
NMRC NWB Standardized Structure

Release 1.0

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Contents:

ABOUT NWB

Neurodata Without Borders (NWB) format is unified data format designed in the Neurodata Without Borders: Neurophysiology (NWB:N) to incorporate several types of data, including electrophysiological and optical physiology data, stimuli and behavior data et.al.

The official website of NWB:N project can be found [here](#).

PRE-INSTALLED TOOLBOXES

Contents

- *Pre-installed Toolboxes*
 - *MatNWB*
 - *TDTMatlabSDK*

Important: Please installed the following toolboxes before using NWB standardized processing codes.

2.1 MatNWB

MatNWB is the Matlab interface for reading and writing NWB file. To generate and use NWB structure, MatNWB should be inside the folder /util/.

1. Download the [MatNWB](#) .
2. From the Matlab command line, generate matlab m-files:

```
generateCore('schema/core/nwb.namespace.yaml');
```

3. Copy the folder matnwb into /util/

2.2 TDTMatlabSDK

TDTMatlabSDK is the Matlab TDT data import tool. TDTMatlabSDK should be inside the folder /util/ when converting tdt data to NWB structure.

1. Download the zipped [TDTMatlabSDK](#) tool.
2. Extrac the zip files into /util/ folder

INPUT SYSTEMS

3.1 TDT System

3.1.1 Structure of TDT System

tdt filed	sub-field	chair	gait	description	user def.
.epocs	.Cam1	yes	yes	Cam1/2: onset and offset time of each frame	n/a
	.Cam2	no	yes		n/a
	.Spd_	no	yes	Spd_ : onset and offset time of gait mat	Spdg
.steams	.BUGG	yes	yes	BUGG: store the neural data [n_chns, n_temporal] start_time = 0	Neur
	.EYEa	yes	no	x,y positions of eyes [2, n_temporal] start_time = 9.5367e-07	EYEa
	.EYEt	yes	no	sync data from eye tracking system [1, n_temporal] start_time = 9.5367e-07	EYEt
	.Stpd	yes	no	Stpd: synchronization signal from the touch pad. [1, n_temporal] start_time = 9.5367e-07	Stpd
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	.Para	yes	no	For what? [4, n_temporal] start time =	Para

Example dataset:

- setup-chair: Bug-190111 -> Block-1
- setup-gait: Bug-181130 -> Block-1

3.1.2 NWB Structure Storing TDT data

3.2 Motion Analysis System

3.3 Eye Tracking System

3.4 Gait Mat System

FUNCTIONS

4.1 Convert to NWB Functions

4.2 Read from NWB Structure