CSC 112: Computer Operating Systems Lecture 2

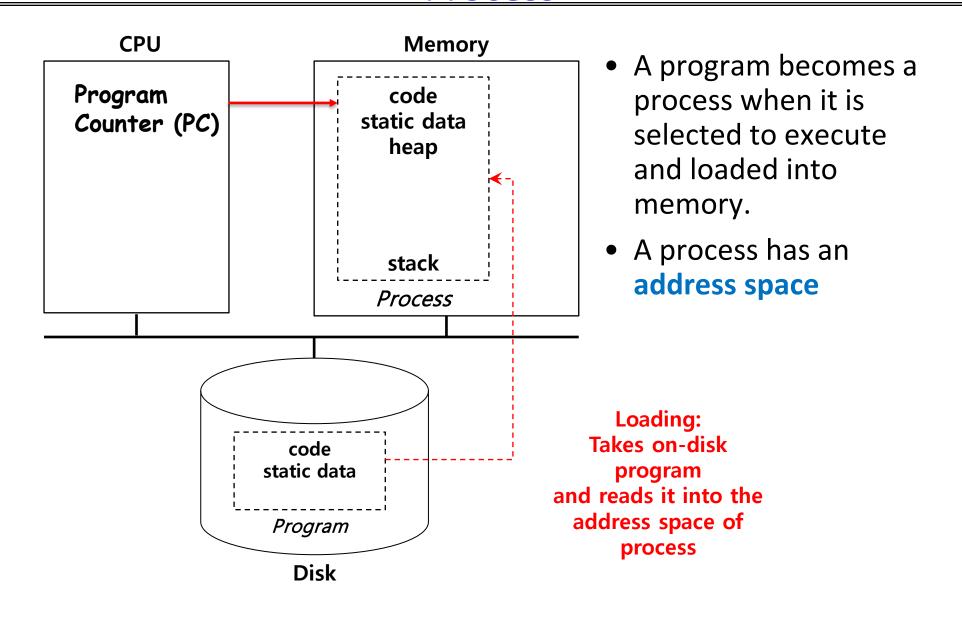
Processes

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Overview

- Process concept
- Process state
- Process API (creation, wait)
- Process tree

- Program is a static entity stored on disk (executable file), process is active
 - Program becomes process when executable file loaded into memory
 - Process is an abstraction of CPU
- Execution of program started via Graphic User Interface (GUI) mouse clicks, command line entry of its name, etc
- A physical CPU is shared by many processes
 - Time sharing: run one process for a little while, then run another one, and so forth.
 - Processes believe they are using CPU alone



Process: a running program

MAX

0

• Consists of:

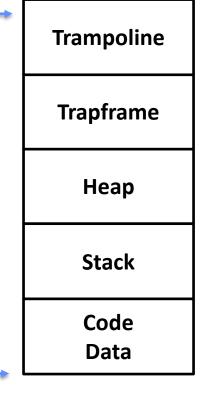
Code: Instructions

 Stack: Temporary data, e.g., function parameters, returned addresses, local variables

 Registers: Program counter (PC), general purpose, stack pointer

Data: Global variables

Heap: Dynamically allocated



XV6 Address Space

```
struct proc {
         struct spinlock lock; // p->lock must be held when using these: •
         enum procstate state; // Process state
         void *chan; // If non-zero, sleeping on chan
         int killed; // If non-zero, have been killed
         int xstate; // Exit status to be returned to parent's wait
         int pid; // Process ID
         // wait_lock must be held when using this:
         struct proc *parent; // Parent process
         // these are private to the process, so p->lock need not be
held.
         uint64 kstack: // Virtual address of kernel stack
         uint64 sz; // Size of process memory (bytes)
         pagetable_t pagetable; // User page table
         struct trapframe *trapframe; // data page for trampoline.5
         struct context; // swtch() here to run process
         struct file *ofile[NOFILE]; // Open files
         struct inode *cwd; // Current directory
         char name[16]; // Process name (debugging)
};
                         XV6 (proc.h)
```

- A process is represented by a process control block (PCB)
 - Process ID (PID, unique)
 - State
 - Parent process
 - Opened files
 - etc.

