

Big Data Computing

Master's Degree in Computer Science
2025-2026



SAPIENZA
UNIVERSITÀ DI ROMA

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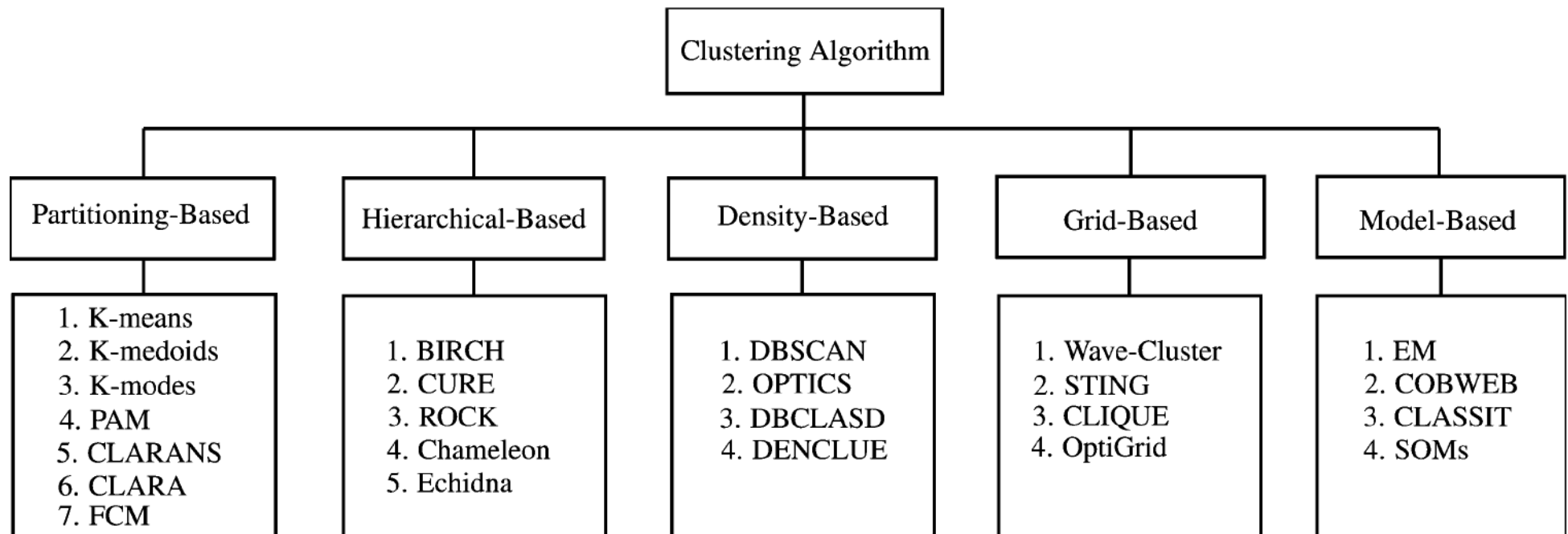
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Recap from Last Lecture(s)

- Clustering is an unsupervised learning technique to group "similar" data objects together
- Depends on:
 - object representation
 - similarity measure
- Harder when data dimensionality gets large (**curse of dimensionality**)
- Number of output clusters is part of the problem itself!

