

OS 2017

Homework3: scheduling simulation

(Due date 12/28 23:59:59)

Objectives

- Simulate task scheduling
- Understand how to implement context switch
- Understand how signal works in Linux

Requirements (1/2)

1. Write a user application (scheduling_simulator)
 - Shell mode
 - Implement 4 commands (*must follow the formats in slide 6*)
 - ***add***: Add new task(s)
 - ***remove***: Remove task(s)
 - ***ps***: Show the information of all tasks (PID, task name, task state, and queueing time)
 - ***start***: Start or continue simulation (switch to simulation mode)
 - Simulation mode
 - Use **ucontext** and the related APIs to implement context switch
 - Implement the variable time quantum RR(round robin) scheduling
 - As in *slide 7*
 - Should receive a signal (SIGALRM) every 10 ms then determine whether to reschedule or not
 - ***Ctrl* + z** should pause the simulation and switch to shell mode
 - ***start*** should resume the simulation
 - continue simulation from where it pauses

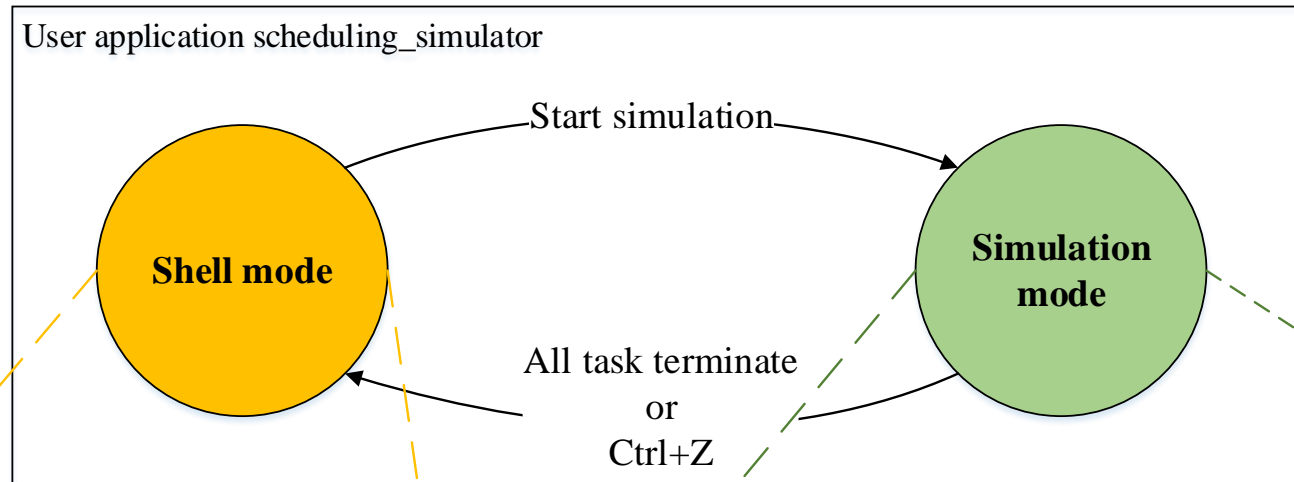
Requirements (2/2)

2. Implement the APIs that can be used by the tasks (*described in slide 8*)
 - `void hw_suspend(int msec_10);`
 - `void hw_wakeup_pid(int pid);`
 - `int hw_wakeup_taskname (char *task name);`
 - `int hw_task_create(char *task_name);`
3. Task
 - The state of each task is shown in *slide 5*
 - A task is a function in 'tasks.c' (*task_name* = function name)
 - All the functions are provided by TAs and can not be changed

Notice:

- Register signal handlers to handle ctrl+z and SIGALRM
- *Signal may occur anytime even in signal handlers and APIs*