Process State

Process has different states

- READY

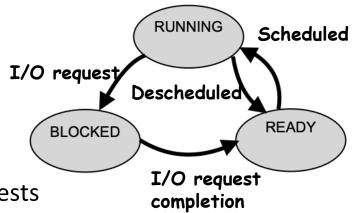
» Ready to run and pending for running

- RUNNING

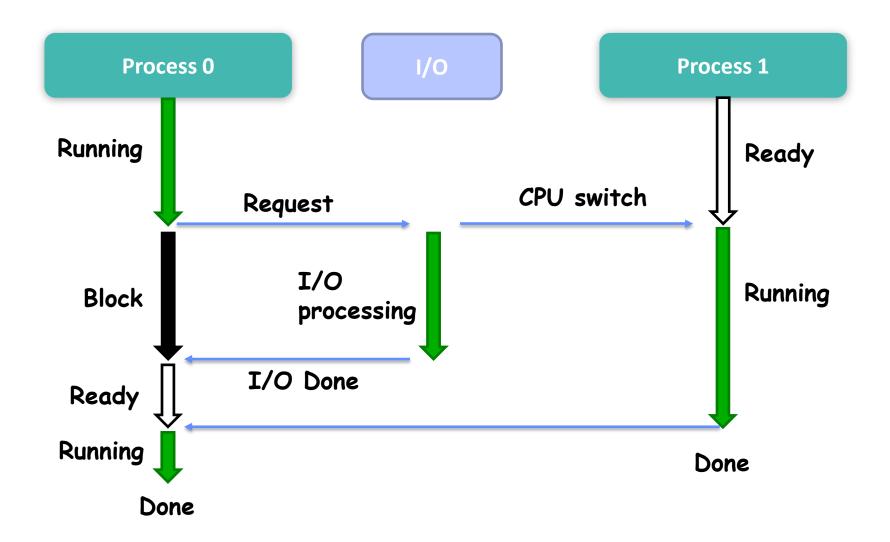
» Being executed by OS

- BLOCKED

» Suspended due to some other events, e.g., I/O requests



Process State



Process API

Process API to manipulate processes

- CREATE

» Create a new process, e.g., double click, a command in terminal

- WAIT

- » Wait for a process to stop
- » Like I/O request

- **DESTROY**

» Kill the processes

- STATUS

» Obtain the information of a process

- OTHERS

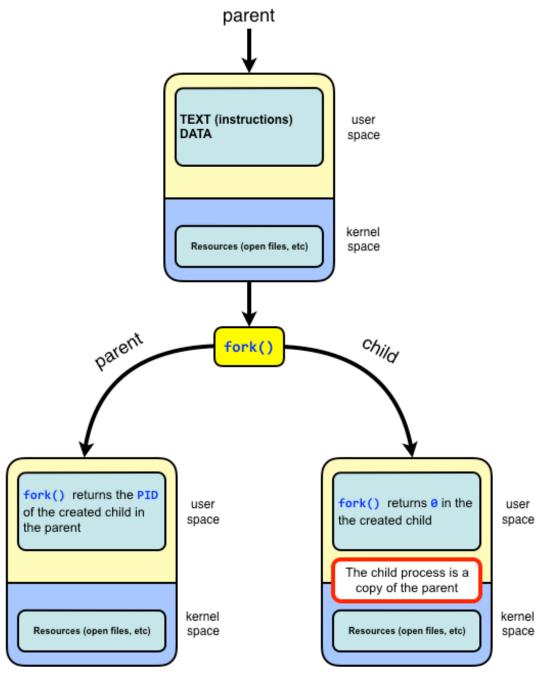
» Suspend or resume a process

Process Creation

- A process is created by another process, parent process or calling process
- Process creation relies on two system calls
 - fork()
 - » Create a new process and clone its parent process
 - exec()
 - » Overwrite the created process with a new program

fork()

