

CSC 112: Computer Operating Systems

Lecture 3

Threads

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What's in a process?

- A process consists of:
 - an address space
 - the code for the running program
 - the data for the running program
 - at least one thread
 - » Registers, IP
 - » Floating point state
 - » Stack and stack pointer
 - a set of OS resources
 - » open files, network connections, sound channels, ...
- Today: decompose ...
 - threads of control
 - (other resources...)

Concurrency

- Imagine a web server that handles multiple requests concurrently
 - While waiting for the credit card server to approve a purchase for one client, it could be retrieving the data requested by another client from disk, and assembling the response for a third client from cached information
- Imagine a web client (browser), which might like to initiate multiple requests concurrently
- Imagine a parallel program running on a multiprocessor, which might like to employ “physical concurrency”
 - For example, multiplying a large matrix – split the output matrix into k regions and compute the entries in each region concurrently using k processors

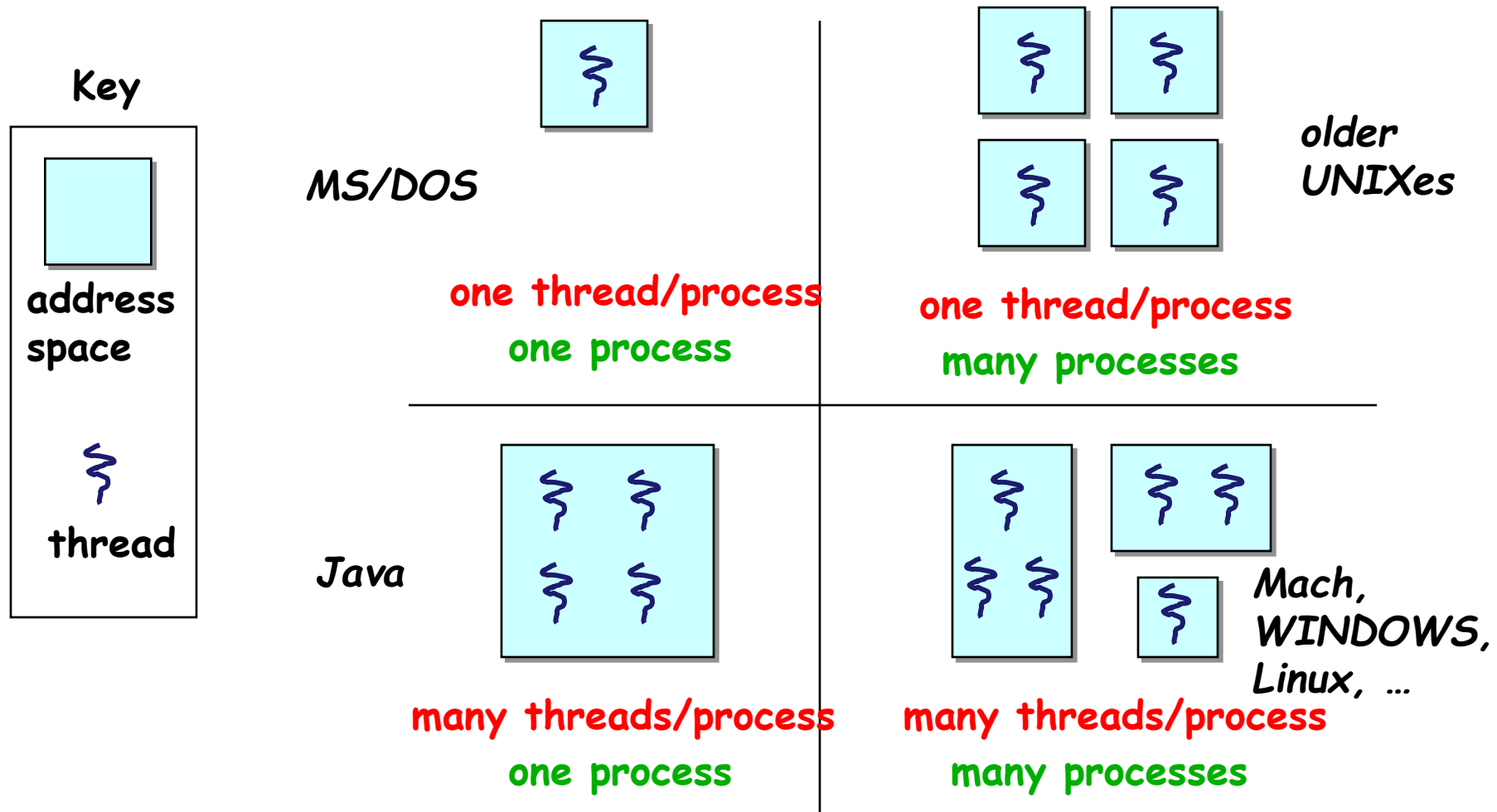
What's needed?

