Systems and Networking I

Applied Computer Science and Artificial Intelligence 2024–2025



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Recap from Previous Lecture

- A thread is a single execution stream within a process
- Thread vs. Process:
 - common vs. separate address spaces → quicker communication
 - lightweight vs. heavyweight → faster context switching
- On a single core:
 - Fully CPU-bound processes do not take advantage of multithreading
 - Concurrency between threads in mixed CPU- and I/O-bound processes

Multi-threading: Support and Management

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 - at the kernel level → kernel threads
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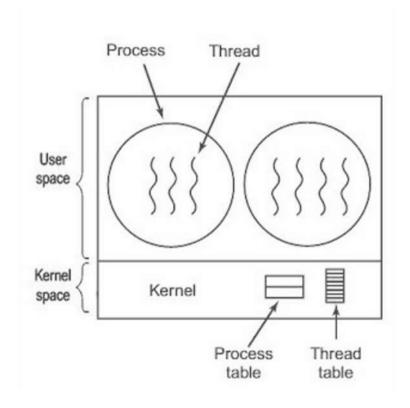
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 - at the kernel level → kernel threads
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- Kernel threads
 - managed directly by the OS kernel itself
- User threads
 - managed in user space by a user-level thread library, without OS intervention

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- The OS is responsible for supporting and managing all threads

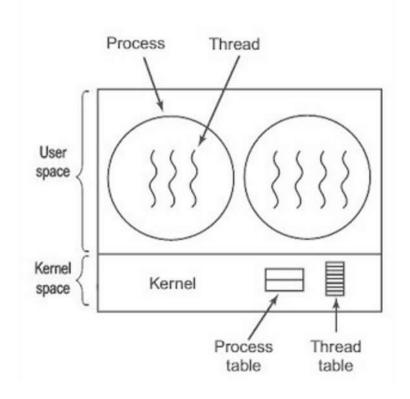
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- The OS is responsible for supporting and managing all threads
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- The OS usually provides system calls to create and manage threads from user space



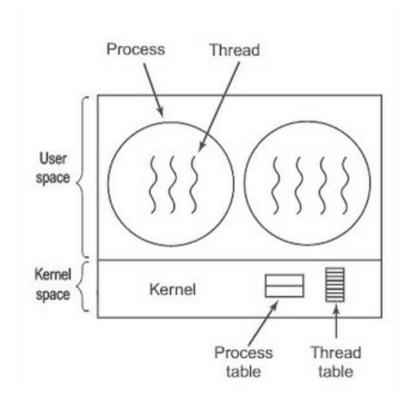
• PROs

- The kernel has full knowledge of all threads
- Scheduler may decide to give more CPU time to a process having a large numer of threads
- Good for applications that frequently block
- Switching between threads is faster than switching between processes



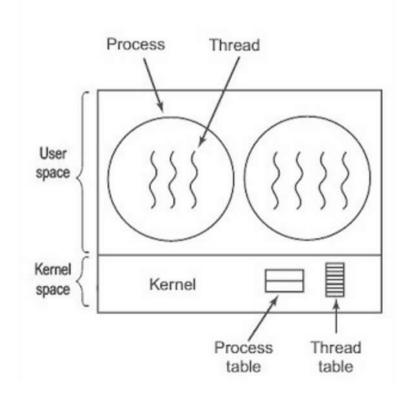
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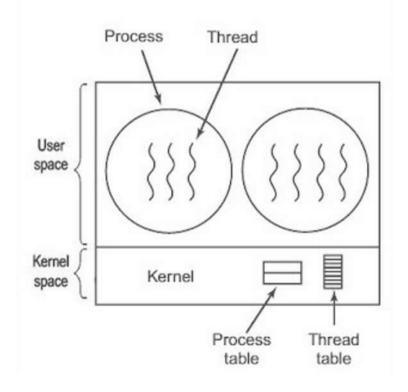
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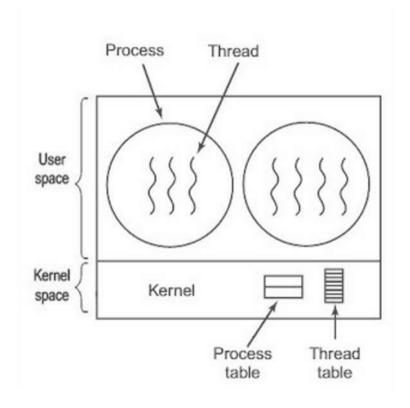
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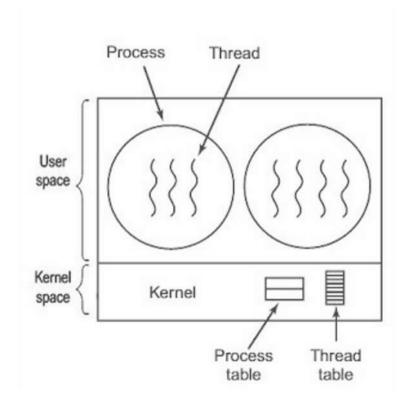
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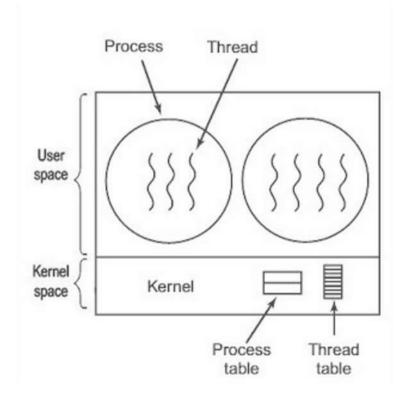
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- Significant overhead and increase in kernel complexity
- Slow and inefficient (need kernel invocations)
- Context switching, although lighter, is managed by the kernel