- A function without any arguments
 - pid = fork()
- Both parent process and child process continue to execute the instruction following the fork()
- The return value indicates which process it is (parent or child)
 - Non-0 pid (pid of child process): return value of the parent process,
 - 0 : return value of the new child process
 - -1: an error or failure occurs when creating new process
- Child process is a duplicate of its parent process and has same
 - instructions, data, stack
- Child and parents have different
 - PIDs, memory spaces

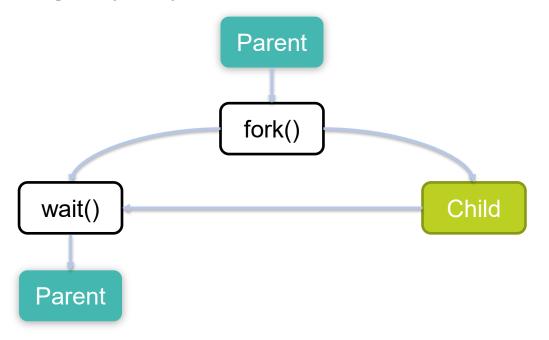


fork()

```
Output
int main(int argc, char *argv[])
                                                                hello world (pid:96744)
                                                                hello, I am parent of 96745 (pid:96744)
                                                                hello, I am child (pid:96745)
   printf("hello world (pid:%d)\n", (int) getpid());
    int rc = fork();
    if (rc < 0) {
                  // fork failed; exit
                  fprintf(stderr, "fork failed\n"); exit(1);
                                                             Child Process
    } else if (rc == 0) {
                   // child (new process)
                  printf("hello, I am child (pid:%d)\n", (int) getpid());
    } else {
                  // parent goes down this path (original process)
                  printf("hello, I am parent of %d (pid:%d)\n", rc, (int) getpid());
                                                             Parent Process
    return 0;
```

wait()

- Let the parent process wait for the completion of the child process
 - pid = wait()
- wait() suspends the execution of the calling process until one of its child processes terminates. It does not allow the parent to specify which child process to wait for. It will reap any terminated child arbitrarily.
- waitpid(pid) is an advanced version of wait. It allows the parent process to specify
 which child process (or group of processes) it wants to wait for.



wait()

```
int main(int argc, char *argv[])
                                                                                      Child process sleeps for 1 second
                                                                                      Parent process waits for the child process
           printf("hello world (pid:%d)\n", (int) getpid());
                                                                                     to finish sleeping
           int rc = fork();
           if (rc < 0) {
                       // fork failed; exit
                       fprintf(stderr, "fork failed\n");
                       exit(1);
                                                                         Child Process
           } else if (rc == 0) {
                       // child (new process)
                       printf("hello, I am child (pid:%d)\n", (int) getpid());
                       sleep(1);
           } else {
                       // parent goes down this path (original process). wc stores pid of the child process that is waited for
                       int wc = wait(NULL);
                       printf("hello, I am parent of %d (wc:%d) (pid:%d)\n", rc, wc, (int) getpid());
                                                                        Parent Process
           return 0;
```

wait()

• Without wait(): it is nondeterministic which process (parent or child) runs first

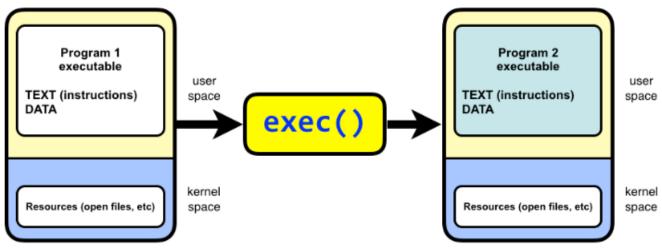
```
hello world (pid:96744)
hello, I am parent of 96745 (pid:96744)
hello, I am child (pid:96745)
```

With wait(): child runs first, and parents waits for child to finish

```
hello world (pid:96848)
hello, I am child (pid:96849)
hello, I am parent of 96849 (wc:96849) (pid:96848)
```

