## Final Exam Sample Questions

1.	The attack named MobilBye targets which type of sensor?
A.	Camera
B.	Lidar
C.	Radar
ANS:	
A	
2.	Can an ASIL-D system be composed of multiple ASIL-B subsystems?
A.	Yes
B.	No
AN	IS:
A	
3.	In PID control, which term(s) can be used to eliminate steady-state error?
A.	P
B.	I
C.	D
AN	IS:
В	
4.	True or False: twiddle() for PID controller tuning can be viewed as a form of
	Reinforcement Learning.
A.	True
B.	False
AN	IS:
A	
5.	Why does AlphaGo not use Tabular RL, such as tabular Q Learning or Sarsa?
ANS: the state space is too large.	
6.	What is the probability of selecting the greedy action (assuming there is only one) in state

s in epsilon-greedy action selection, if the total number of possible actions in state s is N?

ANS:  $1 - \epsilon + \frac{\epsilon}{N}$ 

- 7. What is an Episodic task?
- A. A task that has a limited number of actions and then ends.
- B. A task with memory

ANS: A

8. Convolutional Neural Networks (CNNs)

Input volume:  $56 \times 56 \times 64$  ( $W_1 = H_1 = N_1 = 56, D_1 = 64$ ).  $32.1 \times 1 \times 64$  filters (K = 32, F = 1)

w. stride S = 1, no pad P = 0. Show the formulas and calculation process.

- 1) Calculate the dimensions of the output volume, including spatial size and depth.
- 2) Calculate the total number of parameters, including weights and biases.

ANS:

Each activation map:

Spatial size: 
$$W_2 = H_2 = N_2 = \frac{1}{s}(N_1 + 2P - F) + 1 = \frac{1}{1}(56 - 1) + 1 = 56$$

Depth:  $D_2 = K = 32$ 

Output volume:  $56 \times 56 \times 32$ 

No. params: each filter has 1 \* 1 \* 64 + 1 = 65 params, so 32 filters add up to 65 \* 32 = 2080

params