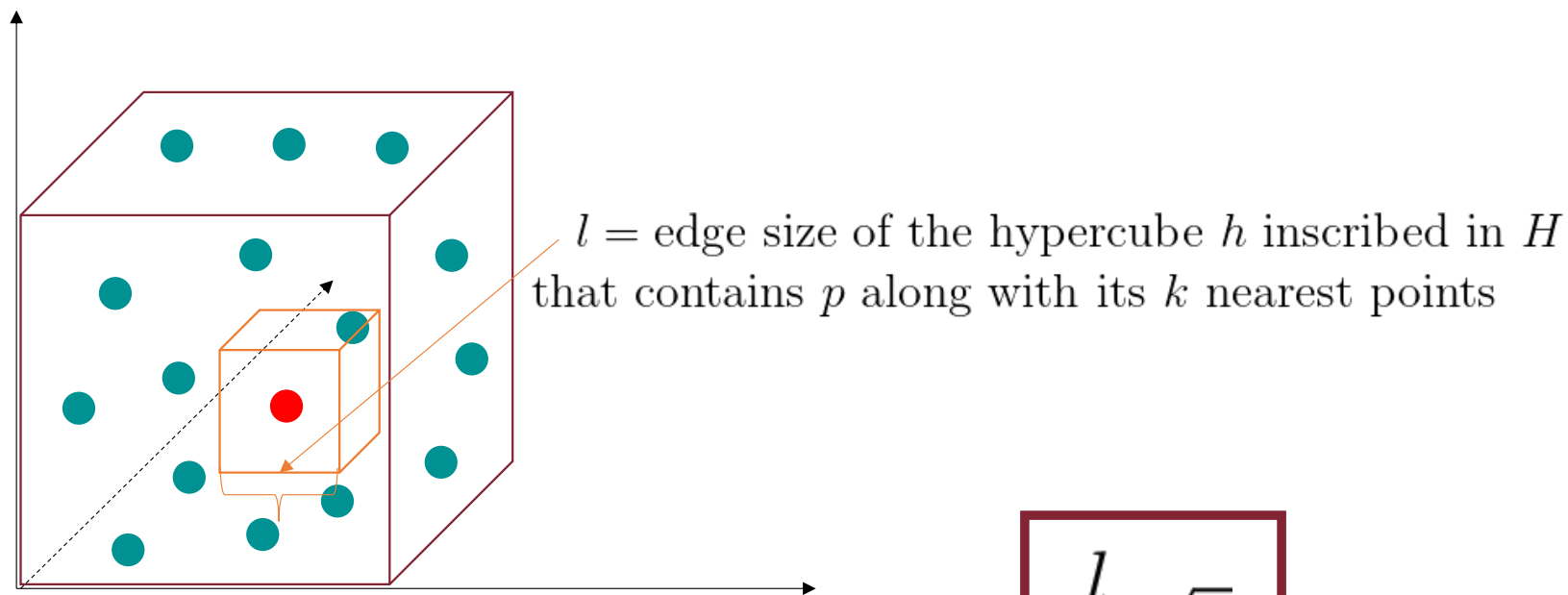
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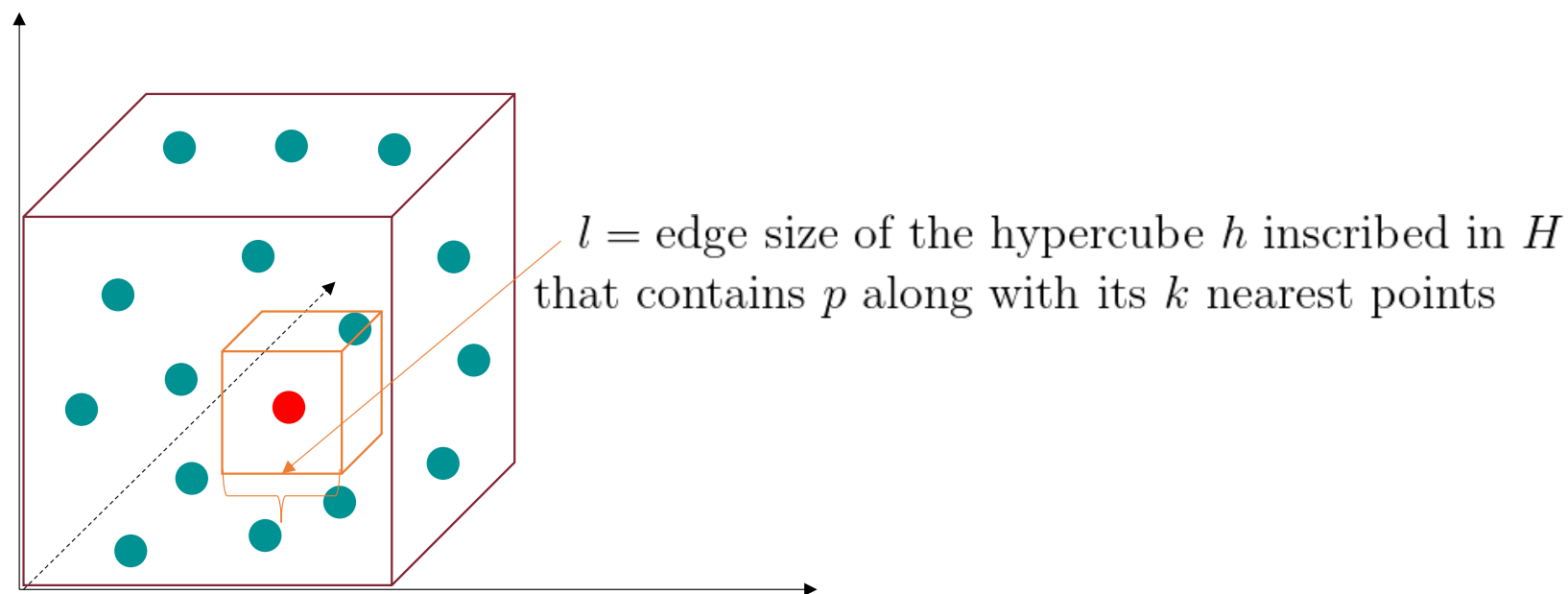
The Curse of Dimensionality