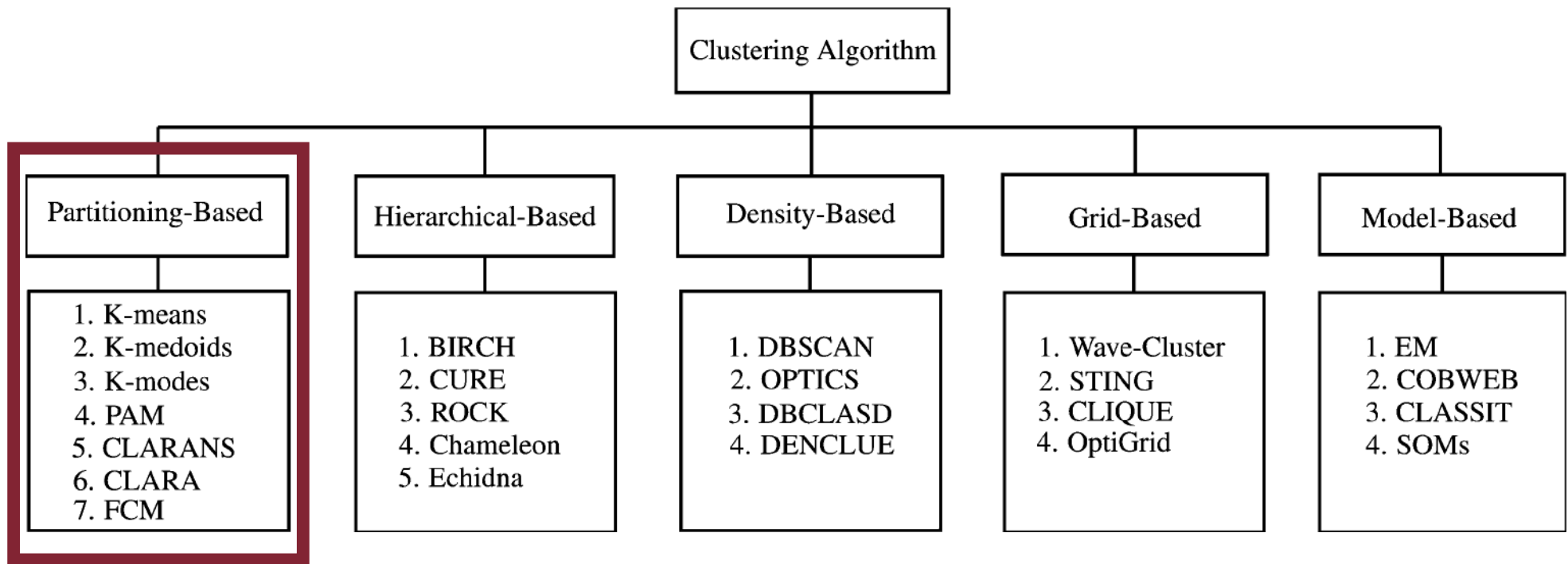
Clustering Algorithms

Clustering Algorithms: Taxonomy



source: <https://www.computer.org/csdl/journal/ec/2014/03/06832486/13rRUEgs2xB>

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Partitioning: Hard Clustering

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- **Output:** A partition of the N data points into K clusters
- **Goal:** Find the partition which optimizes a certain criterion

Partitioning: Intuition

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Here is a possible assignment (i.e., clustering output):

	0	1	2			...				N-1
C	0	1	1	...	0	0	1	...	0	1

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Roughly, 2^N ; More generally, K^N

0	1	2		...					N-1
{0..K-1}	{0..K-1}	{0..K-1}	...	{0..K-1}	{0..K-1}	{0..K-1}	...	{0..K-1}	{0..K-1}

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Actually, **slightly less** than that because we want each of the K clusters to contain at least one data point!

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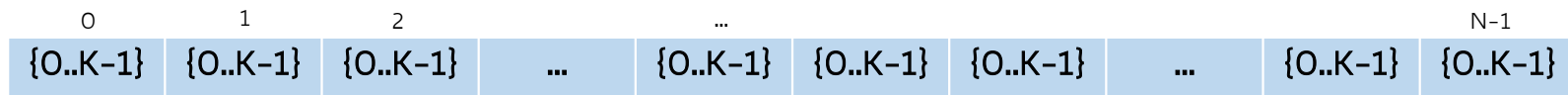
In the previous example ($K=2$), the following is **not** allowed

0	1	2	...				N-1		0	1	2	...				N-1			
0	0	0	...	0	0	0	...	0	0	1	1	1	...	1	1	1	...	1	1

Partitioning: Intuition

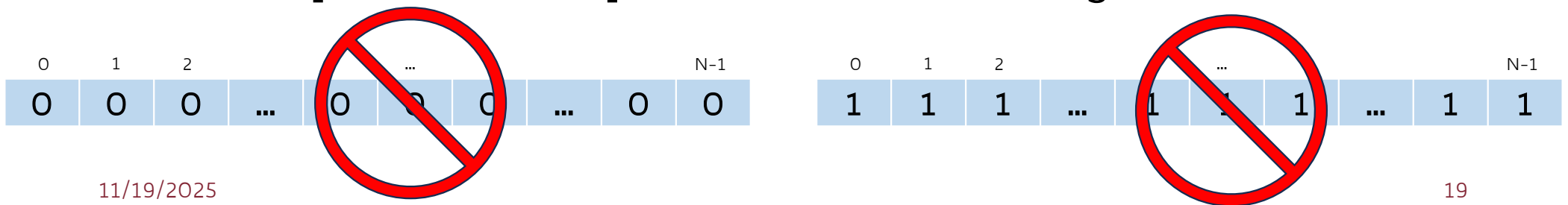
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$\{\{5\}, \{1,2,3,4\}\} \rightarrow (1,1,1,1,0)$

