

# Simple v/s non-simple repair policies for systems under simultaneous failures of its components

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# MMR 2025

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# Team



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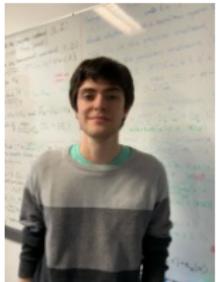
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# Introduction

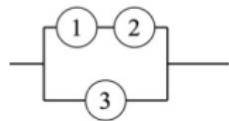
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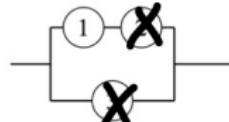
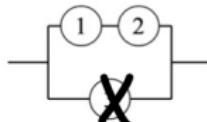
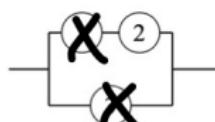
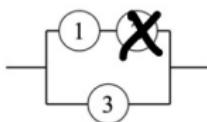
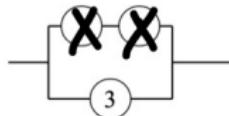
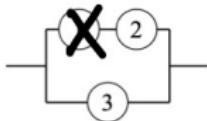
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$n = 3$  components



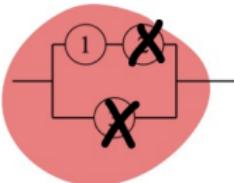
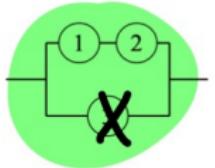
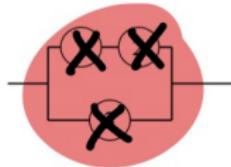
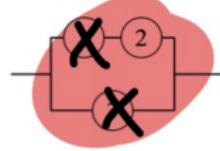
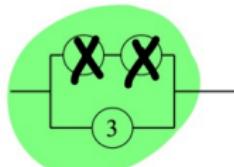
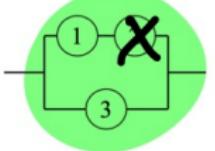
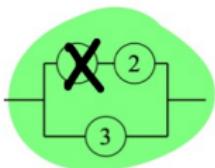
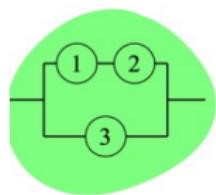
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$\Rightarrow 2^n = 8$  states



