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Visual Features

- Pixel colour: Binary, pseudo, real colour, etc.
- Histogram: Color histogram, vector histogram, etc.
- Texture: Gabor texture, Tamura texture, GLCM, etc.
- Edge: Canny (5×5) , Sobel (3×3) , Robert (2×2) , etc.
- Gradient: Horizontal, vertical, both, etc.
- Local features: SIFT, HOG, etc.
-

Visual Object Segmentation

- Thresholding
- Clustering methods
- Histogram-based methods
- Edge detection
- Region growing methods
- Watershed segmentation
-

MALAB: Watershed Segmentation



MATLAB: Watershed Segmentation







- Use gradient magnitude as segmentation function;
- Mark foreground objects;
- Compute background markers.

MATLAB: Texture Image Segmentation



- Create a rough mask for the texture;
- Use the rough mask to segment the top texture;
- Display segmentation result.

OpenCV: Image Segmentation



Questions?



Questions?

In image segmentation, gradient includes:

- Vertical gradient
- Horizontal gradient
- Vertical and horizontal gradients
- One of the given options

The wrong answer is:___

Questions?



Visual Object Detection

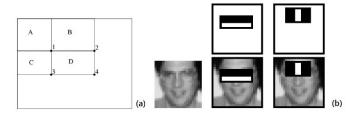
- Given positive and negative samples (well selected)
- Supervised learning provides a natural framework for studying object recognition.
- Train a function that can map novel images to one of labels (e.g., face or non-face).

OpenCV: Face Detection - Training Set



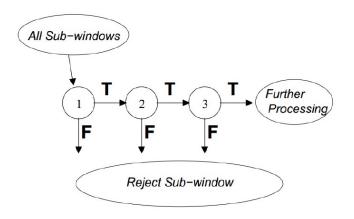
OpenCV: Viola & Jones Face Detection

- Haar Feature Selection
- Creating Integral Image
- AdaBoost Training algorithm
- Cascaded Classifiers



Paul Viola and Michael Jones (2001) Rapid Object Detection using a Boosted Cascade of Simple Features. CVPR 2001.

OpenCV: Viola & Jones Face Detection (Cascade Classifier)



Paul Viola and Michael Jones (2001) Rapid Object Detection using a Boosted Cascade of Simple Features. CVPR 2001.

OpenCV: Viola & Jones Face Detection (Advantage)

- Extremely fast feature computation
- Efficient feature selection
- Scale and location invariant detector
- Detect other types of objects (e.g., cars, hands, etc.).

OpenCV: Viola & Jones Face Detection (Disadvantage)

- Detector is most effective only on frontal images of a face.
- It can hardly cope with 45° face rotation both around vertical and horizontal axes.
- Sensitive to lighting conditions

Questions?



Questions?

The V&J algorithm for human face detection in OpenCV is,

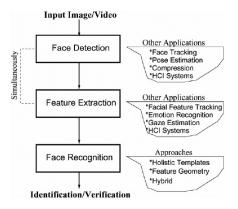
- Extremely fast.
- 2 Efficient.
- 3 Scale and location invariant.
- **4** None of the given options.

The wrong answer is: ___

Questions?



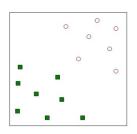
OpenCV: Face Detection and Recognition System

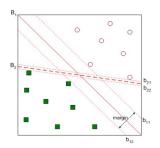


W. Zhao, et al. Face recognition: a literature survey, ACM Computing Surveys, Vol. 35, No. 4, 2003, pp. 399-458.

Support Vector Machine

- *Problem*: Given a vector dataset, find a linear hyperplane (decision boundary) that will separate the data.
- Solution: Find a hyperplane maximizes the margin $(B_1$ is better than B_2),
- SVM Readings: http://www.csie.ntu.edu.tw/~cjlin/libsvm/