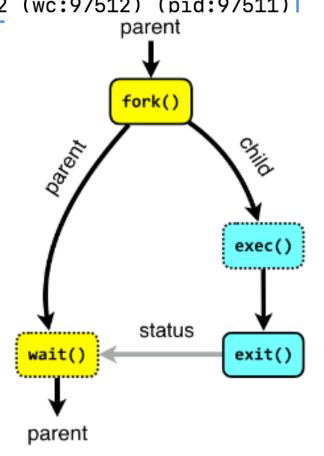
exec()

- exec(cmd, argv) replaces the current process image with a new process image specified by the path to an executable file.
 - It does not return. It starts to execute the new program.
- There is a family of exec(), e.g., execl(), execvp()
 - execl() takes a variable number of arguments that represent the program name and its arguments.
 - » int execl(const char *path, const char *arg, ..., NULL);
 - execvp() takes an array of arguments instead of a variable-length argument list
 - » int execvp(const char *file, char *const argv[]);



exec() Example

```
wc: counts Lines, Words, and Bytes in a File:
int main(int argc, char *argv[])
                                                                 Output format: [lines] [words] [bytes] [filename]
                                                                 hello world (pid:97511)
     printf("hello world (pid:%d)\n", (int) getpid());
                                                                 hello, I am child (pid:97512)
     int rc = fork();
                                                                          32
                                                                                     123
                                                                                                 966 p3.c
     if (rc < 0) {
                                                                 hello, I am parent of 97512 (wc:97512) (pid:97511)
                        // fork failed; exit
                       fprintf(stderr, "fork failed\n"); exit(1);
     } else if (rc == 0) { // child (new process)
                       printf("hello, I am child (pid:%d)\n", (int) getpid());
                       char *myargs[3];
                       myargs[0] = strdup("wc"); // program: "wc" (word count)
                       myargs[1] = strdup("p3.c"); // argument: file to count
                       myargs[2] = NULL; // marks end of array
                       execvp(myargs[0], myargs); // run word count
                       printf("this will be replaced, so not printed out");
     } else { // parent
                       int rc wait = wait(NULL);
                       printf("hello, I am parent of %d (rc_wait:%d) (pid:%d)\n", rc, rc_wait, (int) getpid());}
     return 0;
```



10 redirection and pipe

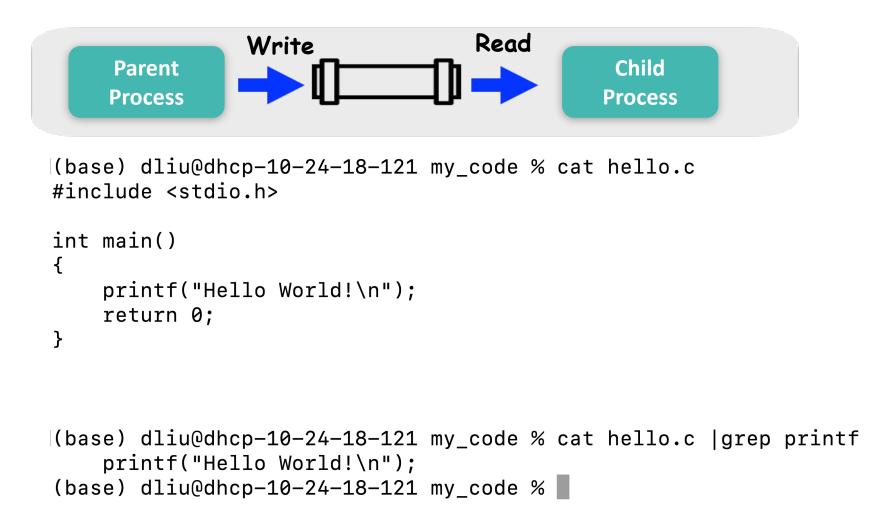
• By separating **fork** () and **exec** (), we can manipulate various settings just before executing a new program and **make the IO redirection and pipe possible**.

