# Sistemi Operativi

## Corso di Laurea in Informatica

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SAPIENZA
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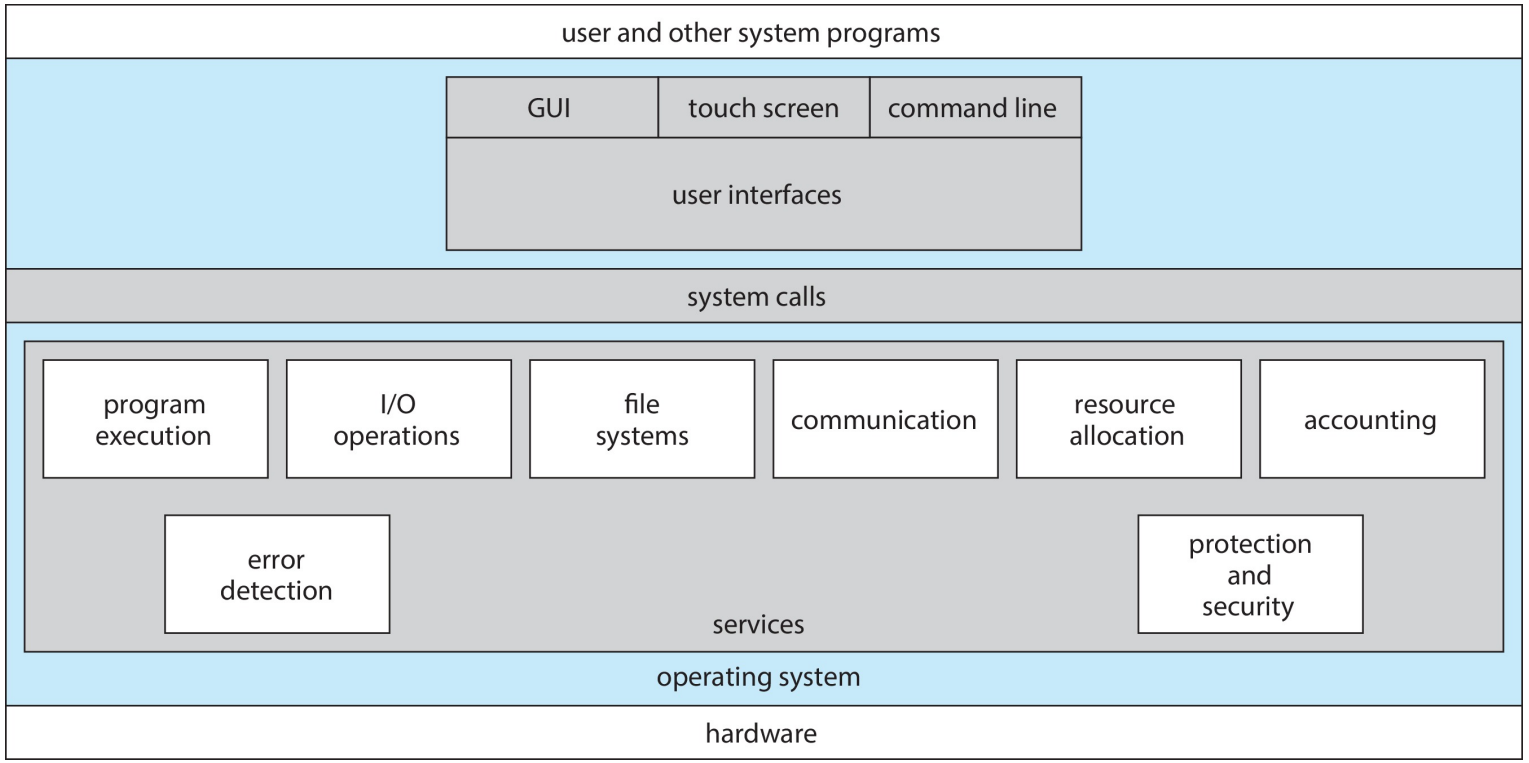
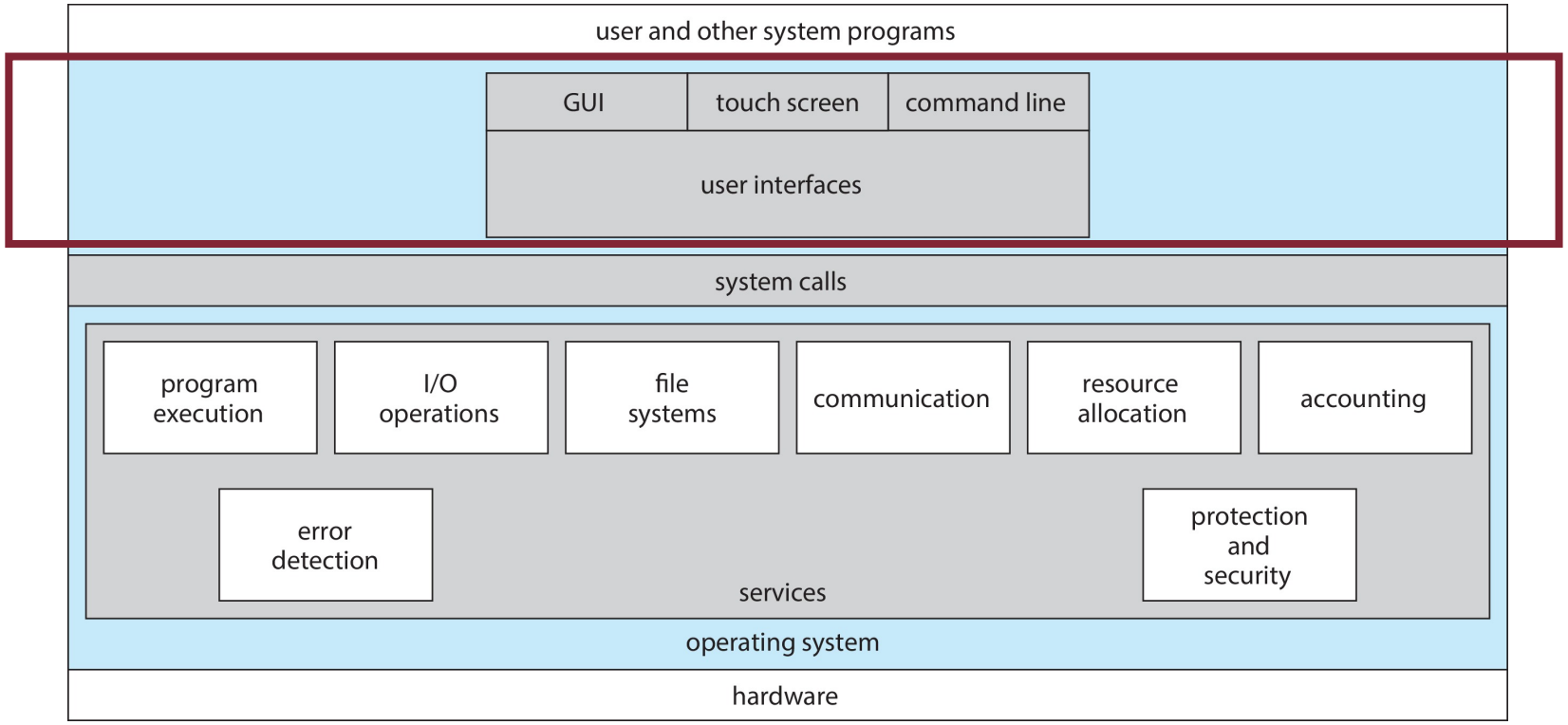
  - **Synchronization/Scheduling** → traps and interrupt vector table
  - **Virtualization** → virtual memory and virtual address space

# Modern OS Functionalities



# User to OS Interface



# User-OS Interface: CLI

- Command Line Interpreter (CLI) allows direct command entry
  - Sometimes implemented in kernel, sometimes by system programs
  - Multiple implementation: e.g., Bourne shell (`sh`/`bash`), Korn shell (`ksh`), etc.

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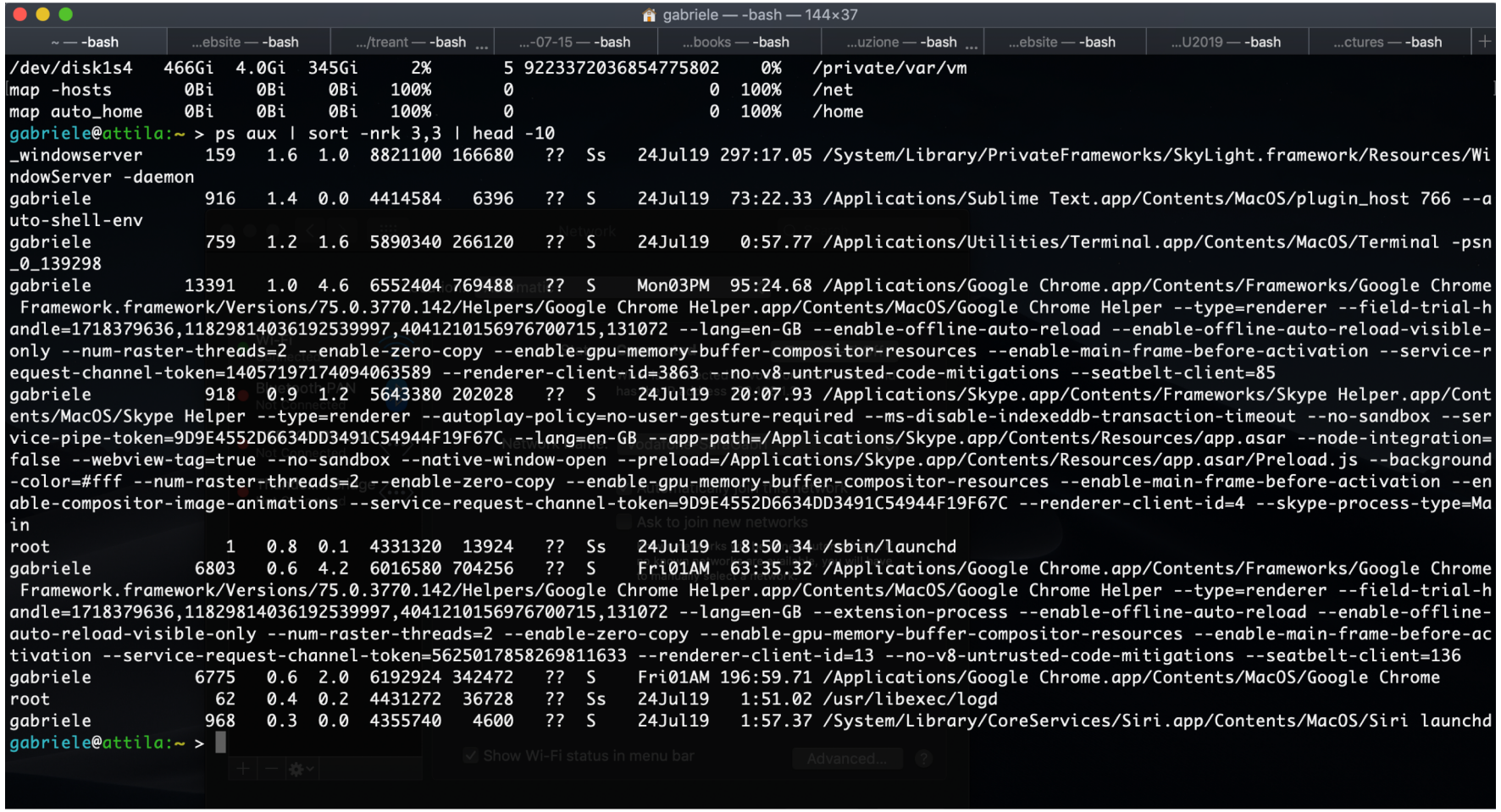
- Fetches a command from user prompt and executes it
- Some commands are built-in, some others are just names of programs