- In each of these examples of concurrency (web server, web client, parallel program):
 - Everybody wants to run the same code
 - Everybody wants to access the same data
 - Everybody has the same privileges
 - Everybody uses the same resources (open files, network connections, etc.)
- But you'd like to have multiple hardware execution states:
 - an execution stack and stack pointer (SP)
 - » traces state of procedure calls made
 - program counter (PC), indicating the next instruction
 - a set of general-purpose processor registers and their values
- Creating multiple processes is inefficient
- Key idea: separate the concept of a process (address space, etc.) from that of a minimal “thread of control” (execution state: PC, etc.)
- This execution state is usually called a **thread**, or sometimes, a **lightweight process**

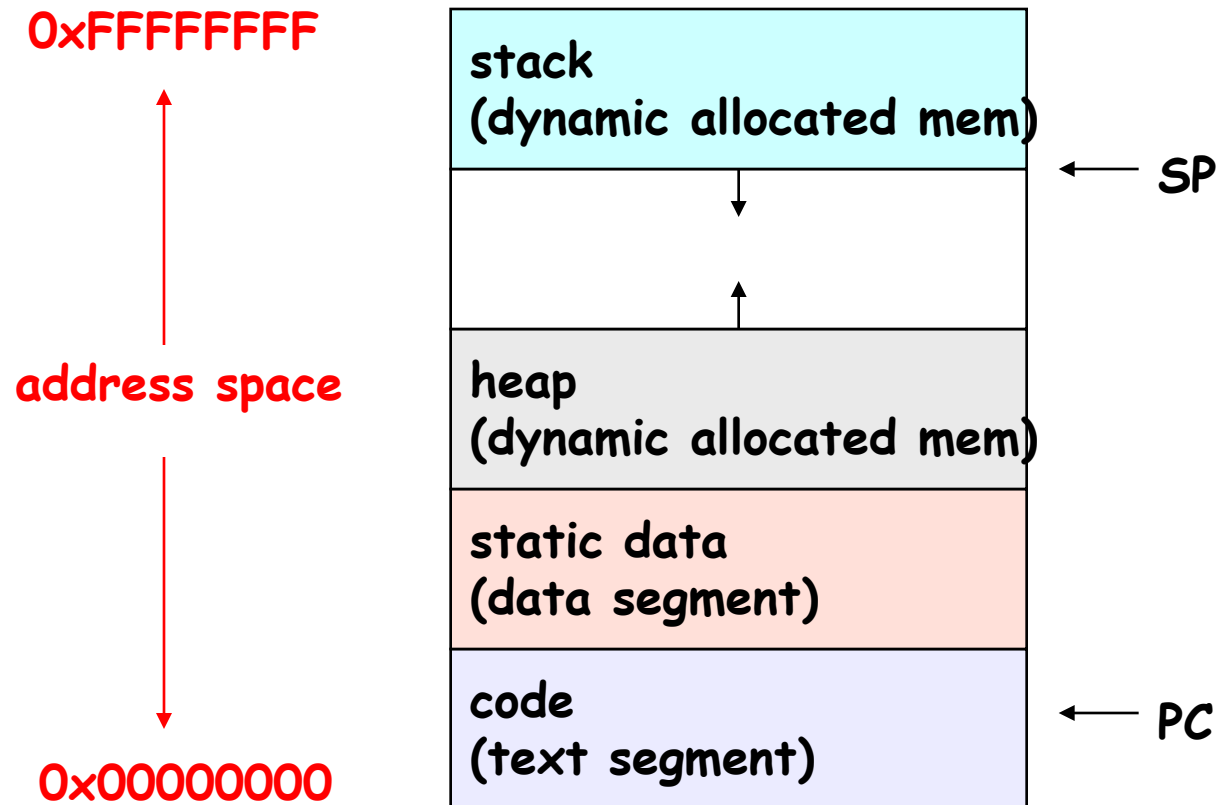
Processes and Threads

- Modern OSes support two entities:
 - the **process**, which defines the address space and general process attributes (such as open files, etc.)
 - the **thread**, which defines a sequential execution stream within a process
- A thread is bound to a single process / address space
 - address spaces, however, can have multiple threads executing within them
 - sharing data between threads is cheap: all see the same address space
 - creating threads is cheap too!
- Threads become the unit of scheduling
 - processes / address spaces are just **containers** in which threads execute

