

10/11.

CS182 HWS.

1. (a). 1. CNN uses fewer parameters than FCN, CNN is more efficient.
 2. CNN notices the spatial connection of image data, so its performance is better than FCN.

b).

$$\begin{array}{l} 1 \quad x \\ 4 \quad y \\ 0 \quad z \\ -2 \\ 3 \end{array} \quad \begin{array}{l} x+4y = -2 \\ 4x-2z = 2 \\ 3z-2y = 11 \end{array} \Rightarrow \begin{cases} x = 2 \\ y = -1 \\ z = 3 \end{cases}$$

\therefore filter is: $[2, -1, 3]$

c).

$$\begin{array}{l} a \quad b \quad c \\ x \quad \quad \quad ax \\ y \quad \quad \quad ay \\ z \quad x \quad \quad az+bx \Rightarrow [ax, ay, az+bx, by, bz+cx, cy, cz] \\ \quad y \quad \quad by \\ \quad \quad x \quad bz+cx \\ \quad \quad y \quad cy \\ \quad \quad z \quad cz \end{array}$$

for $2D$ transpose conv:

$$\text{output} = \text{input} + k - 1 = 2 + 2 - 1 = 3.$$

$$\begin{bmatrix} -1 & 1 \\ 0 & -1 \end{bmatrix} + \begin{bmatrix} 2 & -2 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} -1 & 3 & -2 \\ 0 & -1 & 2 \end{bmatrix} \xrightarrow{+} \begin{bmatrix} -1 & 3 & -2 \\ 3 & -3 & 1 \\ 0 & 3 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 3 & -3 \\ 0 & 3 \end{bmatrix} + \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 3 & -2 & -1 \\ 0 & 3 & 1 \end{bmatrix}$$

$$\begin{bmatrix} -K & 2K \\ 3K & K \end{bmatrix}.$$

2. / (a). 1. A. 2. B.

(b). $y_i = \gamma \hat{x}_i + \beta = \gamma x_i - \gamma \mu + \beta.$

$$\frac{\partial L}{\partial x_i} = \sum_{j=1}^n \frac{\partial L}{\partial y_j} \cdot \frac{\partial y_j}{\partial x_i}$$

$$= \left[\sum_{j=1}^n -\frac{\gamma}{n} \frac{\partial L}{\partial y_j} \right] + \left[\gamma \frac{\partial L}{\partial y_i} \right]$$

$$= \gamma \left[\frac{\partial L}{\partial y_i} - \frac{1}{n} \sum_{j=1}^n \frac{\partial L}{\partial y_j} \right]$$

3. / (a). $3 \times 3 \times 3 \times 4 = 108$

(b). $3 \times 3 \times 3 + 3 \times 4 = 39$

4. / (a).