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- Finding the **global optimum** \rightarrow Intractable for many objective function (enumerate all the possible partitions)*
- Effective heuristics \rightarrow K-means, K-medoids, K-means++, etc.

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Flat Hard Clustering: General Framework

$\{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ the set of N input data points
 $\{C_1, \dots, C_K\}$ the set of K output clusters
 C_k the generic k -th cluster
 $\boldsymbol{\theta}_k$ is the *representative* of cluster C_k

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 C_k the generic k -th cluster
 θ_k is the *representative* of cluster C_k

Note:

At this stage we haven't yet specified what a cluster representative actually is

Objective Function

$$L(A, \Theta) = \sum_{n=1}^N \sum_{k=1}^K \alpha_{n,k} \delta(\mathbf{x}_n, \boldsymbol{\theta}_k)$$

where:

- A is an $N \times K$ matrix s.t. $\alpha_{n,k} = 1$ iff \mathbf{x}_n is assigned to cluster C_k , 0 otherwise
- $\Theta = \{\boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_K\}$ are the cluster representatives
- $\delta(\mathbf{x}_n, \boldsymbol{\theta}_k)$ is a function measuring the distance between \mathbf{x}_n and $\boldsymbol{\theta}_k$

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$$A^*, \Theta^* = \operatorname{argmin}_{A, \Theta} \underbrace{\sum_{n=1}^N \sum_{k=1}^K \alpha_{n,k} \delta(\mathbf{x}_n, \theta_k)}_{L(A, \Theta)}$$

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exact solution must explore
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 $S(K, N) \sim O(K^N)$



NP-hard

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NP-hard

non-convex due to the
discrete assignment matrix A



multiple local
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Iterative Solution: Lloyd-Forgy Algorithm

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- **NP-hardness** doesn't allow us to compute the exact solution (i.e., global optimum)
- **Non-convexity** doesn't allow us to rely on nice property of convex optimization (unique global optimum)
- A convex objective can be (approximately) solved with numerical methods to find the global optimum

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- **Lloyd-Forgy Algorithm:** 2-step **iterative** approximated solution

Iterative Solution: Lloyd-Forgy Algorithm

- Lloyd-Forgy Algorithm: 2-step **iterative** approximated solution
- Assignment step
- Update step

Iterative Solution: Lloyd-Forgy Algorithm

- **Lloyd-Forgy Algorithm:** 2-step **iterative** approximated solution
- **Assignment step**
- **Update step**

Does not guarantee to find the global optimum as it may stuck to a local optimum or a saddle point

2-Step Optimization: Assignment Step

Minimize L w.r.t. A by fixing Θ

$L(A|\Theta) = L(A; \Theta) = L$ is a function of A parametrized by Θ

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Note:

Can't take the gradient of L w.r.t. A
since A is discrete!

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Intuitively, given a set of fixed representatives, L is minimized if each data point is assigned to the closest cluster representative according to δ

(L is the sum of all the distances from each data point to its representative)

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$$\alpha_{n,k} = \begin{cases} 1 & \text{if } \delta(\mathbf{x}_n, \boldsymbol{\theta}_k) = \min_{1 \leq j \leq K} \{\delta(\mathbf{x}_n, \boldsymbol{\theta}_j)\} \\ 0 & \text{otherwise} \end{cases}$$

2-Step Optimization: Update Step

Minimize L w.r.t. Θ by fixing A

$L(\Theta|A) = L(\Theta; A) = L$ is a function of Θ parametrized by A

2-Step Optimization: Update Step

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We can minimize L by taking the **gradient** of L w.r.t Θ (i.e., the vector of partial derivatives), set it to 0 and solve it for Θ