# Bourne-Again SHell (BASH)



# User-OS Interface: GUI

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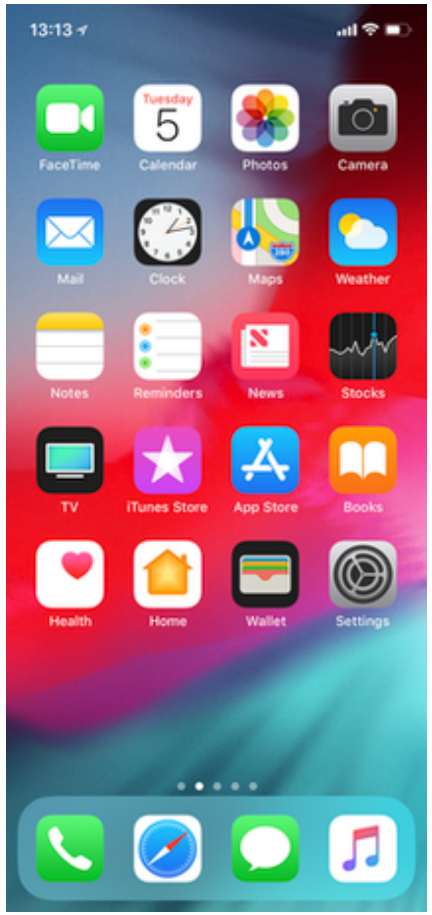
  - Icons represent files, programs, actions, etc.
- Many systems now include both CLI and GUI interfaces
  - Microsoft Windows is GUI with CLI "command" shell
  - Apple macOS has "Aqua" GUI interface with UNIX kernel underneath and shells available
  - UNIX and Linux have CLI with optional GUI interfaces (CDE, KDE, GNOME)

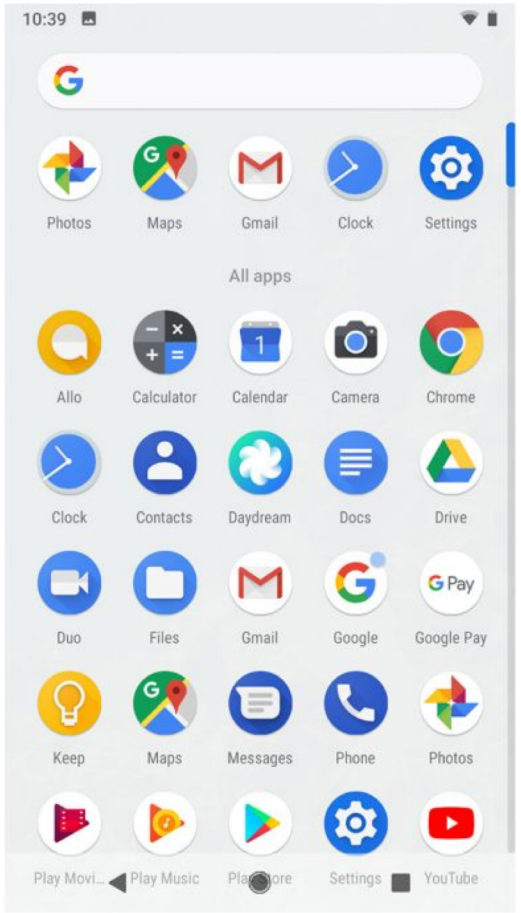
# macOS Mojave "Aqua" GUI

# User-OS Interface: Touchscreen

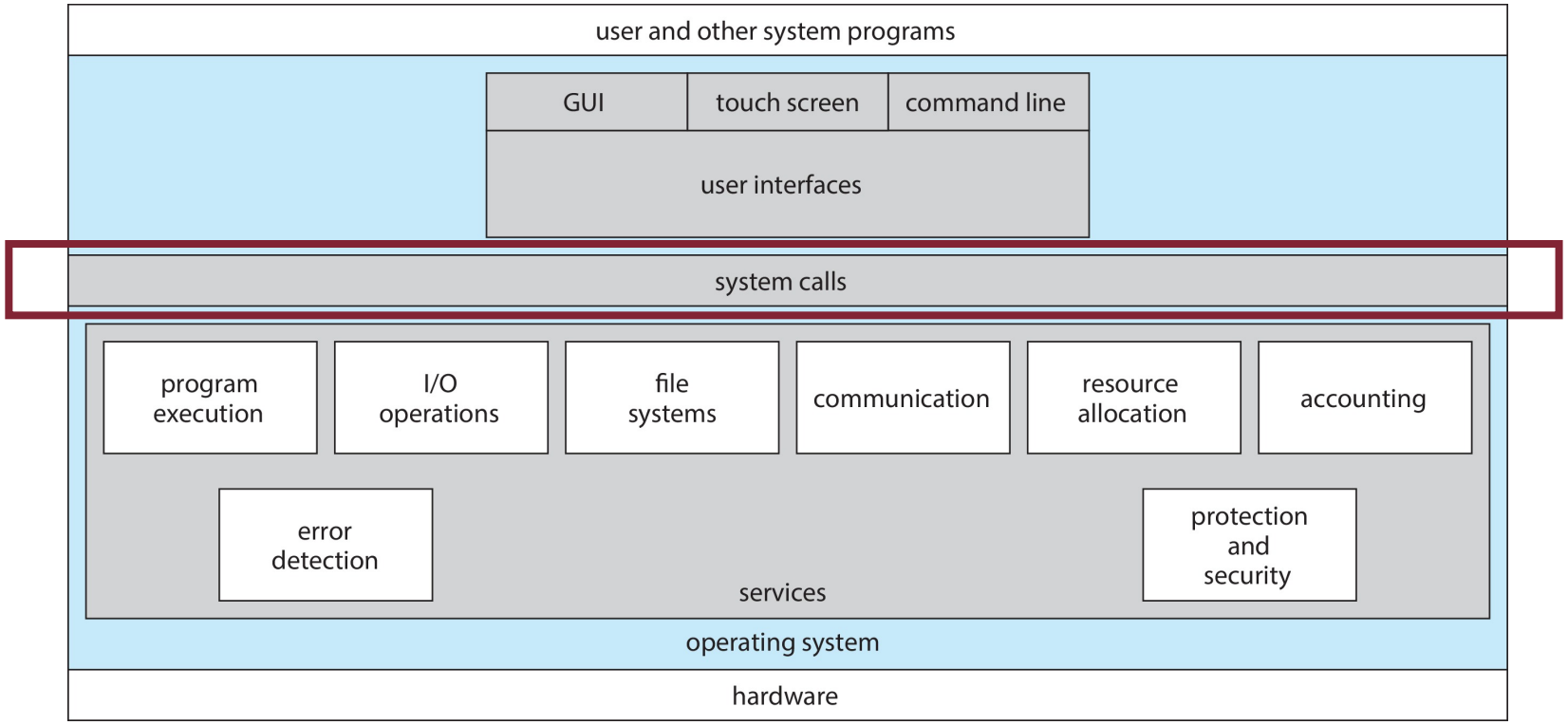
- Used by mobile smartphones and tablets
- Main features:
  - Mouse not possible or not desired
  - Actions and selection based on gestures
  - Virtual keyboard for text entry
  - Voice commands

# Touchscreen: iOS vs. Android



# User-Programs to OS Interface



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- OS procedures that execute privileged instructions (e.g., I/O)
- Programming interface to the services provided by the OS
- Typically written in a high-level language (C or C++)
- Mostly accessed by programs via a high-level Application Programming Interface (API) rather than direct system call
  - GNU C Library (POSIX-based systems like UNIX, Linux, macOS)
  - Win32 API (Windows systems)
  - Java API (JVM)

# System Calls: Categories

- **6 main categories** of system calls:
  - Process control
  - File management
  - Device management
  - Information maintenance
  - Communications

# System Calls: Process Control

- Include end, abort, load, execute, create process, terminate process, get/set process attributes, wait for time or event, signal event, and allocate and free memory

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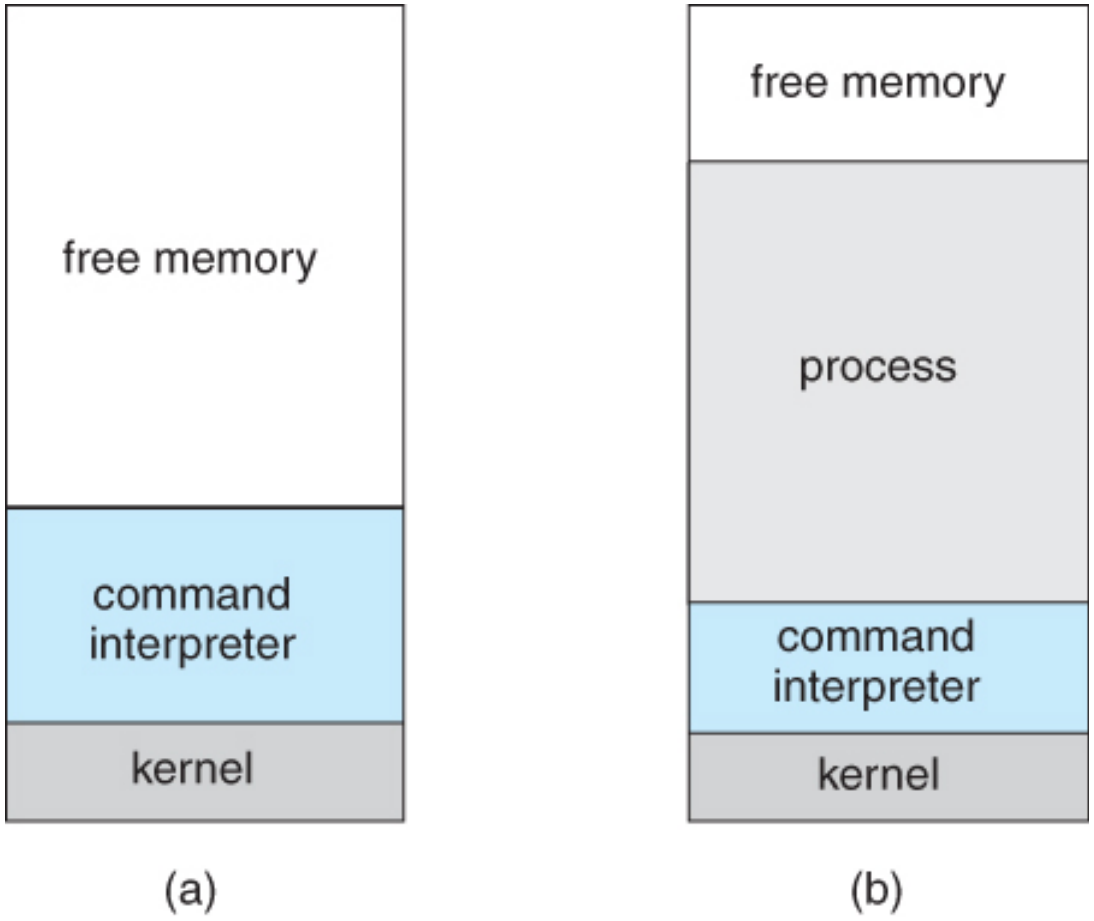
- When processes stop abnormally it may be necessary to provide core dumps and/or other diagnostic or recovery tools

# Process Control: MS-DOS (single-tasking)



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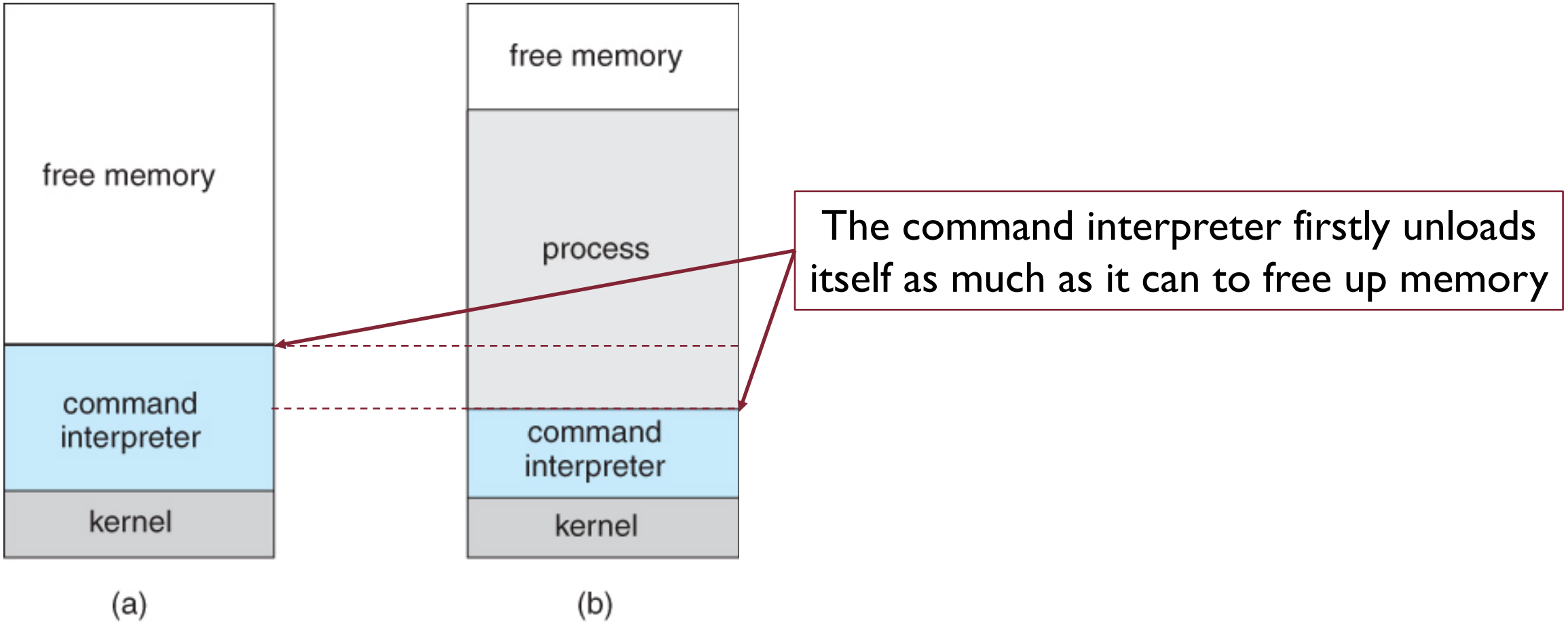