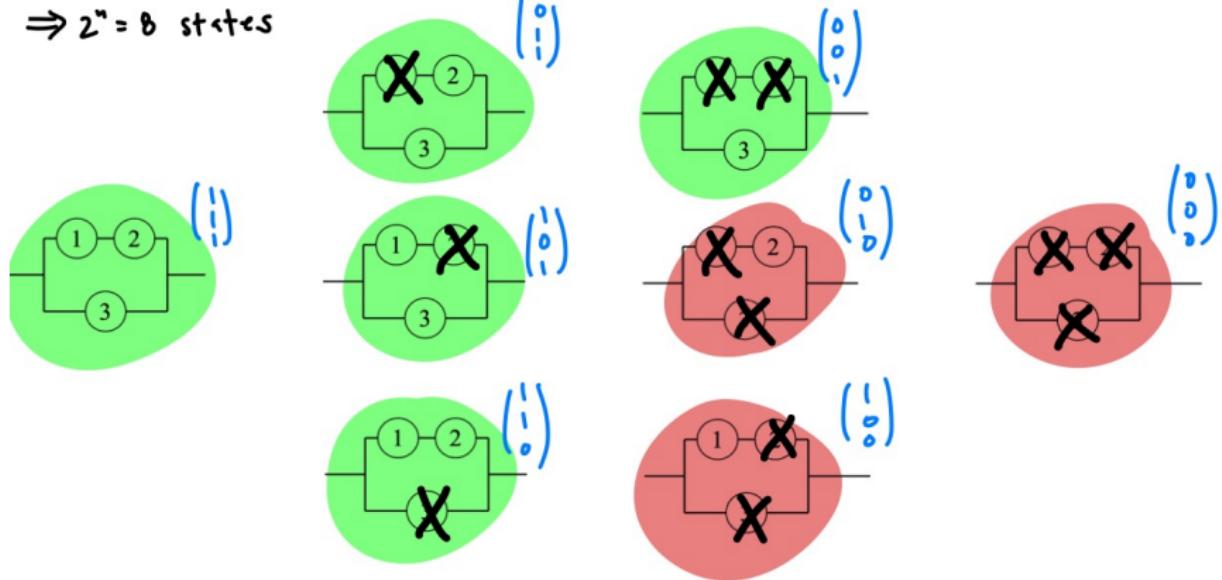
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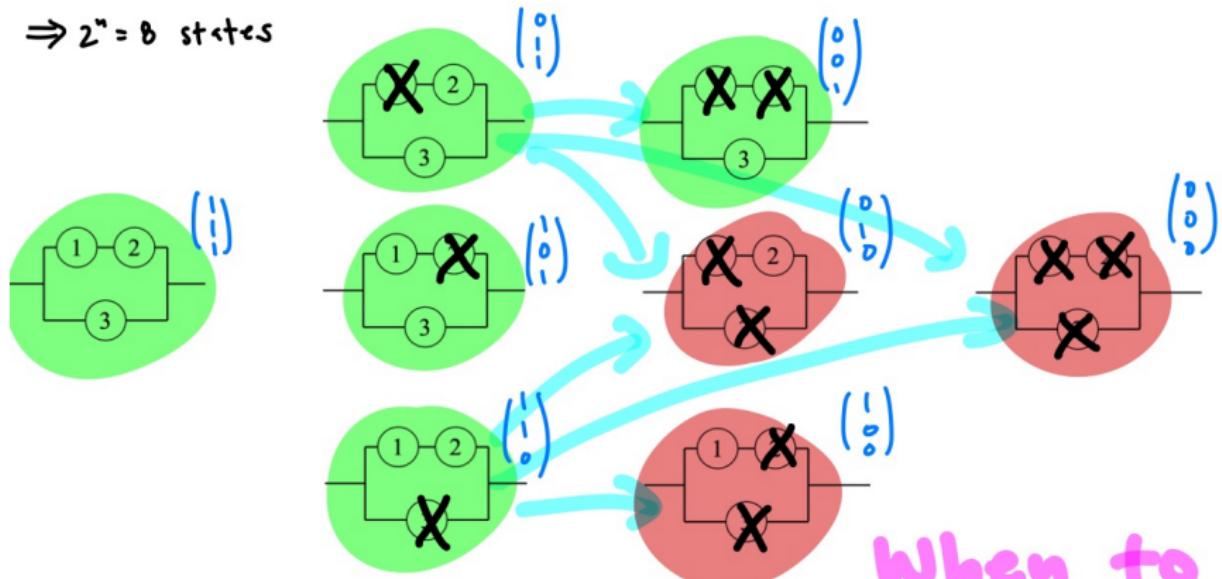
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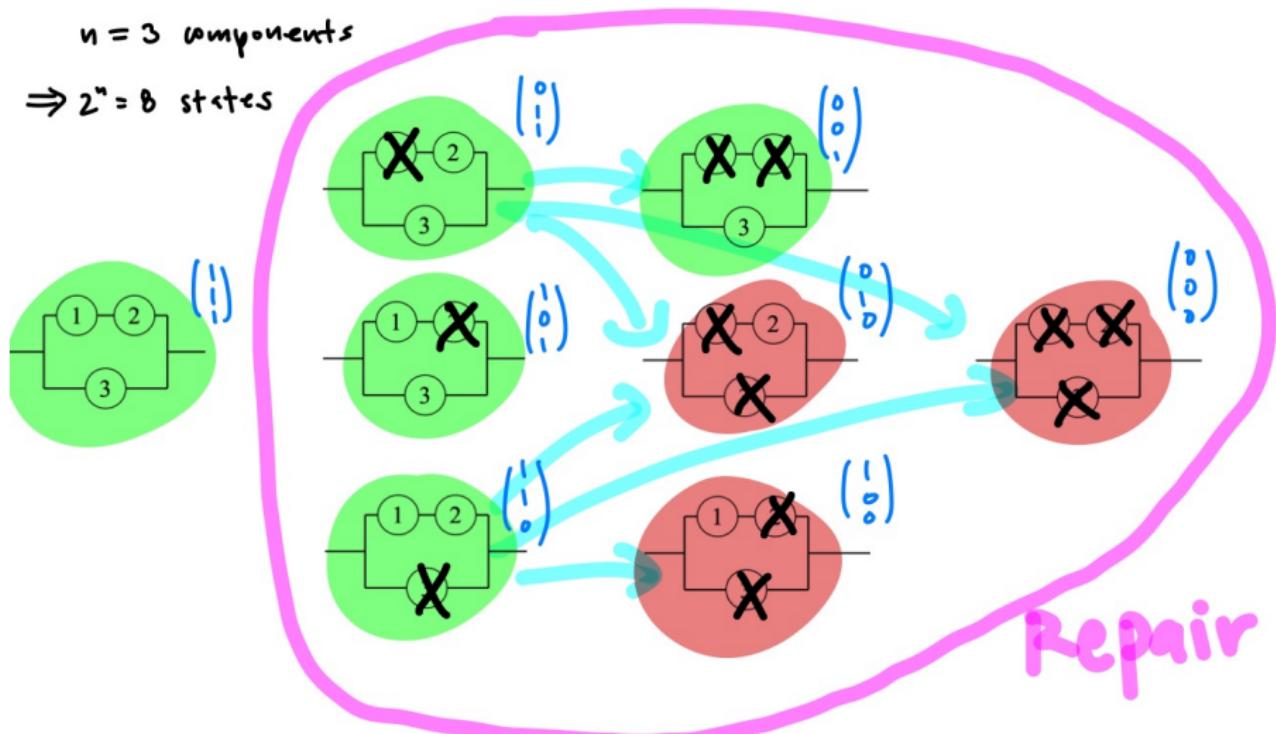


When to  
repair?