2-Step Optimization: Update Step

$$\nabla L(\Theta; A) = \left(\frac{\partial L(\Theta; A)}{\partial \theta_1}, \dots, \frac{\partial L(\Theta; A)}{\partial \theta_K} \right)$$

2-Step Optimization: Update Step

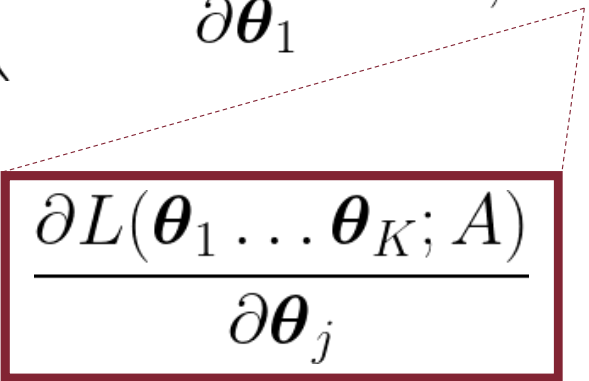
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$$\frac{\partial L(\theta_1 \dots \theta_K; A)}{\partial \theta_j}$$

The general j-th partial derivative

2-Step Optimization: Update Step

$$\nabla L(\Theta; A) = \mathbf{0} \Leftrightarrow \frac{\partial L(\theta_1, \dots, \theta_K; A)}{\partial \theta_j} = 0 \quad \forall j \in \{1, \dots, K\}$$

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$$\downarrow$$
$$\frac{\partial L}{\partial \theta_j}$$

To make the notation easier!

2-Step Optimization: Update Step

$$\frac{\partial L}{\partial \boldsymbol{\theta}_j} = \frac{\partial}{\partial \boldsymbol{\theta}_j} \left[\sum_{n=1}^N \sum_{k=1}^K \alpha_{n,k} \delta(\mathbf{x}_n, \boldsymbol{\theta}_k) \right] = 0$$

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When computing the partial derivative w.r.t. $\boldsymbol{\theta}_j$ any other term $\boldsymbol{\theta}_k$ of the inner summation is treated as constant!

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Solve for each $\boldsymbol{\theta}_j$
independently

Depends on the distance
function δ

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- The centroid of a cluster is the **mean** of the instances assigned to that cluster
- (Re)Assignment of instances to clusters is based on distance/similarity to the current cluster centroids
- The basic idea is constructing clusters so that the total within-cluster **Sum of Square Distances (SSD)** is minimized

K-means: Setup

$\{\mathbf{x}_1, \dots, \mathbf{x}_N\}$ the set of N input data points
 $\{C_1, \dots, C_K\}$ the set of K output clusters
 C_k the generic k -th cluster

$$\boldsymbol{\theta}_k = \frac{\sum_{n=1}^N \alpha_{n,k} \mathbf{x}_n}{\sum_{n=1}^N \alpha_{n,k}} = \boldsymbol{\mu}_k = \frac{1}{|C_k|} \sum_{n \in C_k} \mathbf{x}_n$$

$$\text{where } |C_k| = \sum_{n=1}^N \alpha_{n,k}$$

K-means: Objective Function

$$L(A, \Theta) = \sum_{n=1}^N \sum_{k=1}^K \alpha_{n,k} \underbrace{(\|\mathbf{x}_n - \boldsymbol{\theta}_k\|_2)^2}_{\delta(\mathbf{x}_n, \boldsymbol{\theta}_k)} \text{Euclidean space}$$

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$$\begin{aligned} \delta(\mathbf{x}_n, \boldsymbol{\theta}_k) &= (\|\mathbf{x}_n - \boldsymbol{\theta}_k\|_2)^2 = \\ &= \left[\sqrt{(\mathbf{x}_n - \boldsymbol{\theta}_k)^2} \right]^2 = (\mathbf{x}_n - \boldsymbol{\theta}_k)^2 \end{aligned}$$

Sum of Square Distances
(SSD)

