

$$X = UDV^T, \quad U = [u_1 \dots u_p], \quad D = \text{diag}(d_1 \dots d_p)$$

$n \times p$                        $n \times p$                        $p \times p$

$$V = [v_1 \dots v_p]$$

$p \times p$

$$Z = \tilde{U} \tilde{D}. \quad \tilde{U} = [u_1 \dots u_r], \quad \tilde{D} = \text{diag}(d_1 \dots d_r), \quad r < p.$$

목표:  $Z = \tilde{U} \tilde{D} = X \tilde{V}, \quad \tilde{V} = [v_1 \dots v_r]$

(증명)  $X \tilde{V} = UDV^T \tilde{V} = UD \begin{bmatrix} v_1^T \\ \vdots \\ v_r^T \\ \vdots \\ v_p^T \end{bmatrix} [v_1 \dots v_r]$

$$= UD \begin{bmatrix} v_1^T v_1 & \dots & v_1^T v_r \\ \vdots & & \vdots \\ v_r^T v_1 & \dots & v_r^T v_r \\ \vdots & & \vdots \\ v_p^T v_1 & \dots & v_p^T v_r \end{bmatrix} = UD \begin{bmatrix} I_{r \times r} \\ 0 \end{bmatrix}$$

$$= U \begin{bmatrix} D_1 & D_2 \end{bmatrix} \begin{bmatrix} I_{r \times r} \\ 0 \end{bmatrix} = U D_1 = U \begin{bmatrix} d_1 & \dots \\ \vdots & \ddots & \vdots \\ \vdots & \vdots & d_r \\ \vdots & \vdots & \vdots & 0 \end{bmatrix}$$

$$= U \begin{bmatrix} \tilde{D} \\ 0 \end{bmatrix} = [\tilde{U} \quad ?] \begin{bmatrix} \tilde{D} \\ 0 \end{bmatrix} = \tilde{U} \tilde{D}$$