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$$\frac{d_2^* + d_1^* z^{-1} + z^{-2}}{1 + d_1 z^{-1} + d_2 z^{-2}}$$

$$\frac{d_1^* + z^{-1}}{1 + d_1 z^{-1}}$$

$$\frac{d_1^* + e^{-j\omega}}{1 + d_1 e^{-j\omega}} = \frac{e^{-j\omega} (d_1^* e^{j\omega} + 1)}{1 + d_1 e^{-j\omega}}$$

$$= D^* \left( \frac{1}{z^*} \right)$$

$$D \left( \frac{1}{z^*} \right) = 1 + d_1 \left( \frac{1}{z^*} \right)^{-1} = 1 + d_1 z^*$$

$$\frac{d_1^* + z^{-1}}{1 + d_1 z^{-1}} = \frac{z^{-1}(d_1^* z + 1)}{D(z)}$$

$D(\lambda) = 0$  be the pole

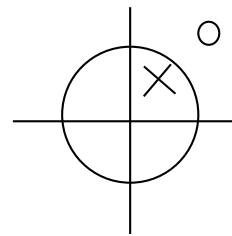


$\frac{1}{\lambda^*}$  be the zero

$$\therefore \frac{1}{z^*} = \frac{1}{(1/\lambda^*)^*} = \lambda$$

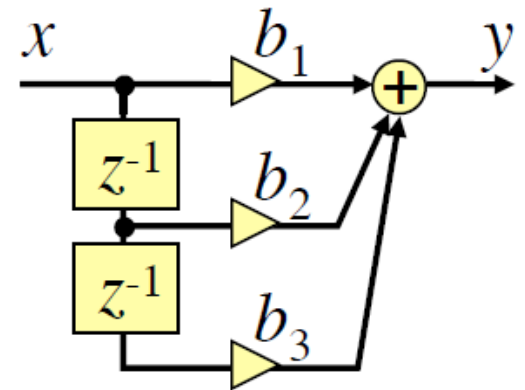
$$\lambda = r e^{j\theta} \quad \frac{1 - \frac{1}{d_1^*} z^{-1}}{1 - d_1 z^{-1}} = \frac{\frac{1}{d_1^*} (d_1^* - z^{-1})}{1 - d_1 z^{-1}}$$