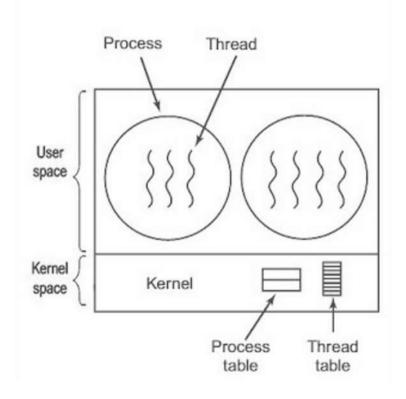
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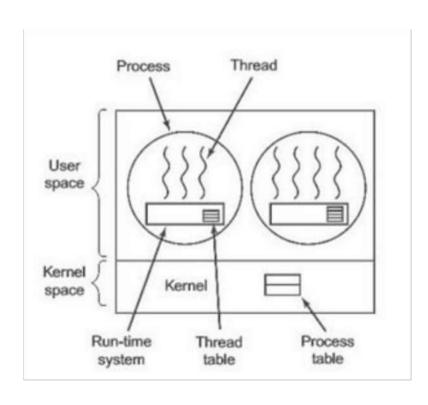
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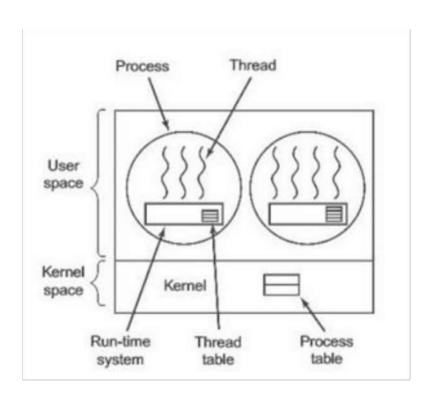
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- Ideally, thread operations should be as fast as a function call



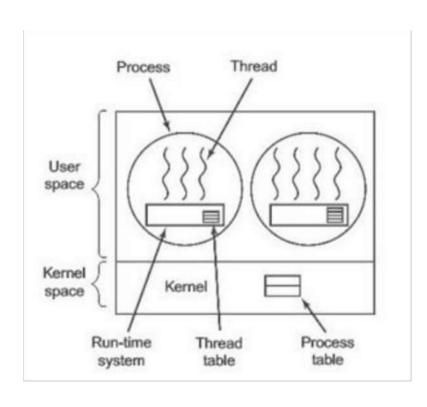
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- Really fast and lightweight
- Scheduling policies are more flexible
- Can be implemented in OSs that do not support threading
- No system calls involved, just userspace function calls
- No actual context switch



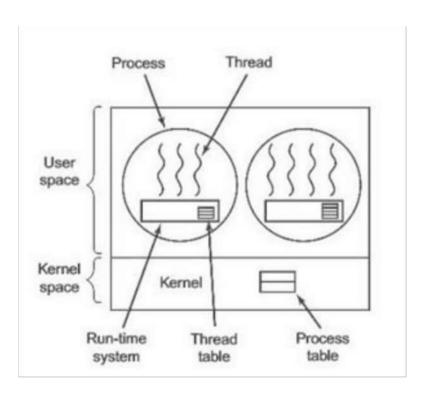
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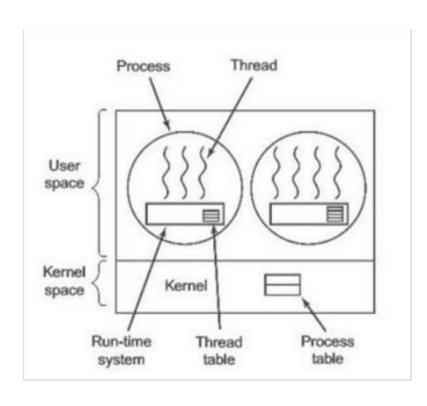
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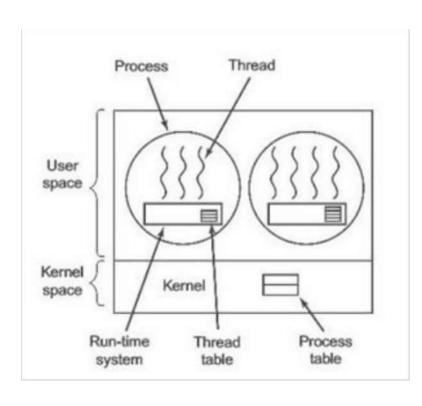
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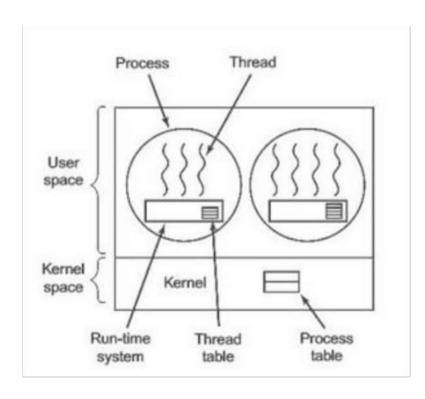
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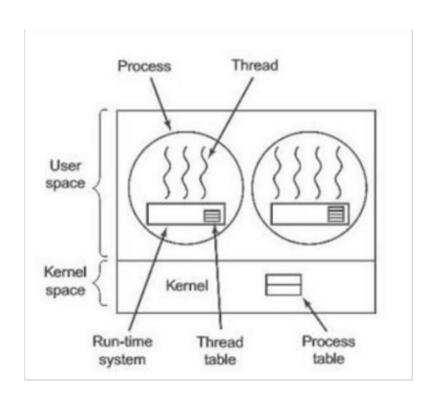
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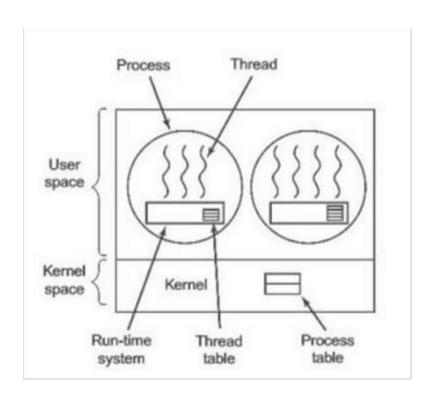
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- No true concurrency of multi-threaded processes
- Poor scheduling decisions
- Lack of coordination between kernel and threads
 - A process with 100 threads competes for a time slice with a process with just 1 thread
- Requires non-blocking system calls, otherwise all threads within a process have to wait



