# Teoria degli Algoritmi

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#### Gabriele Tolomei

Dipartimento di Informatica Sapienza Università di Roma tolomei@di uniroma1 it





Lecture 5: Complexity





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- Introduction
- Measuring Complexity
- Asymptotic Analysis
- 4 Analyzing Algorithms
- **5** Complexity Relationships





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- We have seen that there exist some problems that are not decidable, nor even recognizable
- Even though a problem is decidable, and thus computationally solvable in theory, it may not be solvable in practice
- The reason of such intractability is related to the extraordinary amount of resources (mostly, time and space/memory) required by a solution to the problem
- We now delve into the realm of computational complexity theory, which investigates the time, space/memory, and any other resource needed to solve a computational problem





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- Then, we show how to classify problems according to the amount of time they required to be solved
- After that, we discuss the possibility that certain decidable problems need a huge amount of time therefore making them intractable in practice
- Finally, we try to determine when we are facing with such intractable problems





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- Consider the language  $A = \{0^k 1^k \mid k \ge 0\}$
- Obviously, A is a decidable language, i.e., we can build a TM that decides A
- How much time does a single-tape TM need to decide A?
- To answer the question above, let us describe a TM  $M_A$  that decides A, so that we can count the **number of steps** it takes





#### Example (A decider for $A = \{0^k 1^k \mid k \ge 0\}$ )

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Let's see how  $M_A$  works on a specific input x = 0011

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- Loop test Scan all four cells to check if some 0s and 1s are still on the tape: NO! → accept!

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- For example, if the input is a graph, the number of steps may depend on the number of nodes, the number of edges, or some combination of those
- For the sake of simplicity, we compute the running time of an algorithm purely as a function of the string representing the input
- In worst-case analysis, which we focus on here, we consider the longest running time of all inputs of a fixed size
- In average-case analysis, instead, we consider the average of all the running times of all inputs of a fixed size





# The Definition of Running Time

#### Definition (Running Time (Time Complexity))

Let M be a deterministic Turing machine that halts on all inputs (i.e., a decider).

The **running time** (or **time complexity**) of M is the function:

$$f: \mathbb{N} \mapsto \mathbb{N}$$

where f(n) is the **maximum** number of steps that M needs to perform in order to halt on **any** input of size n.





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- We do not need to be extremely accurate, and an estimation of the running time is sufficient
- A convenient form of estimation is called asymptotic analysis
- Such an estimation tries to capture the running time of an algorithm when this is input with large size inputs





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#### Example

Let  $f(n) = 6n^3 + 2n^2 + 20n + 45$ . This is a 4-term polynomial expression, and the highest order term is  $6n^3$ . Disregarding the coefficient 6, we say that f(n) is **asymptotically** at most  $n^3$ 





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Analyzing Algorithms

#### Definition (Big-O)

Let f, g be two functions such that  $f, g : \mathbb{N} \to \mathbb{R}_{>0}$ . We say that  $\mathbf{f}(\mathbf{n}) = \mathbf{O}(\mathbf{g}(\mathbf{n}))$  if there exist  $c, n_0 \in \mathbb{Z}^+$ , such that for every  $n \geq n_0$ :

$$f(n) \leq cg(n)$$

When f(n) = O(g(n)) we say that g(n) is an **upper bound** for f(n), or more precisely, that g(n) is an **asymptotic upper bound** for f(n), to stress the fact that we are not considering any constant factor.





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- We can think of O as representing a suppressed constant
- In practice, most functions f that we will encounter have an obvious highest order term





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Let's verify that this result satisfies our formal definition of asymptotic upper bound. We must find c and  $n_0$ , such that:

$$\underbrace{5n^3 + 2n^2 + 22n + 6}_{f(n)} \le cn^3 \ \forall n \ge n_0$$

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For c = 6 and  $n_0 = 10$ , it holds that:

$$5n^3 + 2n^2 + 22n + 6 \le 6n^3 \ \forall n \ge 10$$

#### Note

In the example above, it also holds (trivially) that  $f(n) = O(n^4)$ , because  $n^4 \ge n^3$  and so it is still an asymptotic upper bound of f.