$$\frac{1}{r e^{-j\theta}} = \frac{1}{r} e^{j\theta}$$

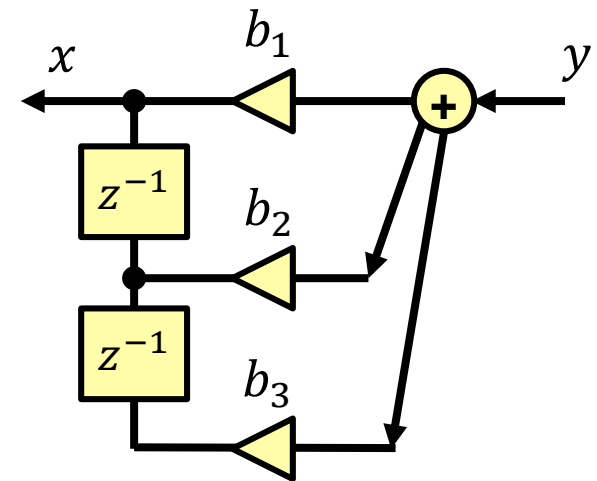


$$\frac{-d_1^* + z^{-1}}{1 - d_1 z^{-1}}$$

- Transpose
  - reverse paths

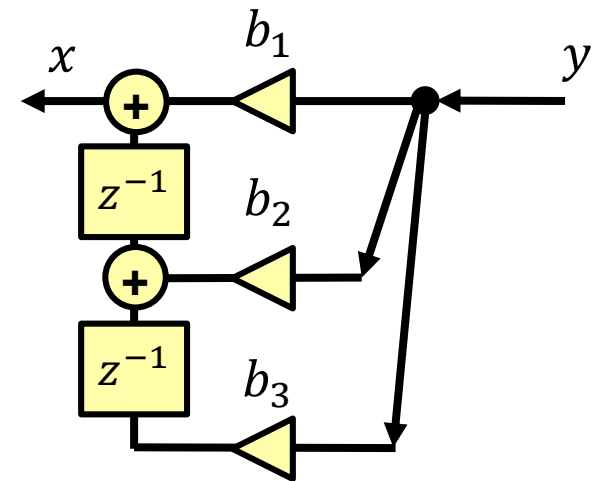
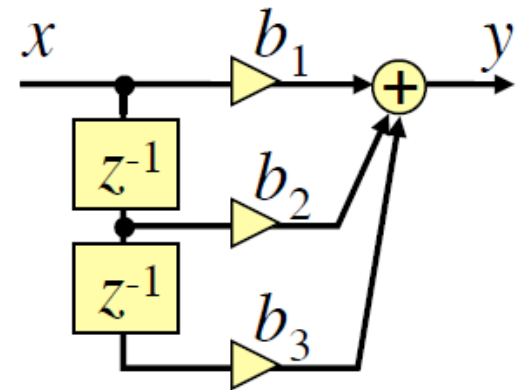


$\equiv$



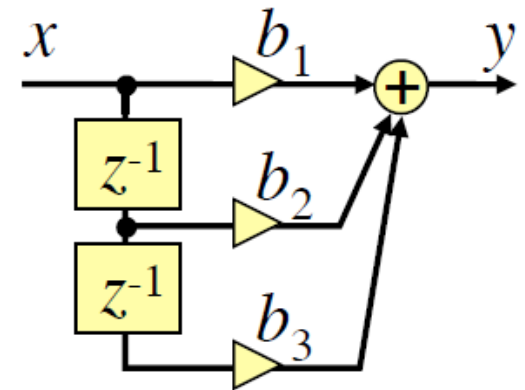
- Transpose

- reverse paths
- adders $\leftrightarrow$ nodes

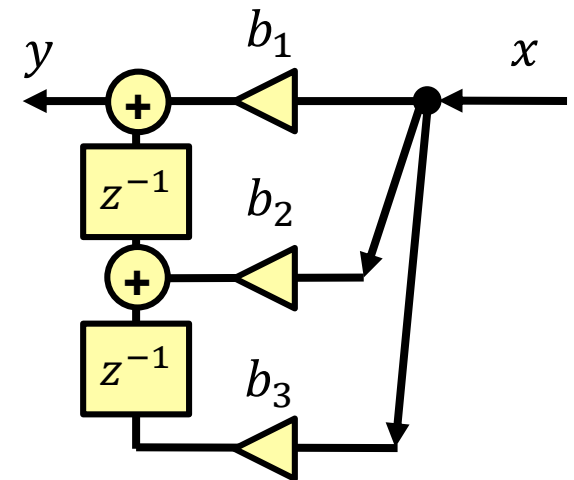


## ■ Transpose

- reverse paths
- adders  $\leftrightarrow$  nodes
- input  $\leftrightarrow$  output



