CPE301 - SPRING 2019

Design Assignment DA5

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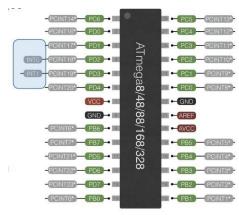
Primary Github address: https://github.com/guerrj1/Submission_DA.git
Directory: DA5 - https://github.com/guerrj1/Submission_DA/tree/master/DA5

Submit the following for all Labs:

- 1. In the document, for each task submit the modified or included code (only) with highlights and justifications of the modifications. Also, include the comments.
- 2. Use the previously create a Github repository with a random name (no CPE/301, Lastname, Firstname). Place all labs under the root folder ESD301/DA, sub-folder named LABXX, with one document and one video link file for each lab, place modified asm/c files named as LabXX-TYY.asm/c.
- 3. If multiple asm/c files or other libraries are used, create a folder LabXX-TYY and place these files inside the folder.
- 4. The folder should have a) Word document (see template), b) source code file(s) and other include files, c) text file with youtube video links (see template).

1. COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS

- -ATMega328p
- -Male to male wires
- -Male to female wires
- -Breadboard
- -NRF24L01 Module
- -FTDI Basic
- -LM34 Temperature Sensor



Atmega328P using PB0-PB5 for the ESP module. PC0 for input of LM34 sensor output.

2. DEVELOPED CODE OF TASK 1 C CODE

```
//DA5
#ifndef F CPU
#define F_CPU 16000000UL
#endif
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>
#include <stdbool.h>
#include <stdio.h>
#include <string.h>
       Set up UART for printf();
#ifndef BAUD
#define BAUD 9600
#endif
#include "libraries\STDIO_UART.c"
       Include nRF24L01+ library
#include "libraries\nrf24l01.c"
#include "libraries\nrf24l01-mnemonics.h"
#include "libraries\spi.c"
void print_config(void);
       Used in IRQ ISR
volatile bool message_received = false;
volatile bool status = false;
```