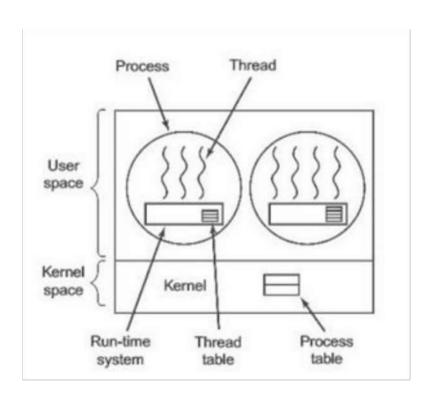
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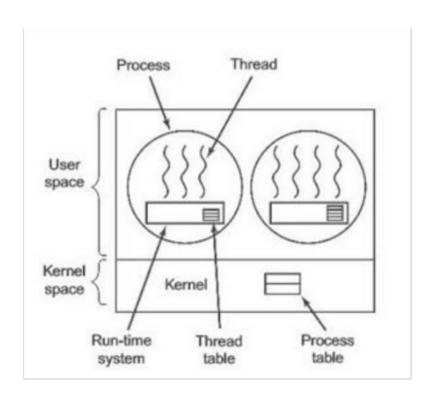
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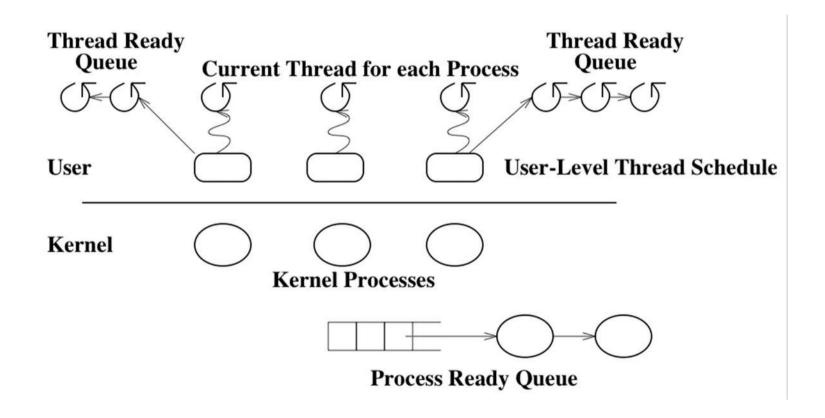
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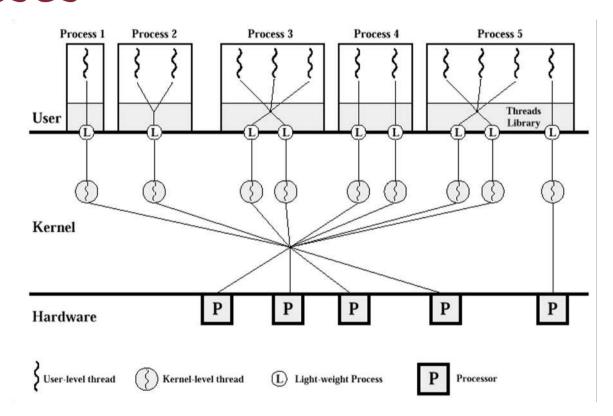


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Hybrid Management: Lightweight Processes



Multi-threading Models

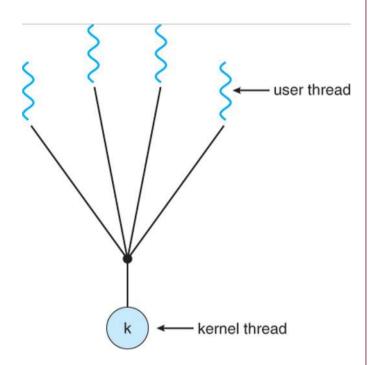
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 - Many-to-One
 - One-to-One
 - Many-to-Many
 - Two-level

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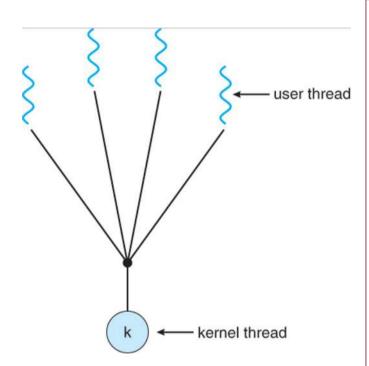
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Remember:

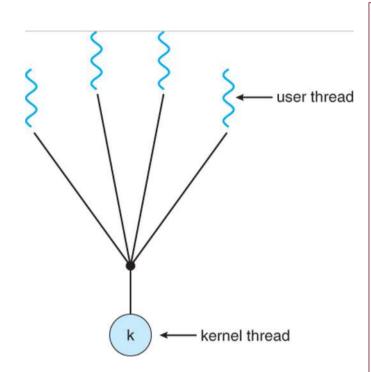
A kernel thread is the unit of execution that is scheduled by the OS to run on the CPU (similar to single-threaded process)



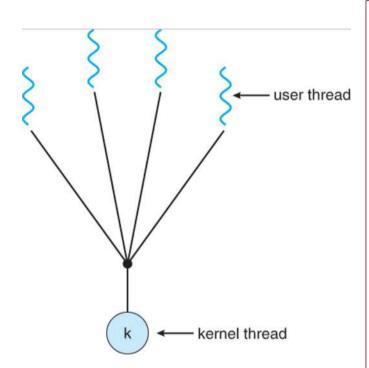
- Many user threads are all mapped onto a single kernel thread
- The process can only run one user thread at a time because there is only one kernel thread associated with it
- As single kernel thread can operate on a single CPU, multi-user-thread processes cannot be split across multiple CPUs
- If a blocking system call is made, the entire process blocks, even if other user threads would be able to continue