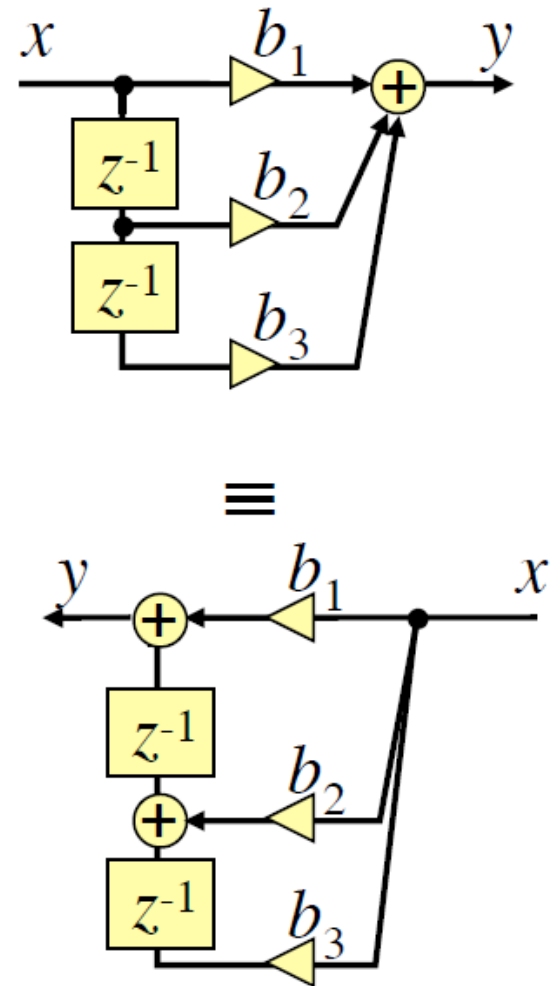
$\equiv$



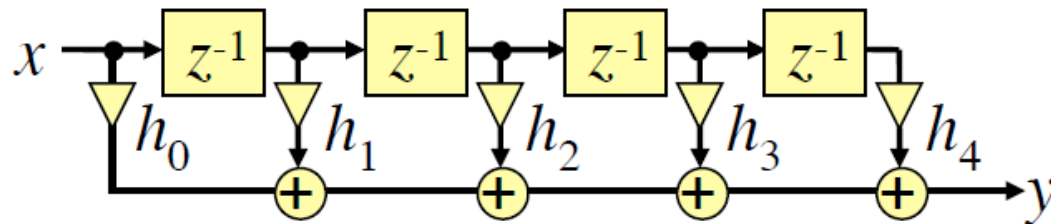
## ■ Transpose

- reverse paths
- adders  $\leftrightarrow$  nodes
- input  $\leftrightarrow$  output

$$\begin{aligned} Y &= b_1 X + b_2 z^{-1} X + b_3 z^{-2} X \\ &= b_1 X + z^{-1} (b_2 X + z^{-1} b_3 X) \end{aligned}$$