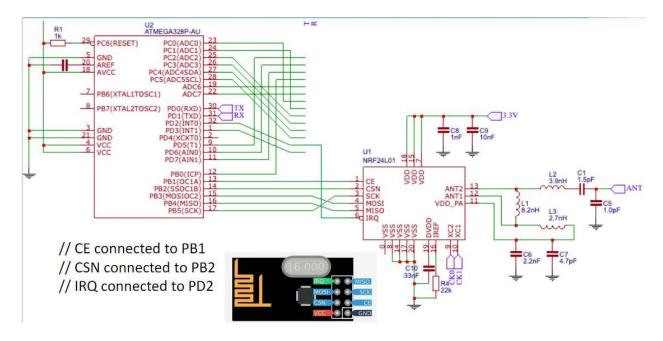
```
volatile uint8_t ADCvalue;
                                      //Global variable, set to volatile if used with ISR
volatile unsigned char ADCtemp[5];
int main(void)
              Set cliche message to send (message cannot exceed 32 characters)
       char tx_message[32];
                                                 // Define string array
       strcpy(tx_message,"Hello World!"); // Copy string into array
       //
              Initialize UART
       uart init();
              Initialize nRF24L01+ and print configuration info
       nrf24_init();
       print_config();
              Start listening to incoming messages
       nrf24_start_listening();
       nrf24_send_message(tx_message);
       adc_init();
       while (1)
              if (message_received)
              {
                            Message received, print it
                     message received = false;
                     printf("Received message: %s\n",nrf24_read_message());
                            Send message as response
                     _delay_ms(500);
                     status = nrf24 send message(ADCtemp);
                     if (status == true) printf("Message sent successfully\n");
              }
       }
}
       Interrupt on IRQ pin
ISR(INT0_vect)
{
       message_received = true;
}
void print config(void)
       uint8 t data;
       printf("Startup successful\n\n nRF24L01+ configured as:\n");
       printf("-----\n");
       nrf24_read(CONFIG,&data,1);
       printf("CONFIG
                            0x%x\n",data);
       nrf24_read(EN_AA,&data,1);
       printf("EN AA
                                   0x%x\n",data);
       nrf24_read(EN_RXADDR,&data,1);
       printf("EN RXADDR
                                   0x%x\n",data);
       nrf24 read(SETUP_RETR,&data,1);
       printf("SETUP RETR
                                   0x%x\n",data);
       nrf24_read(RF_CH,&data,1);
       printf("RF_CH
                                   0x%x\n",data);
       nrf24_read(RF_SETUP,&data,1);
```

```
printf("RF_SETUP
                                     0x%x\n",data);
       nrf24_read(STATUS,&data,1);
       printf("STATUS 0x%x\n",data);
       nrf24_read(FEATURE,&data,1);
       printf("FEATURE 0x%x\n",data);
       printf("-----\n\n");
}
void adc_init(void)
       //ADC intializations
       ADMUX = 0;
                                //use ADC0
       ADMUX |= (1 << REFS0); //use AVcc as the reference
       ADMUX |= (1 << ADLAR); //Right adjust for 8 bit resolution
       ADCSRA |= (1 << ADATE); //Set ADC Auto Trigger Enable
                                //0 for free running mode
       ADCSRB = 0;
       ADCSRA |= (1 << ADEN); //Enable the ADC
       ADCSRA |= (1 << ADIE); //Enable Interrupts

ADCSRA |= (1 << ADSC); //Start the ADC conversion

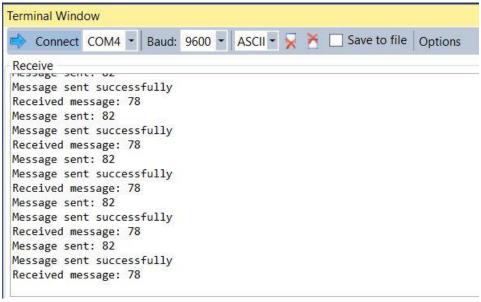
ADCSRA |= (1 << ADPS2) | (1 << ADPS1) | (1 << ADPS0); //set prescaler to 128
}
ISR(ADC_vect)
       volatile unsigned int j=0;
       char temp[5];
       ADCvalue = (ADCH<<1); //shifts ADCH by 1 to the left
       itoa(ADCvalue, temp, 10);
       while(j<5)</pre>
       {
               ADCtemp[j] = temp[j]; //set temp as ADCtemp
               j++; //increment the j temp
       }
}
```

3. SCHEMATIC



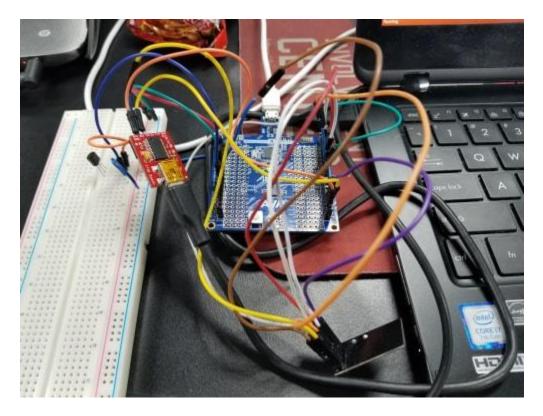
Atmega328P connection to the FTDI Basic and the NRF24L01 module.

4. SCREENSHOTS OF EACH TASK OUTPUT (ATMEL STUDIO OUTPUT)



Terminal window of the SPI communication with another source.

5. SCREENSHOT OF EACH DEMO (BOARD SETUP)



Board set up for the SPI configuration.

6. VIDEO LINKS OF EACH DEMO

https://youtu.be/O378Oeloj74

7. GITHUB LINK OF THIS DA

https://github.com/guerrj1/Submission_DA/tree/master/DA5

Student Academic Misconduct Policy

http://studentconduct.unlv.edu/misconduct/policy.html

"This assignment submission is my own, original work".

Jett Guerrero