

ICE503/IMPTE502/IICD524 DSP – Midterm

1. (10%) To determine the impulse response of an unknown causal, linear time-invariant (LTI) system, Kai applies the following input $x[n]$ to the system:

$$x[n] = 0, \text{ if } n < 0; \quad x[n] = 1, \text{ if } n \geq 0.$$

The corresponding output $y[n]$ is given as: $y[n] = 0$ for $n < 0$; $y[n] = 8, 12, 14, 15, 15.5$ for $n = 0, 1, 2, 3, 4$, respectively; $y[n] = 15.75$ for $n \geq 5$.

- (a) (5%) Find the impulse response of this system.
 - (b) (5%) Given any input $x[n]$, determine the input-output relationship for this system.
2. (35%) The block diagram of a causal LTI system is illustrated in Figure 1.

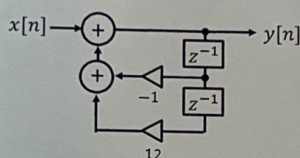


Figure 1: Block diagram of a causal LTI system.

- a) (5%) Derive the difference equation that characterizes the relationship between the input $x[n]$ and output $y[n]$.
 - b) (5%) Compute the Z -transform of the system, $H(z)$, and specify the Region of Convergence (ROC) for $H(z)$.
 - c) (5%) Sketch the poles and zeros of the system in the complex plane.
 - d) (5%) Determine whether the system is stable. Justify your answer.
 - e) (5%) Find the impulse response $h[n]$ of the system.
 - f) (10%) Given the system input $x[n] = \delta[n]$ and the initial conditions $y[-1] = -1$ and $y[-2] = -0.5$, compute the system's response $y[n]$ for $n \geq 0$.
3. (25%) Figure 2(a) shows the overall system for filtering a continuous-time signal using a discrete-time filter. The frequency responses of the reconstruction filter $H_r(j\Omega)$ and the discrete-time filter $H(e^{j\omega})$ are shown in Figure 2(b).
- a) (20%) For $X_c(j\Omega)$ as shown in Figure 2(d) and $1/T_1 = 10\text{kHz}$, sketch $X_p(j\Omega)$, $X(e^{j\omega})$, $Y(e^{j\omega})$, $Y_p(j\Omega)$, and $Y_r(j\Omega)$.
 - b) (5%) For a certain range of values of T_1 , the overall system, with input $x_c(t)$ and output $y_r(t)$, is equivalent to a continuous-time lowpass filter with frequency response $H_{\text{eff}}(j\Omega)$ sketched in Figure 2(e).
Determine the range of values of T_1 for which the information presented in (a) is true when $X_c(j\Omega)$ is bandlimited to $|\Omega| \leq 2\pi \times 5 \times 10^3$ as shown in Figure 2(d).

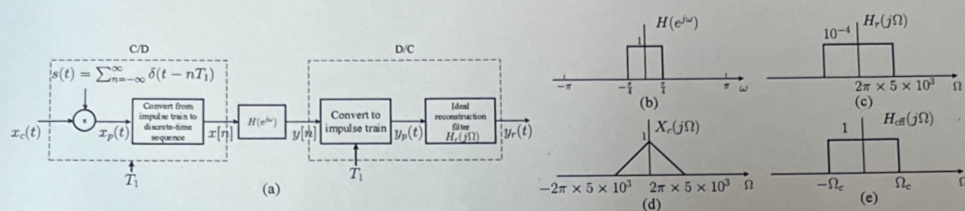


Figure 2: (a) A system. (b), (c), (d), (e) Frequency responses.

4. (15%) Figure 3(a) below illustrates two systems, System A and System B, each consisting of a compressor and an expander.

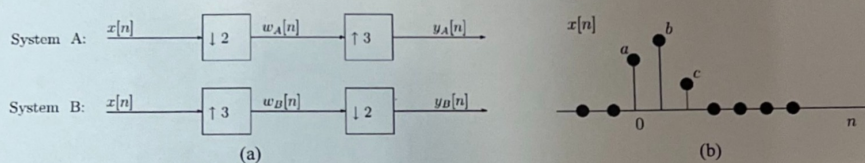


Figure 3: (a) System A and System B. (b) Sequence $x[n]$.

