

## Multimodal Object Detection via Probabilistic Ensembling





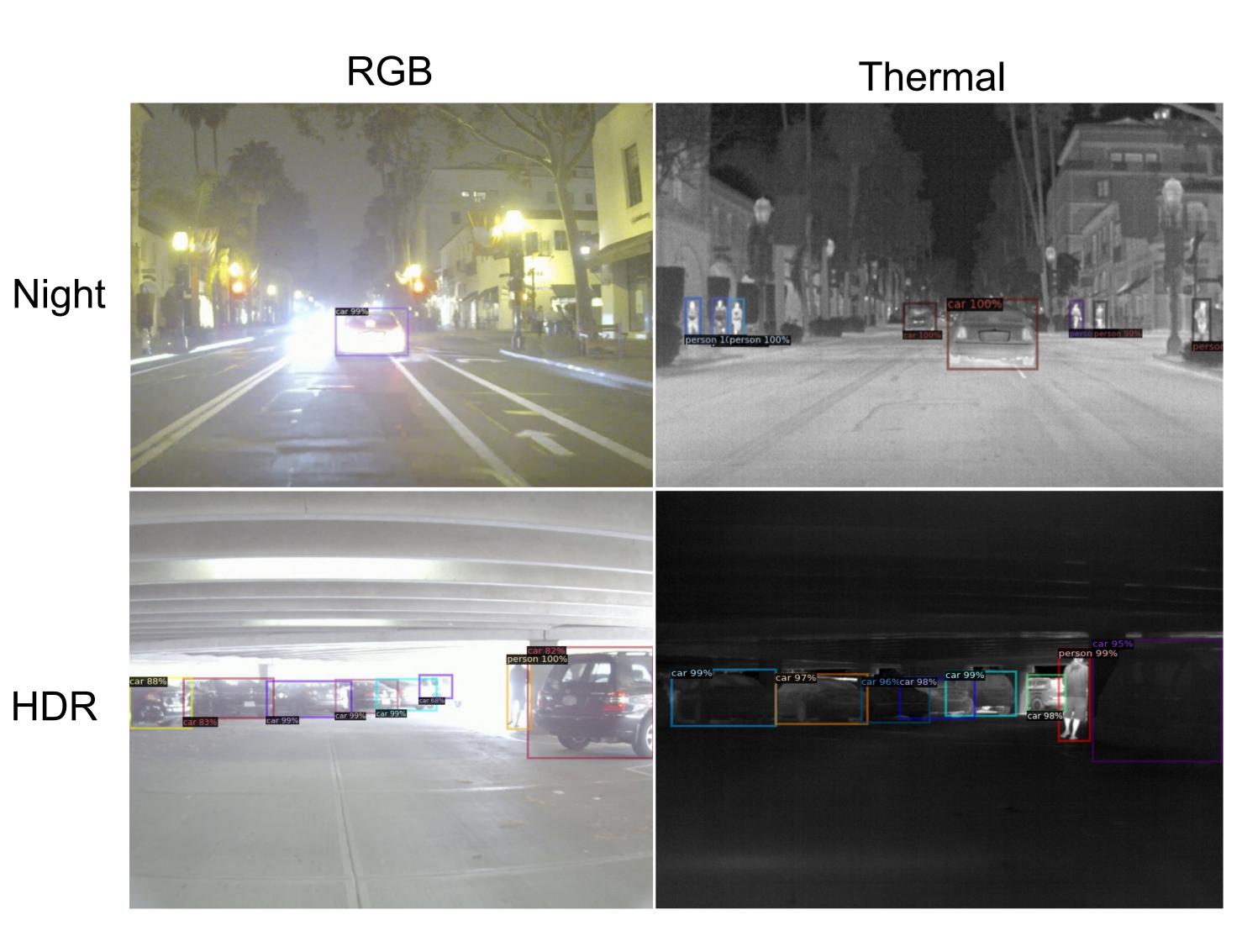


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### Motivation

- RGB and thermal modalities are complementary
- Different scenarios



## Proposed Method

Score fusion NMS

Probabilistic Ensembling

ProbEn

p(z|x2)

 $p(y|x_1)$  $p(y|x_2)$ Late fusion \_\_\_

Measurement

Pooling

 Assume conditional independence  $p(x_1, x_2|y) = p(x_1|y)p(x_2|y)$ 

Avg

Given multimodal measurement

$$p(y|x_1, x_2) = \frac{p(x_1, x_2|y)p(y)}{p(x_1, x_2)} \propto p(x_1, x_2|y)p(y)$$