We consider **edge points** whose distance from p is **at most** $\frac{l}{2}\sqrt{d}$

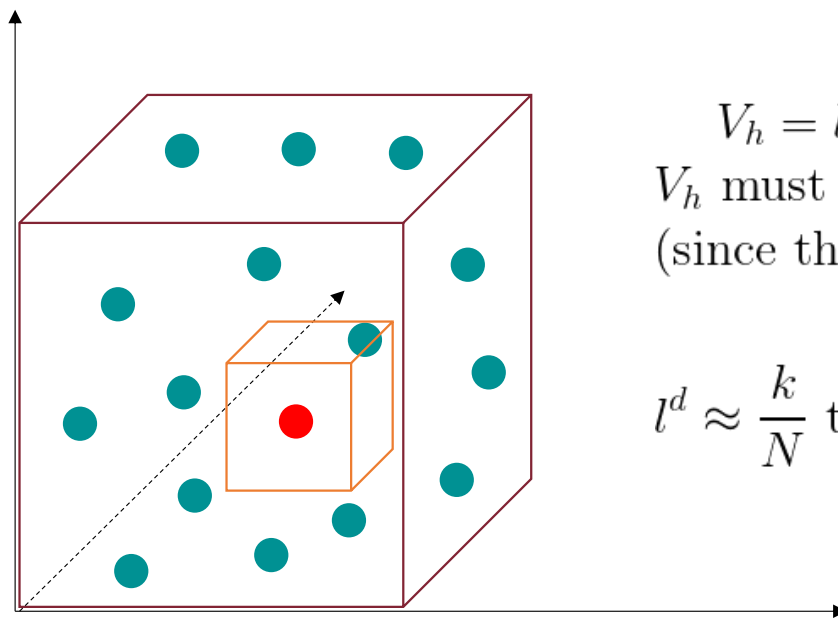
$$\frac{l}{2}\sqrt{3}$$

The Curse of Dimensionality



The same question can be formulated in terms of the radius l of an inscribed hypersphere