Conversely,  $f(n) \neq O(n^2)$ : regardless of the values we assign to c and  $n_0$ , the condition we seek for according to the definition remains unsatisfied





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  constant factor, as it holds that

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• When we write  $f(n) = O(\log n)$  we don't need to specify the base as constant factors are suppressed anyway

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- Similarly, when O occurs at the exponent like  $f(n) = 2^{O(n)}$  the same idea applies
- Here, the expression represents an upper bound of 2<sup>cn</sup> for some constant c





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- As such,  $2^{O(\log n)}$  represents an upper bound for  $n^c$  for some constant c
- Finally, the expression f(n) = O(1) is a "convention" to represent a value that is never more than a constant (i.e., it does not depend on n)





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#### Big-O vs. small-o

- Big-O notation has a companion called small-o
- Intuitively, Big-O notation says that one function is asymptotically no greater than another
- Instead, we use small-o to indicate that a function is asymptotically less than another
- The difference between Big-O and small-o is the same as the difference between < and <





#### small-o: Definition

#### Definition (small-o)

Let f, g be two functions such that  $f, g : \mathbb{N} \to \mathbb{R}_{\geq 0}$ . We say that  $\mathbf{f}(\mathbf{n}) = \mathbf{o}(\mathbf{g}(\mathbf{n}))$  if:

$$\lim_{n\to\infty}\frac{f(n)}{g(n)}=0.$$

In other words, f(n) = o(g(n)) means that, for any real number c > 0 there exists a number  $n_0$ , such that f(n) < cg(n) for all  $n \ge n_0$ .





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We already know that  $f(n) = O(n^3)$ , i.e., we have found there **exist** c = 6and  $n_0 = 10$ , such that:

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$$f(n) = 5n^3 + 2n^2 + 22n + 6 \le cn^3 \ \forall n \ge n_0$$

However,  $f(n) \neq o(n^3)$  as we can find a value c for which there is no  $n_0$ such that f(n) < cg(n) for all  $n \ge n_0$ , e.g., c = 5:

$$5n^3 + 2n^2 + 22n + 6 \not< 5n^3 \forall n \ge n_0$$





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Let's analyze the algorithm implemented by the TM that decides the language  $A = \{0^k 1^k \mid k \ge 0\}$ 

## Example (A decider for $A = \{0^k 1^k \mid k \ge 0\}$ )

 $M_A$  = "On input string x:

- Scan across the tape and if a 0 occurs to the right of a 1, reject;
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To analyze  $M_A$ , we consider each stage separately

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- Using Big-O notation, that means O(n) steps





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- This is the test  $M_A$  needs to take to check whether it should enter the loop or not
- Since this involves a full scan of the tape, it costs n steps





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- Each iteration is composed by two full scans (i.e., one for testing the loop condition and the other for crossing off symbols): 2n = O(n)
- Overall,  $n/2 * O(n) = O(n^2)$  steps





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- The time taken by this stage is again O(n)
- Thus, the total time of execution of  $M_A$  on an input x whose length is *n* is:

$$O(n) + O(n^2) + O(n) = O(n^2)$$





#### Definition (The class **TIME**(t(n)))

Let  $t : \mathbb{N} \mapsto \mathbb{R}_{\geq 0}$  be a function.

We define the **time complexity class TIME**( $\mathbf{t}(\mathbf{n})$ ) as the collection of all languages that are decidable by an O(t(n)) time Turing machine





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- One quick improvement to  $M_A$  would be to cross off four symbols (i.e., two 0s and two 1s) on every scan, instead of just two
- That would improve the running time by a factor of 2 since we would need to do n/4 iterations rather than n/2
- Unfortunately, this won't affect the asymptotic running time (Remember: constant factors do not count!)





We can design another TM  $M'_A$  that still decides A, yet it shows that  $A \in TIME(n \log n)$ 

#### Example (Another decider for $A = \{0^k 1^k \mid k \ge 0\}$ )

 $M'_A$  = "On input string x:

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- Scan across the tape and if a 0 occurs to the right of a 1, reject;
- Repeat as long as some 0s and 1s are left on the tape:
  - a Scan across the tape, checking if the total number of 0s and 1s remaining is even or odd: if it is odd **reject**;
  - b Scan again across the tape, crossing off every 0 (resp. 1) in alternating way, starting from the first 0 (resp. 1) encountered;
- 3 If no 0s (resp. 1s) are left on the tape, accept; otherwise, reject."