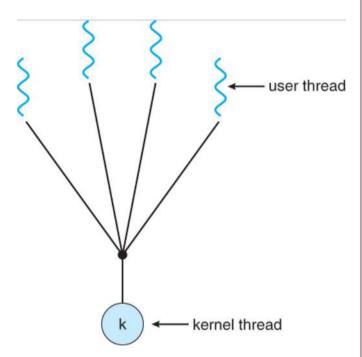
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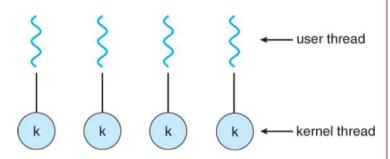
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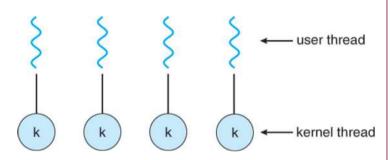
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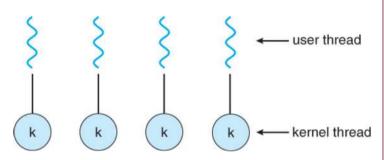
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- A separate kernel thread to handle each user thread
- Overcomes the limitations of blocking system calls and splitting of processes across multiple CPUs
- The overhead of managing the one-to-one model is more significant and may slow down the system
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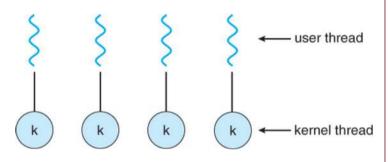


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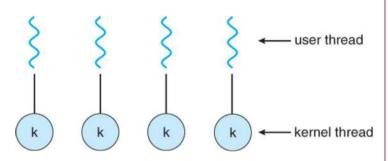


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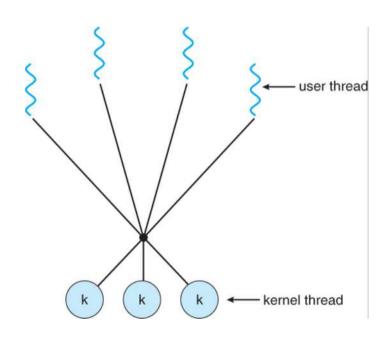


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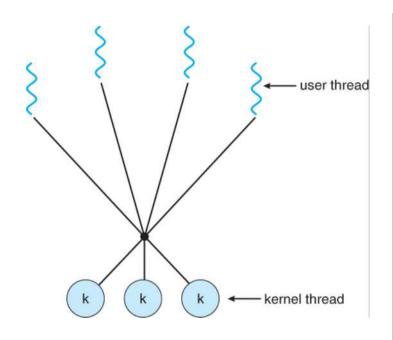


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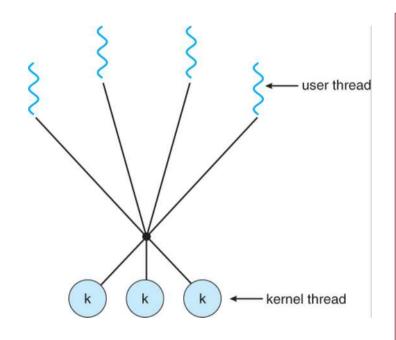
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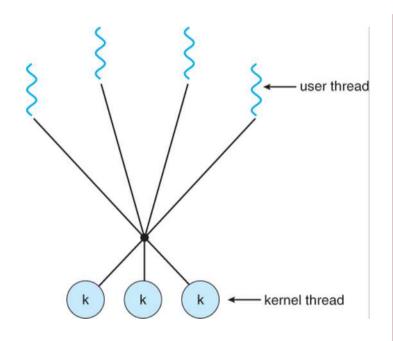
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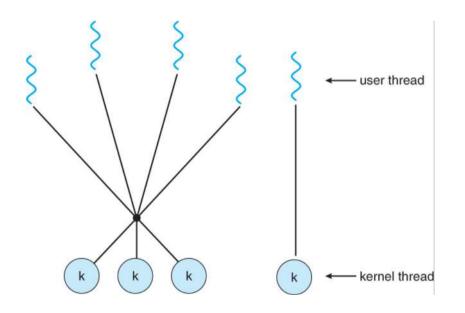


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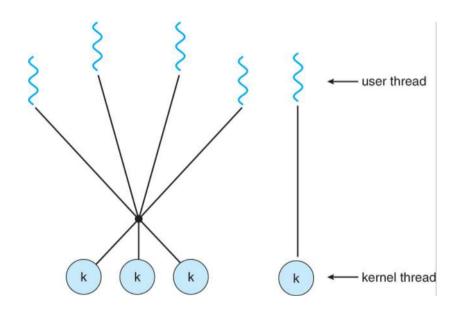
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- Increases the flexibility of scheduling policies

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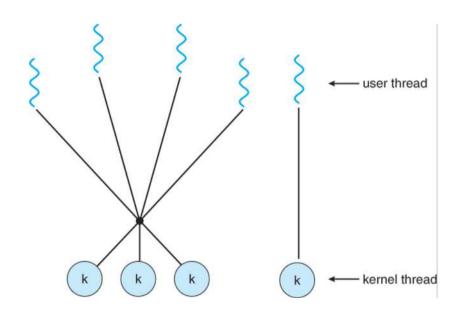


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- 2 primary ways of implementing it:
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 - kernel space → implemented in kernel space within a kernel that supports threads (system calls)

Thread Libraries: Examples

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 - POSIX Pthreads → may be provided as either a user or kernel library, as an extension to the POSIX standard
 - Win32 threads → provided as a kernel-level library on Windows systems
 - Java threads → the implementation of threads is based upon whatever OS and hardware the JVM is running on, e.g., either Pthreads or Win32 threads

