



Duet Robust Deep Subspace Clustering

P3D-07



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Motivation

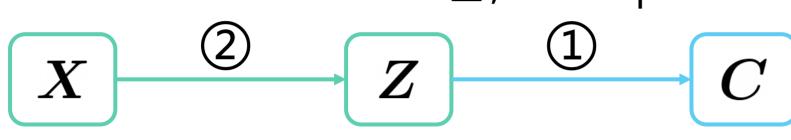
General form of subspace clustering:

s.t. $diag(\mathbf{C}) = 0$

① self-expression ② data reconstruction ③ structure prior
$$\min_{\pmb{C}} \ \underline{\mathcal{L}(\pmb{Z}-\pmb{Z}\pmb{C})} + \lambda_1 \sum_i \underline{\mathcal{P}(\pmb{X}_i, \hat{\pmb{X}}_i)} + \lambda_2 \underline{\mathcal{R}(\pmb{C})}$$

When facing corruptions:

- Influence via (1): directly distort the estimated subspace structures (corruption flow)
- Influence via (2): induce an unfaithful Z, then spread to C



...most existing work only focuses on reduce the influence on (1)

Framework

Double-assurance for robustness with two-fold explicit noise modeling:

• Robust reconstruction with $\mathcal{P}(\cdot)$

corruption indicator for each sample
$$\mathcal{P}(m{X}_i, \hat{m{X}}_i) = rac{1}{2}\|m{X}_i - \hat{m{X}}_i - m{E}_i\|_F^2 + \eta_1 \|m{E}_i\|_F$$

F-norm to prevent the loss from being dominated by the corruptions

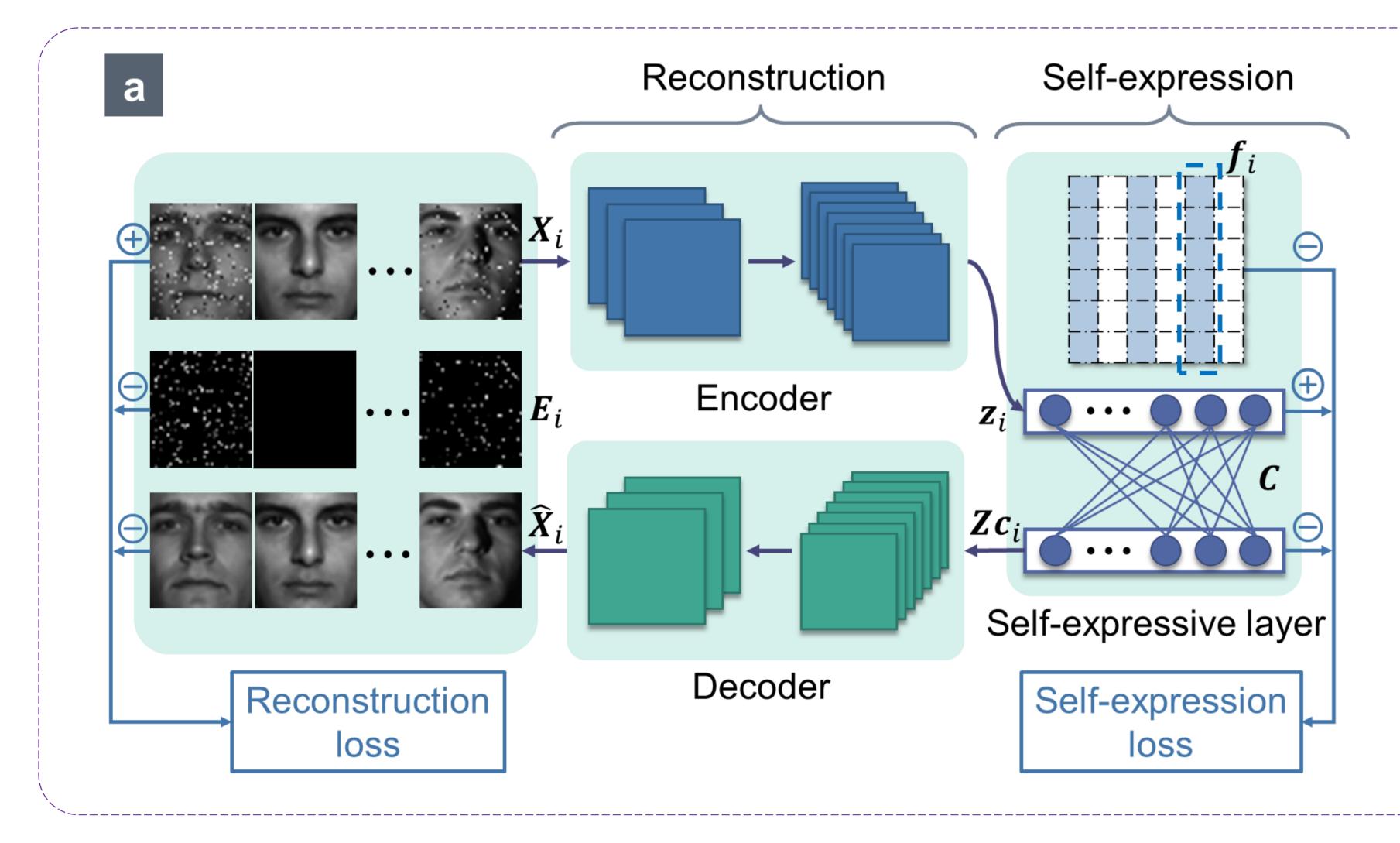
• Robust self-expression with $\mathcal{L}(\cdot)$