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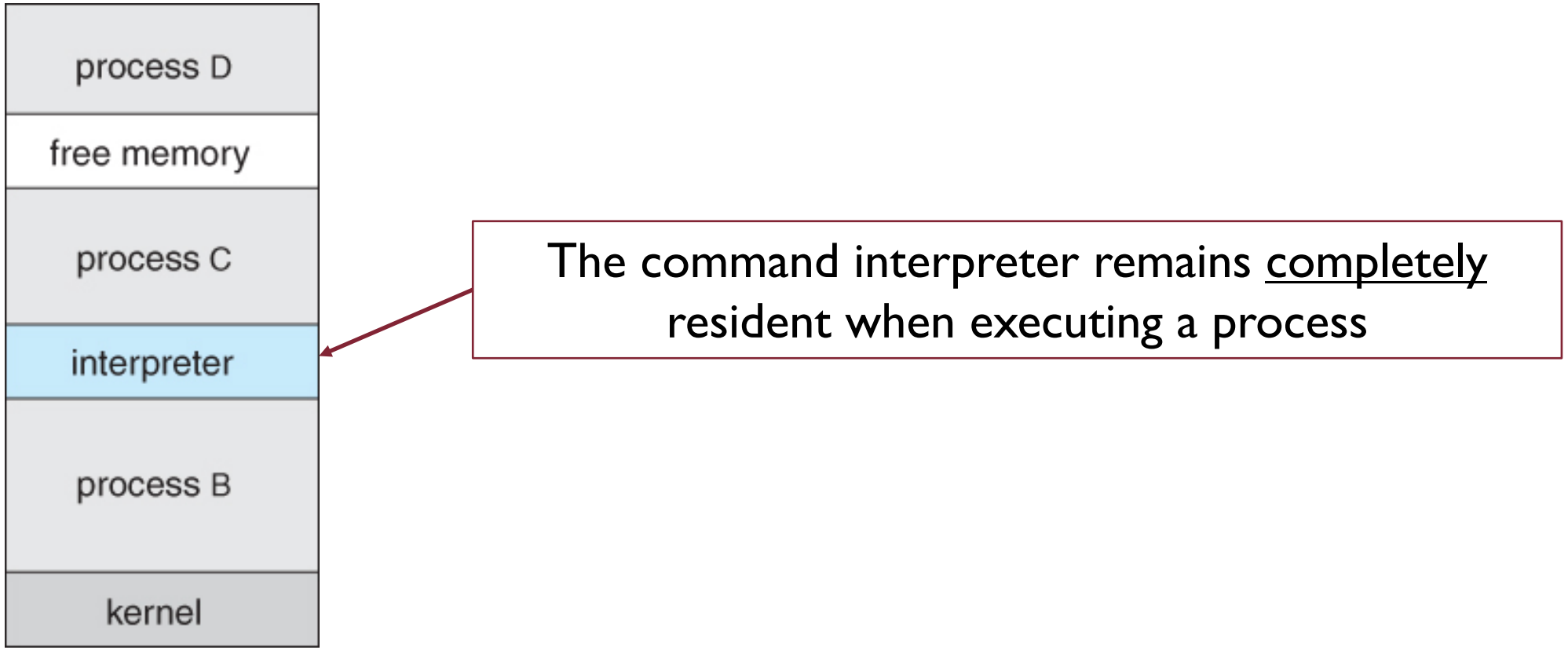

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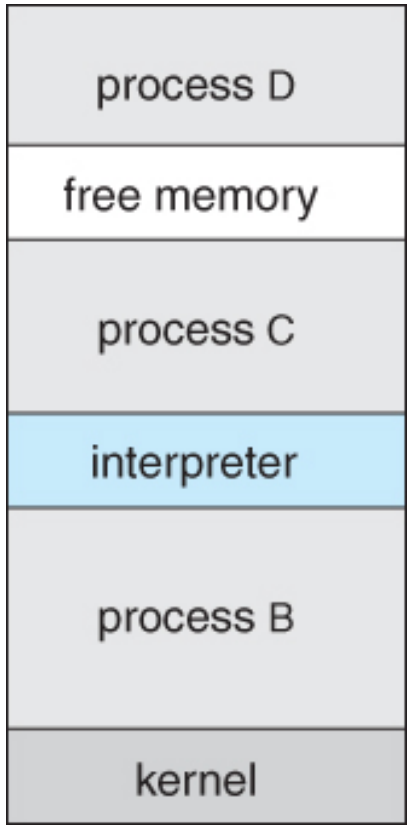


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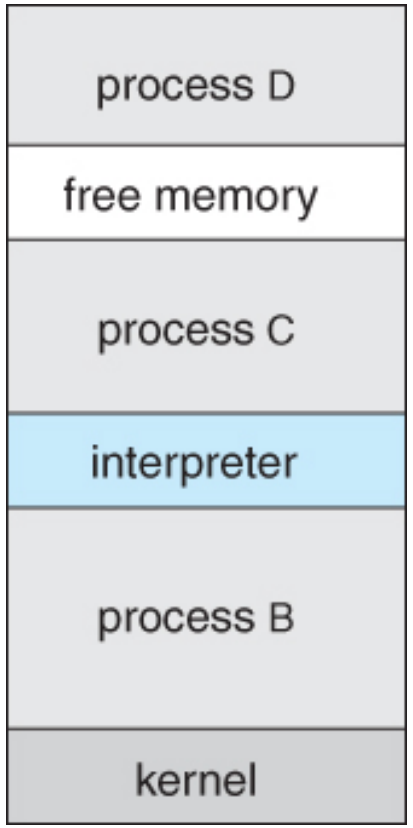


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The command interpreter achieves that by issuing `fork/exec` system calls

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- The actual directory structure may be implemented using ordinary files on the file system, or through other means (more on this later)

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- Some systems represent devices as special files in the file system, so that accessing the "file" calls upon the appropriate OS device driver
  - e.g., the `/dev` directory on any UNIX system

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- Systems may also provide the ability to dump memory at any time
- Single step programs pausing execution after each instruction, and tracing the operation of programs (debugging)

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- Include create/delete communication connection, send/receive messages, transfer status information, and attach/detach remote devices

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- **2 models** of communication:
  - **message passing**
  - **shared memory**

# Communication: Message Passing

- The **message passing** model must support calls to:
  - Identify a remote process and/or host with which communicate to
  - Establish a connection between the two processes
  - Open and close the connection as needed
  - Transmit messages along the connection
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Simpler and easier (particularly for inter-computer communications) and generally appropriate for small amounts of data

# Communication: Shared Memory

- The **shared memory** model must support calls to:
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Faster and generally the better approach where large amounts of data are to be shared

Ideal when most processes need to read data rather than write

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- System calls allow the access mechanisms to be adjusted as needed
- Non-priveleged users may temporarily be granted elevated access permissions under specific circumstances
- Crucial in the age of ubiquitous network connectivity

# The Anatomy of a System Call

# System Call: `read` (C Library)

*EXAMPLE OF STANDARD API*

As an example of a standard API, consider the `read()` function that is available in UNIX and Linux systems. The API for this function is obtained from the `man` page by invoking the command

```
man read
```

on the command line. A description of this API appears below:

```
#include <unistd.h>

ssize_t    read(int fd, void *buf, size_t count)
```

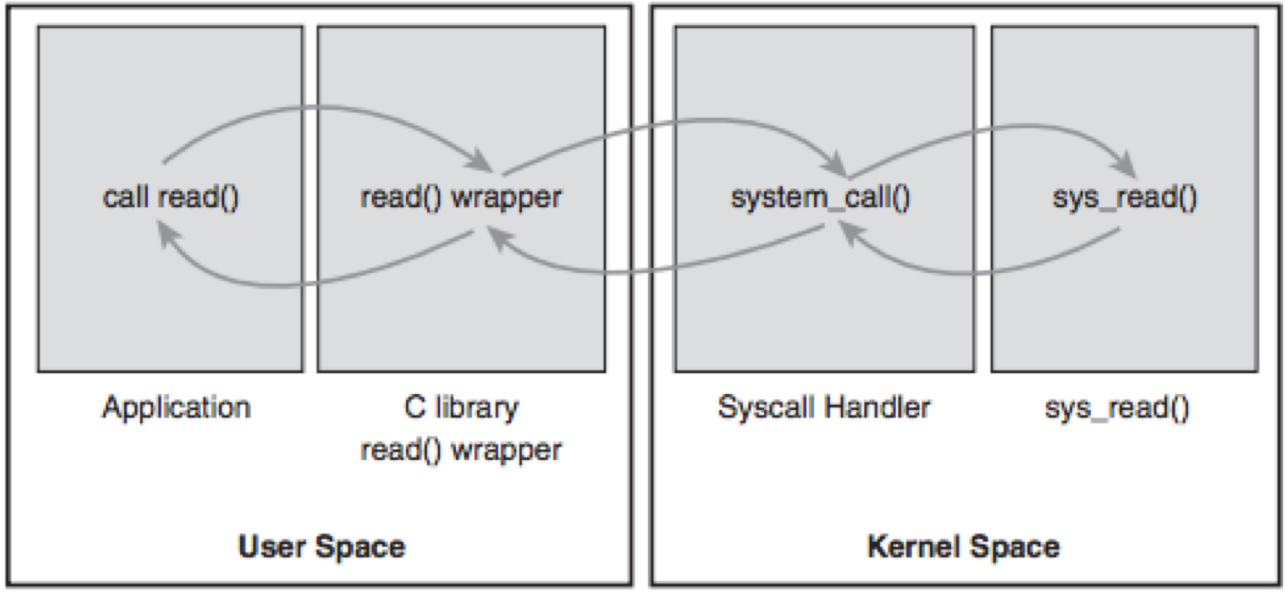
return value — function name — parameters

A program that uses the `read()` function must include the `unistd.h` header file, as this file defines the `ssize_t` and `size_t` data types (among other things). The parameters passed to `read()` are as follows:

- `int fd`—the file descriptor to be read
- `void *buf`—a buffer into which the data will be read
- `size_t count`—the maximum number of bytes to be read into the buffer

On a successful read, the number of bytes read is returned. A return value of 0 indicates end of file. If an error occurs, `read()` returns −1.