ProbEn

Bayes rule

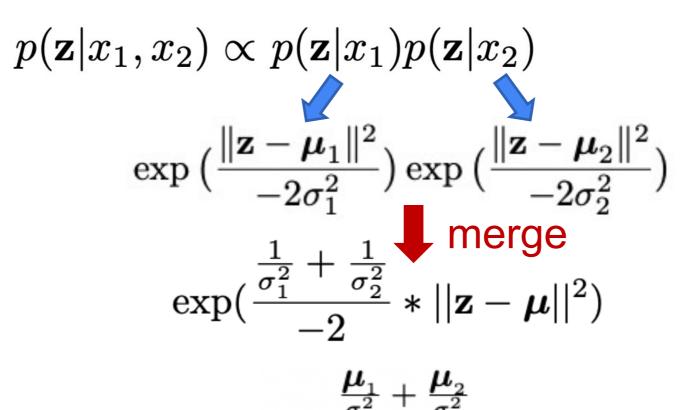
 $p(y|x_1,x_2) \propto p(x_1|y)p(x_2|y)p(y)$  $\propto \frac{p(x_1|y)p(y)p(x_2|y)p(y)}{p(y)}$  $\propto rac{p(y|x_1)p(y|x_2)}{2}$ 

Box fusion

p(z|x1)

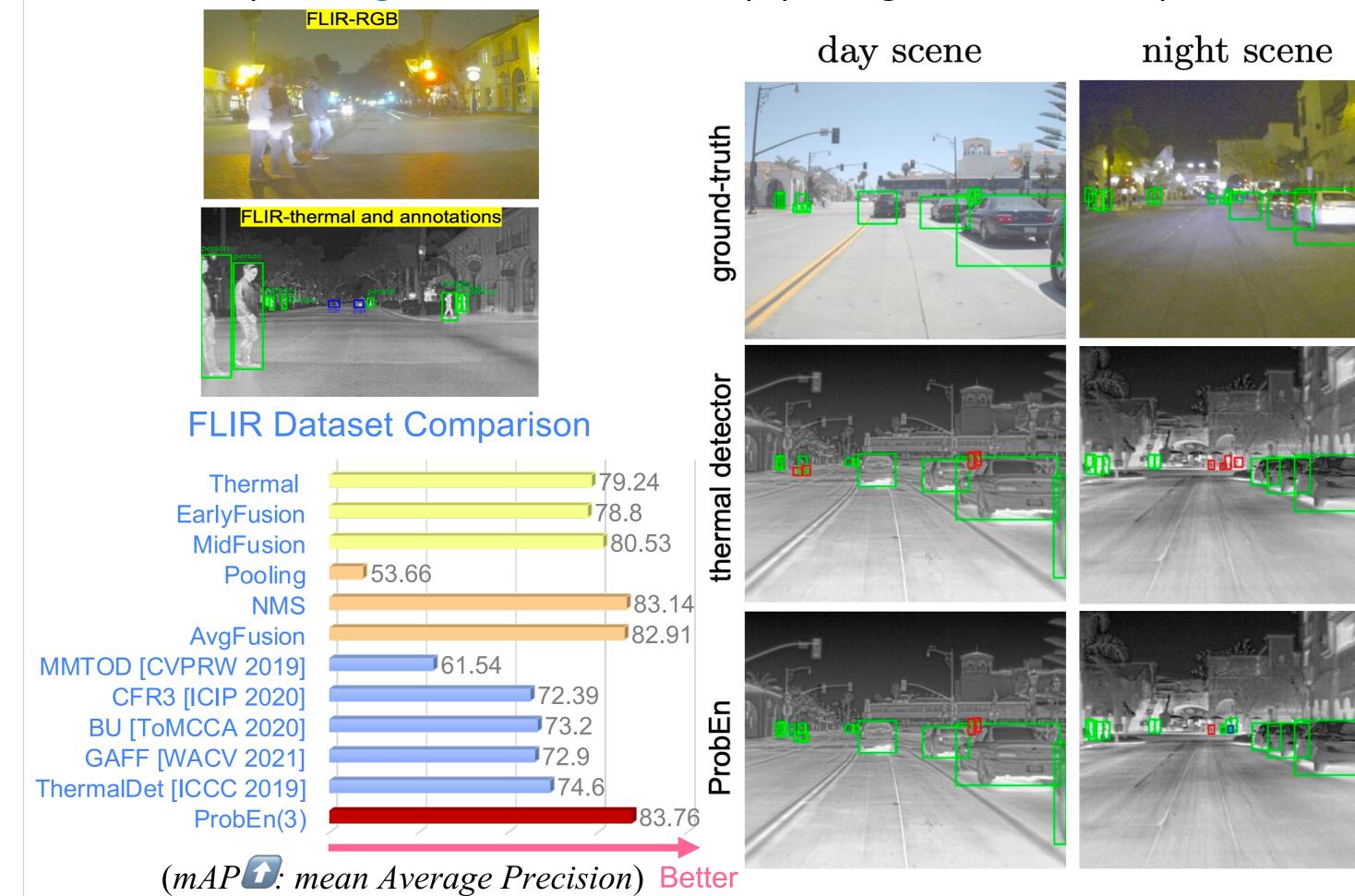
 Assume Gaussian posterior  $p(\mathbf{z}|x_i) = \mathcal{N}(\boldsymbol{\mu}_i, \sigma_i^2 \mathbf{I})$ 