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- On stage 2.a  $M_A'$  checks on the agreement of the parity of the 0s with the parity of the 1s (if the parities agree, the numbers of 0s and 1s are equal)
- On every scan performed in stage 2.b, the number of 0s (resp., 1s) is cut in half and any reminder discarded





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- The total time of stages 2, 2.a, and 2.b is:  $(1 + \log_2 n) * O(n) = O(n \log n)$
- Putting everything together, the total running time of  $M'_A$  is:  $O(n) + O(n \log n) = O(n \log n)$





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- This result cannot be improved on a single-tape TM
- However, we can decide the language A in O(n) time (a.k.a. linear time) if the TM has a second tape





The following two-tape TM  $M''_{\Delta}$  decides A in O(n) time

# Example (Another decider for $A = \{0^k 1^k \mid k > 0\}$ )

 $M''_{\Delta}$  = "On input string x:

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- Scan across the tape and if a 0 occurs to the right of a 1, reject.
- 2 Scan across the 0s on tape 1 until the first 1; simultaneously, copy the 0s on tape 2.

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- Scan across the 1s on tape 1 until the end of the input; for each 1 read on tape 1, cross off a 0 on tape 2. If all 0s are crossed off before all the 1s are read, reject.
- If we reached the end of the input and all 0s have been crossed off, accept; if any 0s remain, reject."



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- This machine is pretty easy to analyze!
- Each of the 4 stages uses O(n) steps, so the total running time is O(n)
- Note that this is the best possible running time because *n* steps are necessary at least to read the input!





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- Finally, we exhibit a two-tape TM  $M''_A$  which decides A in O(n) time (i.e., linear time)
- It turns out that the time complexity of *A* depends on the characteristics of the model of computation





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- There is an important difference between complexity and computability theory
- In computability theory, the Church-Turing thesis guarantees that all reasonable models of computation are equivalent, i.e., they all decide the same class of languages
- In complexity theory, the choice of the actual model of computation affects the time complexity of languages
- Languages may be decidable in, say, linear time using one model but not necessarily on other models





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- Analyzing Algorithms
- **6** Complexity Relationships





# Complexity Relationships Among Models

 We examine how the choice of computational model may affect the time complexity of languages



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# Complexity Relationships Among Models

- We examine how the choice of computational model may affect the time complexity of languages
- To achieve that, we consider 3 models of computation:
  - 1 single-tape TM
  - multi-tape TM
  - non-deterministic TM







#### Theorem

Let t(n) be a function where  $t(n) \ge n$ . Then every t(n) multi-tape TM has an equivalent  $O(t^2(n))$  time single-tape TM.





#### **Theorem**

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#### Proof.

We already showed how to convert any multi-tape TM M into a corresponding single-tape TM S that simulates it. The sketch of the proof is to demonstrate that simulating each step of M on S requires at most O(t(n)) steps. Hence, the total time used by S is  $O(t^2(n))$ 





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- Tapes are stored contiguously, with the position of each k heads of M marked on the appropriate cell
- Initially, S puts its tape into the format that represents all the k tapes of M, then starts simulating M's steps





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# Single- vs. Multi-Tape TM Time Complexity: Proof

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- Basically, S has to shift a portion of its tape to the right





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Complexity Relationships

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- Each of these active portions has length at most t(n) because M uses t(n) tape cells in t(n) steps if the head just moves rightward at every single step (**Remember**: M runs in t(n) steps)





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- A scan of the active portion of S's tape takes O(t(n)) steps



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- In total, we have  $O(n) + O(t^2(n))$  steps; since we have assumed  $t(n) \ge n$ , the running time of S is  $O(t^2(n))$





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#### Introduction

### Deterministic vs. Non-Deterministic TM Time Complexity

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- Before doing so, let's define the running time of a non-deterministic TM
- Remember that a non-deterministic TM is a decider if all its computation branches halt on all inputs.