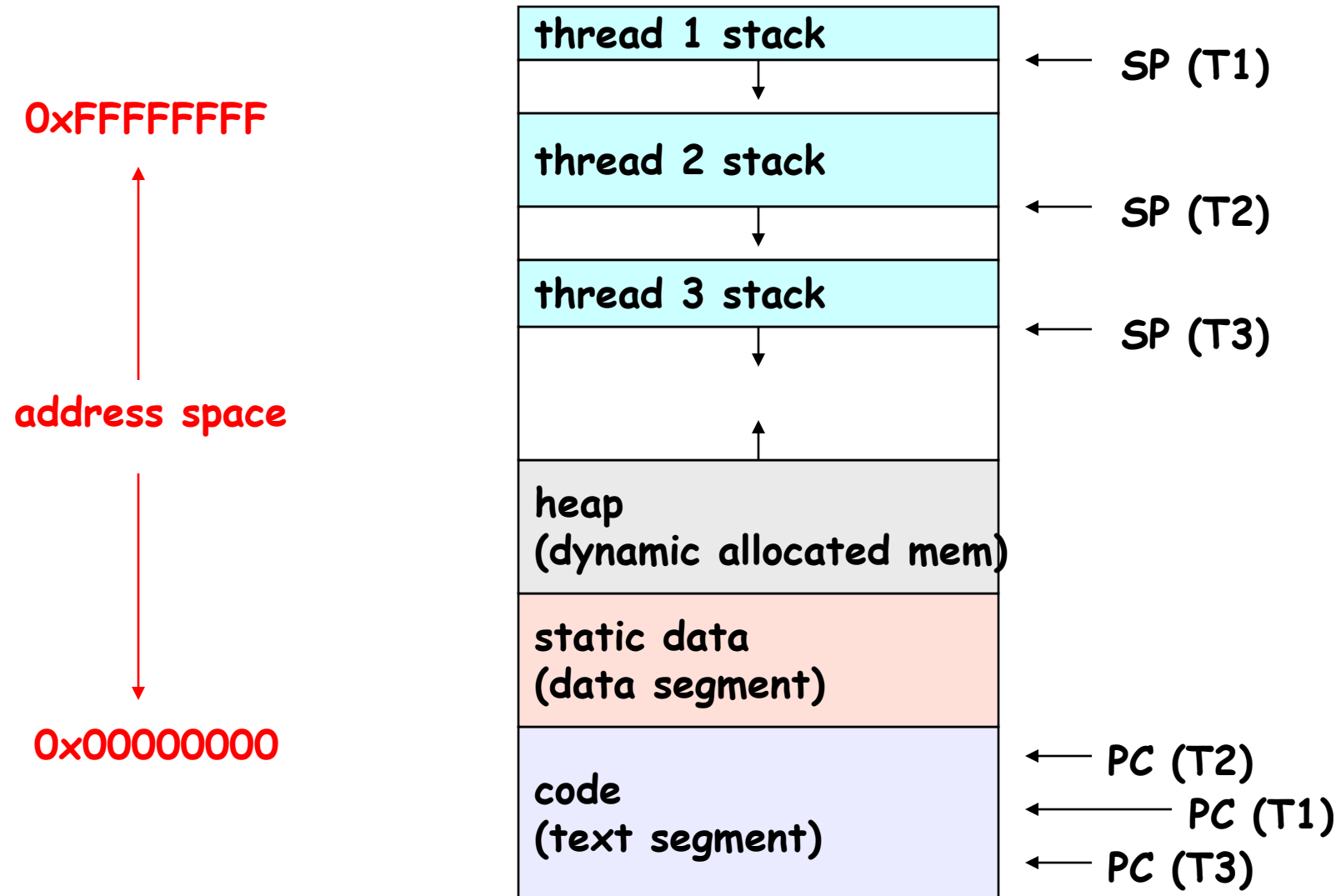
The design space



(old) Process address space



(new) Process address space with threads



Process/thread separation

- Concurrency (multithreading) is useful for:
 - handling concurrent events (e.g., web servers and clients)
 - building parallel programs (e.g., matrix multiply, ray tracing)
 - improving program structure (the Java argument)
- Multithreading is useful even on a uniprocessor
 - even though only one thread can run at a time
- Supporting multithreading – that is, separating the concept of a **process** (address space, files, etc.) from that of a minimal **thread of control** (execution state), is a big win
 - creating concurrency does not require creating new processes
 - “faster / better / cheaper”

“Where do threads come from?”

- The kernel is responsible for creating/managing threads
 - for example, the kernel call to create a new thread would
 - » allocate an execution stack within the process address space
 - » create and initialize a Thread Control Block
 - stack pointer, program counter, register values
 - » stick it on the ready queue
 - we call these **kernel threads**

“Where do threads come from?” (2)

- Threads can also be managed at the user level (that is, entirely from within the process)
 - a library linked into the program manages the threads
 - » because threads share the same address space, the thread manager doesn't need to manipulate address spaces (which only the kernel can do)
 - » threads differ (roughly) only in hardware contexts (PC, SP, registers), which can be manipulated by user-level code
 - » the Linux **thread package** multiplexes user-level threads on top of kernel thread(s), which it treats as “virtual processors”
 - we call these **user-level threads**