The Curse of Dimensionality



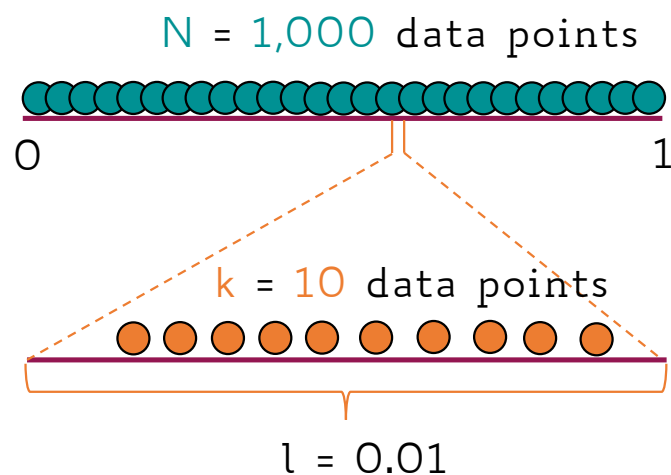
$V_h = l^d$ volume of the hypercube h
 V_h must roughly contain k/N points
(since those are randomly distributed)

$$l^d \approx \frac{k}{N} \text{ therefore } l \approx \left(\frac{k}{N} \right)^{1/d}$$

The Curse of Dimensionality

A few numbers... $N = 1,000; k = 10 \quad l \approx \left(\frac{10}{1000}\right)^{1/d} = \left(\frac{1}{100}\right)^{1/d}$