K-means: Objective Function

$$L(A, \Theta) = \sum_{n=1}^N \sum_{k=1}^K \alpha_{n,k} \underbrace{(\|\mathbf{x}_n - \boldsymbol{\theta}_k\|_2)^2}_{\delta(\mathbf{x}_n, \boldsymbol{\theta}_k)}$$

$$\begin{aligned} \delta(\mathbf{x}_n, \boldsymbol{\theta}_k) &= (\|\mathbf{x}_n - \boldsymbol{\theta}_k\|_2)^2 = \\ &= \left[\sqrt{(\mathbf{x}_n - \boldsymbol{\theta}_k)^2} \right]^2 = (\mathbf{x}_n - \boldsymbol{\theta}_k)^2 \end{aligned}$$

Sum of Square Distances
(SSD)

$$L(A, \Theta) = \sum_{n=1}^N \sum_{k=1}^K \alpha_{n,k} (\mathbf{x}_n - \boldsymbol{\theta}_k)^2$$

K-means: Assignment Step

Minimize L w.r.t. A by fixing Θ

Intuitively, given a set of fixed centroids, L is minimized if each data point is assigned to the centroid with the smallest SSD

(L is just the SSD from each data point to its assigned centroid)

$$\alpha_{n,k} = \begin{cases} 1 & \text{if } (\mathbf{x}_n - \boldsymbol{\theta}_k)^2 = \min_{1 \leq j \leq K} \{(\mathbf{x}_n - \boldsymbol{\theta}_j)^2\} \\ 0 & \text{otherwise} \end{cases}$$

K-means: Update Step

Minimize L w.r.t. Θ by fixing A

$$\Theta^* = \operatorname{argmin}_{\Theta} \underbrace{\left\{ \sum_{n=1}^N \sum_{k=1}^K \alpha_{n,k} (\mathbf{x}_n - \boldsymbol{\theta}_k)^2 \right\}}_{L(\Theta; A)}$$

Compute the gradient w.r.t. Θ , set it to 0 and solve it for Θ

K-means: Update Step

$$\frac{\partial L}{\partial \boldsymbol{\theta}_k} = \frac{\partial}{\partial \boldsymbol{\theta}_k} \left[\sum_{n=1}^N \alpha_{n,k} (\mathbf{x}_n - \boldsymbol{\theta}_k)^2 \right] = 0 \quad \forall k \in \{1, \dots, K\}$$

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$$\text{Find } \boldsymbol{\theta}_k^* \text{ s.t. } \sum_{n=1}^N -2\alpha_{n,k} (\mathbf{x}_n - \boldsymbol{\theta}_k^*) = 0$$

K-means: Update Step

$$\begin{aligned}\sum_{n=1}^N -2\alpha_{n,k}(\mathbf{x}_n - \boldsymbol{\theta}_k^*) &= 0 \Leftrightarrow \\ 2 \sum_{n=1}^N \alpha_{n,k} \boldsymbol{\theta}_k^* &= 2 \sum_{n=1}^N \alpha_{n,k} \mathbf{x}_n \\ \boldsymbol{\theta}_k^* \sum_{n=1}^N \alpha_{n,k} &= \sum_{n=1}^N \alpha_{n,k} \mathbf{x}_n\end{aligned}$$

K-means: Update Step

$$\sum_{n=1}^N -2\alpha_{n,k}(\mathbf{x}_n - \boldsymbol{\theta}_k^*) = 0 \Leftrightarrow$$

$\boldsymbol{\theta}_k^*$ does not depend on N , therefore it can be factored out

$$2 \sum_{n=1}^N \alpha_{n,k} \boldsymbol{\theta}_k^* = 2 \sum_{n=1}^N \alpha_{n,k} \mathbf{x}_n$$

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K-means: Update Step

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The cluster centroid (i.e., **mean**) minimizes the objective
(for a fixed assignment A)

K-means: Lloyd-Forgy Algorithm

1. Specify the number of output clusters K

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5. Iteratively repeat steps 3-4 until a **stopping criterion** is met

Stopping Criterion

- Several options to choose from:
 - Fixed number of iterations
 - Cluster assignments stop changing (beyond some threshold)
 - Centroid doesn't change (beyond some threshold)

Lloyd-Forgy's Convergence

- How/Why are we guaranteed the K-means algorithm ever reaches a fixed point?
 - A state in which clusters do not change

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- How/Why are we guaranteed the K-means algorithm ever reaches a fixed point?
 - A state in which clusters do not change
- Intuitively, in both steps we either improve the objective or not
- It is an instance of more general **Expectation Maximization (EM)**
 - EM is known to converge (although not necessarily to a global optimum)