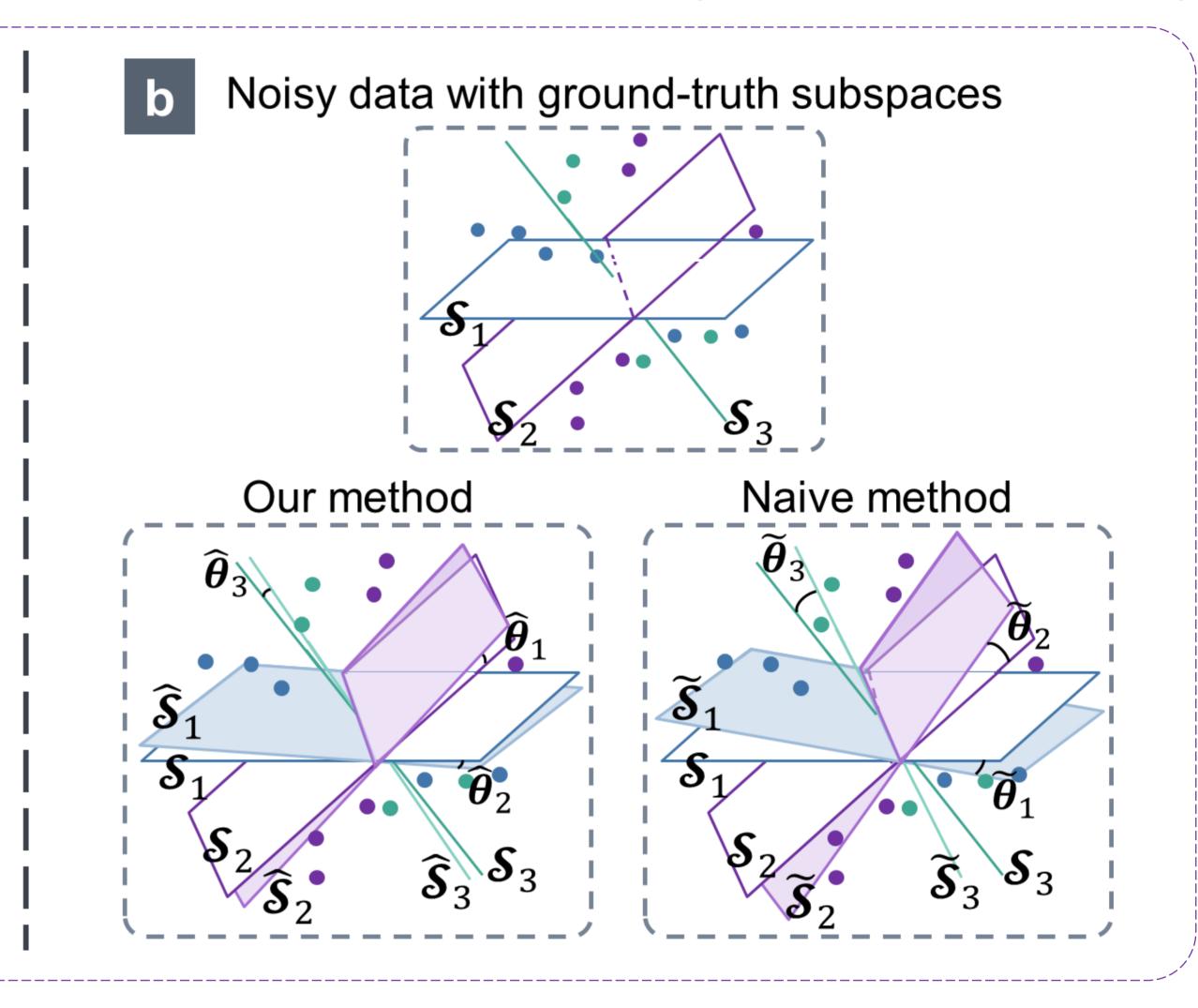
$$\mathcal{L}(m{Z} - m{Z}m{C}) = \sum_{i=1}^{n} \frac{1}{2} \|m{z}_i - m{Z}m{c}_i - m{f}_i\|_2^2 + \eta_2 \|m{f}_i\|_2$$