- (a) (5%) For the sequence $x[n]$ shown in Figure 3(b), sketch the output sequences $y_A[n]$ and $y_B[n]$, assuming that $x[n] = 0$ outside the interval shown.
- (b) (5%) Let $X(e^{j\omega})$ denote the Fourier transform of an arbitrary sequence $x[n]$. Derive and express $Y_B(e^{j\omega})$ in terms of $X(e^{j\omega})$. Your answer should be presented as an equation, not as a graph.
- (c) (5%) For any arbitrary $x[n]$, will $y_A[n] = y_B[n]$? If your answer is **yes**, provide an algebraic justification. If your answer is **no**, clearly explain or provide a counterexample.
5. (20%) Consider a finite length sequence
- $$x[n] = \begin{cases} 1, & n = 0, 1, \dots, N/2 - 1, \\ 0, & \text{otherwise.} \end{cases}$$
- a) (10%) Compute the DTFT and N -point DFT of $x[n]$.
- b) (10%) Sketch the magnitude of the DTFT and N -point DFT of $x[n]$ when $N = 8$.
6. (10%) Write a MATLAB function to reconstruct the continuous signal $x_a(t)$ from discrete-time signals $x[n]$. The format of the function should be function `[x_t] = D2A(x, T_s)`.

```
% Reconstruct the continuous signal from discrete-time signals
% [x_a] = D2A(x, T_s, t)
%
% x_a(t) = continuous signal at time t
% x[n] = discrete-time signals in vector
% T_s = sampling period
% t = time instance
```

$$(a) \chi[n] = \begin{cases} 0, & n < 0 \\ 1, & n \geq 0 \end{cases}$$

$$y[n] = \sum_{k=0}^n h[k]$$

$$y[0] = 8, y[1] = 12, y[2] = 14, y[3] = 15, y[4] = 15.5, y[5] = 15.75 \quad (n \geq 5)$$

$$\Rightarrow h[n] = y[n] - y[n-1]$$

$$h[0] = y[0] = 8$$

$$h[1] = y[1] - y[0] = 12 - 8 = 4$$

$$h[2] = y[2] - y[1] = 14 - 12 = 2$$

$$h[3] = y[3] - y[2] = 15 - 14 = 1$$

$$h[4] = y[4] - y[3] = 15.5 - 15 = 0.5$$

$$h[5] = y[5] - y[4] = 15.75 - 15.5 = 0.25$$

$$\text{when } n \geq 6, h[n] = y[n] - y[n-1] = 0$$

$$\Rightarrow h[n] = \begin{cases} 8, & n=0 \\ 4, & n=1 \\ 2, & n=2 \\ 1, & n=3 \\ 0.5, & n=4 \\ 0.25, & n=5 \\ 0, & n \geq 6 \end{cases} = 8\delta[n] + 4\delta[n-1] + 2\delta[n-2] + \delta[n-3] + 0.5\delta[n-4] + 0.25\delta[n-5] \quad \#$$

$$(b) y[n] = \chi[n] * h[n] = \sum_{k=0}^n \chi[k] h[n-k]$$

$$y[0] = \chi[0] h[0] = 8\chi[0]$$

$$y[1] = \chi[0] h[1] + \chi[1] h[0] = 4\chi[0] + 8\chi[1]$$

$$y[2] = 2\chi[0] + 4\chi[1] + 8\chi[2]$$

...