## ■ Direct form “Tapped Delay Line”

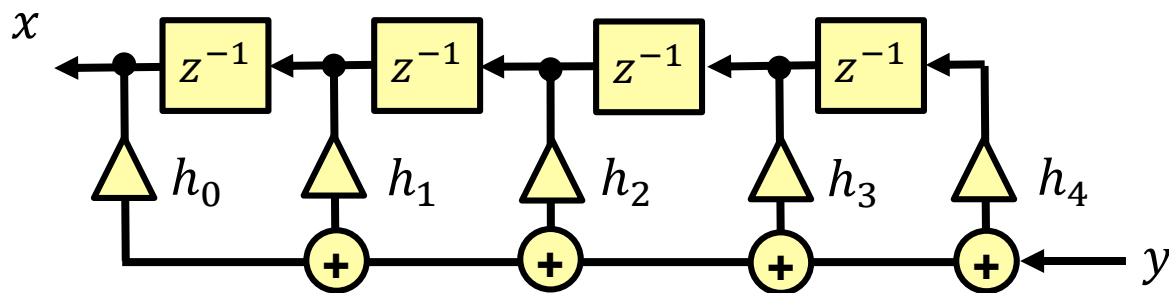


$$y[n] = h_0 x[n] + h_1 x[n-1] + \dots$$

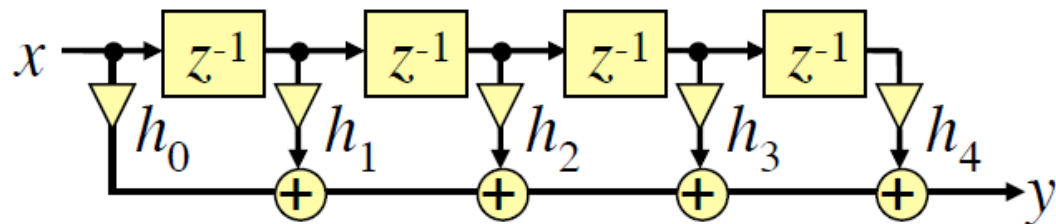
$$= \sum_{k=0}^4 h_k x[n-k]$$

## ■ Transpose

- reverse paths



## ■ Direct form “Tapped Delay Line”

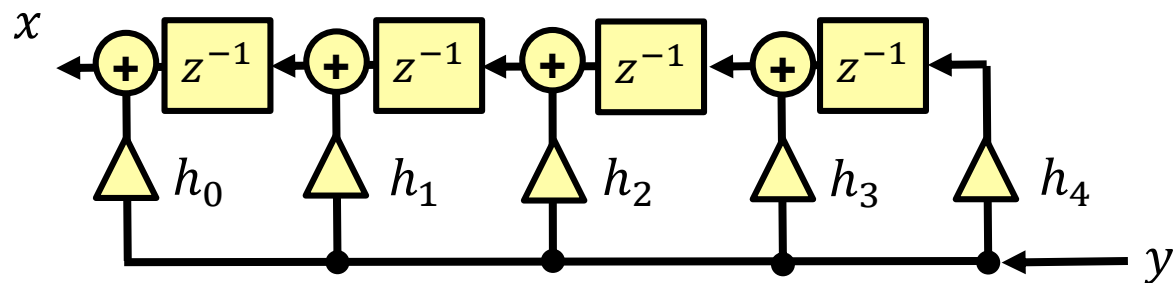


$$y[n] = h_0 x[n] + h_1 x[n-1] + \dots$$

$$= \sum_{k=0}^4 h_k x[n-k]$$

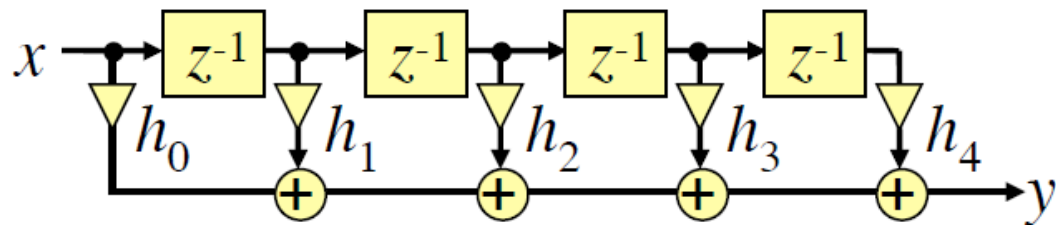
## ■ Transpose

- reverse paths
- adders  $\leftrightarrow$  nodes





## ■ Direct form “Tapped Delay Line”

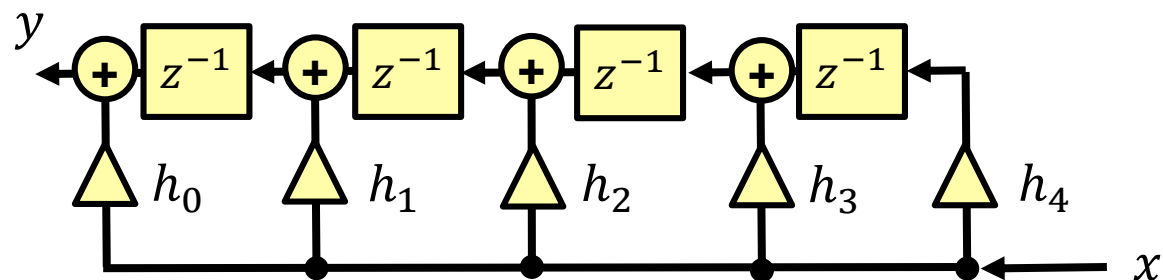