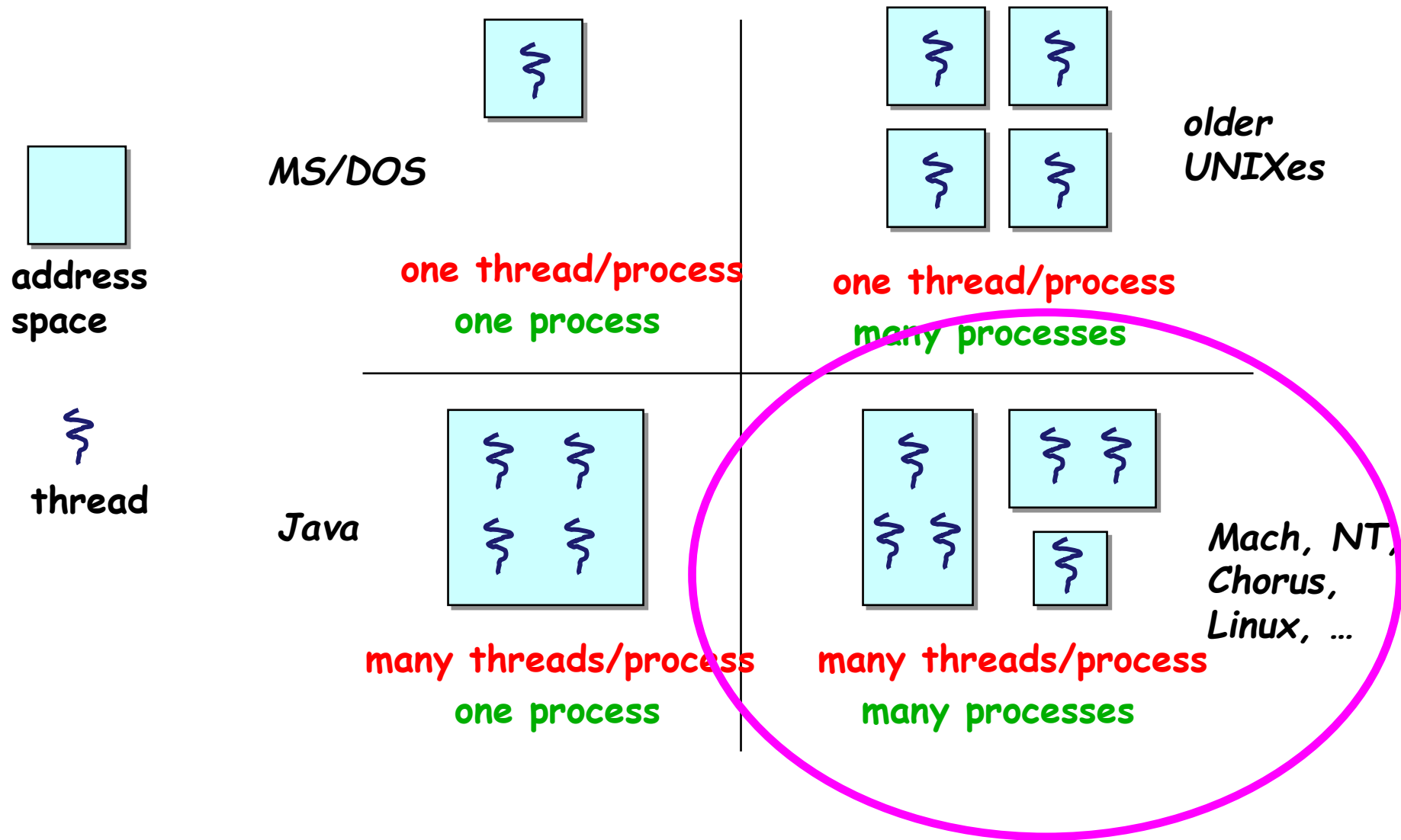
Kernel threads

- OS now manages threads *and* processes
 - all thread operations are implemented in the kernel
 - OS schedules all of the threads in a system
 - » if one thread in a process blocks (e.g., on I/O), the OS knows about it, and can run other threads from that process
 - » possible to overlap I/O and computation **inside** a process
- Kernel threads are cheaper than processes
 - less state to allocate and initialize
- But, they're still expensive for fine-grained use (e.g., orders of magnitude more expensive than a procedure call)
 - thread operations are all system calls
 - » context switch
 - » argument checks
 - must maintain kernel state for each thread

