

7.8

7.10 (1)(2)

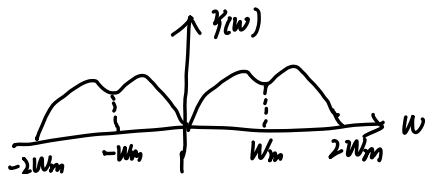
8.2(a)

8.3 (1)

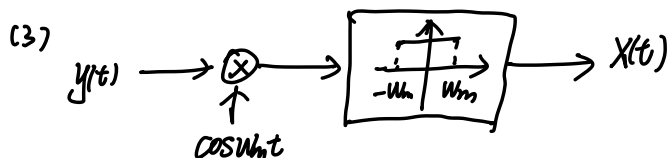
8.15

8.16

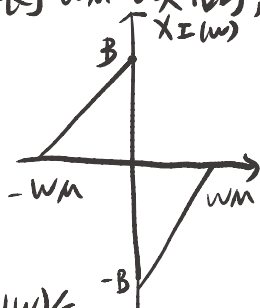
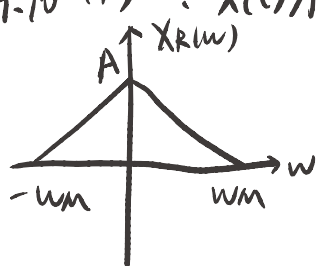
7.8 (1)



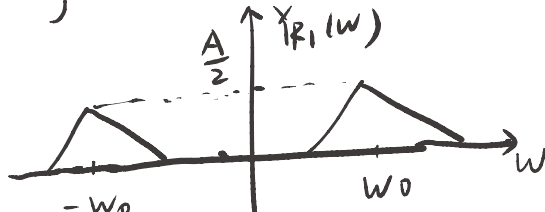
12) $y(t) = 2x(t) \cos w_m t$



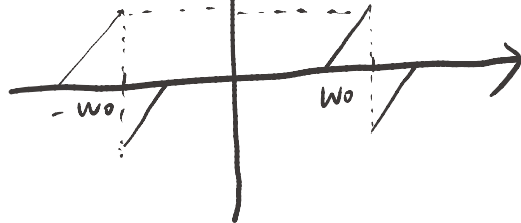
7.10 (1) $\because x(t)$ 为带限于 w_m 的实信号, 则 $X(w) = X_R(w) + jX_I(w)$, $X_R(w)$ 为偶函数, $X_I(w)$ 奇