Lloyd-Forgy's Relationship with EM

- E-step = Assignment step
 - Each object is assigned to the closest centroid, i.e., to the most likely cluster
 - Monotonically decreases SSD

Lloyd-Forgy's Relationship with EM

- **E-step = Assignment step**
 - Each object is assigned to the closest centroid, i.e., to the most likely cluster
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- **M-step = Update step**
 - The model (i.e., centroids) are updated (i.e., SSD optimization)
 - Monotonically decreases each SSD_k

Lloyd-Forgy's Complexity Analysis

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- Overall: $O(RKNd)$ if the 2 steps above are repeated R times

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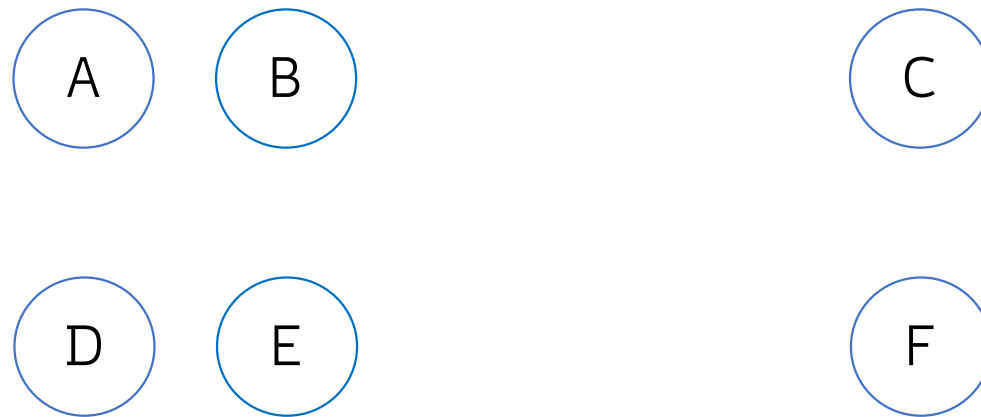
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Problem Mitigation:

Execute several runs of the Lloyd-Forgy algorithm with multiple random initialization seeds