# System Call: Flow



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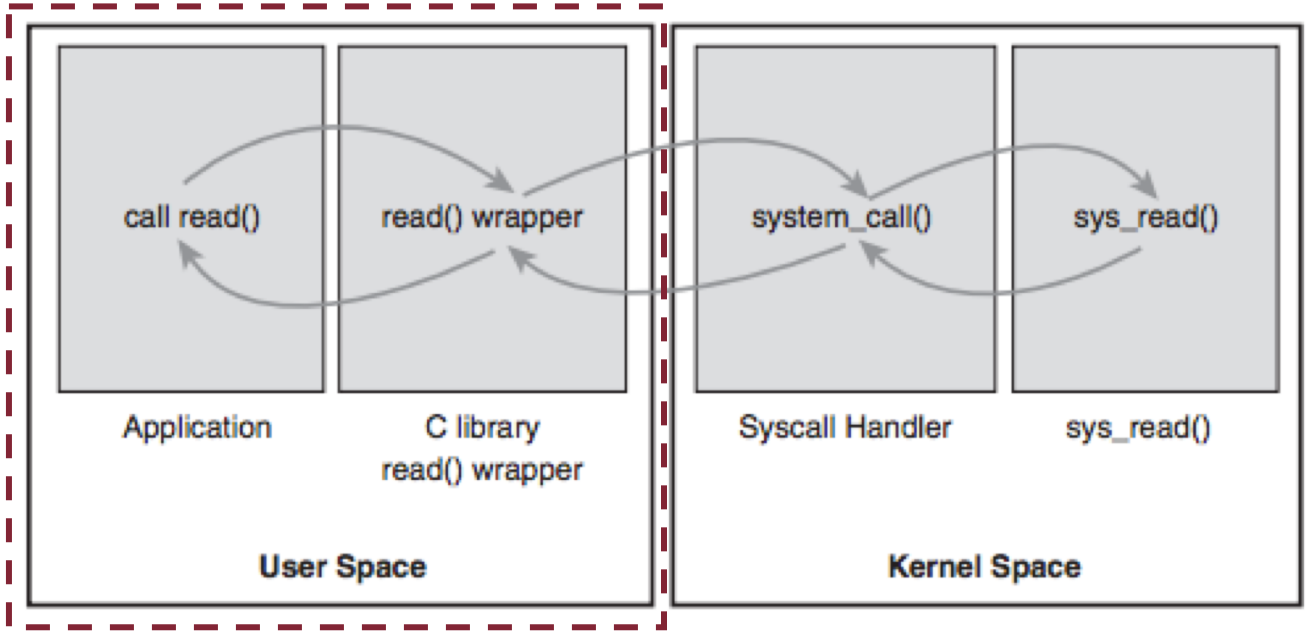

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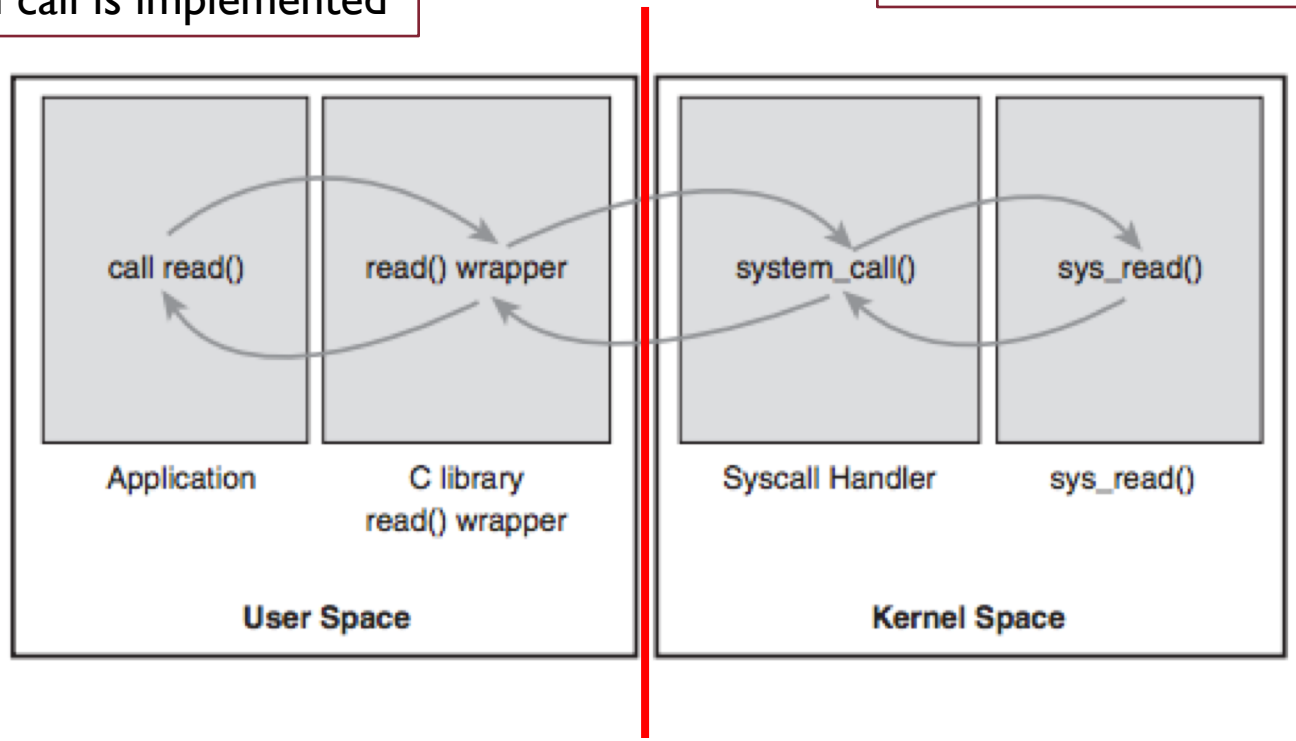

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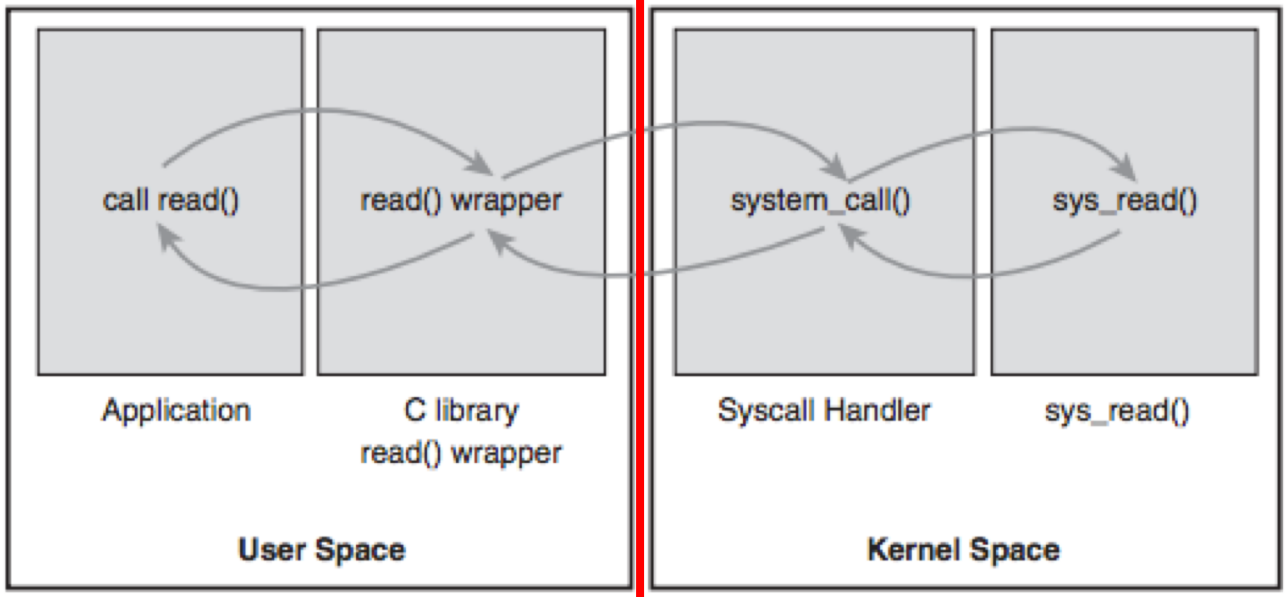


The caller must only obey to the API
(know the input arguments and the expected output from the OS)

# System Call Example: Reading from File

```
int main() {
    …
    int nRead = read(fd, buf, count);
    …
}
```

C library's **`read`** function call

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```
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MOV %eax, $sys_read
INT $0x80
…
```

store the number which uniquely identifies the system call requested

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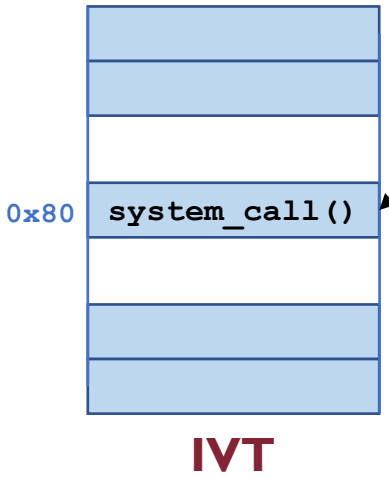
A **trap** jumps to the **interrupt vector table** (IVT) in the OS kernel



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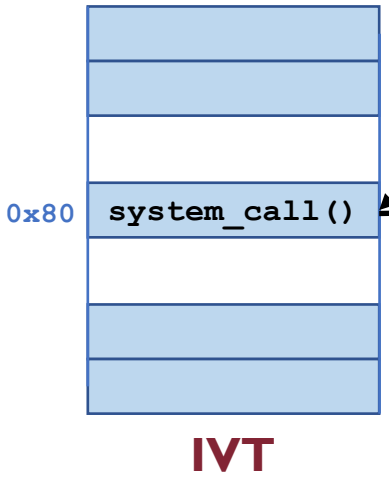