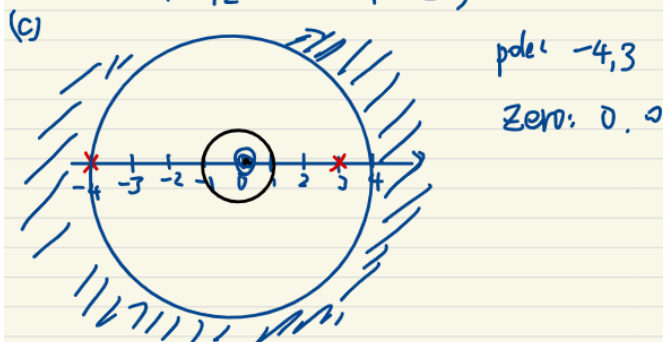
$$y[5] = 0.25\chi[0] + 0.5\chi[1] + \chi[2] + 2\chi[3] + 4\chi[4] + 8\chi[5]$$

$$\Rightarrow \begin{bmatrix} y[0] \\ y[1] \\ y[2] \\ y[3] \\ y[4] \\ y[5] \end{bmatrix} = \begin{bmatrix} 8 & 0 & 0 & 0 & 0 & 0 \\ 4 & 8 & 0 & 0 & 0 & 0 \\ 2 & 4 & 8 & 0 & 0 & 0 \\ 1 & 2 & 4 & 8 & 0 & 0 \\ 0.5 & 1 & 2 & 4 & 8 & 0 \\ 0.25 & 0.5 & 1 & 2 & 4 & 8 \end{bmatrix} \begin{bmatrix} \chi[0] \\ \chi[1] \\ \chi[2] \\ \chi[3] \\ \chi[4] \\ \chi[5] \end{bmatrix} \quad \#$$

2.

(a) $y[n] = x[n] - y[n-1] + 12y[n-2]$
 $\Rightarrow y[n] + y[n-1] - 12y[n-2] = x[n]$

(b) Z.T. $Y(z)(1 + z^{-1} - 12z^{-2}) = X(z)$
 $H(z) = \frac{Y(z)}{X(z)} = \frac{1}{1 + z^{-1} - 12z^{-2}} = \frac{1}{(1+4z^{-1})(1-3z^{-1})}$
 $= \frac{4}{7} \frac{1}{1+4z^{-1}} + \frac{3}{7} \frac{1}{1-3z^{-1}}, \text{ ROC: } |z| > 4 \text{ (causal)}$



(d) The system is not stable, because the ROC didn't cover unit circle.

(e) $H(z) \xrightarrow{\text{Z.T.}} h[n] = \frac{4}{7}(-4)^n u[n] + \frac{3}{7}(3)^n u[n]$

(f) $y[n] = y_p[n] + y_c[n]$

for complementary solution, $y[n] = \lambda^n, X[n] = 0$

$\lambda^n + \lambda^{n-1} - 12\lambda^{n-2} = 0, \lambda = -4, 3 \Rightarrow y_c[n] = \alpha_1(-4)^n + \alpha_2(3)^n$

for particular solution $y[n] = \beta, X[n] = 1$
 $\beta + \beta - 12\beta = 0, \beta = 0$

for $n=0, y[0] + y[-1] - 12y[-2] = x[0]$
 $= x[0]$

$\alpha_1 + \alpha_2 - 12(-0.5) = 1$
 $\alpha_1 + \alpha_2 = -4 - 6$

for $n=1, y[1] + y[0] - 12y[-1] = x[1]$
 $-3\alpha_1 + 4\alpha_2 = -12 - 6$

$\Rightarrow \alpha_2 = -\frac{24}{7}, \alpha_1 = -\frac{4}{7}$

$y[n] = -\frac{4}{7}(-4)^n + (-\frac{24}{7})(3)^n, n \geq 0$

3. (25%) Figure 2(a) shows the overall system for filtering a continuous-time signal using a discrete-time filter. The frequency responses of the reconstruction filter $H_r(j\Omega)$ and the discrete-time filter $H(e^{j\omega})$ are shown in Figure 2(b).

a) (20%) For $X_c(j\Omega)$ as shown in Figure 2(d) and $1/T_1 = 10\text{kHz}$, sketch $X_p(j\Omega)$, $X(e^{j\omega})$, $Y(e^{j\omega})$, $Y_p(j\Omega)$, and $Y_r(j\Omega)$.