Vanilla MDP:  $2^n$  policies

$n = 3$  components

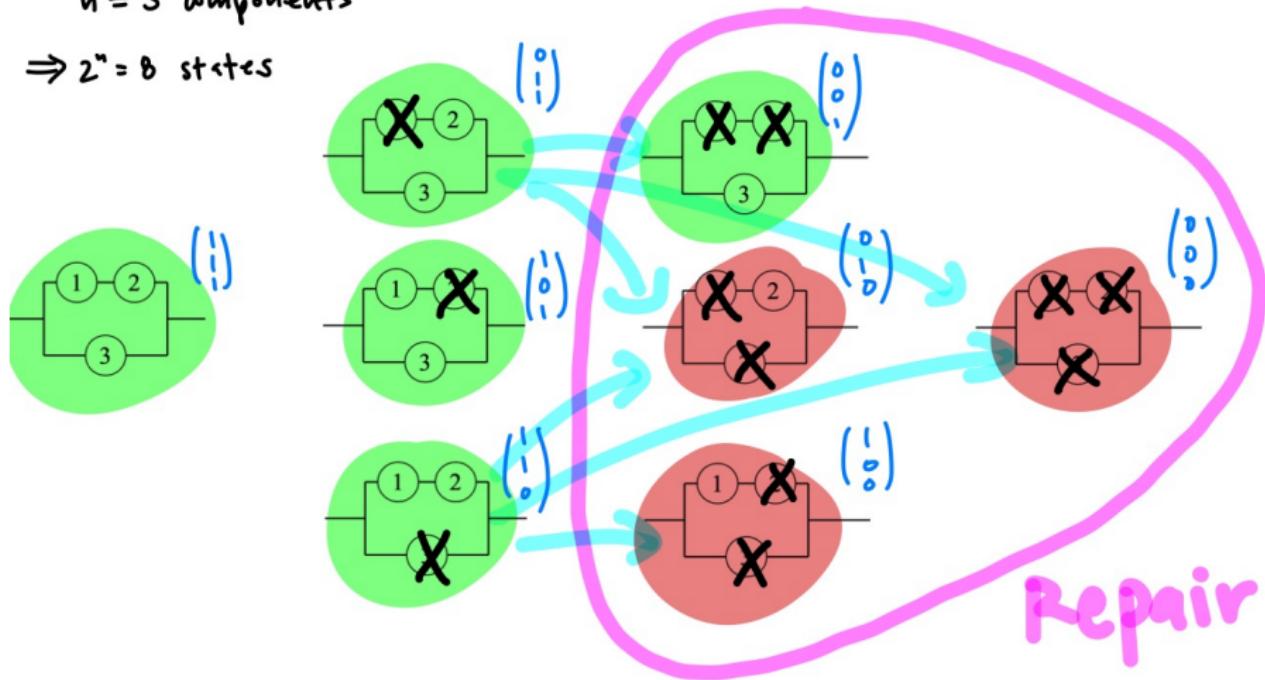
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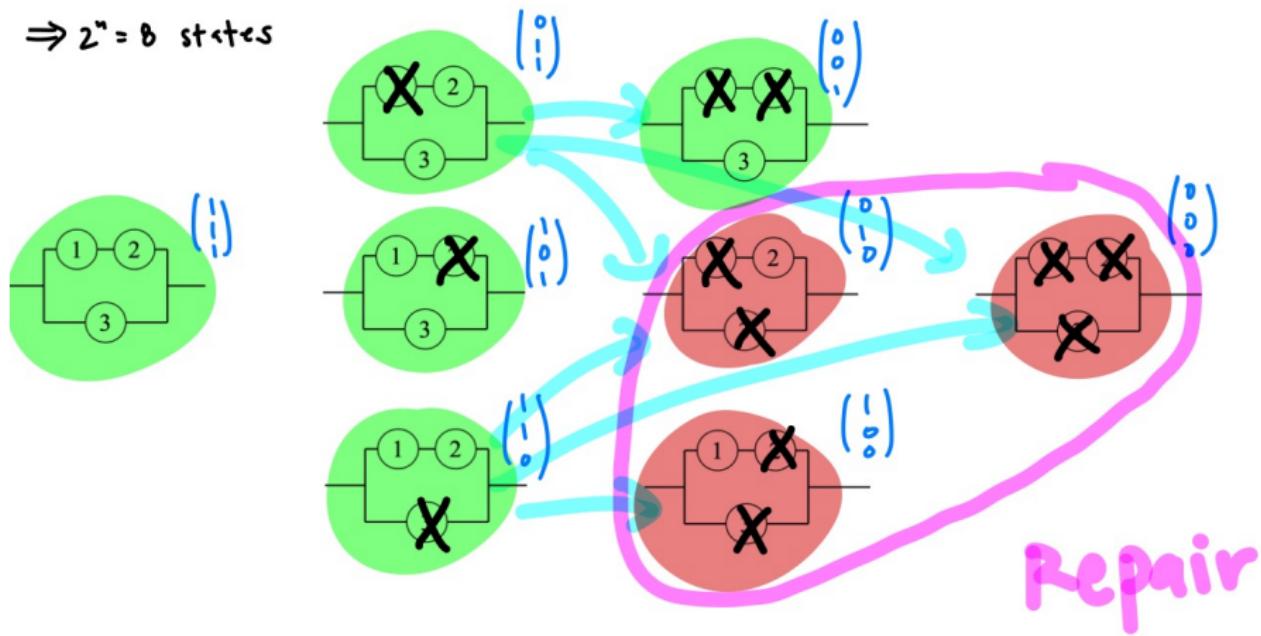
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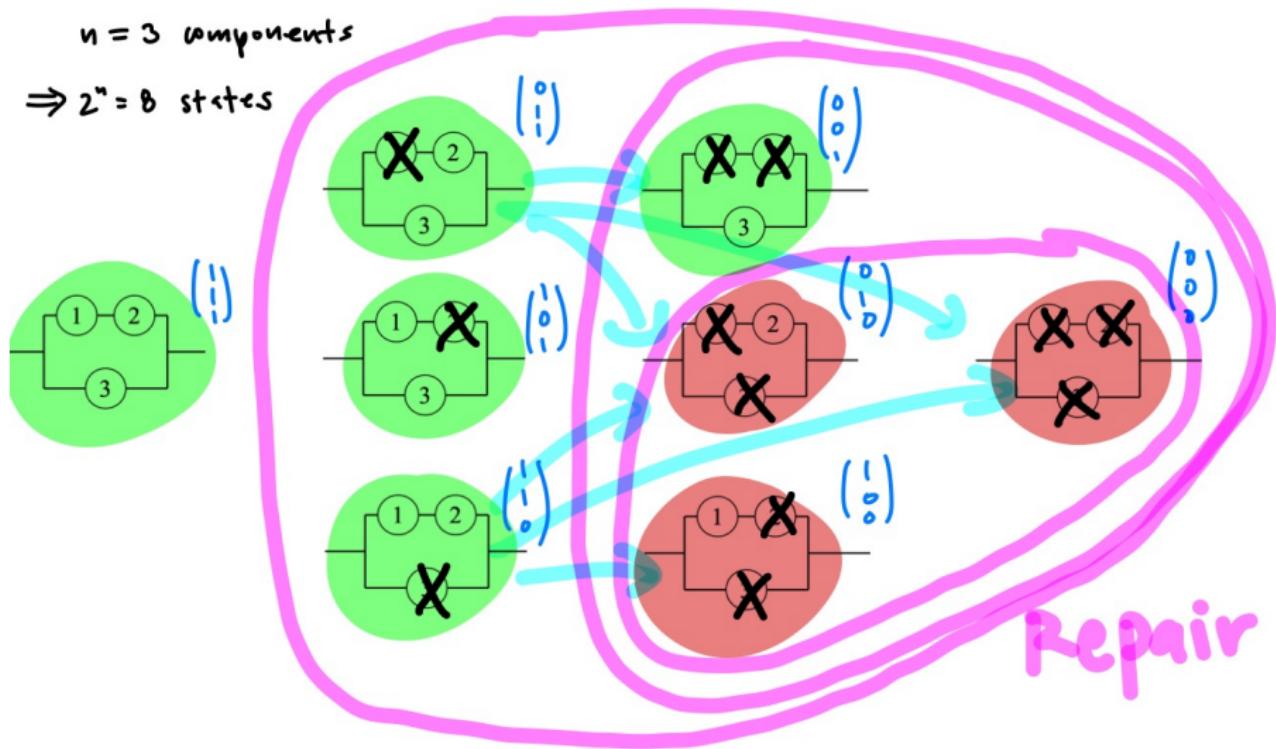
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Vanilla MDP:  $2^n$  policies

