



§ 2.1.

#1. 2.1 F

2.2.

(a) F

(b) T

(c) F

(d) T

(e) F

2.4. T

2.7. T.

#2 #109 2.1 (i) Indep.
2.1 (f) Indep

#3. pg 110 2.3 ab) $\left(\begin{array}{cccc|c} 1 & 0 & -2 & 8 & -5 \\ 0 & 1 & 1 & 1 & 4 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right) \Rightarrow$ Pivot Columns are $\begin{pmatrix} 2 \\ -1 \\ 2 \end{pmatrix}$ and $\begin{pmatrix} 3 \\ 0 \\ -1 \end{pmatrix}$

2.8 (a) 3 pivots, \Rightarrow apply Gauss-Jordan Elimination.

(b) Restricting down to the 3×3 Matrix, we should obtain Identity Matrix.

§ 2.2

2.14 T This would force the matrix to be the zero matrix.

2.15 F If x_i 's are scalar multiples of each other, this is simply not true.

2.16 F If $\{x_1, x_2, x_3, x_4\}$ contains the dependent vector, its span is 3-dimensional.

2.17 T

2.18 T

#2. 2.32

(c) Apply row reduction to find 3 pivot columns.

Consider $\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \right\}$ as another Basis.

(d) Same as above, take $\{e_1, e_2, e_3, e_4\}$ as a Basis.

#3

pg 124.

2.38 (a) $\left(\begin{array}{ccc|c} 1 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array}\right)$ Rank 1.

$$x_1 + 2x_2 + x_3 = 0 \quad \rightarrow \quad x_1 + 0 = -2x_2 - x_3$$

$$0 + x_2 + 0 = x_2 \quad \rightarrow \quad 0 + x_2 + 0 = x_2$$

$$0 + 0 + x_3 = x_3 \quad \rightarrow \quad 0 + 0 + x_3 = x_3$$

↓

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ 0 \end{pmatrix} x_2 + \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} x_3.$$

(c) Basis for nullspace, $\left\{ \begin{pmatrix} 1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -3 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -4 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\}$

Basis for nullspace.

Rank 1

pg 125.

2.42. $\dim = 2$, W, Z are dependent.

2.46. $\begin{pmatrix} 1 & 3 \\ 3 & -5 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ so yes they are indep

§ 2.3

#143. 2.20

(a) T. $A: \mathbb{R}^5 \rightarrow \mathbb{R}^5$, with at $\dim(\ker A) \geq 3 \Rightarrow \dim(\text{Rank}(A)) \leq 2$

(b) F.

(c) F.

2.21 T

2.22 T

2.23 F

2.25 T

2.27 F

The rank is at least 3.

But the # of pivots possible is 3, so \exists exactly 3 pivots i.e. Rank = 3.Rank + Nullity = 4 $\Rightarrow A$ is $n \times 4$ matrix, nothing more can be said

$$\begin{matrix} A^t \\ \nearrow \text{rank } A^t = m \end{matrix}$$

$$\Rightarrow \text{Rank } A = m$$

 $A^{n \times n}$

$$\Rightarrow \text{if } Ax=b$$

is always solvable.

pg. 143

2.64

B is, C is not.

2.65 (a) $\begin{pmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$

(b) $(10001)^t, (01005)^t, (001-2)^t$

(c) $A_1 = 2R_1 + 2R_2 + 3R_3$

$A_2 = R_1 + R_2 + 3R_3$

$A_3 = 0R_1 + R_2 + 2R_3$

$A_4 = 3R_1 + 3R_2 + 8R_3$

d) Nope, Need 4 pivots.

(e) Verify Theorem

2.66.

(b) Column Space = $\left\{ \begin{pmatrix} -1 \\ 4 \\ 3 \end{pmatrix}, \begin{pmatrix} 4 \\ 4 \\ 0 \end{pmatrix}, \begin{pmatrix} -2 \\ 2 \\ -3 \end{pmatrix} \right\}$

Row Space = $\{ e_1^t, e_2^t, e_3^t \}$

(d) Column Space = $\left\{ \begin{pmatrix} 1 \\ 2 \\ 3 \\ -2 \end{pmatrix} \right\}$

Row Space = $\left\{ \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} \right\}$

2.72. (a) A is 4×5 , $\dim(\text{Rank } A) + \dim(\text{Null } A) = 5$

$2 + \dim(\text{Null } A) = 5$
 $\dim(\text{Null } A) = 3$

It is enough to prove that $\{x_1, x_2, x_3\}$ are lin. independent. This would prove it is a basis for Null A

via Computation $\rightarrow (x_1 | x_2 | x_3) = \begin{pmatrix} 17 & 1 & 5 \\ 0 & 2 & 4 \\ -13 & 3 & 5 \\ 1 & 1 & 2 \\ 2 & 5 & 1 \end{pmatrix} \approx \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ \leftarrow Spn Solution space for $Ax=0$
 \Rightarrow Columns are lin dep

(b) $\exists? B_{4 \times 5}$, $\dim(\text{Rank } B) = 3$, $\dim(\text{Nul } A) = 2$

If there were such a B , its null space would have $\dim 3$ which is not possible.