```
system_call() {
    …
    sys_call_table[%eax]()
    …
}
```

System Call Handler

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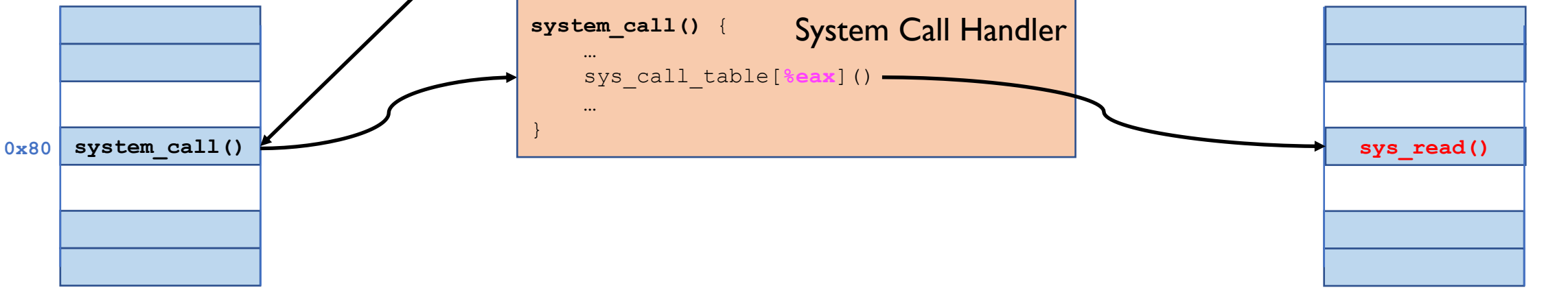

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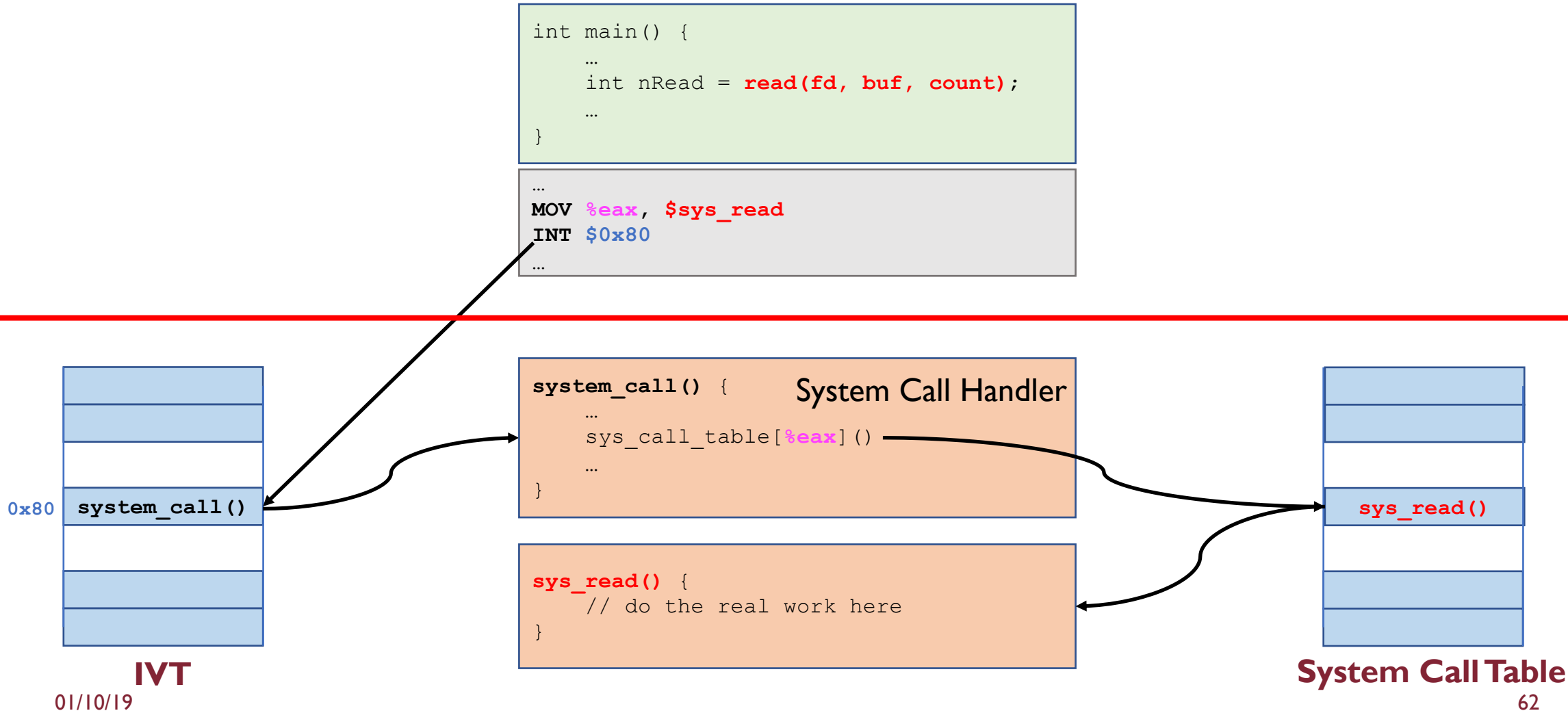

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- The system call handler is responsible for:
  - saving the status of user-mode computation on dedicated registers
  - finding and jumping to the correct routine for that trap (e.g., `sys_read()`)
  - restoring user-mode program's state upon the service routine is done (e.g., `IRET` privileged instruction)

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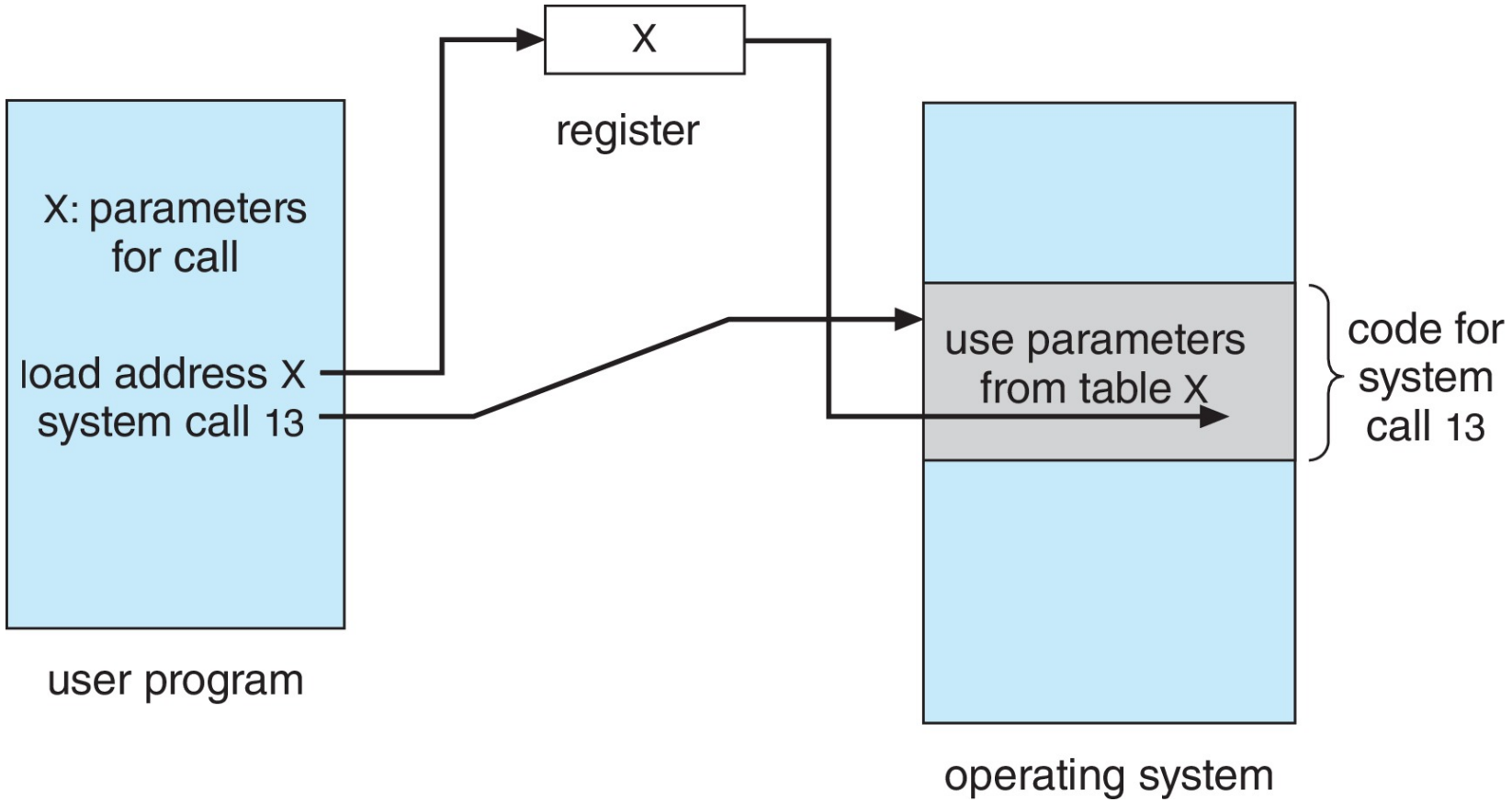
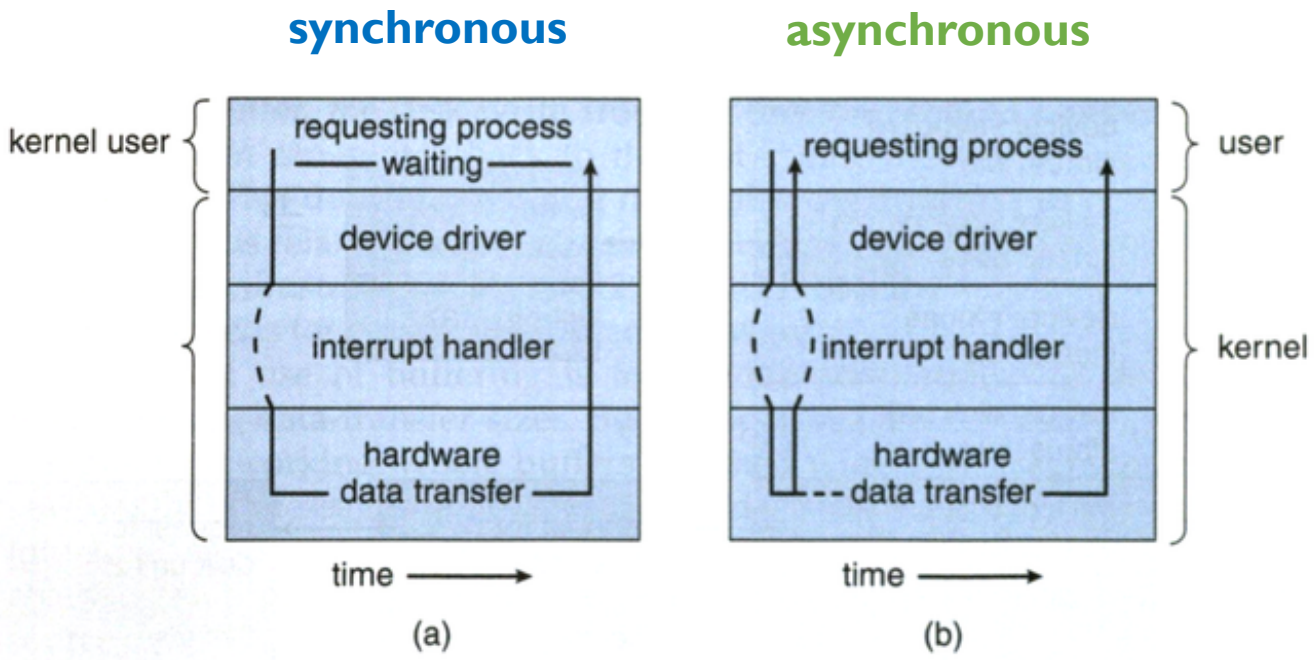
Block and stack methods do not limit the number or length of parameters being passed

# Parameter Passing via Table



# Blocking vs. Non-Blocking I/O



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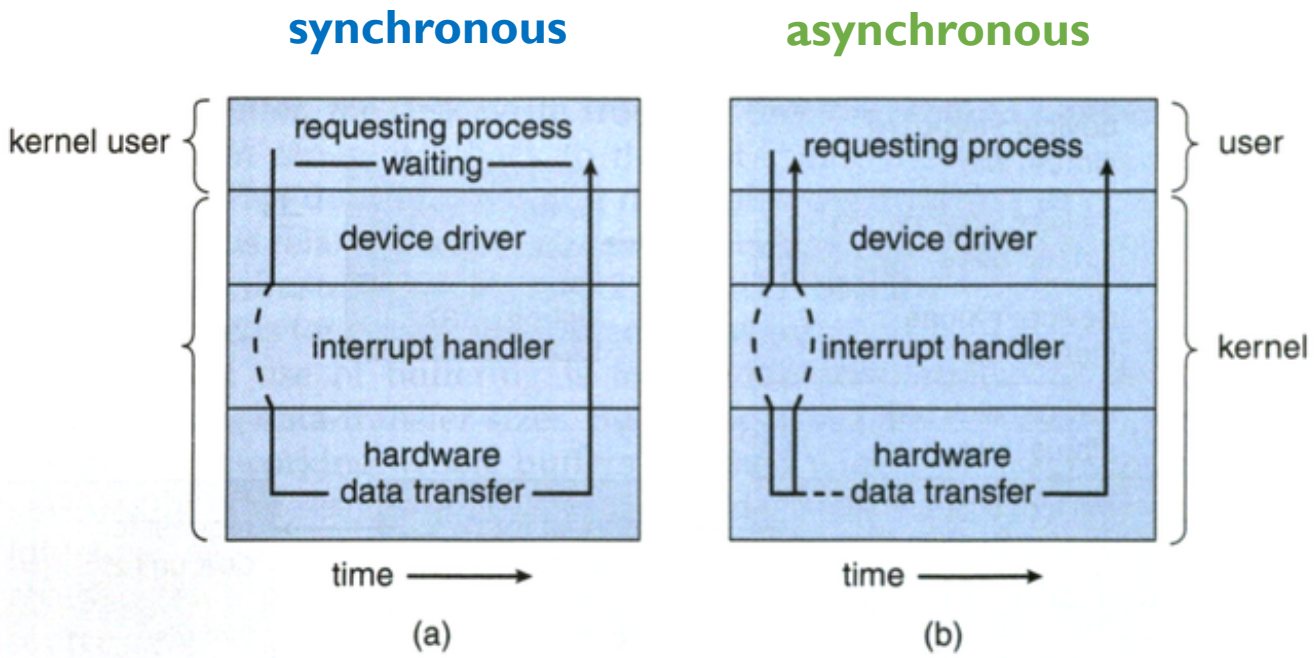



**NOTE**

In a multi-programming, multi-tasking system blocking I/O **does not** mean the CPU will be left idle until I/O task is completed! In fact, the CPU will schedule another (ready) process to take over

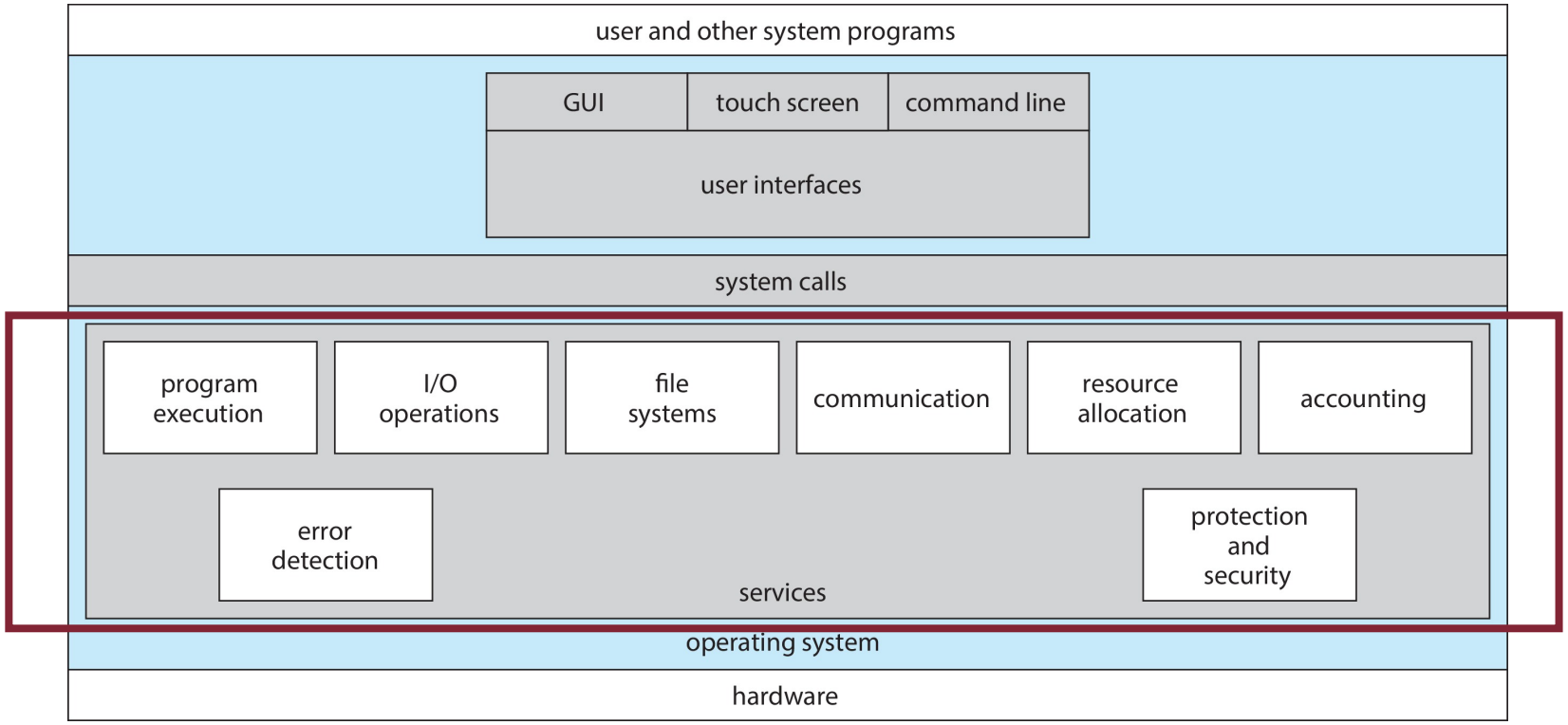
# System Calls: Windows vs. UNIX APIs

*EXAMPLES OF WINDOWS AND UNIX SYSTEM CALLS*

The following illustrates various equivalent system calls for Windows and UNIX operating systems.

| | Windows | Unix |
|---|---|---|
| **Process control** | `CreateProcess()` | `fork()` |
| | `ExitProcess()` | `exit()` |
| | `WaitForSingleObject()` | `wait()` |
| **File management** | `CreateFile()` | `open()` |
| | `ReadFile()` | `read()` |
| | `WriteFile()` | `write()` |
| | `CloseHandle()` | `close()` |
| **Device management** | `SetConsoleMode()` | `ioctl()` |
| | `ReadConsole()` | `read()` |
| | `WriteConsole()` | `write()` |
| **Information maintenance** | `GetCurrentProcessID()` | `getpid()` |
| | `SetTimer()` | `alarm()` |
| | `Sleep()` | `sleep()` |
| **Communications** | `CreatePipe()` | `pipe()` |
| | `CreateFileMapping()` | `shm_open()` |
| | `MapViewOfFile()` | `mmap()` |
| **Protection** | `SetFileSecurity()` | `chmod()` |
| | `InitlializeSecurityDescriptor()` | `umask()` |
| | `SetSecurityDescriptorGroup()` | `chown()` |