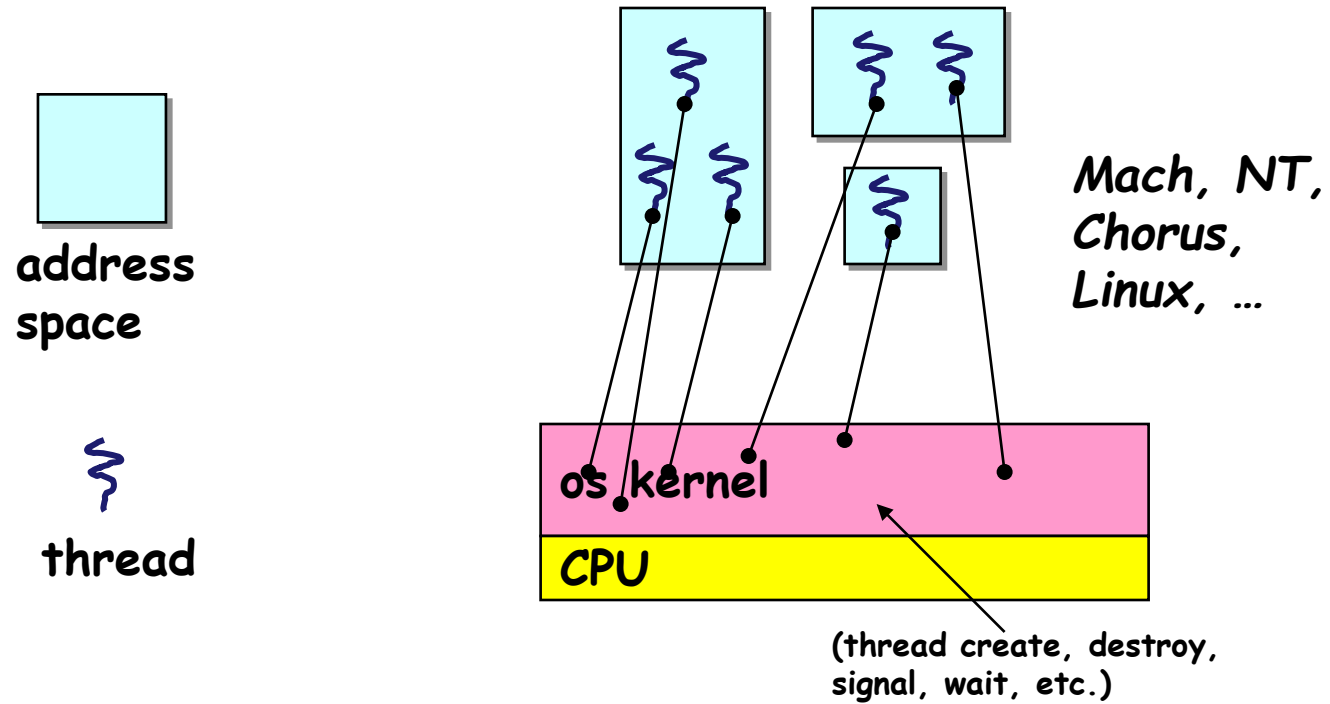
User-level threads

- To make threads cheap and fast, they may be implemented at the user level
 - managed entirely by user-level library, e.g., **libpthreads.a**
- User-level threads are small and fast
 - each thread is represented simply by a PC, registers, a stack, and a small **thread control block** (user-space TCB)
 - creating a thread, switching between threads, and synchronizing threads are done via procedure calls
 - » no kernel involvement is necessary!
 - user-level thread operations can be 10-100x faster than kernel threads as a result