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- One thread can wait for the others to rejoin before continuing

Java Threads

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 - Extending the Thread class
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- Both solutions require to override the run() method
- Note that Java doesn't support multiple inheritance!
 - If your class extends the Thread class, it cannot extend any other class
 - In such a situation, implementing Runnable is preferable

```
public class SingleThreadedServer implements Runnable {
   protected int
                          serverPort = 8080;
   protected ServerSocket serverSocket = null;
    public SingleThreadedServer(int port){
        this.serverPort = port;
   public void run() {
            this.serverSocket = new ServerSocket(this.serverPort);
        catch (IOException e) {
           throw new RuntimeException("Cannot open port " + this.serverPort, e);
        while(!this.isStopped) {
            Socket clientSocket = null;
               clientSocket = this.serverSocket.accept();
            } catch (IOException e) {
                if(this.isStopped) {
                    System.out.println("Server Stopped.");
                throw new RuntimeException(
"Error accepting client connection", e);
               processClientRequest(clientSocket);
            } catch (Exception e) {
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This is the simplest (not optimal)

single-threaded implementation of a

Java web server

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The Server Loop

- 1. Wait for a client request
- 2. Process a single client request
- 3. Repeat from 1

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This is not a good idea as clients can connect to the server <u>only</u> when this is inside the <u>serverSocket.accept()</u> method call

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Java Threads: Multi-Threaded Web

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public class MultiThreadedServer implements Runnable {
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   protected ServerSocket serverSocket = null;
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    protected boolean
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The server loop is very similar to that of a single-threaded server

Java Threads: Multi-Threaded Web

```
public class MultiThreadedServer implements Runnable {
   protected int
                          serverPort = 8080;
   protected ServerSocket serverSocket = null;
   protected boolean
                          isStopped = false;
   public MultiThreadedServer(int port){
       this.serverPort = port;
   public void run() {
           this.serverSocket = new ServerSocket(this.serverPort);
       catch (IOException e) {
           throw new RuntimeException("Cannot open port " + this.serverPort, e);
       while(!this.isStopped) {
           Socket clientSocket = null;
               clientSocket = this.serverSocket.accept();
           } catch (IOException e) {
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The risk of clients being denied access to the server because the listening thread is outside the accept() call is minimized

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Java Threads: Multi-Threaded Web Server

```
public class WorkerRunnable implements Runnable{
    protected Socket clientSocket = null;
    protected String serverText = null;

    public WorkerRunnable(Socket clientSocket, String serverText) {
        this.clientSocket = clientSocket;
        this.serverText = serverText;
    }

    public void run() {
        // process client request here ...
    }
}
```

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- If no threads are available in the pool the server waits for one

Thread Pools: Benefits

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- A thread pool limits the number of threads that exist at any one point
- Separating the task to be performed from the mechanics of creating the task allows us to use different strategies for running the task
 - Example: the task could be scheduled to execute after a time delay or to execute periodically

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- A1: System dependent
- A2: If the new process execs right away, there is no need to copy all the other threads, otherwise the entire process should be copied
- A3: Many versions of UNIX provide multiple versions of the fork call for this purpose

Threading Issues: Signal Handling

• Q: When a multi-threaded process receives a signal, to what thread should that signal be delivered?

Threading Issues: Signal Handling

- Q: When a multi-threaded process receives a signal, to what thread should that signal be delivered?
- A: There are 4 major options:
 - Deliver the signal to the thread to which the signal applies
 - Deliver the signal to every thread in the process
 - Deliver the signal to certain threads in the process
 - Assign a specific thread to receive all signals in a process

Threading Issues: Signal Handling (UNIX)

- UNIX allows individual threads to indicate which signals they are accepting and which they are ignoring
- Provides 2 separate system calls for delivering signals to process/threads, respectively:
 - kill(pid, signal)
 - pthread_kill(tid, signal)

Thread Scheduling: Contention Scope

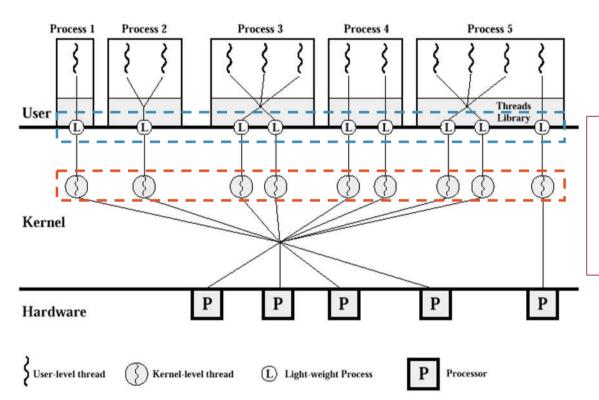
• The scope in which threads compete for the use of physical CPUs

Thread Scheduling: Contention Scope

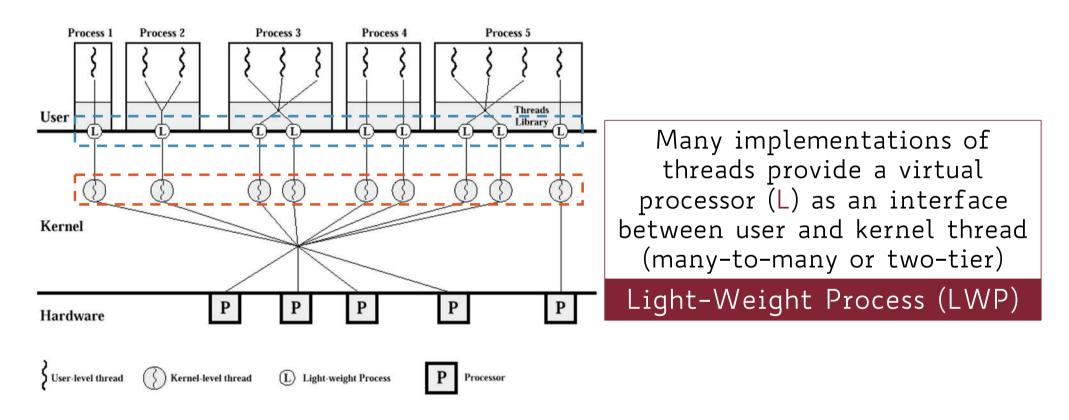
- The scope in which threads compete for the use of physical CPUs
- Process Contention Scope (PCS)
 - competition occurs between threads that are part of the same process (multiple user threads mapped to a single kernel thread, managed by the thread library)
 - on systems implementing many-to-one and many-to-many threads