d	l
1	0.01

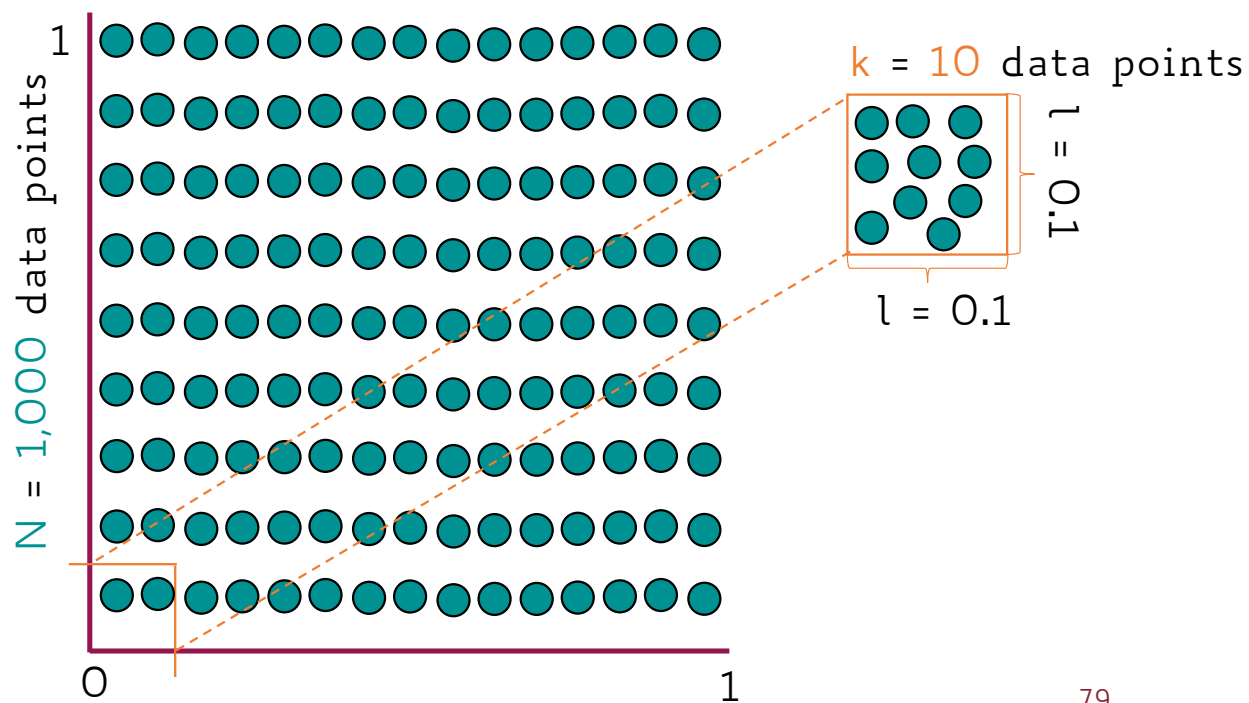


The Curse of Dimensionality

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d	l
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2	0.1



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d	l
1	0.01
2	0.1
3	0.215
...	...
10	0.631

When d is equal 10 the length of the edge of the inscribed hypercube is already about 63% of the largest hypercube

The Curse of Dimensionality

A few numbers...

$$N = 1,000; k = 10 \quad l \approx \left(\frac{10}{1000} \right)^{1/d} = \left(\frac{1}{100} \right)^{1/d}$$

d	l
1	0.01
2	0.1
3	0.215
...	...
10	0.631
...	...
1000	0.995

When d is equal 1,000 there is basically no difference between the two hypercubes!

The Curse of Dimensionality: Why Bother?

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The Curse of Dimensionality: Why Bother?

- Points are more likely to be located at the edges of the region
- Nearest points are not close at all!
- Distance between points indistinguishable (**distance concentration**)
 - Hard to separate between nearest and furthest data points
 - Hard to find clusters among so many pairs that are all at approximately the same distance

The Curse of Dimensionality: The Edge

Let ε define the **edge** (i.e., border) of our space

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See how the probability of picking a data point that is **not** located at the edge changes as the number of dimensions grow

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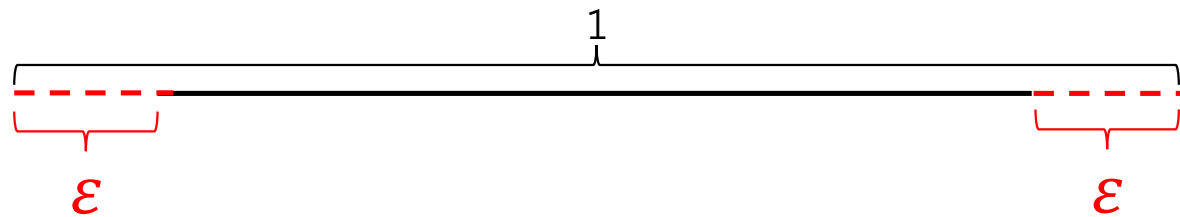
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Remember:

We assume data points are **uniformly distributed at random** on the space

The Curse of Dimensionality: The Edge

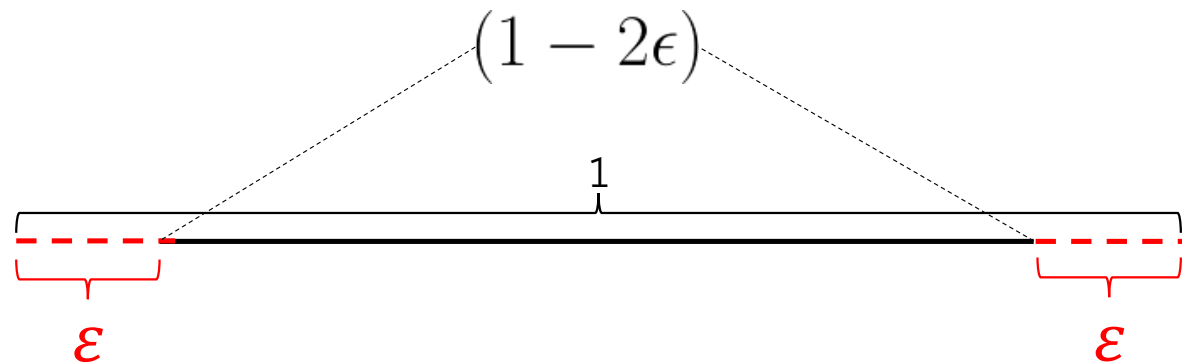
$$d = 1$$



The Curse of Dimensionality: The Edge

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The Curse of Dimensionality: The Edge