# System Programs



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- Most systems also ship with useful applications such as calculators and simple editors (e.g., Emacs)
- Some debate arises as to the border between system and non-system applications

# System Programs

- They can be grouped into **7 categories**:
  - **File management:** programs to create, delete, copy, rename, print, list, and manipulate files and directories
  - **Status information:** utilities to check on the date, time, number of users, processes running, data logging, etc.
  - **File modification:** text editors and other tools which can change file contents
  - **Programming-language support:** compilers, linkers, debuggers, profilers, assemblers, library archive management, interpreters for common languages, and support for make
  - **Program loading and execution:** loaders, dynamic loaders, overlay loaders, debuggers, etc.
  - **Communications:** email, web browsers, remote login, file transfer, etc.
  - **Background services:** network daemons, print servers, process schedulers, and system error monitoring services

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- Most users' views of the system is determined by their command interpreter and the application programs
- Users never make system calls, even through the API, unless they develop programs (e.g., requiring I/O operations)

# OS Design and Implementation

# Design Goals

- The internal structure of different OSs can vary widely

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- **User** vs. **System** goals
  - easy to use vs. easy to design/implement
- It is crucial to separate policies from mechanisms
  - **policy** → *what* will be done
  - **mechanism** → *how* to do it

# Policy vs. Mechanism

- Decoupling policy logic from the underlying mechanism is a general design principle in computer science, as it improves system's:
  - **flexibility** → addition and modification of policies can be easily supported
  - **reusability** → existing mechanisms can be reused for implementing new policies
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# OS Implementation

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- Early OSs developed in assembly language,
  - **PRO** → direct control over the HW (high efficiency)
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- Today, a mixture of languages:
  - Lowest levels in assembly
  - Main body in C