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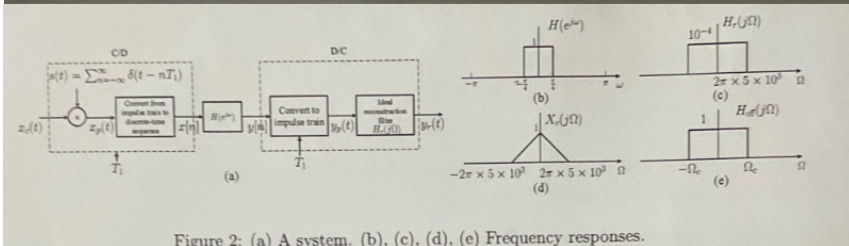
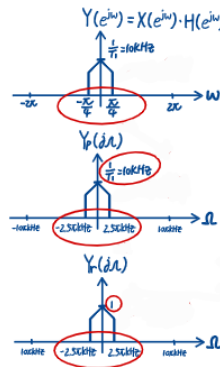
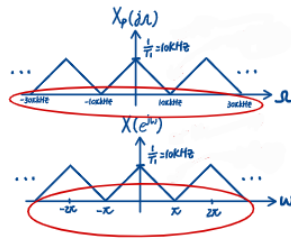
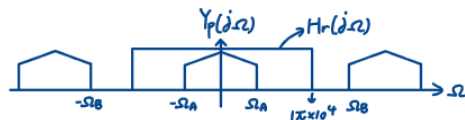


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3. (a) $\frac{1}{T_1} = 10\text{kHz}$, $\Omega \cdot T = \omega = 2\pi \rightarrow \frac{2\pi}{T_1} = 20\pi\text{kHz}$



(b) Find the range of T_1 , $\Omega T_1 = \omega$



$$\begin{cases} \Omega_A = \frac{\pi}{T_1} \\ \Omega_B = \frac{2\pi}{T_1} - \Omega_A = \frac{\pi}{T_1} \end{cases} \text{ where } \Omega_A < 1\pi \times 10^4 < \Omega_B$$

$$\rightarrow \frac{1}{4 \times 10^4} < T_1 < \frac{2}{4 \times 10^4}$$

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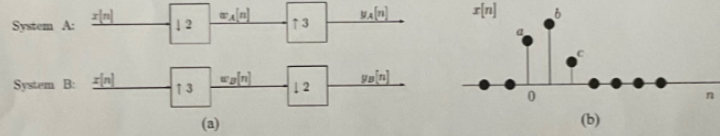
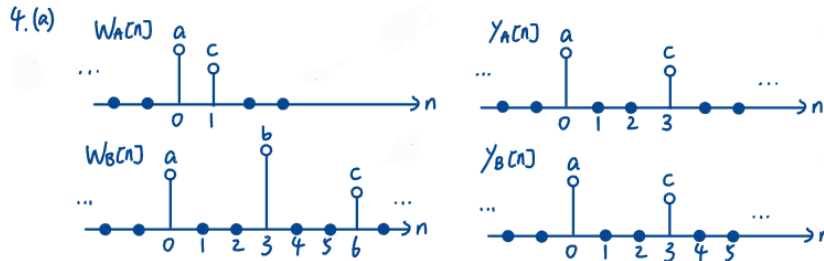


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- (c) (5%) For any arbitrary $x[n]$, will $y_A[n] = y_B[n]$? If your answer is **yes**, provide an algebraic justification. If your answer is **no**, clearly explain or provide a counterexample.