$$d > 1$$

The probability of being **not** at the edge is
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$$(1 - 2\epsilon)^d$$

assuming each dimension is independent from each other

The Curse of Dimensionality: The Edge

$$d > 1$$

The probability of being **not** at the edge is
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$$(1 - 2\epsilon)^d$$

assuming each dimension is independent from each other

$$\lim_{d \rightarrow \infty} (1 - 2\epsilon)^d = 0$$

The Curse of Dimensionality

A Notebook where the Curse of Dimensionality is (visually) explained is available at the following link:

https://github.com/gtolomei/big-data-computing/blob/master/notebooks/The_Curse_of_Dimensionality.ipynb

So What Can We Do?

- If data are really uniformly distributed in a high-dimensional space... nothing!

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- Luckily, though, real-world (interesting) data have patterns underneath (i.e., they are **not random!**)
- Lower intrinsic dimensionality

So What Can We Do?

The Manifold Hypothesis

- High dimensional data (e.g., images) lie on low-dimensional manifolds (i.e., sub-space) embedded in the high-dimensional space

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The Manifold Hypothesis

- High dimensional data (e.g., images) lie on low-dimensional manifolds (i.e., sub-space) embedded in the high-dimensional space
- Dimensionality reduction techniques (more on this later...)

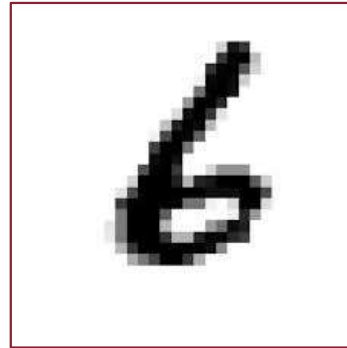
Modeled vs. True Dimensionality

Example

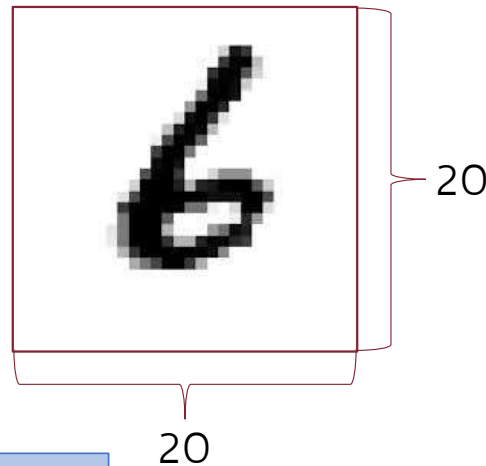
Handwritten digit recognition



Modeled vs. True Dimensionality



Modeled vs. True Dimensionality

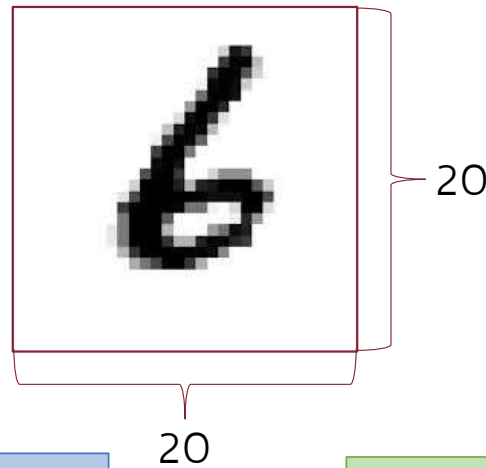


Modeled dimensionality

Each digit represented by
20x20 bitmap