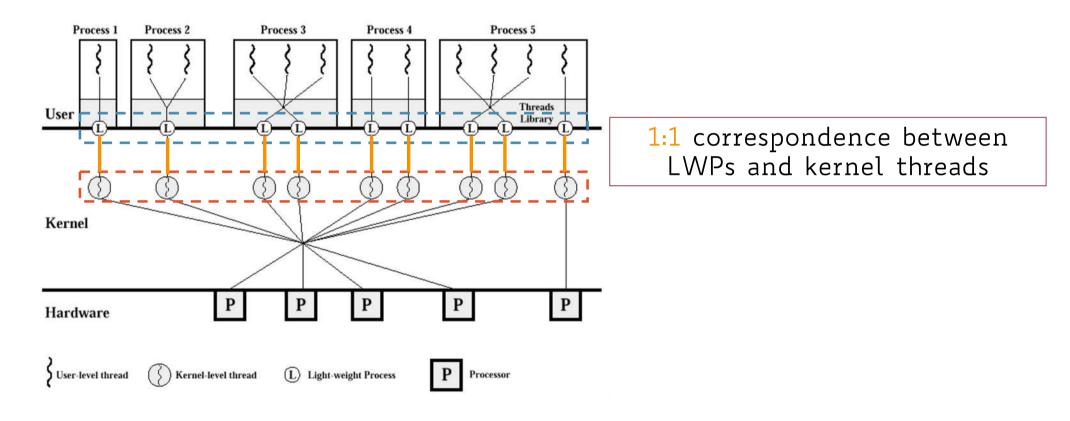
Thread Scheduling: Contention Scope

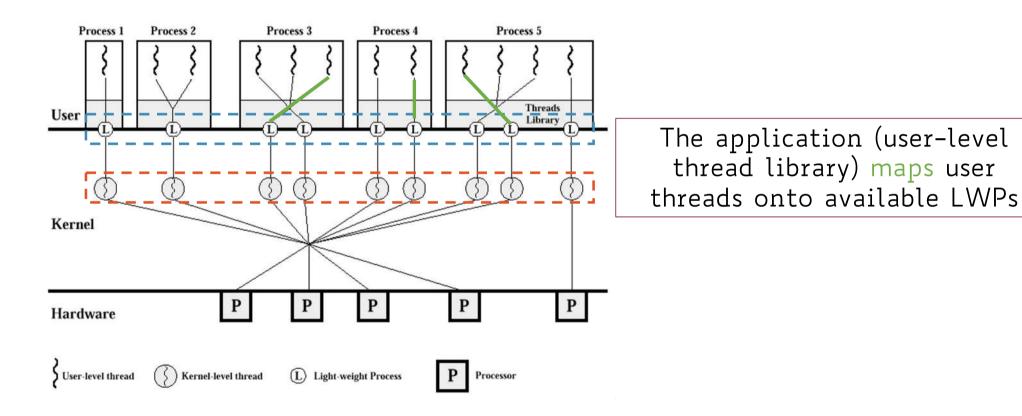
- The scope in which threads compete for the use of physical CPUs
- System Contention Scope (SCS)
 - involves the system scheduler scheduling kernel threads to run on one or more CPUs
 - on systems implementing one-to-one threads

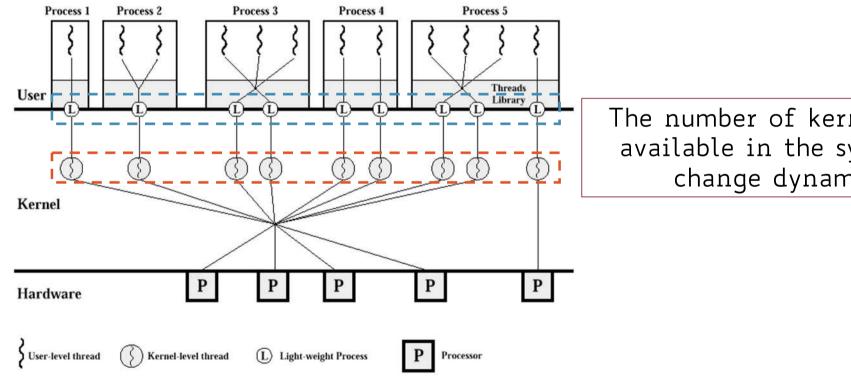


Many implementations of threads provide a virtual processor (L) as an interface between user and kernel thread (many-to-many or two-tier)