(b)

$$W_B(e^{j\omega}) = X_B(e^{j3\omega})$$

$$\rightarrow Y_B(e^{j\omega}) = \frac{1}{2} W_B(e^{j\frac{\omega}{2}} + e^{j(\frac{\omega}{2} - \pi)})$$

$$\Rightarrow Y_B(e^{j\omega}) = \frac{1}{2} X_B(e^{j\frac{\omega}{2}} + e^{j(\frac{\omega}{2} - \pi)})$$

(c)

$$W_A(e^{j\omega}) = \frac{1}{2} X_A(e^{j\frac{\omega}{2}} + e^{j(\frac{\omega}{2} - \pi)})$$

$$\rightarrow Y_A(e^{j\omega}) = W_A(e^{j3\omega})$$

$$\Rightarrow Y_A(e^{j\omega}) = \frac{1}{2} X_A(e^{j\frac{\omega}{2}} + e^{j(\frac{\omega}{2} - \pi)})$$

Yes, by the above $Y_A(e^{j\omega}) = Y_B(e^{j\omega})$

$$\therefore Y_A[n] = Y_B[n]$$

5.
(a)

$$\text{DTFT: } X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} = \sum_{n=0}^{N-1} e^{-j\omega n}$$

$$= \frac{1 - e^{-j\omega(\frac{N}{2})}}{1 - e^{-j\omega}}$$

$$N\text{-point DFT: } X[k] = \sum_{n=0}^{N-1} x[n] W_N^{kn} = \sum_{n=0}^{N-1} W_N^{kn}$$

$$= \frac{1 - e^{-j\frac{2\pi}{N}k(\frac{N}{2})}}{1 - e^{-j\frac{2\pi}{N}k}}$$

$$= \frac{1 - e^{-j\pi k}}{1 - e^{-j\frac{2\pi}{N}k}}$$

$$= \begin{cases} \frac{N}{2}, & k=0 \\ \frac{2}{1 - e^{-j\frac{2\pi}{N}k}}, & k=\text{odd} \\ 0, & k=\text{even} \end{cases}$$

$\omega = \frac{2\pi k}{N}$

(b) When $N=8$, $x[n] = [1, 1, 1, 1, 0, 0, 0, 0]$

$$X[k] = \sum_{n=0}^3 W_8^{kn}$$

$$X[0] = \sum_{n=0}^3 W_8^0 = 1 + 1 + 1 + 1 = 4$$

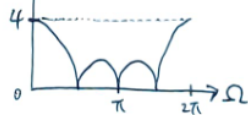
$$X[1] = \sum_{n=0}^3 W_8^1 = 1 + e^{-j\frac{\pi}{4}} + e^{-j\frac{\pi}{2}} + e^{-j\frac{3\pi}{4}} = 1 + \left(\frac{\sqrt{2}}{2} - j\frac{\sqrt{2}}{2}\right) + (-j) + \left(-\frac{\sqrt{2}}{2} - j\frac{\sqrt{2}}{2}\right) = 1 - j(1 + \sqrt{2})$$

$$X[2] = \sum_{n=0}^3 W_8^2 = 1 + e^{-j\frac{\pi}{2}} + e^{-j\pi} + e^{-j\frac{3\pi}{2}} = 1 - j - 1 + j = 0$$

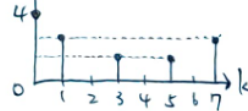
$$X[3] = \sum_{n=0}^3 W_8^3 = 1 + e^{-j\frac{3\pi}{4}} + e^{-j\frac{3\pi}{2}} + e^{-j\frac{9\pi}{4}} = 1 + \left(-\frac{\sqrt{2}}{2} - j\frac{\sqrt{2}}{2}\right) + j + \left(\frac{\sqrt{2}}{2} - j\frac{\sqrt{2}}{2}\right) = 1 + j(1 - \sqrt{2})$$

$$X[4] = \sum_{n=0}^3 W_8^4 = 1 + e^{-j\pi} + e^{-j2\pi} + e^{-j3\pi} = 1 - 1 + 1 - 1 = 0$$

DTFT: $|x(\omega)|$



8-point DFT: $|X[k]|$



6.

$$\text{rate} = T/t;$$

$$m = 0 : 1/t : 1/T;$$

for $i = 1 : \text{length}(X[n])$

$$y_c(i, :) = X[n](i) * \text{sinc}((1-i+1) * 1/t + m);$$

end

$$X_a = \text{sum}(y_c);$$