$$y[n] = h_0 x[n] + h_1 x[n-1] + \dots$$

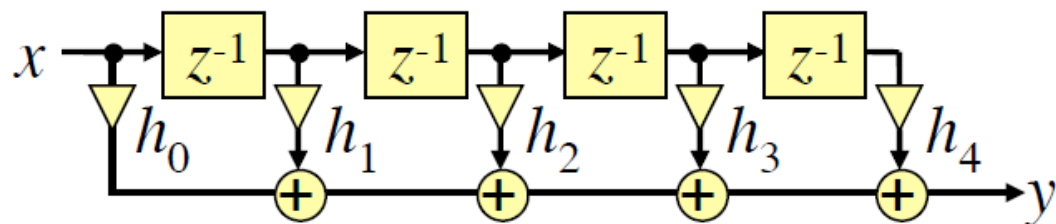
$$= \sum_{k=0}^4 h_k x[n-k]$$

## ■ Transpose

- reverse paths
- adders  $\leftrightarrow$  nodes
- input  $\leftrightarrow$  output



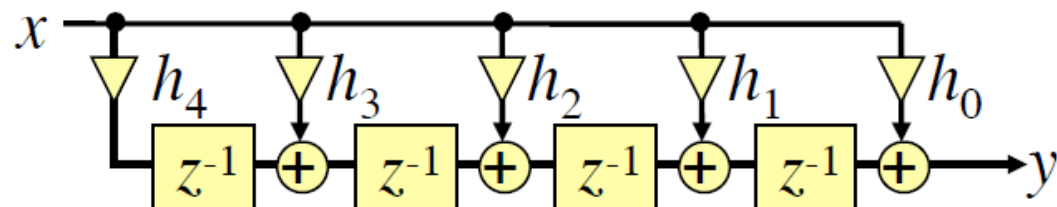
## ■ Direct form “Tapped Delay Line”



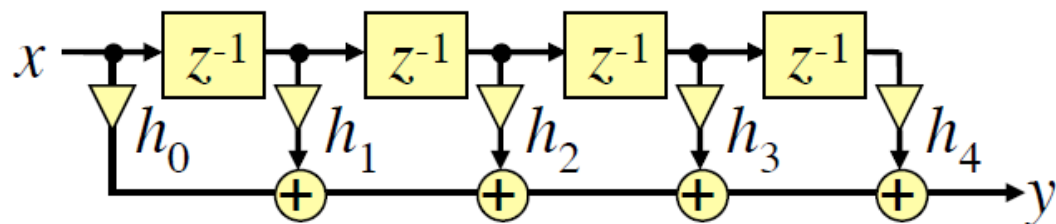
$$y[n] = h_0 x[n] + h_1 x[n-1] + \dots$$

$$= \sum_{k=0}^4 h_k x[n-k]$$

## ■ Transpose



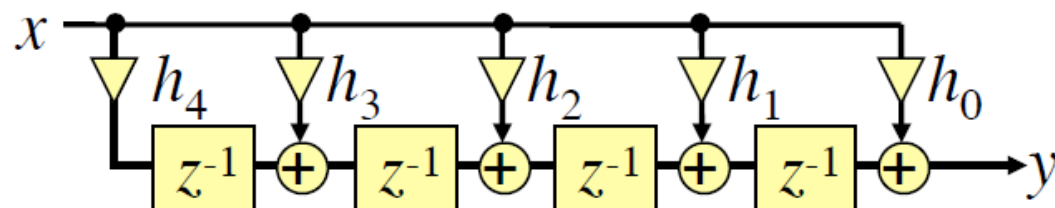
## ■ Direct form “Tapped Delay Line”