- IO redirection % cat w3.c > newfile.txt

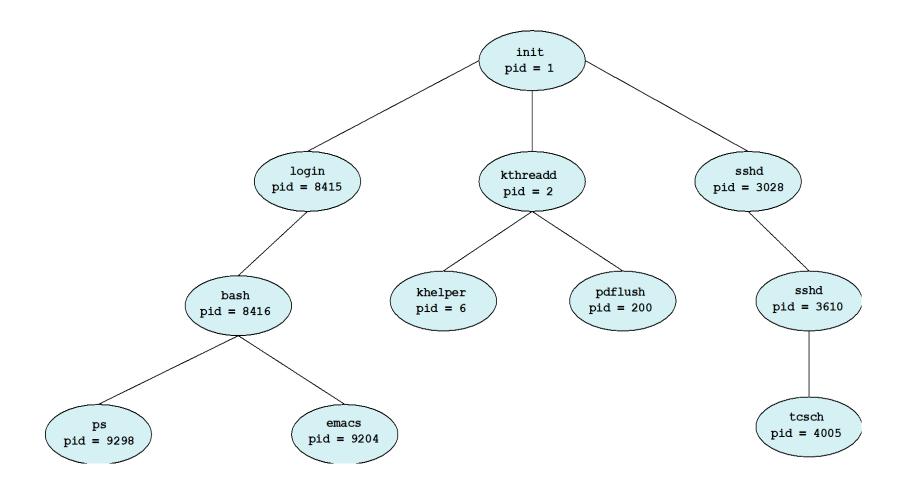
- pipe % echo hello world | wc

<u>pipe</u>

• A communication method between two processes



Process Tree



Process Tree

% pstree (to show the process tree)

```
(base) dliu@dhcp-10-24-17-236 ~ % pstree
-+= 00001 root /sbin/launchd
|--= 00322 root /usr/libexec/logd
|--= 00323 root /usr/libexec/smd
|--= 00324 root /usr/libexec/UserEventAgent (System)
```

% ps (to show all processes)

```
PID TT STAT TIME COMMAND

1 ?? Ss 17:57.36 /sbin/launchd

322 ?? Rs 6:29.86 /usr/libexec/logd

323 ?? Ss 0:00.19 /usr/libexec/smd

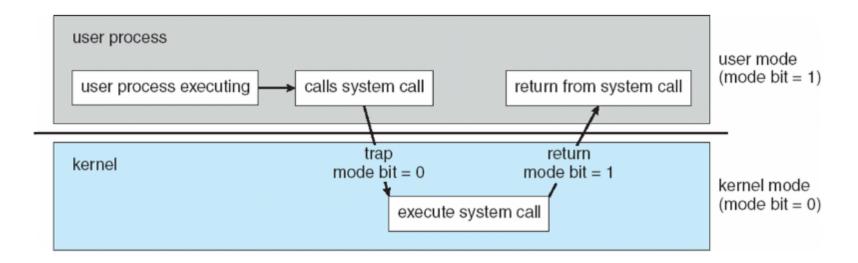
324 ?? Ss 0:19.58 /usr/libexec/UserEventAgent (System)
```

<u>User/Kernel Mode Separation</u>

- **User mode**: restricted, limited operations
 - Processes start in user mode
- Kernel mode: privileged, not restricted
 - OS starts in kernel mode
- What if a process wants to perform some restricted operations?
 - System calls: Allow the kernel services to provide some functionalities to user programs

User/Kernel Mode Separation

- A process starts in user mode
- If it needs to perform a restricted operation, it calls a system call by executing a trap instruction.
- The state and registers of the calling process are stored, the system enters kernel mode, OS completes
 the syscall work.
- Return from syscall, restore the states and registers of the process, and resume the execution of the process



Process Scheduling

- Switching Between Processes
 - Cooperative approach
 - Non-cooperative approach
- Cooperative approach
 - Trust process to relinquish CPU to OS through traps
 - » System calls
 - » Illegal operations, e.g., divided by zero
 - Issue: if no system call
- Non-cooperative approach
 - The OS takes control
 - OS obtains control periodically, e.g., timer interrupter

<u>Summary</u>

- In OS, process is a running program and has an address space
- We use process API to create and manage processes
- Fork() to duplicate a process, exec() to replace the command
- Process scheduling