simple "r-out-of-n:p" repair:  $n$  policies

# Introduction

- We consider: stochastic binary systems<sup>1</sup> + simultaneous failures<sup>2</sup>
- Literature: usually convoluted combinatoric expressions, bounds, or iid assumptions. See review of Pérez-Rosés (2018).

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First result for simultaneous failures and/or general monotone systems!

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Consider a system with  $n$  components subject to failures.

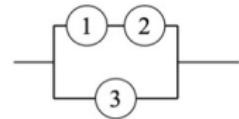
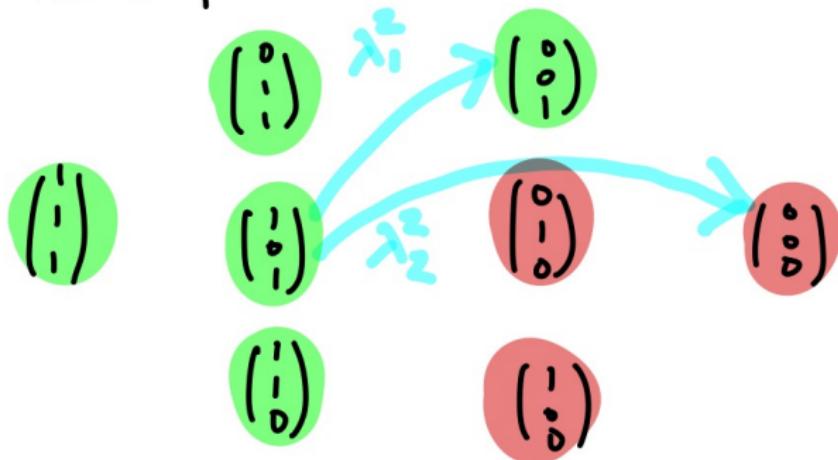
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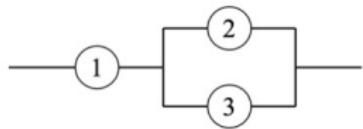
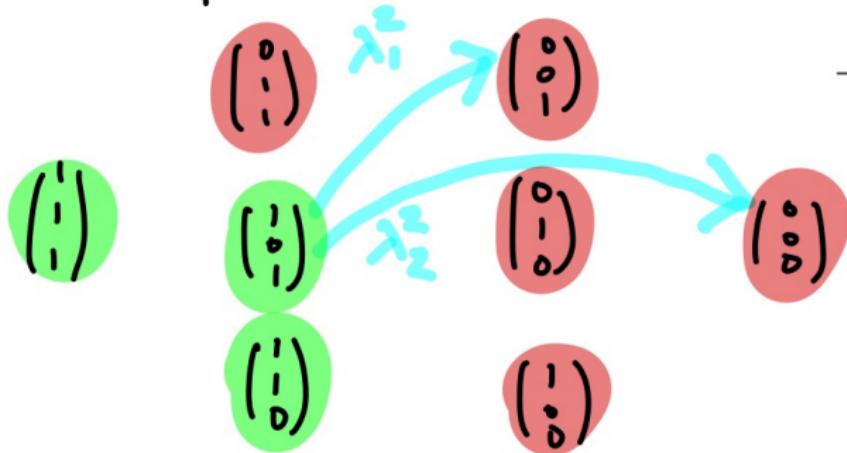
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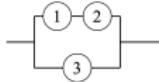
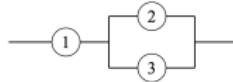
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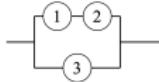
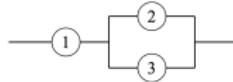
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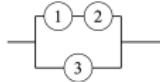
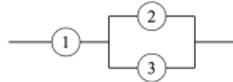
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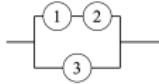
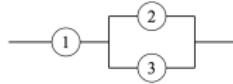
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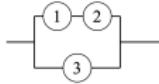
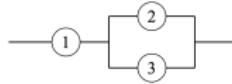
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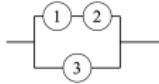
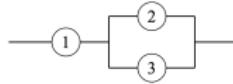
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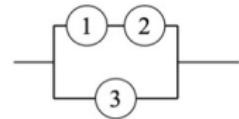
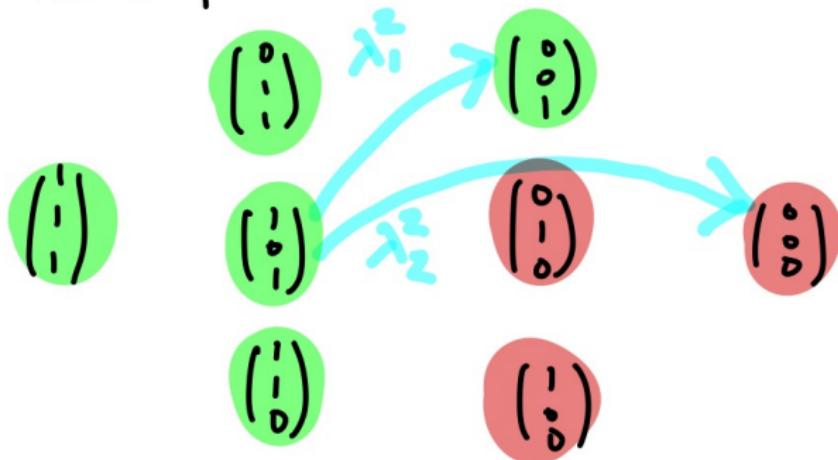
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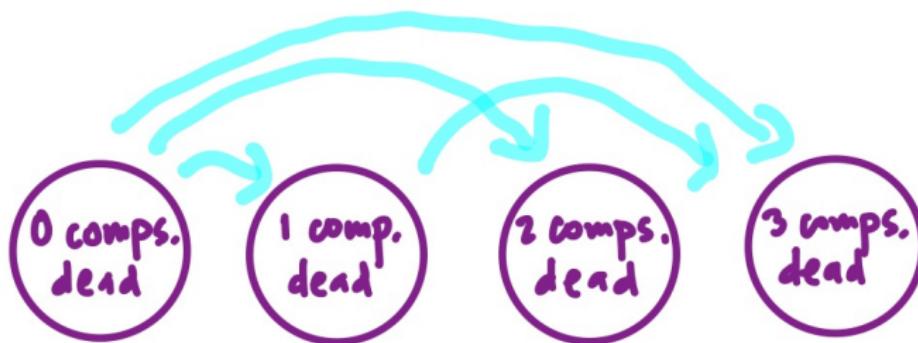
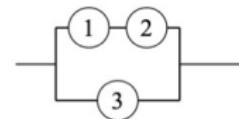
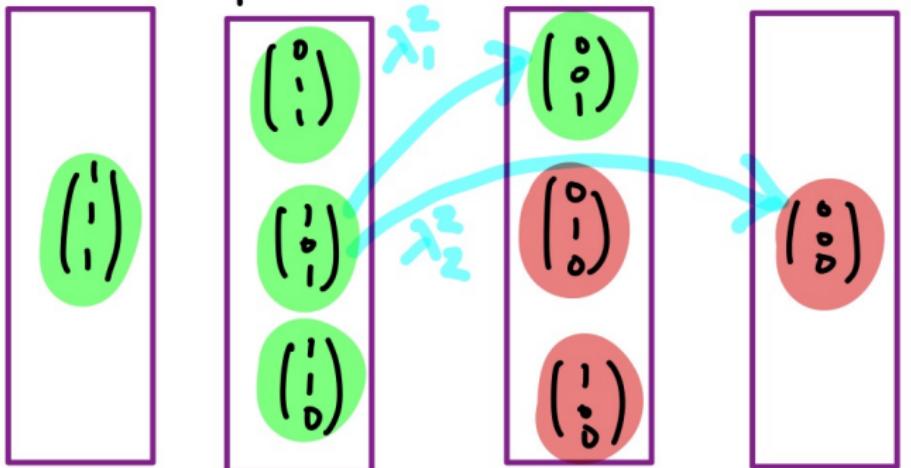
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“with probability  $s_k$ , system behaves as a  $k$ -out-of- $n$  system”