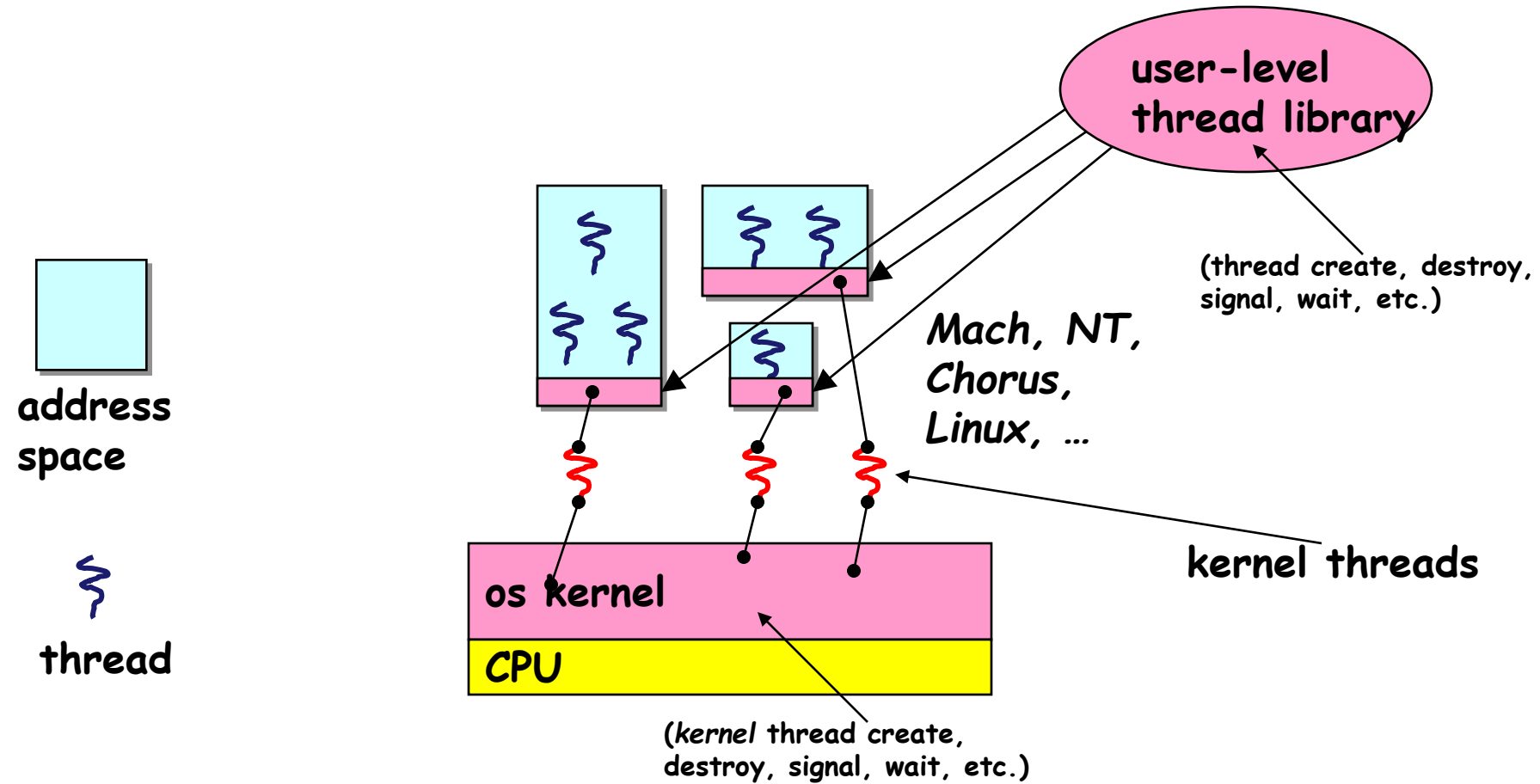
The design space



Kernel threads



User-level threads



User-level thread implementation

- The kernel believes the user-level process is just a normal process running code
 - But, this code includes the thread support library and its associated thread scheduler
- The thread scheduler determines when a thread runs
 - it uses queues to keep track of what threads are doing: run, ready, wait
 - » just like the OS and processes
 - » but, implemented at user-level as a library
- Example implementations of user-level threads
 - Fibers, co-routines

Thread interface

- The POSIX pthreads API:
 - `t = pthread_create(attributes, start_procedure)`
 - » creates a new thread of control
 - » new thread begins executing at `start_procedure`
 - `pthread_cond_wait(condition_variable)`
 - » the calling thread blocks, sometimes called `thread_block()`
 - `pthread_signal(condition_variable)`
 - » starts the thread waiting on the condition variable
 - `pthread_exit()`
 - » terminates the calling thread
 - `pthread_wait(t)`
 - » waits for the named thread to terminate

How to prevent a user-level thread from hogging the CPU?

- Strategy 1: force everyone to cooperate
 - a thread willingly gives up the CPU by calling **yield()**
 - **yield()** calls into the scheduler, which context switches to another ready thread
 - what happens if a thread never calls **yield()**?
- Strategy 2: use preemption
 - scheduler requests that a timer interrupt be delivered by the OS periodically
 - » usually delivered as a UNIX signal (`man signal`)