Conform with conditional independence



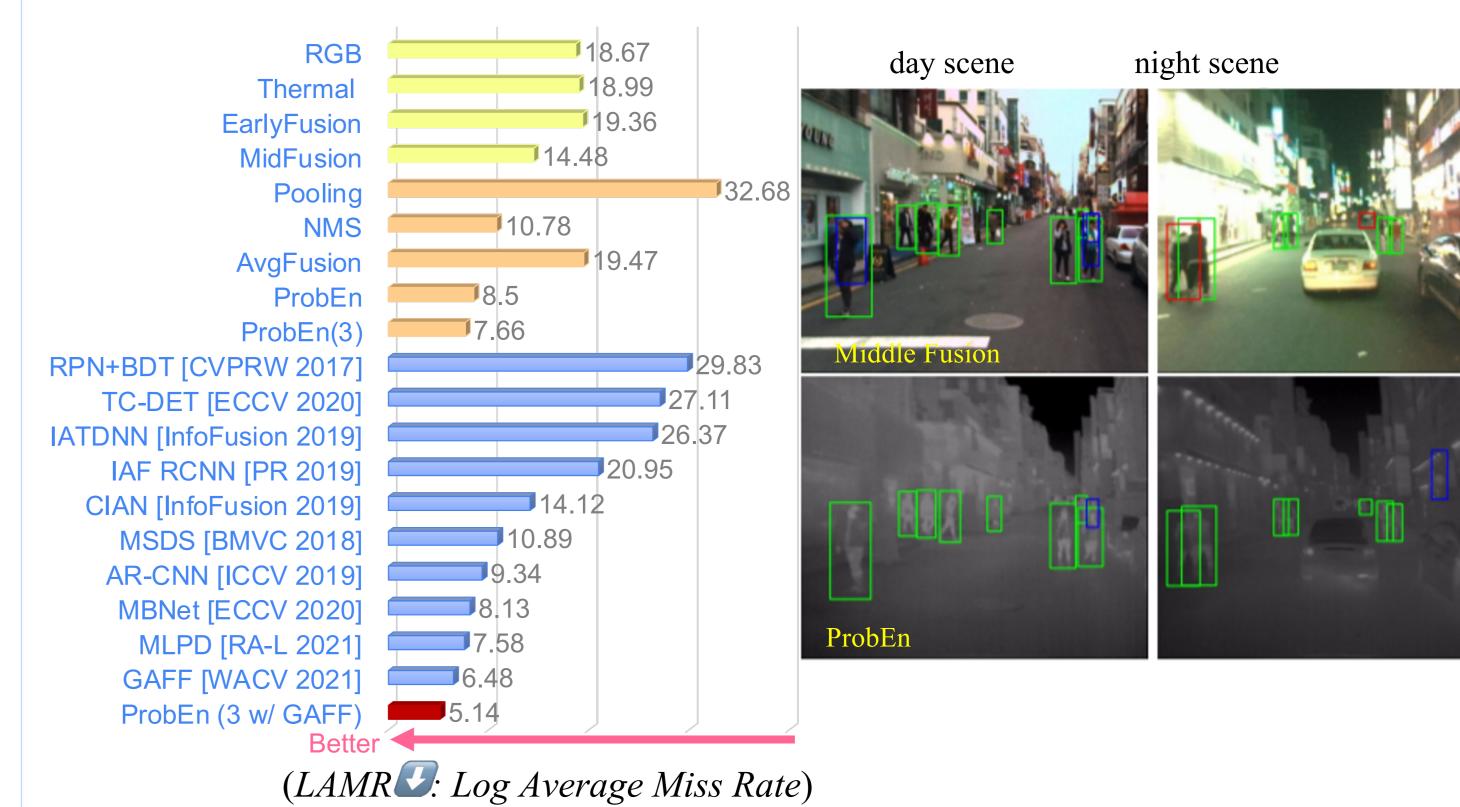
# Experiment

FLIR (Unaligned / multiclass(3) / high resolution)



KAIST (Aligned / one class / low resolution)

**KAIST Dataset Comparison** 



#### Conclusion

- ProbEn is significantly better than heuristic methods (e.g., Avg fusion and NMS).
- ProbEn still improves when the conditional independence assumption does not hold.
- ProbEn outperforms significantly than other fusion methods.

## Multimodal Fusion Strategy