400-dimensional binary vector

Modeled vs. True Dimensionality



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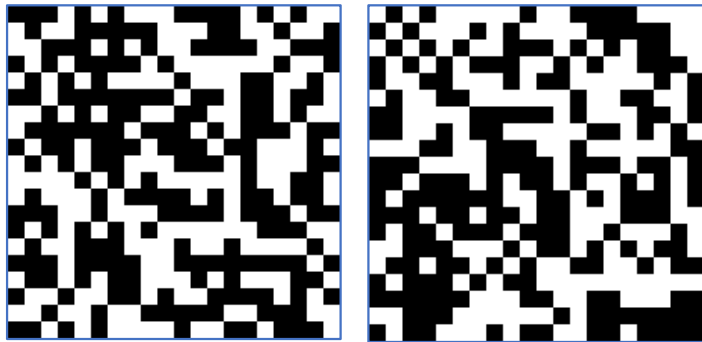
True dimensionality

Actual digits just cover a tiny
fraction of all this huge space

Small variations of the pen-stroke

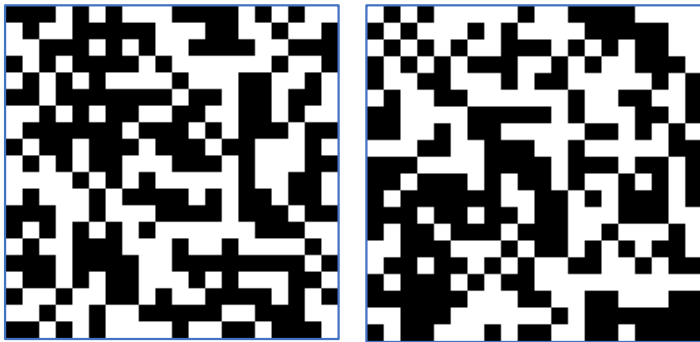
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Random samples
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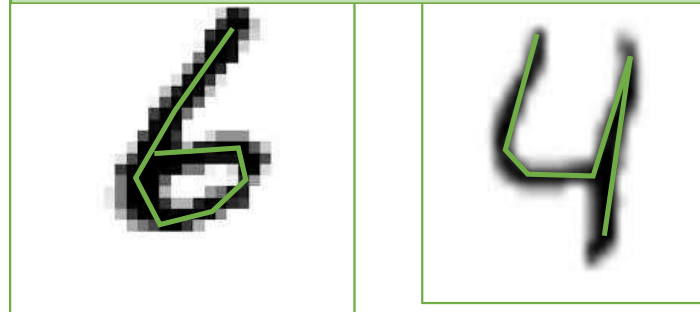


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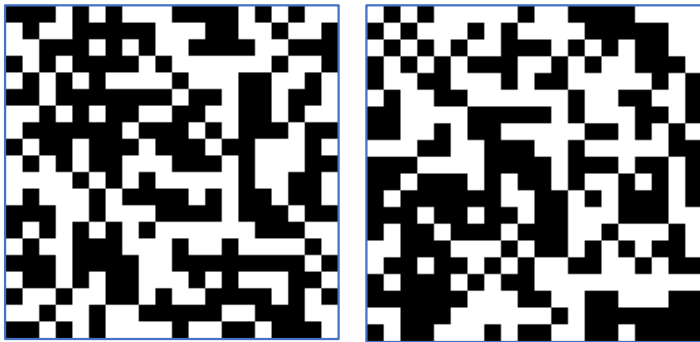


True digits living
in a
400-d space



Modeled vs. True Dimensionality

Random samples
from 400-d space



True digits living
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We model data (i.e., digits) as very high dimensional...
... In fact, they are not so

Take-Home Message of Today

- Many big data tasks are based on finding (hidden) commonalities between input data points

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- For example, clustering is an unsupervised learning technique to group "similar" objects together
- Depends on:
 - **object representation**
 - **similarity measure**

Take-Home Message of Today

- In the Euclidean space, when data dimensionality gets large, similarity/distance becomes meaningless!

Take-Home Message of Today

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- Any set of random data points are far away from each other → **curse of dimensionality**

Take-Home Message of Today

- In the Euclidean space, when data dimensionality gets large, similarity/distance becomes meaningless!
- Any set of random data points are far away from each other → **curse of dimensionality**
- Luckily, real-data may live in lower-dimensional spaces