WEKA: Computational Tool

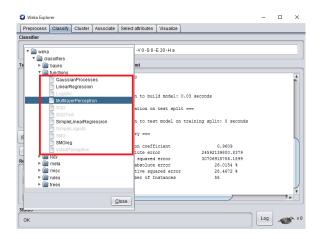
Getting Help



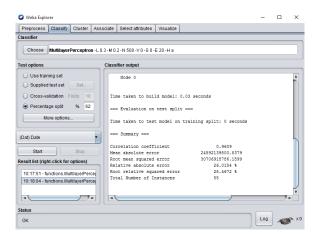
Other Literature

Commercial licenses

WEKA: Computational Tool



WEKA: Computational Tool



WEKA: Computational Tool

4.9,3.0,1.4,0.2, Iris-setosa

```
% 5. Number of Instances: 150 (50 in each of three classes)
% 6. Number of Attributes: 4 numeric, predictive attributes and the class
% 7. Attribute Information:
    1. sepal length in cm
    2. sepal width in cm
   3. petal length in cm
    4. petal width in cm
  5. class:
     -- Iris Setosa
      -- Iris Versicolour
       -- Iris Virginica
% 8. Missing Attribute Values: None
% Summary Statistics:
             Min Max Mean SD Class Correlation
  sepal length: 4.3 7.9 5.84 0.83
                                       0.7826
    sepal width: 2.0 4.4 3.05 0.43 -0.4194
    petal length: 1.0 6.9 3.76 1.76 0.9490 (high!)
     petal width: 0.1 2.5 1.20 0.76 0.9565 (high!)
% 9. Class Distribution: 33.3% for each of 3 classes.
@RELATION iris
@ATTRIBUTE sepallength REAL
@ATTRIBUTE sepalwidth REAL
@ATTRIBUTE petallength REAL
@ATTRIBUTE petalwidth REAL
@ATTRIBUTE class {Iris-setosa, Iris-versicolor, Iris-virginica}
@DATA
5.1,3.5,1.4,0.2, Iris-setosa
```

Evaluations of Empirical Algorithms

- Training set
- Test set
- Ground truth
- Precision: $p = \frac{TP}{TP + FP}$
- Recall: $r = \frac{TP}{TP + FN}$
- F-measure: $F = \frac{2 \cdot p \cdot r}{p+r}$
- G-measure: $G = \sqrt{p \cdot r}$

Note: F-measure is the harmonic mean (average) of recall and precision, G-measure is the geometric mean (average).

Precision?



Questions?



Questions?

In evaluation of empirical algorithms, if TP=60, FP=20, what is the precision $p = \frac{TP}{TP + FP}$?

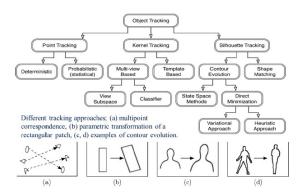
- **1** 20%
- **2** 60%
- **3** 75%
- **a** 80%

The correct answer is:___

Questions?



Visual Object Tracking (Demo)



A. Yilmaz, Object Tracking: A Survey. ACM Computing Surveys, Vol. 38, No. 4, Article 13, 2006.

Visual Object Tracking

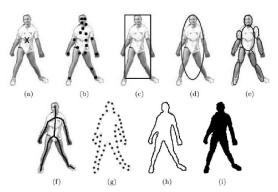


Fig. 1. Object representations. (a) Centroid, (b) multiple points, (c) rectangular patch, (d) elliptical patch, (e) part-based multiple patches, (f) object skeleton, (g) complete object contour, (h) control points on object contour, (i) object shlowette.

A. Yilmaz, Object Tracking: A Survey. ACM Computing Surveys, Vol. 38, No. 4, Article 13, 2006.

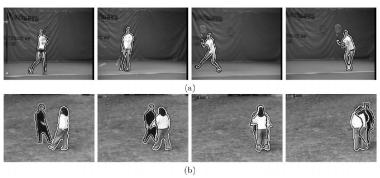
Car Tracking Using Level Set



Car tracking using the level sets method

A. Yilmaz, et al. (2006) Object Tracking: A Survey. ACM Computing Surveys, Vol. 38, No. 4, Article 13.

Contour Tracking



Contour tracking results. (a) tracking of a tennis player, (b) tracking in presence of occlusion

A. Yilmaz, et al. (2006) Object Tracking: A Survey. ACM Computing Surveys, Vol. 38, No. 4, Article 13.

Questions?



Learning Objectives

- Explain how AI theories could be used in visual analytics.
- Evaluate the complexities involved in the automatic extraction of knowledge encoded in free texts and images.