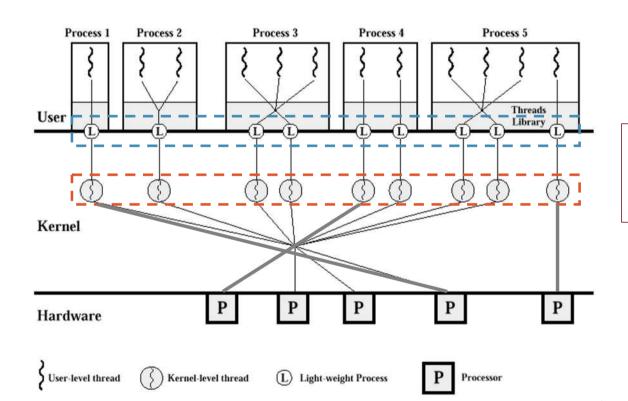






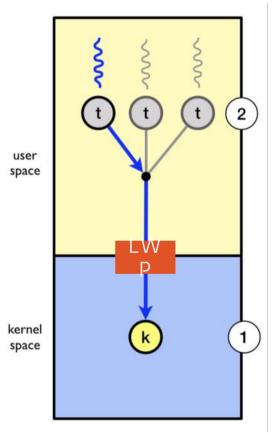


The number of kernel threads available in the system may change dynamically



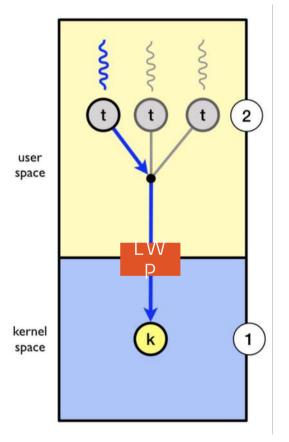
Kernel threads are scheduled onto the real processor(s) by the OS

Scheduler Activations: Example



The kernel has allocated one kernel thread (1) to a process (i.e., an LWP) with three user-level threads (2)

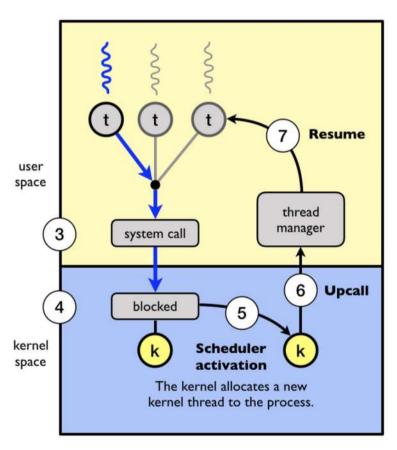
Scheduler Activations: Example



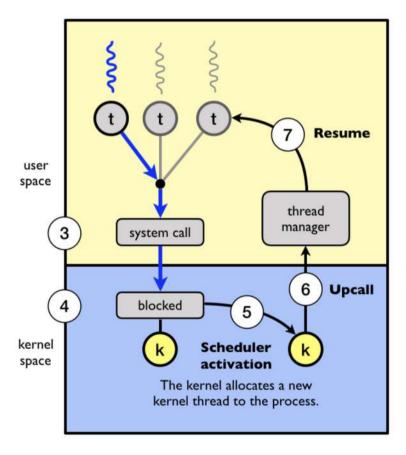
The kernel has allocated one kernel thread (1) to a process (i.e., an LWP) with three user-level threads (2)

The three user level threads take turn executing on the single kernel-level thread

Scheduler Activations: Example

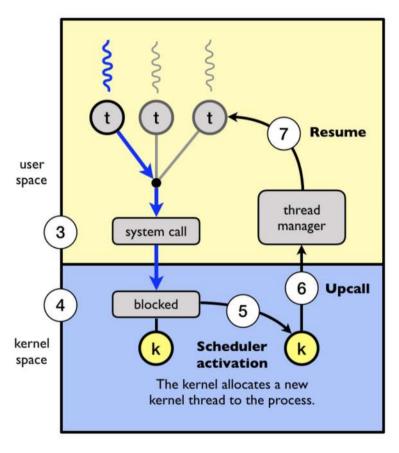


The executing thread makes a blocking system call (3)

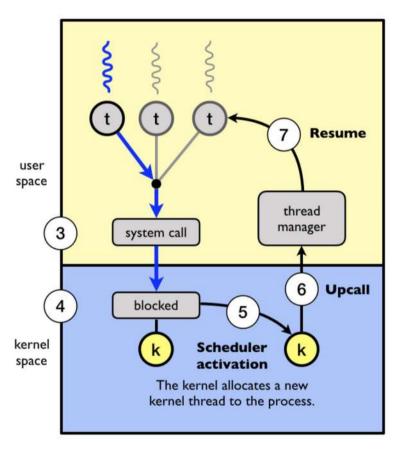


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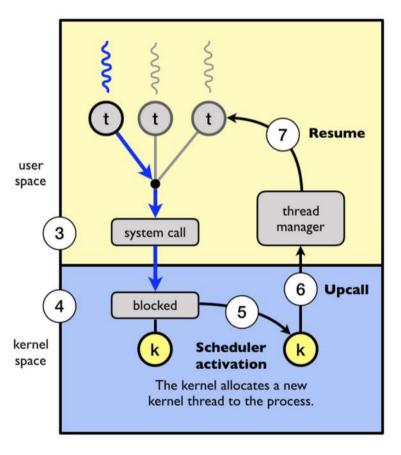
The kernel blocks the calling userlevel thread and the kernel-level thread (LWP) used to execute the user-level thread (4)



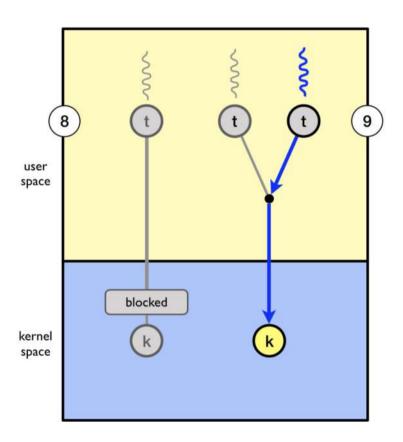
Scheduler activation: the kernel decides to allocate a new kernel-level thread to the process (5)



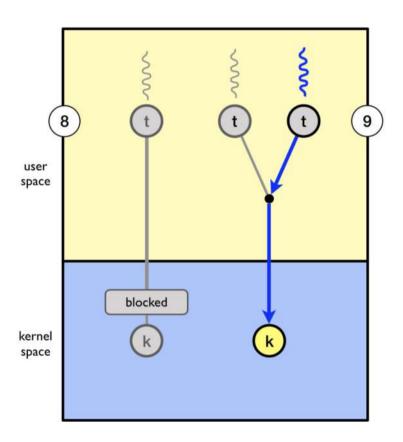
Upcall: The kernel notifies the user-level thread library which user-level thread that is now blocked and that a new kernel-level thread is available (6)



