



## Series 2. Braitenberg

Robotics, BSc Course, 2<sup>nd</sup> Sem., Prof. Béat Hirsbrunner, Simon Studer

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Handout on Thursday, 5 March 2015

Due on Tuesday, 10 March 2015, 22:00

### Reading

Study the lecture notes and [Bra 84], chap. 1-4 (pp 1-19), available at <http://diuf.unifr.ch/pai/rob> > Lectures.

### 1. Explorer and advanced lover

Implement the explore and advanced love behaviour as discussed in class. A playground and a .aesi template is available at <http://diuf.unifr.ch/pai/rob> > Exercises.

- a) Explain the chosen weights for the proximity formula.
- b) Explain the formulas you chose for the speed of the wheels.
- c) Record a short low quality video per group

Remark. If in your experiments you found other interesting sets of weights or speed formulas, please explain them also.

### 2. Proximity Sensors Values

Measure the values  $p$  of a proximity sensor for various values of  $d$ , where  $d$  is the distance between the sensor and an object. Choose  $d$  in the range of 1 to 10 cm. Try to guess a simple function satisfying  $p = f(d)$ . Explain in detail your experiment setup.

**Hand in.** Upload your answer to [diuf.unifr.ch/pai/rob](http://diuf.unifr.ch/pai/rob) > Upload by following the online recommendations.

### Reference

[Bra 84] Valentino Braitenberg: "Vehicules: Eperiments in Synthetic Psychology", MIT Press, 1984