$$y[n] = h_0 x[n] + h_1 x[n-1] + \dots$$

$$= \sum_{k=0}^4 h_k x[n-k]$$

## ■ Transpose



$$y[5]$$

$$= h_0 x[5] + h_1 x[4] + h_2 x[3]$$

$$+ h_3 x[2] + h_4 x[1]$$

$h_4 x[1]$     $h_3 x[1]$     $h_2 x[1]$     $h_1 x[1]$     $h_0 x[1]$

$h_4 x[2]$     $h_3 x[2]$     $h_2 x[2]$     $h_1 x[2]$     $h_0 x[2]$

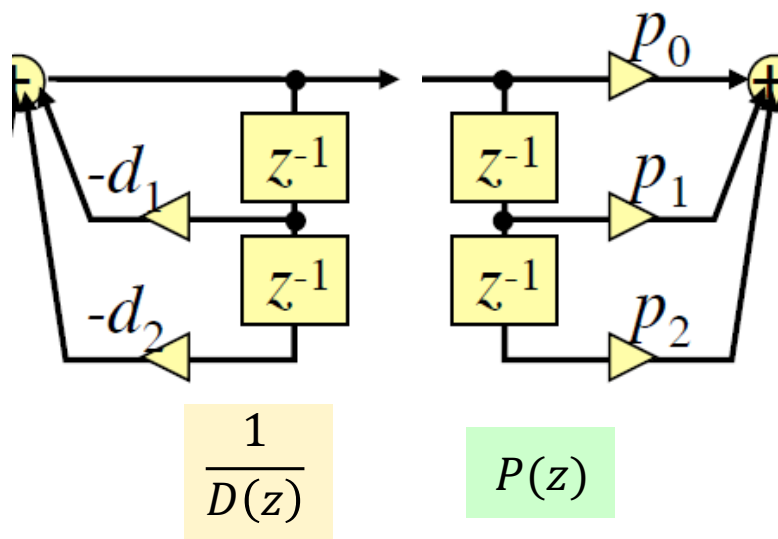
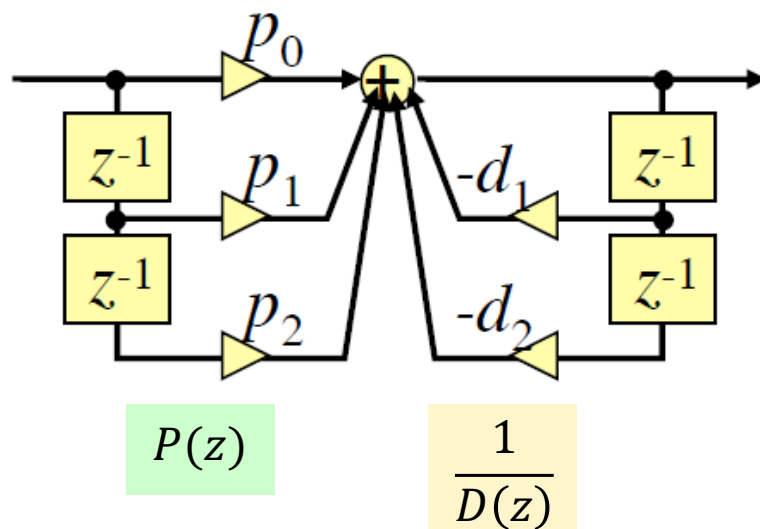
$h_4 x[3]$     $h_3 x[3]$     $h_2 x[3]$     $h_1 x[3]$     $h_0 x[3]$