Upcall handler: The user-level thread library resumes one of the ready threads on to the new kernel thread (7)



While one user-level thread is blocked (8) the other threads can take turn executing on the new kernel thread (9)



When the first thread wakes up, the kernel will notify the user thread library via another upcall

User-Level Thread Scheduling

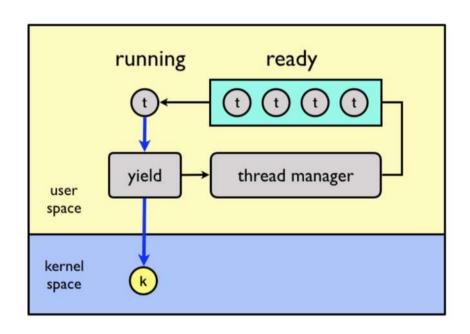
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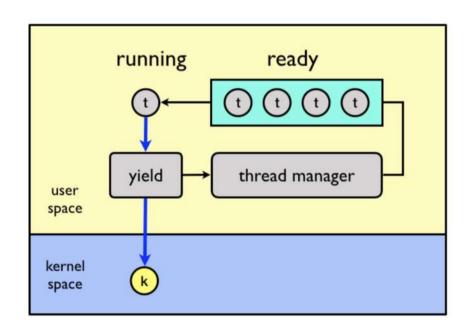
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User-Level Thread Scheduling

- Scheduling user-level threads on the available kernellevel threads (via LWPs)
- Implemented within the user-level thread library in user space (no kernel privileges!)
- Two main scheduling methods:
 - Cooperative
 - Preemptive

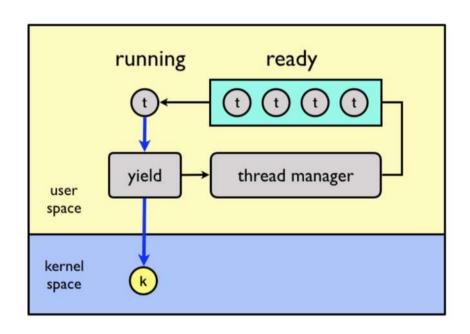


Similar to multiprogramming where a process executes on the CPU until making a I/O request



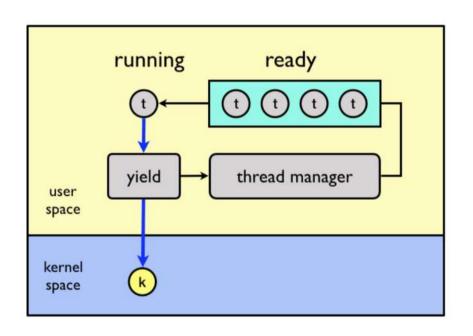
Similar to multiprogramming where a process executes on the CPU until making a I/O request

Cooperative user-level threads execute on the assigned kernel-level thread until they voluntarily give back the kernel thread to the library



Threads yield to each other, either

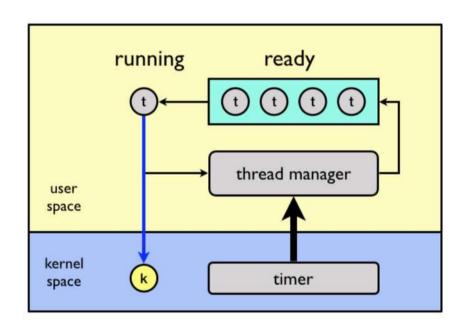
 explicitly (e.g., by calling a yield() provided by the userlevel thread library) or



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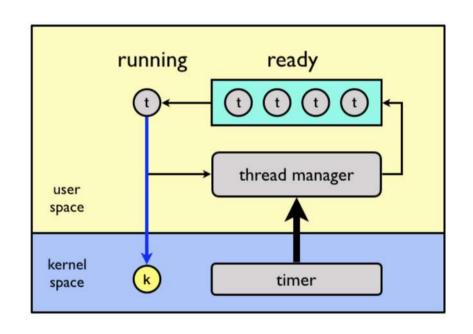
- explicitly (e.g., by calling a yield() provided by the userlevel thread library) or
- implicitly (e.g., requesting a lock held by another thread)

Preemptive Thread Scheduling



Similar to multitasking (a.k.a. time sharing), where a timer is set to cause an interrupt at a regular time interval

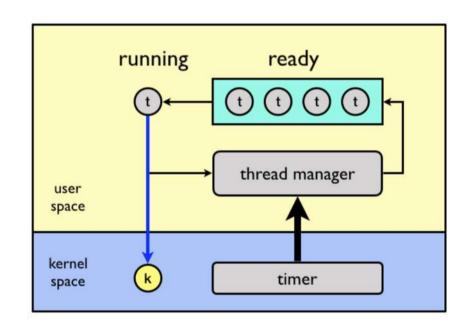
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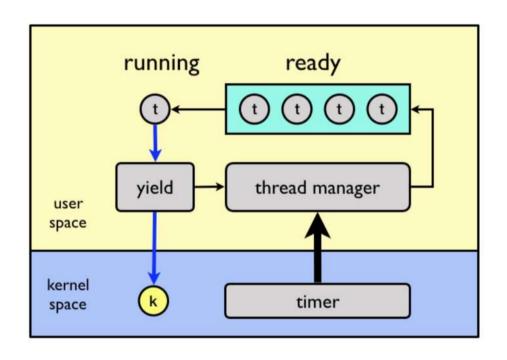


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The running process is replaced if the job requests I/O or if the job is interrupted by the timer

The timer is used to cause execution flow to jump to a central dispatcher thread (in the user-level library), which chooses the next thread to run

Hybrid Thread Scheduling



Cooperative + Preemptive

• A thread is a single execution stream within a process

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