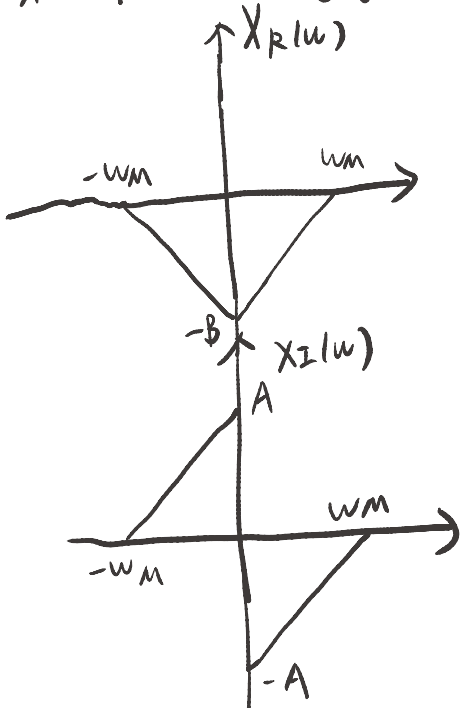
则 $Y_1(w) = Y_{R1}(w) + jY_{I1}(w)$



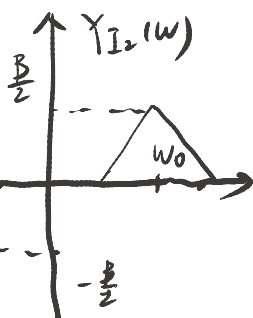
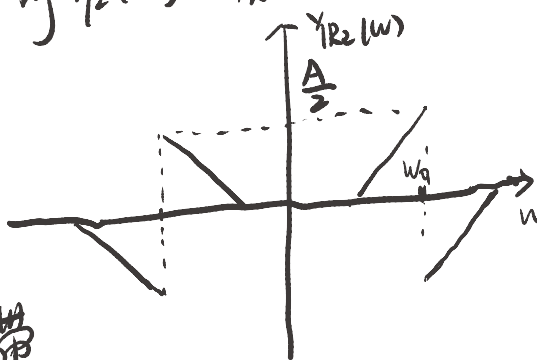
$Y_{I1}(w_0)$



$x(t)$ 通过 $H(w) = -j \operatorname{sgn}(w) K_c$:



则 $Y_2(w) = Y_{R2}(w) + jY_{I2}(w)$:



$Y_1(w) + Y_2(w)$ 即可得下边带

(2) 同理可得

T 8.2 (a)

$$(1) H(s) = \frac{\frac{1}{sC} // R}{\frac{1}{sC} // R + sL} = \frac{R}{R + sL + s^2 RCL} \quad \therefore H(\omega) = \frac{R}{R + j\omega L - \omega^2 RCL}$$

$$(2) H(s) = \frac{1}{1 + \frac{sL}{R} + s^2 RCL} = \frac{1}{CL} \cdot \frac{1}{s^2 + \frac{s}{CR} + \frac{1}{CL}}$$

$$\text{令 } s^2 + \frac{s}{CR} + \frac{1}{CL} = 0 \Rightarrow s_1 = -\frac{1}{2CR} + \sqrt{\frac{1}{4C^2 R^2} - \frac{1}{CL}}, s_2 = -\frac{1}{2CR} - \sqrt{\frac{1}{4C^2 R^2} - \frac{1}{CL}}$$

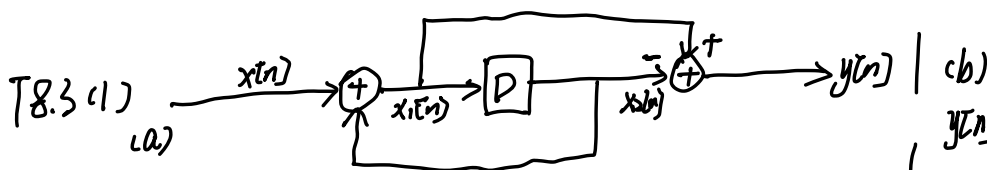
$$\text{设 } H(s) = \frac{A}{s-s_1} + \frac{B}{s-s_2}, \text{ 代入可得: } A = \frac{1}{CL} \cdot \frac{1}{\sqrt{\frac{1}{4C^2 R^2} - \frac{1}{CL}}}, B = \frac{1}{CL} \cdot \frac{-1}{\sqrt{\frac{1}{4C^2 R^2} - \frac{1}{CL}}}$$

$$\therefore h(t) = A e^{s_1 t} + B e^{s_2 t}$$

$$s(t) = h(t) * u(t) = \frac{A}{s_1} [e^{s_1 t} - 1] u(t) + \frac{B}{s_2} [e^{s_2 t} - 1] u(t)$$

$$(3) \frac{1}{CL} \frac{d^2 V_0}{dt^2} + \frac{1}{R} \frac{dV_0}{dt} + V_0 = V_i = \delta(t)$$

