

```
when started
repeat (8)
  drive forward (200) mm
  if [DownEye detects green ?] then
    [ ]
  if [DownEye detects blue ?] then
    [ ]
repeat (4)
  turn right (90) degrees
  drive forward (200) mm
  turn right (90) degrees
  drive forward (1600) mm
  turn left (90) degrees
  drive forward (200) mm
  turn left (90) degrees
repeat (8)
  drive forward (200) mm
  if [DownEye detects green ?] then
    [ ]
  if [DownEye detects blue ?] then
    [ ]
stop driving
```

stop driving