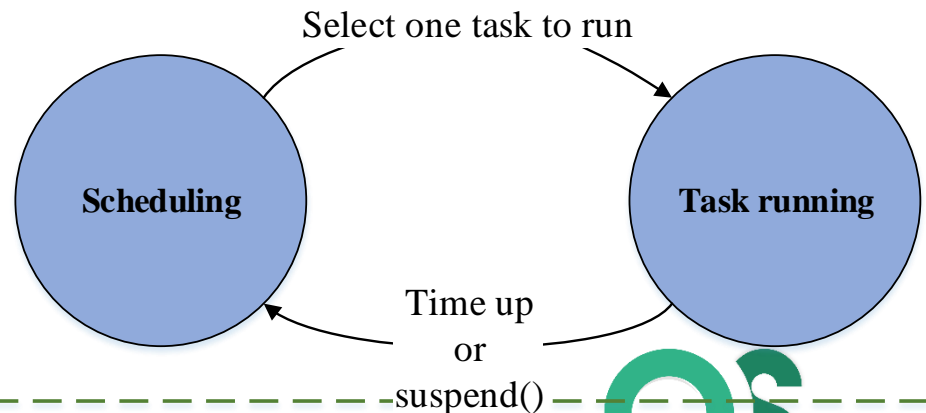
Architecture



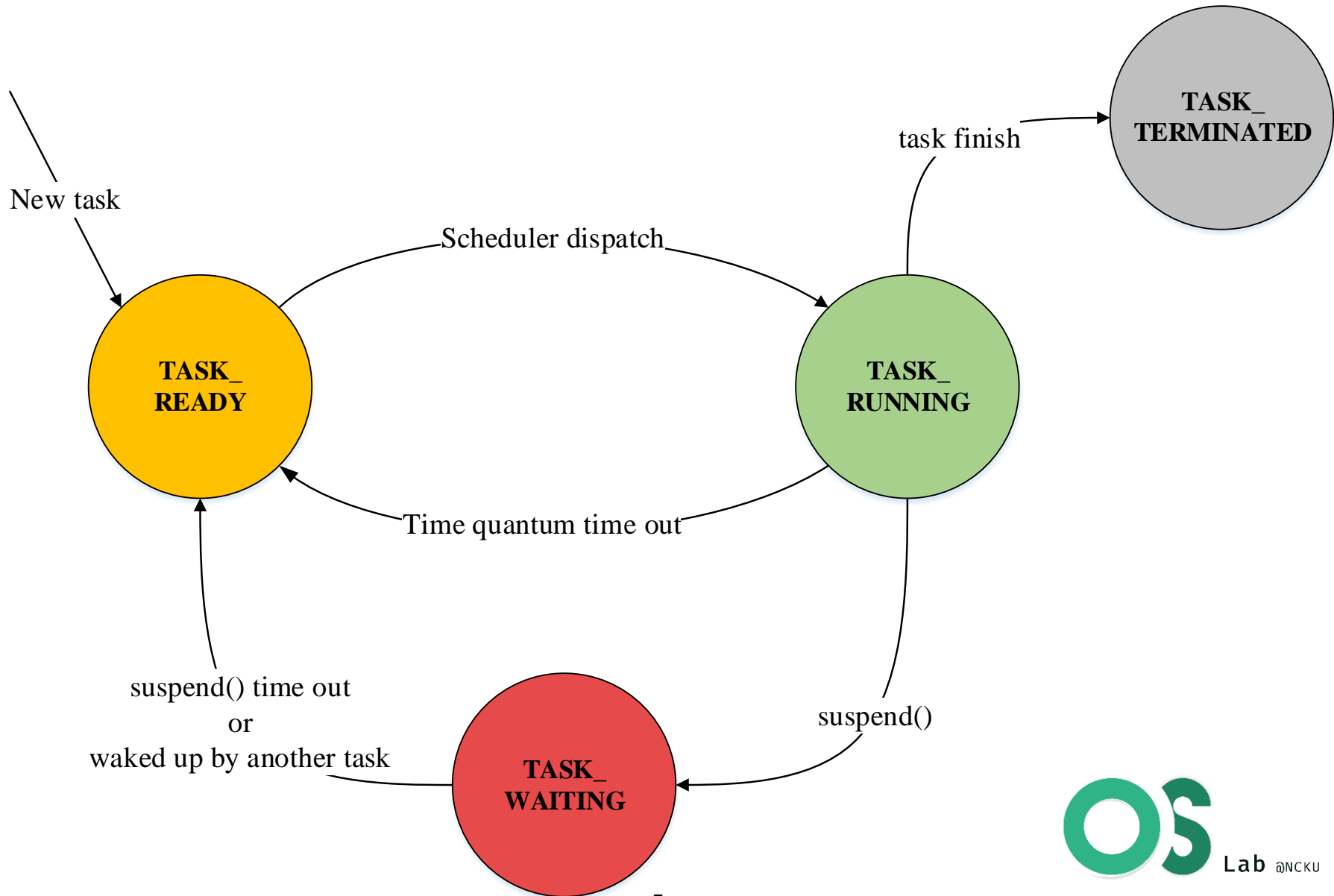
Shell mode

- Add task(s) for simulation
- Remove task(s) from simulation
- Show the information of simulated task(s)

Simulation mode



Task state



Shell commands

- add

\$ add TASK_NAME -t TIME_QUANTUM

- What task to add
- Optional argument
 - L for the larger time quantum
 - S for the small time quantum
- Default value is S

- remove

\$ remove PID

Remove a task with *PID*

- start

\$ start
simulating...