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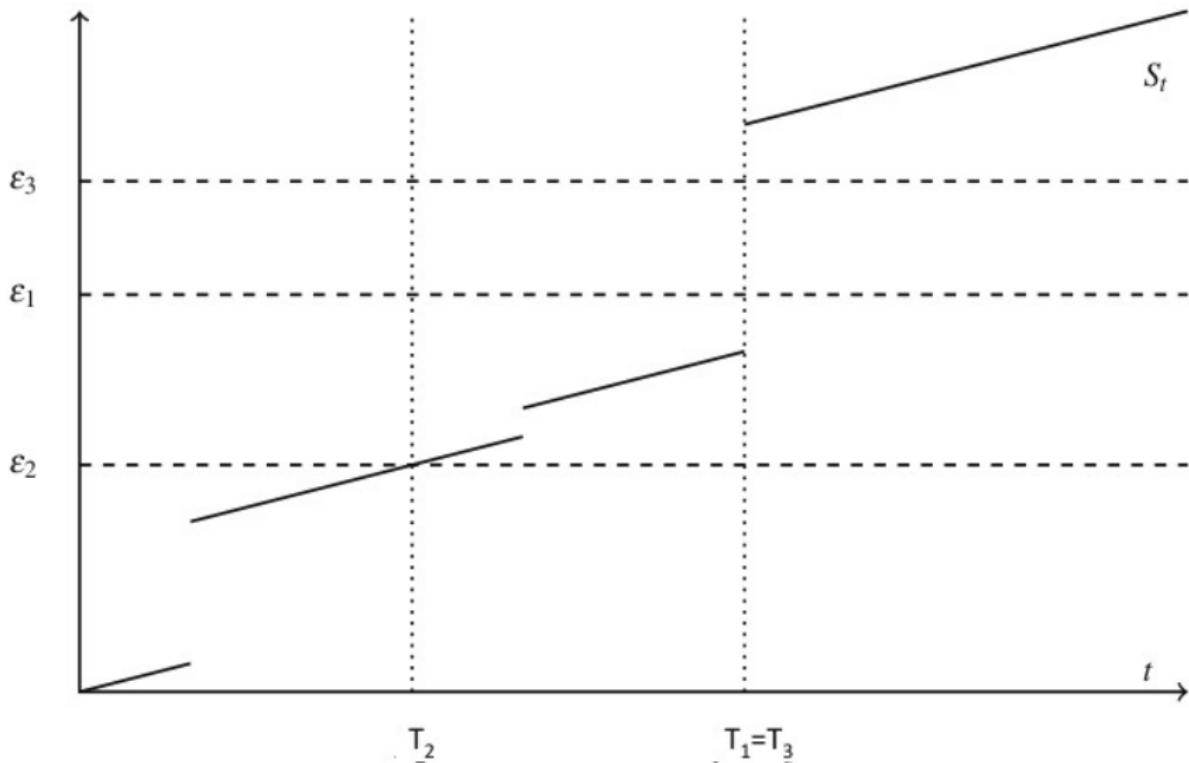
Definition: **Lévy-frailty Marshall-Olkin (LFMO) distribution** (Mai & Scherer 2009)