K-means: Seed Choice

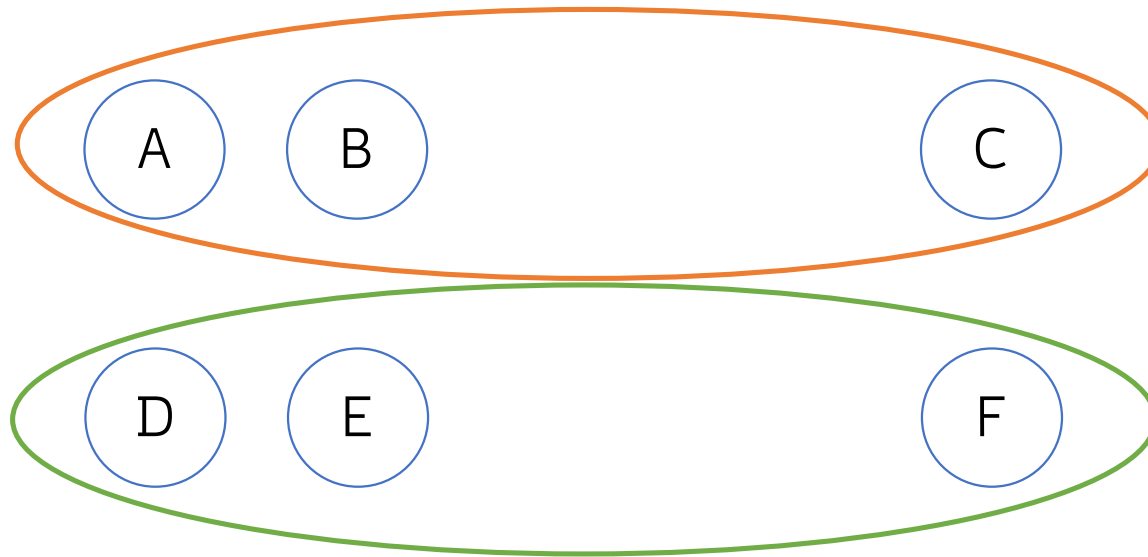


K-means: Bad (Unlucky) Seed Choice



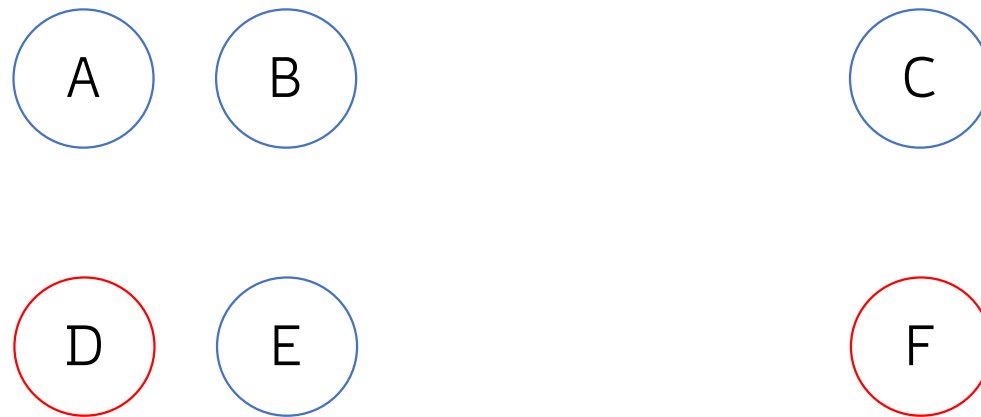
If B and E are randomly chosen as initial centroids...

K-means: Bad (Unlucky) Seed Choice



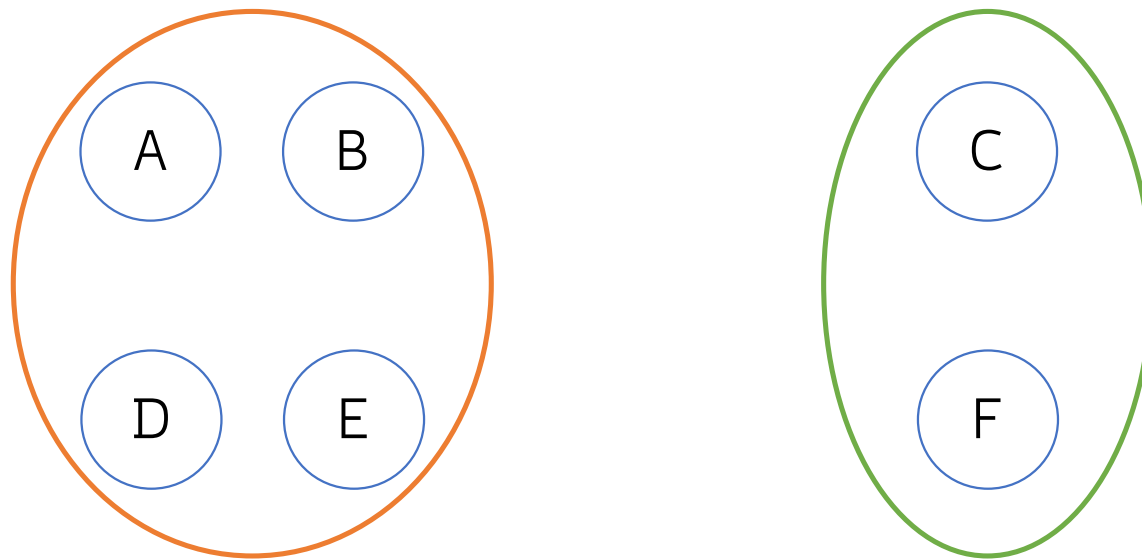
The algorithm converges to the sub-optimal clustering above

K-means: Good (Lucky) Seed Choice



If D and F are randomly chosen as initial centroids instead...

K-means: Good (Lucky) Seed Choice



The algorithm converges to a better clustering

Take-Home Message of Today

- Focus on hard partitioning clustering

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- Formulate hard partitioning clustering as a (**non-convex**) optimization problem
 - Minimizing “some” aggregated internal cluster distance

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Take-Home Message of Today

- Focus on hard partitioning clustering
- Formulate hard partitioning clustering as a (**non-convex**) optimization problem
 - Minimizing “some” aggregated internal cluster distance
- Computing exact solution is **NP-hard** due to exponential search space
- Use an iterative (approximate) solution → e.g., **K-means**