 - » signals are just like software interrupts, but delivered to user-level by the OS instead of delivered to OS by hardware
 - at each timer interrupt, scheduler gains control and context switches as appropriate

Thread context switch

- Very simple for user-level threads:
 - save context of currently running thread
 - » push machine state onto thread stack
 - restore context of the next thread
 - » pop machine state from next thread's stack
 - return as the new thread
 - » execution resumes at PC of next thread
- This is all done by assembly language
 - it works at the level of the procedure calling convention
 - » thus, it cannot be implemented using procedure calls
 - » e.g., a thread might be preempted (and then resumed) in the middle of a procedure call

What if a thread tries to do I/O?

- The kernel thread is lost for the duration of the (synchronous) I/O operation!
- Could have one kernel thread for each user-level thread
 - no real difference from kernel threads – “common case” operations (e.g., synchronization) would be quick
- Could have a limited-size “pool” of kernel threads “powering” all the user-level threads in the address space
 - the kernel will be scheduling these threads, oblivious to what’s going on at user-level

Summary

- We want multiple threads per address space
- Kernel threads are much more efficient than processes, but they're still not cheap
 - all operations require a kernel call and parameter verification
- User-level threads are:
 - fast
 - great for common-case operations
 - » creation, synchronization, destruction
 - can suffer in uncommon cases due to kernel obliviousness
 - » I/O
 - » preemption of a lock-holder