Objective function

$$L = \sum_{i=1}^{n} \frac{1}{2} \| \boldsymbol{X}_i - \hat{\boldsymbol{X}}_i - \boldsymbol{E}_i \|_F^2 + \eta_1 \| \boldsymbol{E}_i \|_F + \lambda_2 \| \boldsymbol{C} \|_p$$

non-smooth! (non-differentiable at zero)





Smoothing of norms

Definition 2 ($\frac{1}{\mu}$ -smooth approximation, [2]). For a convex function $h: \mathbb{E} \to \mathbb{R}$, a convex differentiable function $h_{\mu}: \mathbb{E} \to \mathbb{R}$ is said to be its $\frac{1}{\mu}$ -smooth approximation with parameters (α, β) if for any $\mu > 0$ the following holds:

- 1) $h_{\mu}(\boldsymbol{x}) \leq h(\boldsymbol{x}) \leq h_{\mu}(\boldsymbol{x}) + \beta \mu \text{ for all } \boldsymbol{x} \in \mathbb{E},$
- 2) h_{μ} is $\frac{\alpha}{\mu}$ -smooth.

 $\frac{1}{n}$ -smooth approximation of F-norm and ℓ_2 -norm:

$$\|\boldsymbol{x}\|_{F_{(\mu)}} = \sqrt{\|\boldsymbol{x}\|_F^2 + \mu^2} - \mu$$

 $\|\boldsymbol{x}\|_{2_{(\mu)}} = \sqrt{\|\boldsymbol{x}\|_2^2 + \mu^2} - \mu$

balance the approximation accuracy and smoothness

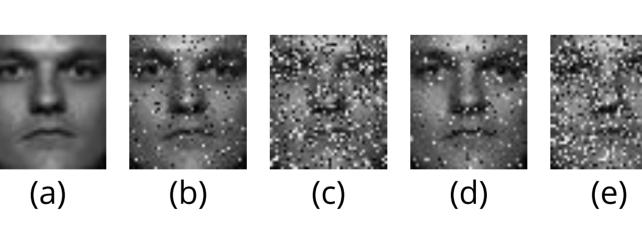
Smoothed objective function:

$$L = \sum_{i=1}^{n} \frac{1}{2} \| \boldsymbol{X}_i - \hat{\boldsymbol{X}}_i - \boldsymbol{E}_i \|_F^2 + \eta_1 \| \boldsymbol{E}_i \|_{F_{(\mu)}} +$$
 $\lambda_1 \left(\frac{1}{2} \| \boldsymbol{z}_i - \boldsymbol{Z} \boldsymbol{c}_i - \boldsymbol{f}_i \|_2^2 + \eta_2 \| \boldsymbol{f}_i \|_{2_{(\mu)}} \right) + \lambda_2 \| \boldsymbol{C} \|_p$

a totally differentiable network, simultaneously update all the params

[self-express coef. $m{C}$] [corruption terms $m{E}_i, m{f}_i$]

Experiments



Corrupted samples on Extended Yale B dataset. (a) Original image, (b/c) 10%/40% corrupted by random pixel corruption, (d/e) 10%/40% corrupted by Gaussian noise.