  - Systems programs in C, C++, scripting languages like PERL, Python, etc.

# OS Structure

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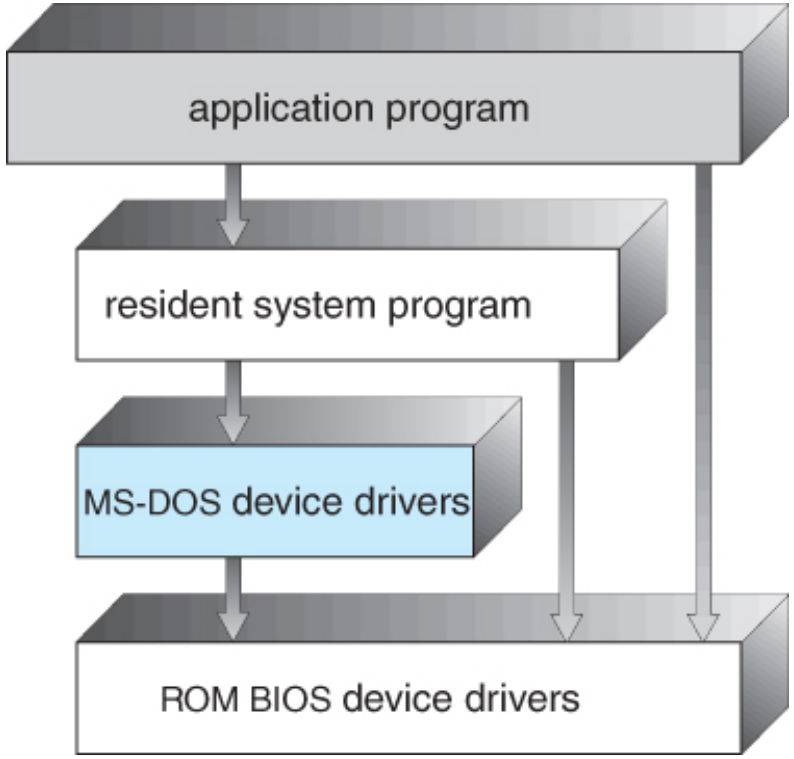
- Various ways to structure an operating system:
  - Simple → MS-DOS
  - Complex → UNIX
  - Layered → MULTICS
  - Microkernel → Mach

# MS-DOS Structure: Simple Structure

No modular subsystems at all!

No separation between
user and kernel mode



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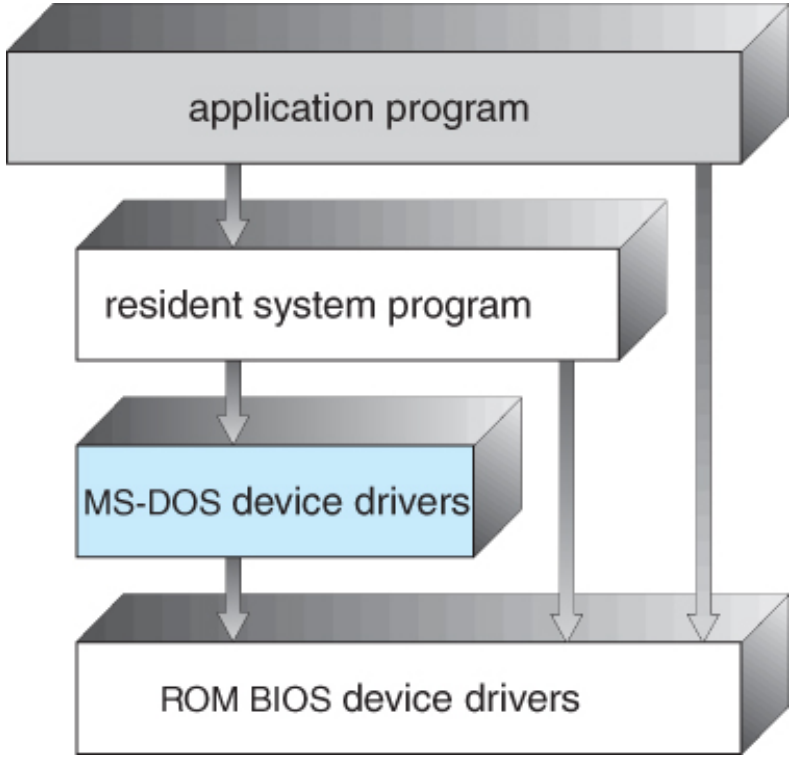
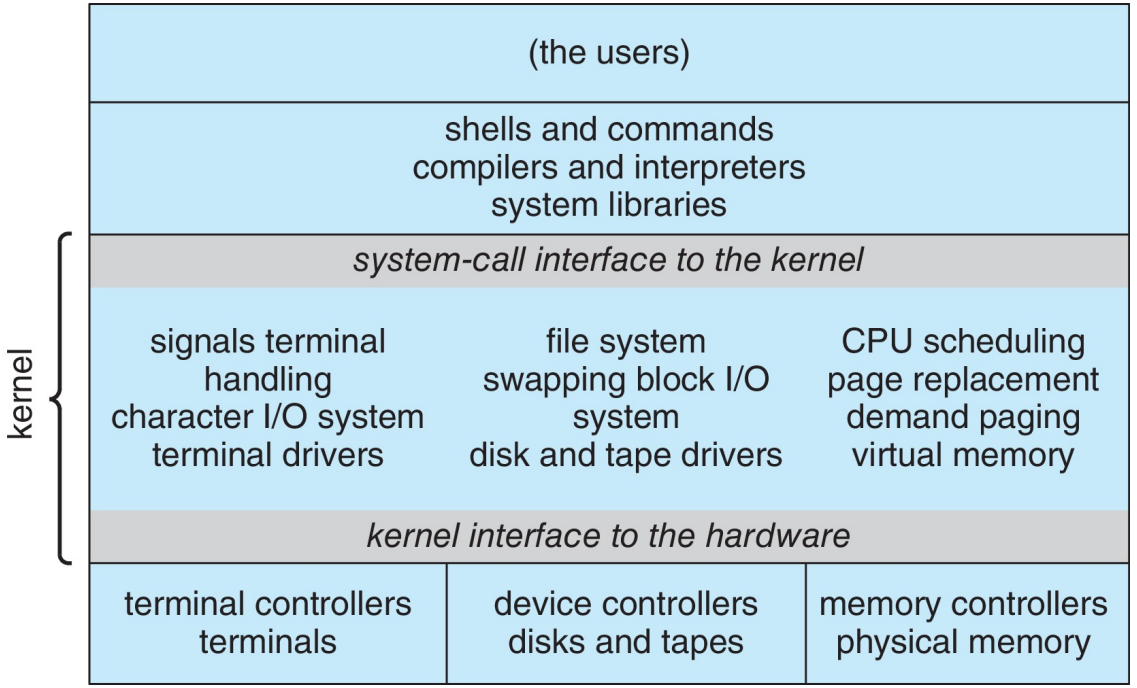


# UNIX Structure: Traditional Monolithic Kernel

Essentially, one huge piece of software with all services living in the same address space as one big process

Most of modern OSs are variant of this traditional monolithic structure



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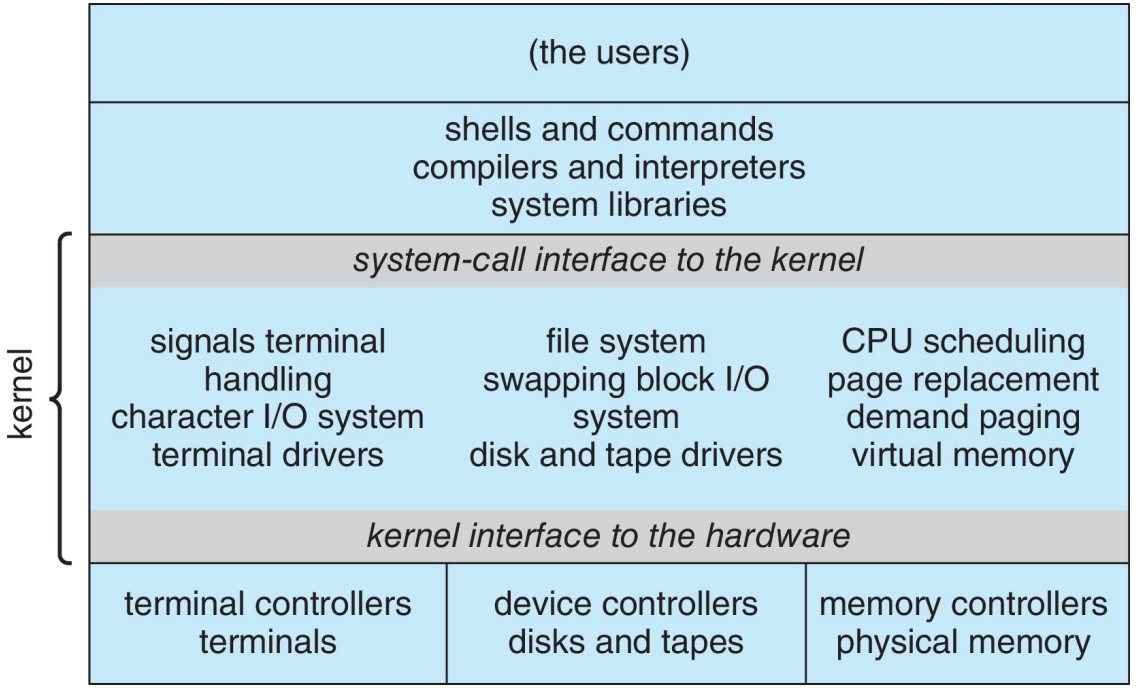
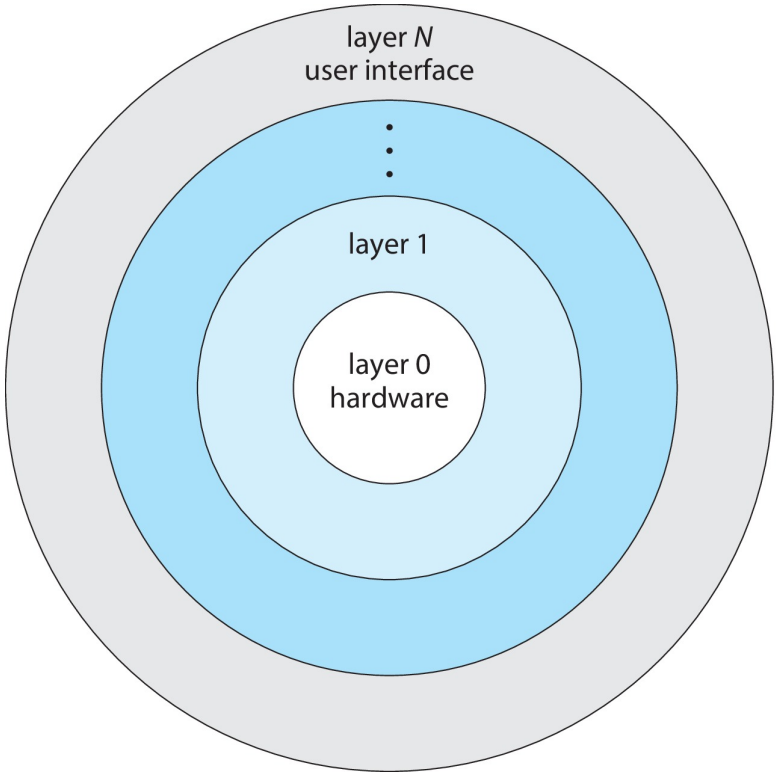


# Layered Structure

The OS is divided into N layers
(HW = layer 0)

Each layer L uses the functionalities implemented by the layer L-1 to expose new functionalities to layer L+1



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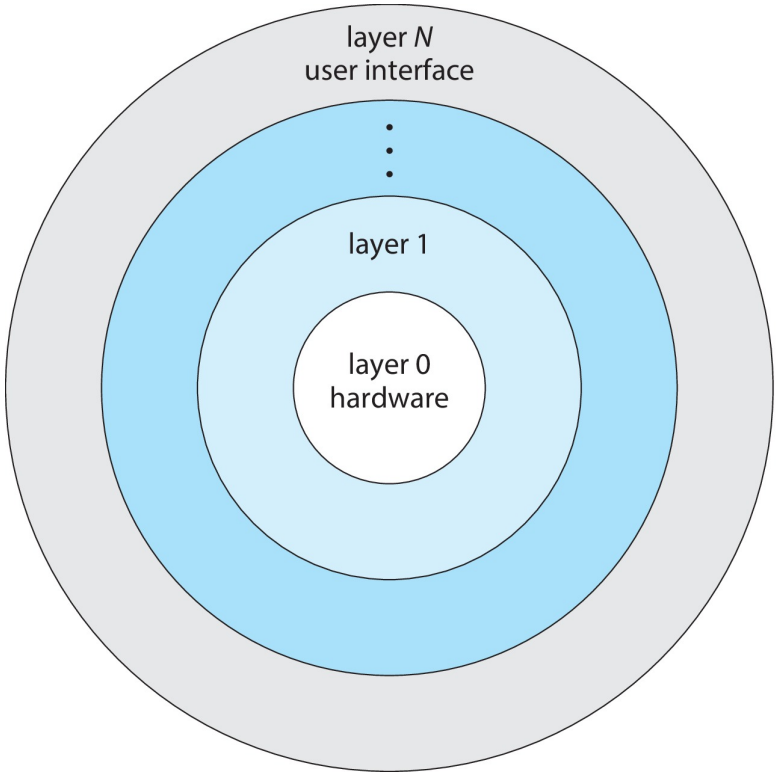
(HW = layer 0)

Each layer L uses the functionalities implemented by the layer L-1 to expose new functionalities to layer L+1

PROs: modularity, portability, easy to debug

CONs: communication overhead, extra copy

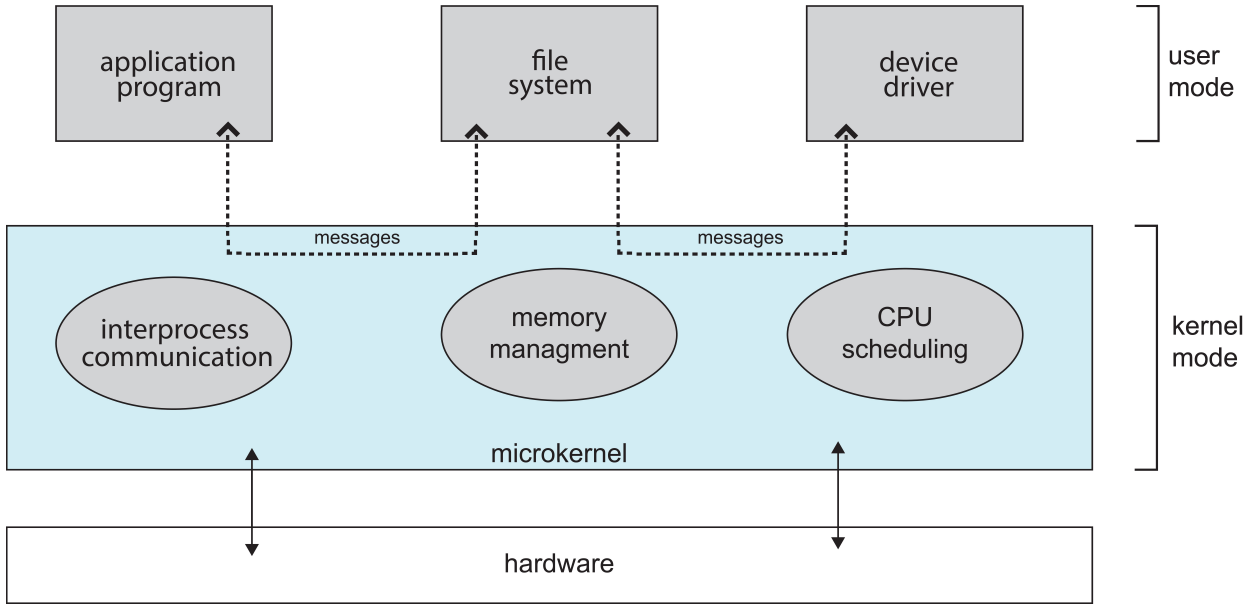


# Microkernel Structure

The opposite approach of monolithic

The kernel just contains very basic functionalities, everything else which is still logically part of the OS runs in user mode

Policy (user mode) vs. mechanism (microkernel) separation



# Microkernel Structure

The opposite approach of monolithic

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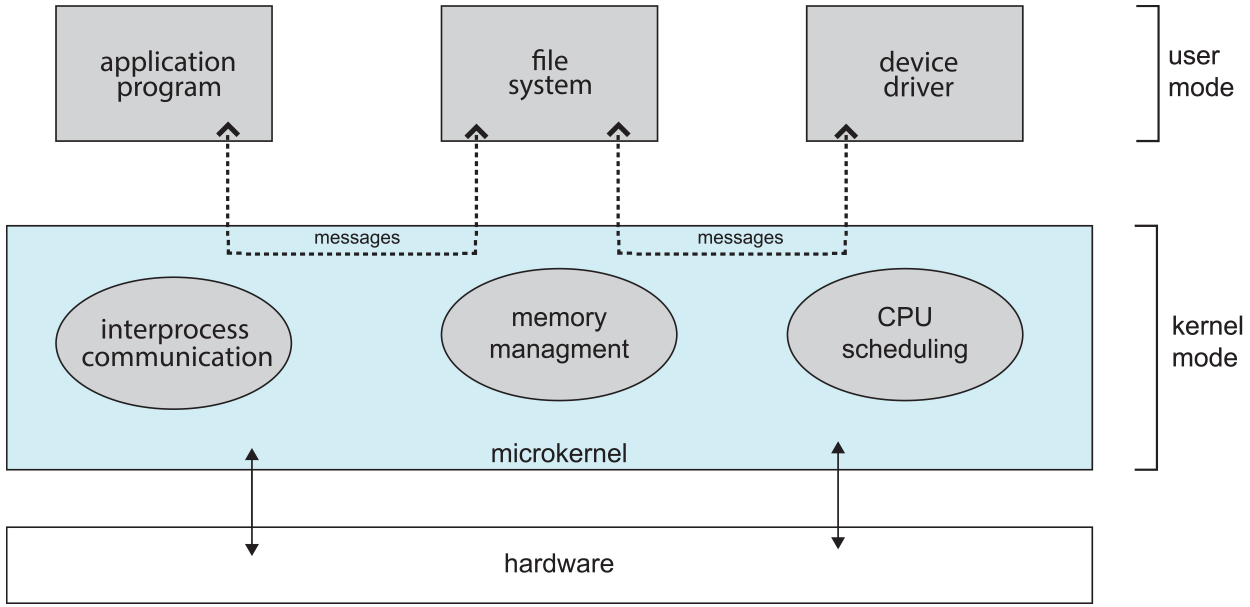
Policy (user mode) vs. mechanism (microkernel) separation

PROs: security, reliability, extendibility

CONs: efficiency (message passing)



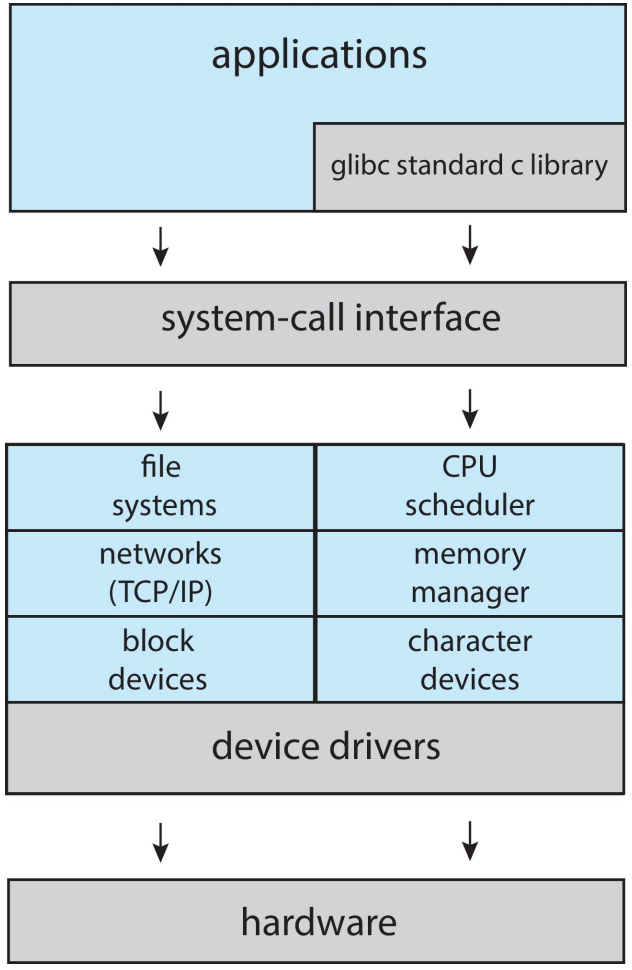
# Loadable Kernel Modules (LKMs)

- Many modern OSs use loadable kernel modules (LKMs)
  - Uses object-oriented approach
  - Each core component is separate
  - Each talks to the others over known interfaces
  - Each is loadable as needed within the kernel (i.e., in kernel space)
- Similar to layered structure but more flexible

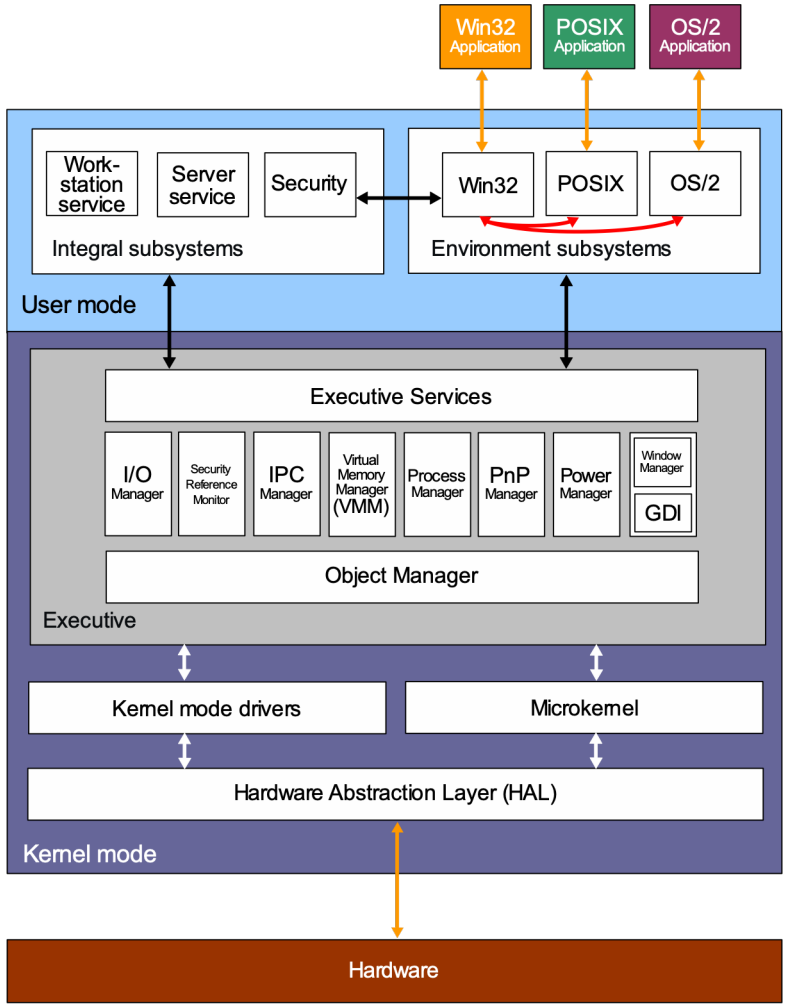