Define  $T_i = \text{time of failure of component } i$  as

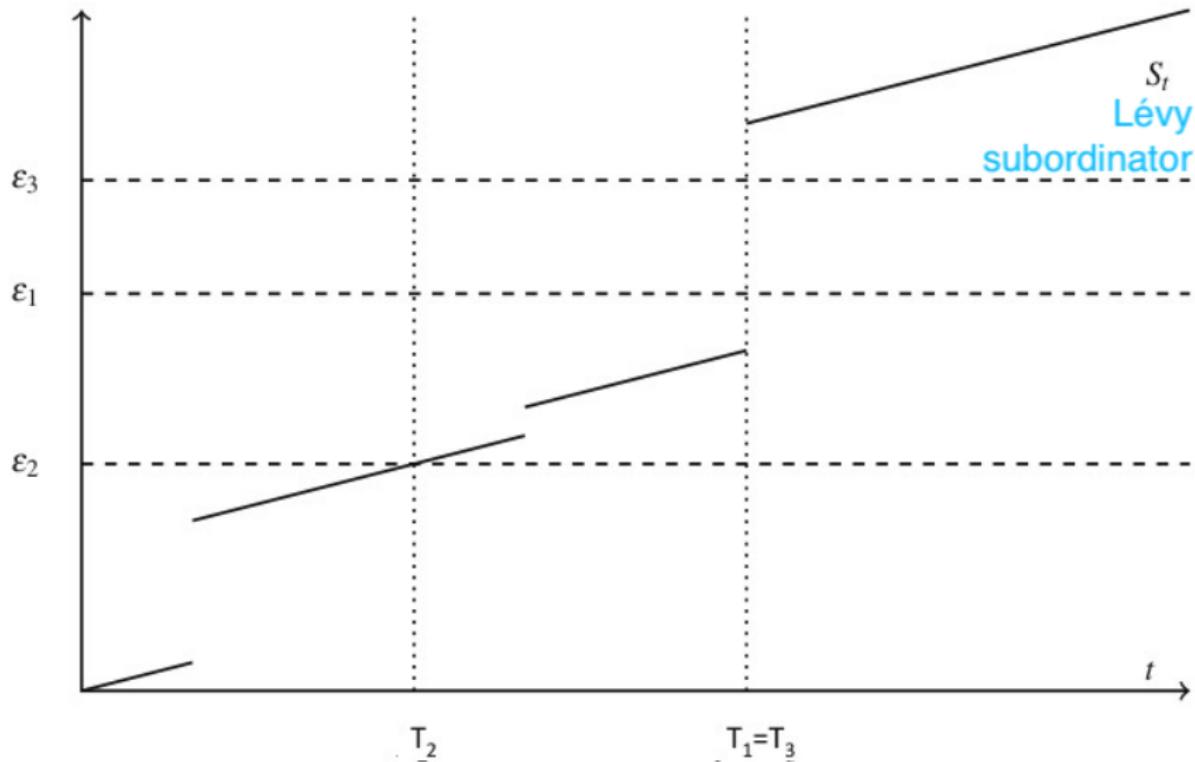
$$T_i := \min\{ t \geq 0 : S_t \geq \varepsilon_i \}, \quad i = 1, \dots, n,$$

where:  $(S_t : t \geq 0)$  is a Lévy subordinator process (Markovian, **degradation process**)  
 $\varepsilon_1, \varepsilon_2, \varepsilon_3, \dots$  are iid exponential(1) random variables (**tolerance of each component**)