- ps
simulating...

^Z

\$ ps

1	task1	TASK_READY	50
2	task2	TASK_TERMINATED	10
3	task2	TASK_READY	50
4	task3	TASK_WAITING	50

PID

Task name

Task state
(in slide p.5)

Queueing time

queueing time

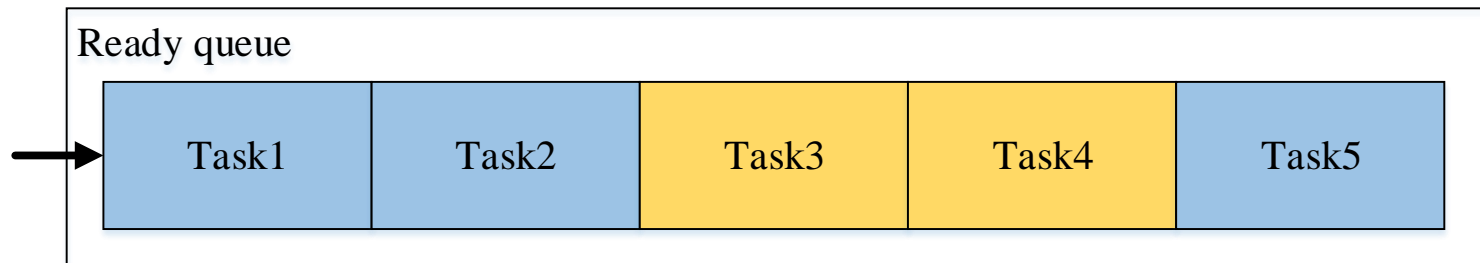
- The total time the task stays in the ready queue during all the simulation period

Variable time quantum RR scheduling

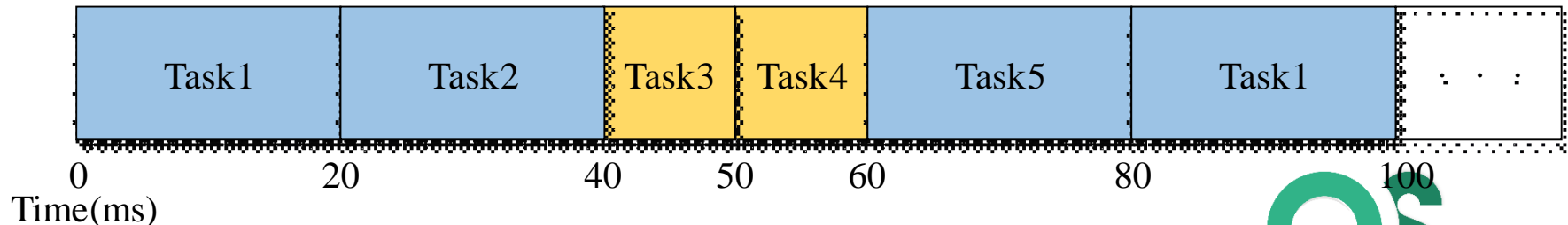
- Scheduling each task by round robin(RR)
- Two types of time quantum
 - Larger time quantum: 20 ms
 - Small time quantum: 10 ms

```
$ add Task1 -t L  
$ add Task2 -t L  
$ add Task3 -t S  
$ add Task4  
$ add Task5 -t L  
$ start
```

Example



Gantt chart



API Description

- `void hw_suspend(int msec_10);`
 - The running task change its state to ***TASK_WAITING***
 - Reschedule (schedule next task to run)
 - Change the state of the suspended task to ***TASK_READY*** after *msec_10**10 ms
- `void hw_wakeup_pid(int pid);`
 - Change the state of task ***PID*** from ***TASK_WAITING*** to ***TASK_READY***
 - Reschedule if needed
- `int hw_wakeup_taskname(char *task_name);`
 - Change the state of all the tasks with ***task_name*** from ***TASK_WAITING*** to ***TASK_READY***
 - Return how many tasks are waken up
 - Reschedule if needed
- `int hw_task_create(char *task_name);`
 - Create task ***task_name***
 - Return ***PID*** of the created task
 - Return -1 if there is no function named ***task_name***
 - Reschedule if needed

References

1. ucontext
 - [The Open Group Library](#)
 - IBM® IBM Knowledge Center
 - [getcontext\(\)](#)
 - [tetcontext\(\)](#)
 - [makecontext\(\)](#)
 - [swapcontext\(\)](#)
2. signal handler
 - [Gitbook](#)
 - [Linux manual page](#)
3. timer
 - [Linux manual page](#)
 - [IBM® IBM Knowledge Center](#)