# Monolithic vs. Microkernel: Hybrid Trade-off

- Try to get the best out of both approaches
  - combining multiple approaches to address performance, security, usability needs
- Linux and Solaris: monolithic + LKMs (i.e., modular monolithic)
- Windows NT: mostly monolithic + microkernel for different subsystems
- Apple Mac OS X: monolithic (BSD UNIX) + microkernel (Mach) + LKMs

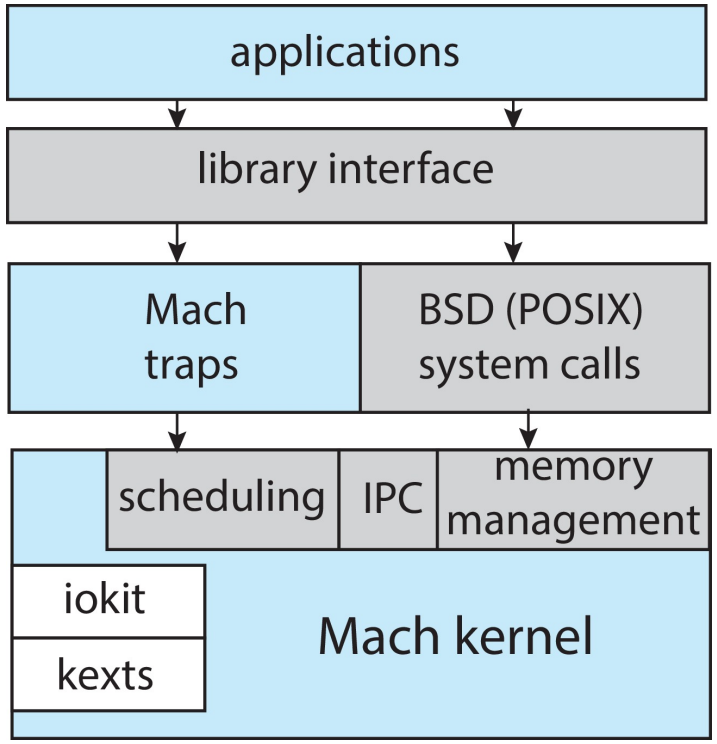
# Linux


applications
glibc standard c library
system-call interface
file systems
CPU scheduler
networks (TCP/IP)
memory manager
block devices
character devices
device drivers
hardware

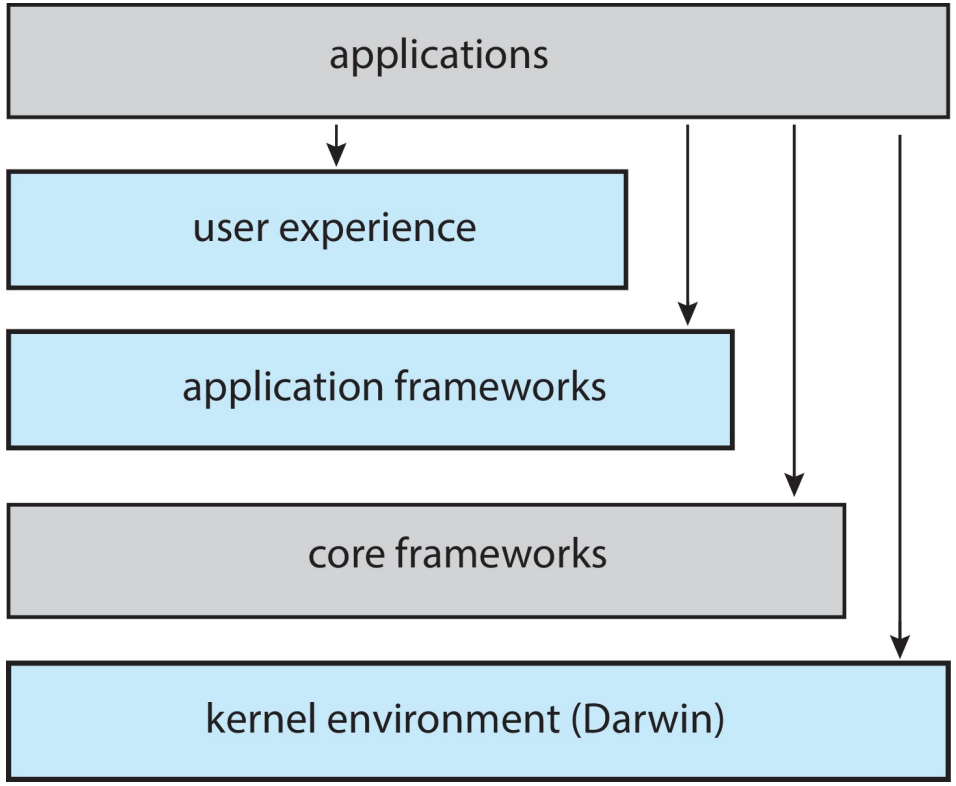
# Windows NT Family



# Mac OS X (Darwin)

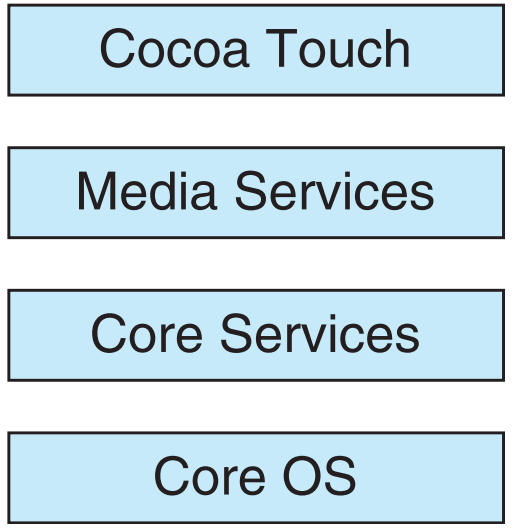


# macOS and iOS



# iOS

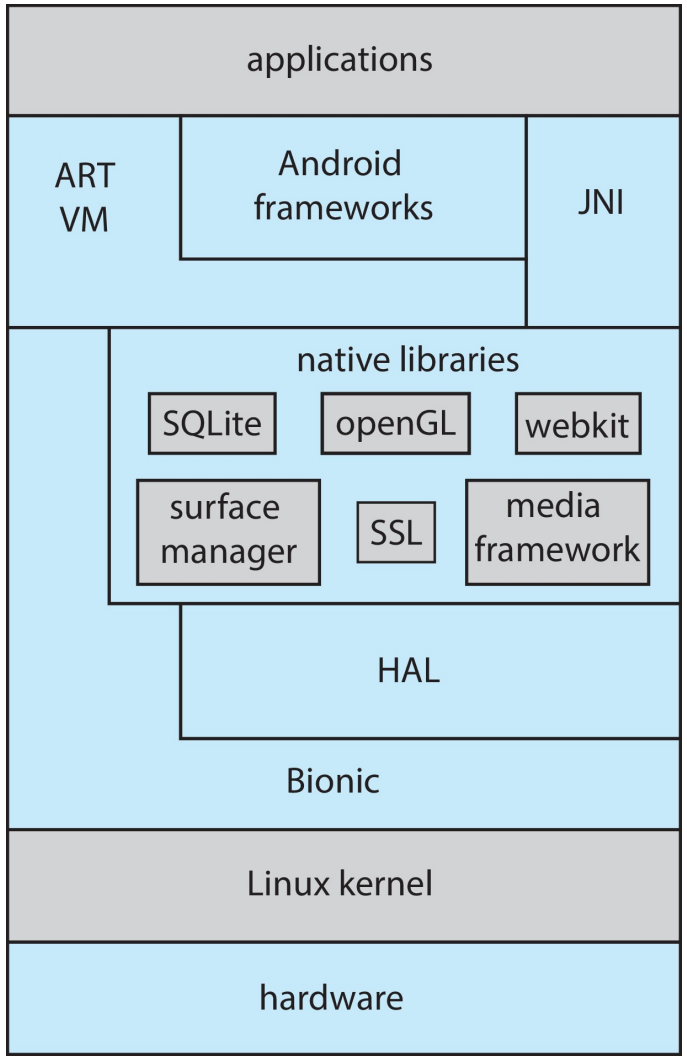
- Apple mobile OS for iPhone and iPad
  - Core operating system based on Mac OS X kernel + added functionalities
  - Does not run OS X applications natively
  - Also runs on different CPU architecture (ARM vs. Intel)
- Cocoa Touch Objective-C API for developing apps
- Media services layer for graphics, audio, video
- Core services provides cloud computing, databases



# Android

- Developed by Open Handset Alliance (mostly Google)
  - Open Source
  - Similar stack to iOS
  - Based on Linux kernel but modified
- Provides process, memory, device-driver management, and power management
- Runtime environment includes core set of libraries and Dalvik virtual machine
  - Apps developed in Java plus Android API
- Libraries include frameworks for web browser (webkit), database (SQLite), multimedia, smaller libc

# Android


applications
ART
VM
Android
frameworks
JNI
native libraries
SQLite
openGL
webkit
surface
manager
SSL
media
framework
HAL
Bionic
Linux kernel
hardware

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  4. The boot loader loads the OS kernel, which:
     - Initializes its own data structures (e.g., interrupt vector table)
     - Loads the first process from disk
     - Switch to user mode (1)

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  - CLI/GUI
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  - CLI/GUI
  - System calls
- Several ways of designing an OS
  - Tradeoff between usability, reliability, security, etc.
- There is no "one size fits all" receipe!
  - Each system must be designed on the basis of its purpose