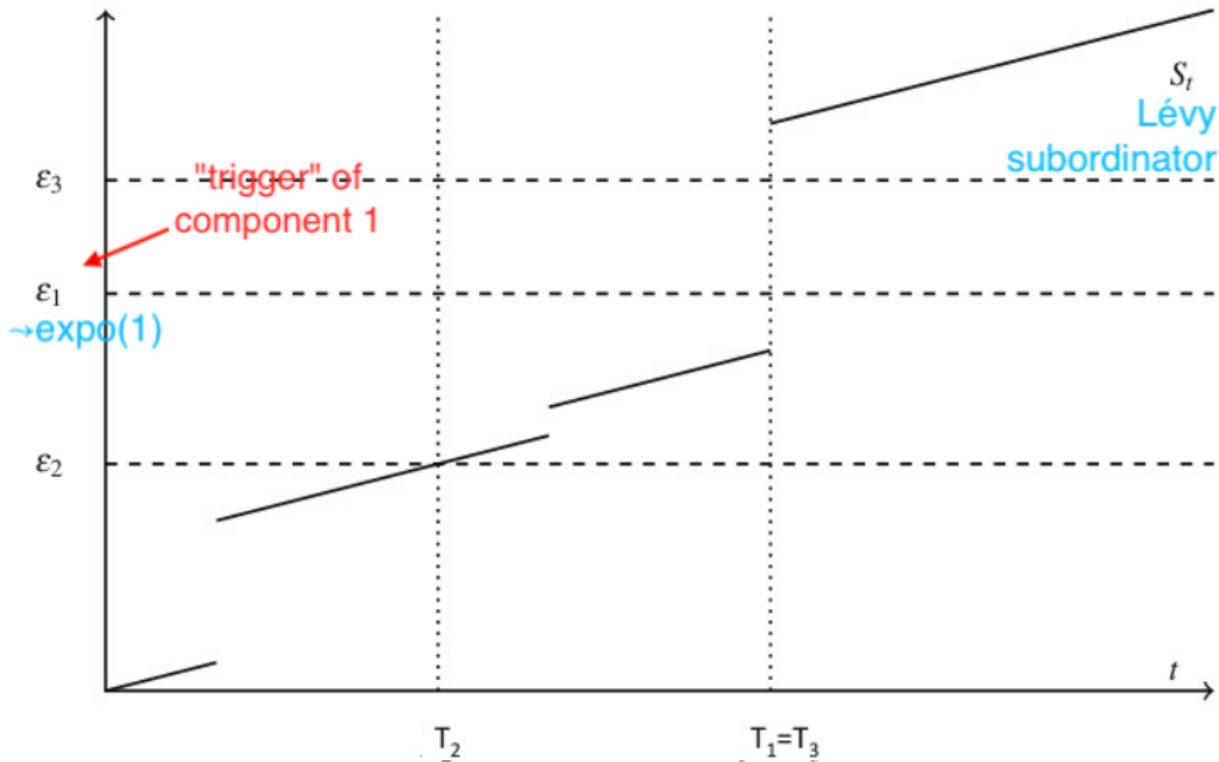
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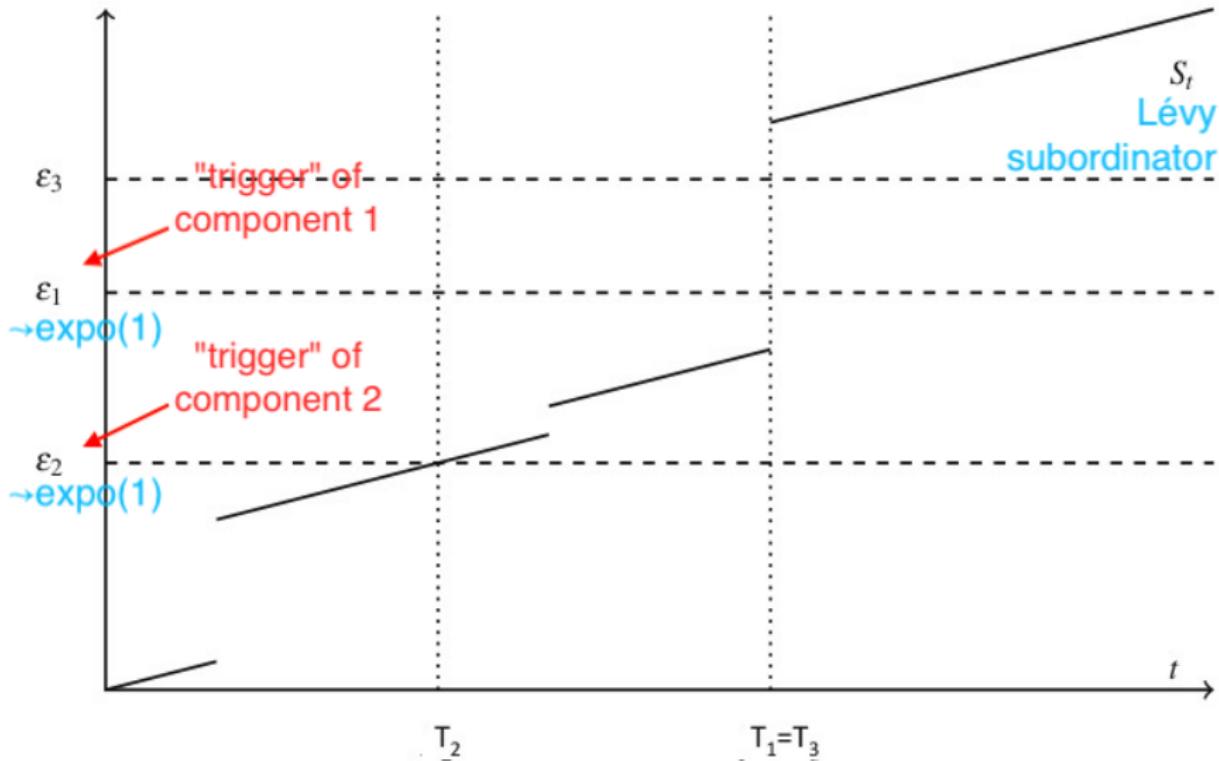
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