代入起始松弛条件即可求解



(b)

$$y[n] = x[n] - 0.5x_2[n] + x_2[n-2]$$

$$\therefore Y(z) = X(z) (1 - 0.5z^{-1} + z^{-2})$$

$$\therefore H(z) = 1 - 0.5z^{-1} + z^{-2}$$

$$\therefore H(\omega) = 1 - 0.5e^{-j\omega} + e^{-2j\omega}$$

T 8.15

原式为: $y[n] - 0.75y[n-1] + 0.125y[n-2] = x[n] - 0.5x[n-1]$

令 $n=1 \Rightarrow y[-1] = -8$ 令 $n=0 \Rightarrow y[-2] = -40$

$$\therefore \frac{1}{8} [Y_u(z)z^{-2} - 8z^{-1} - 40] - \frac{3}{4} [Y_u(z)z^{-1} - 8] + Y_u(z) = -\frac{1}{2}X_u(z)z^{-1} + X_u(z)$$

得: $Y_u(z) = \frac{1 - \frac{1}{2}z^{-1}}{1 - \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2}} X_u(z) + \frac{z^{-1} - 1}{1 - \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2}}$

$$\text{故 } Y_{uzs}(z) = \frac{2}{1-\frac{1}{2}z^{-1}} - \frac{1}{1-\frac{1}{6}z^{-1}}$$

$$Y_{uzi}(z) = \frac{2}{1-\frac{1}{2}z^{-1}} - \frac{3}{1-\frac{1}{6}z^{-1}}$$

$$\text{零状态响应: } y_{zs}[n] = 2 \cdot (\frac{1}{2})^n u[n] - (\frac{1}{6})^n u[n]$$

$$\text{零输入响应: } y_{zi}[n] = 2 \cdot (\frac{1}{2})^n u[n] - 3 \cdot (\frac{1}{6})^n u[n]$$

$$\text{全响应: } y[n] = 4 \cdot (\frac{1}{2})^n u[n] - 4(\frac{1}{6})^n u[n]$$

$$T_{8.16} \quad e^{-2t} \int_{-\infty}^t e^{2\tau} x(\tau) d\tau = \int_{-\infty}^t e^{-2(t-\tau)} x(\tau) d\tau = x(t) * e^{-2t} u(t)$$

$$\text{方程改写为 } y''(t) + 4y'(t) + 3y(t) = 2x(t) + 2x(t) * e^{-2t} u(t)$$

单边拉氏变换:

$$s^2 Y(s) - s y(0^-) - y'(0^-) + 4[sY(s) - y(0^-)] + 3Y(s) = 2X(s) + 2X(s) \cdot \frac{1}{s+2}$$

$$\therefore Y(s) = \frac{2}{s^2+3s+2} X(s) + \frac{s-1}{s^2+4s+3} \quad \text{其中 } X(s) = \mathcal{L}\{u(t)\} = \frac{1}{s}$$

$$\text{则零状态响应: } Y_{uzs}(s) = \frac{2}{s^2+3s+2} \cdot \frac{1}{s} = \frac{1}{s} - \frac{2}{s+1} + \frac{1}{s+2}$$

$$y_{zs}(t) = u(t) - 2e^{-t}u(t) + e^{-2t}u(t)$$

$$\text{零输入响应: } Y_{uzi}(s) = \frac{s-1}{s^2+4s+3} = -\frac{1}{s+1} + \frac{1}{s+3}$$

$$y_{zi}(t) = 2e^{-3t}u(t) - e^{-t}u(t)$$

$$\text{综上: 全响应: } y(t) = 2e^{-3t}u(t) + e^{-2t}u(t) - 3e^{-t}u(t) + u(t) \quad t \geq 0$$

$$\text{零状态: } y_{zs}(t) = u(t) - 2e^{-t}u(t) + e^{-2t}u(t)$$

$$\text{零输入: } y_{zi}(t) = 2e^{-3t}u(t) - e^{-t}u(t)$$

$$\text{自由响应: } 2e^{-3t}u(t) + e^{-2t}u(t) - 3e^{-t}u(t)$$

$$\text{强迫响应: } u(t)$$

$$\text{稳态响应: } u(t)$$

$$\text{暂态响应: } 2e^{-3t}u(t) + e^{-2t}u(t) - 3e^{-t}u(t)$$