$h_4 x[4]$     $h_3 x[4]$     $h_2 x[4]$     $h_1 x[4]$     $h_0 x[4]$

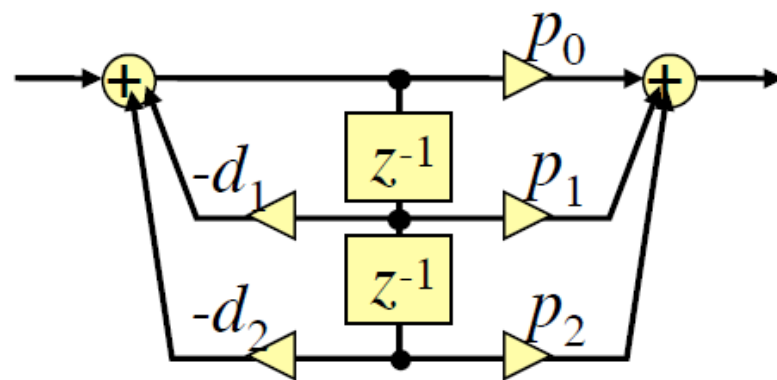
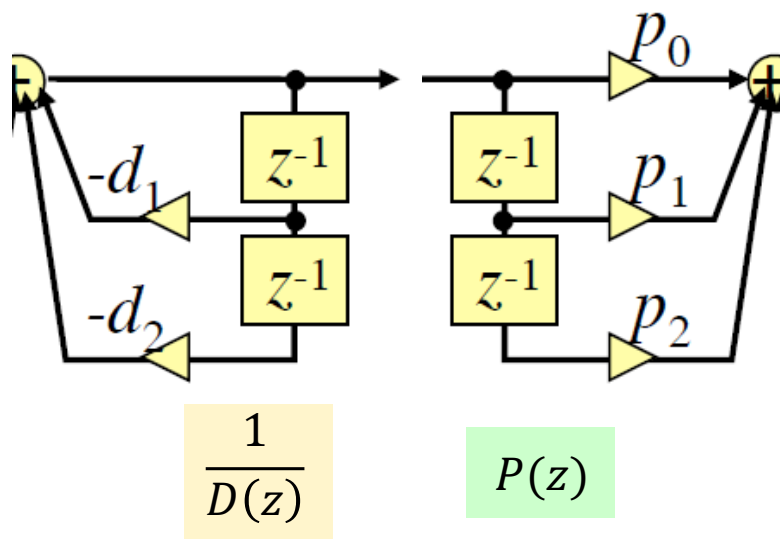
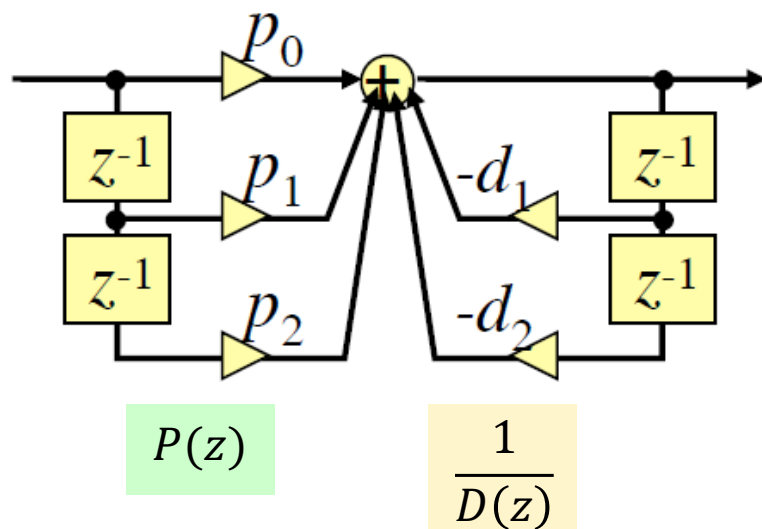
$h_4 x[5]$     $h_3 x[5]$     $h_2 x[5]$     $h_1 x[5]$     $h_0 x[5]$

$h_4 x[6]$     $h_3 x[6]$     $h_2 x[6]$     $h_1 x[6]$     $h_0 x[6]$

- Hence, Direct form I



- Hence, Direct form I



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01.1

$$0 \cdot 2^1 + 1 \cdot 2^0 + 1 \cdot 2^{-1} = 1.5$$

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01.1

$$0 \cdot 2^1 + 1 \cdot 2^0 + 1 \cdot 2^{-1} = 1.5$$

0.11

$$0 \cdot 2^0 + 1 \cdot 2^{-1} + 1 \cdot 2^{-2} = 0.75$$

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01.1

$$0 \cdot 2^1 + 1 \cdot 2^0 + 1 \cdot 2^{-1} = 1.5$$

0.11

$$0 \cdot 2^0 + 1 \cdot 2^{-1} + 1 \cdot 2^{-2} = 0.75$$

011.

$$0 \cdot 2^2 + 1 \cdot 2^1 + 1 \cdot 2^0 + 1 \cdot 2^{-1} = 3.5$$