#### Definition

Let N be a non-deterministic TM that is a decider. The running time of N is given by the function  $f: \mathbb{N} \to \mathbb{N}$ , where f(n) is the **maximum number of steps** that N uses on **any** branch of its computation on any input of length n.



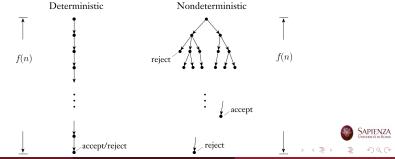
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Gabriele Tolomei

Teoria degli Algoritmi a.a. 2020-21

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#### Theorem

Let t(n) be a function where  $t(n) \ge n$ . Then every t(n) non-deterministic TM has an equivalent  $2^{O(t(n))}$  time deterministic TM.





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- We already saw how to construct a deterministic (3-tape) TM D that simulates N by searching through N's non-deterministic computation tree
- On input of length n, every branch of N's computation tree has length at most t(n)
- Every node in the tree can have at most *b* children, where *b* is the maximum number of legal choices imposed by *N*'s transition function
- It follows that the total number of leaves of the tree is at most  $b^{t(n)}$





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- The simulation proceeds by exploring this tree breadth first
- In other words, we visit all nodes located at depth  $\it d$  before going to any node at depth  $\it d+1$
- The total number of nodes in the tree is less than twice the maximum number of leaves, so we bound it by  $O(b^{t(n)})$





#### Nodes vs. Leaves

Consider a full b-ary tree of height h, and let  $L = b^h$  the **total** number of its leaves.





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Let 
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 the **total** number of nodes.



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#### Nodes vs. Leaves

Consider a full *b*-ary tree of height *h*, and let  $L = b^h$  the **total** number of its leaves.

Let  $N = \sum_{i=0}^{h} b^i = b^0 + b^1 + b^2 + \dots b^h$  the **total** number of nodes. The expression above is a finite geometric series  $\sum_{i=0}^{h} ar^i$ , where a = 1 and r = b, whose closed-form solution is:

$$N = \frac{1 - b^{h+1}}{1 - b} = \frac{1 - (b \cdot b^h)}{1 - b} = \frac{1 - bL}{1 - b} < 2L = O(L) = O(b^h)$$





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As  $b \ge 2$ , we have:

$$N = \frac{1-2L}{1-2} = 2L - 1 \quad (b = 2);$$

$$N = \frac{1-3L}{1-3} = 3/2L - 1/2 \quad (b = 3);$$

$$N = \frac{1-4L}{1-4} = 4/3L - 1/3 \quad (b = 4);$$

At worst, in a binary tree (i.e., when b=2), the total number of nodes is **less than twice** the number of leaves.

4 0 5 4 3 5 4 3 5 5 3

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- Notice that  $b^x = (c^{\log_c b})^x$ ; if we set x = t(n) and c = 2, we obtain:

$$b^{t(n)}=(2^{\log_2 b})^{t(n)}=2^{\log_2 b*t(n)}=2^{k*t(n)}, \text{ where } k=\log_2 b$$
 
$$b^{t(n)}=2^{O(t(n))}$$





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$$b^{t(n)} = (2^{\log_2 b})^{t(n)} = 2^{\log_2 b * t(n)} = 2^{k * t(n)}, \text{ where } k = \log_2 b$$

$$b^{t(n)} = 2^{O(t(n))}$$

• Overall, the running time complexity of *D* is  $O(t(n)) * 2^{O(t(n))} = 2^{O(t(n))}$ 







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$$(2^{O(t(n))})^2 = 2^{O(2t(n))} = 2^{O(t(n))}$$





### Complexity Relationships: Final Remarks

Polynomial differences in running time are considered to be small, whereas exponential differences are considered to be large: this is because of their respective growth rates





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- It is for this reason that, for larger problems and larger inputs, the difference between using a single-tape TM and a multi-tape TM is negligible
- All reasonable deterministic computational models are polynomially equivalent; this means that any one of them can simulate another with only a polynomial increase in running time



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