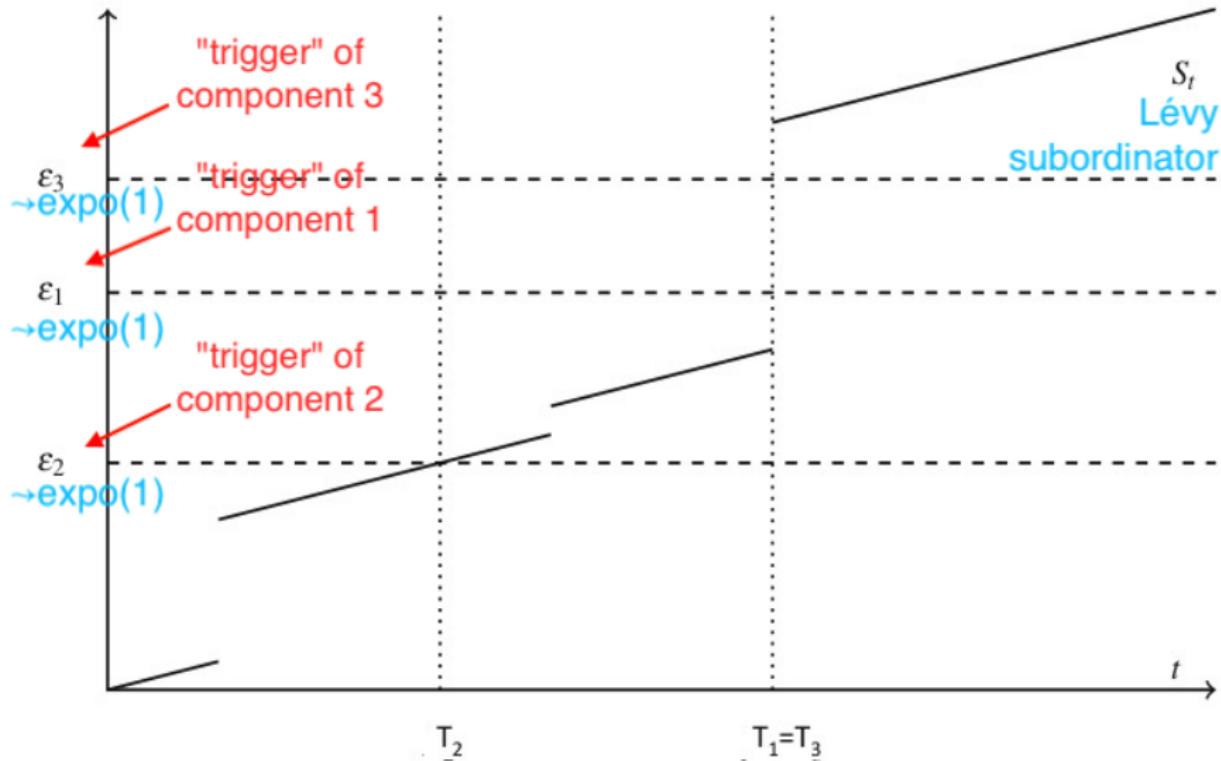
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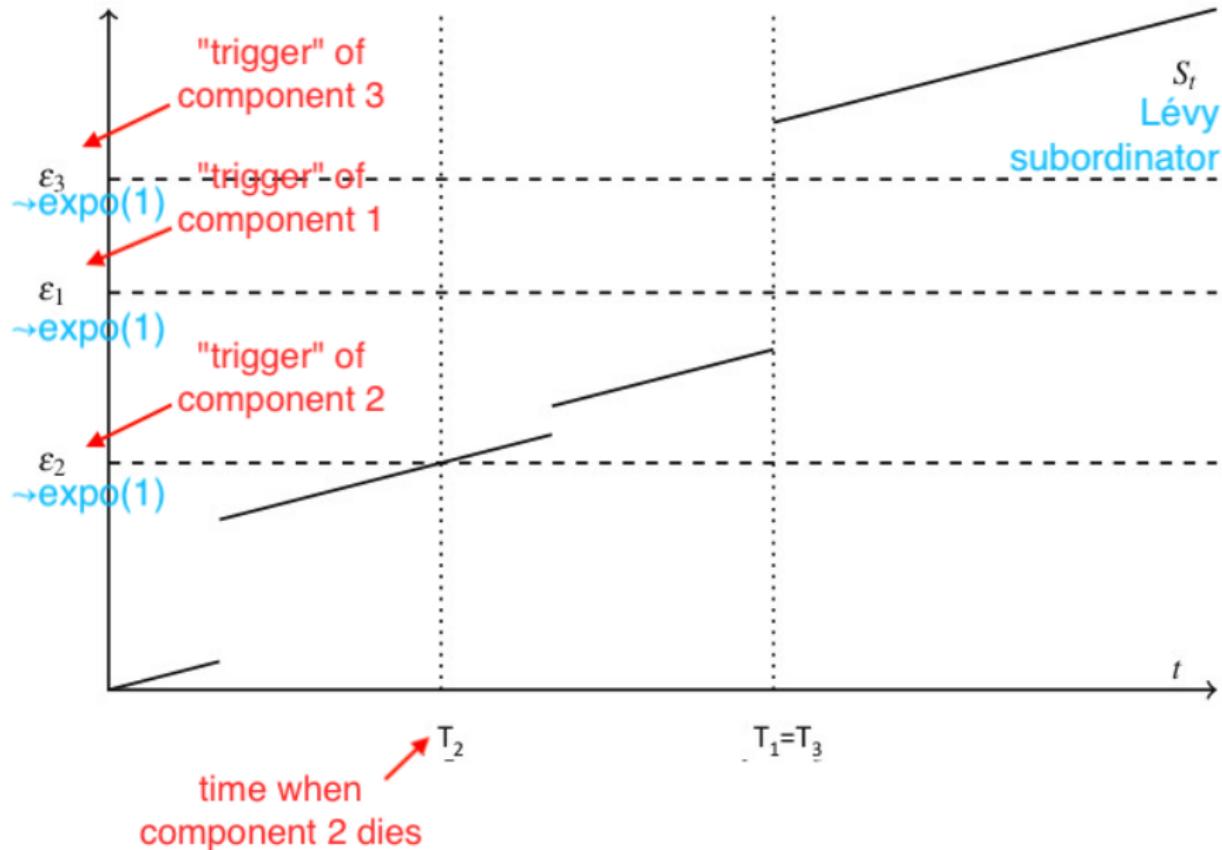
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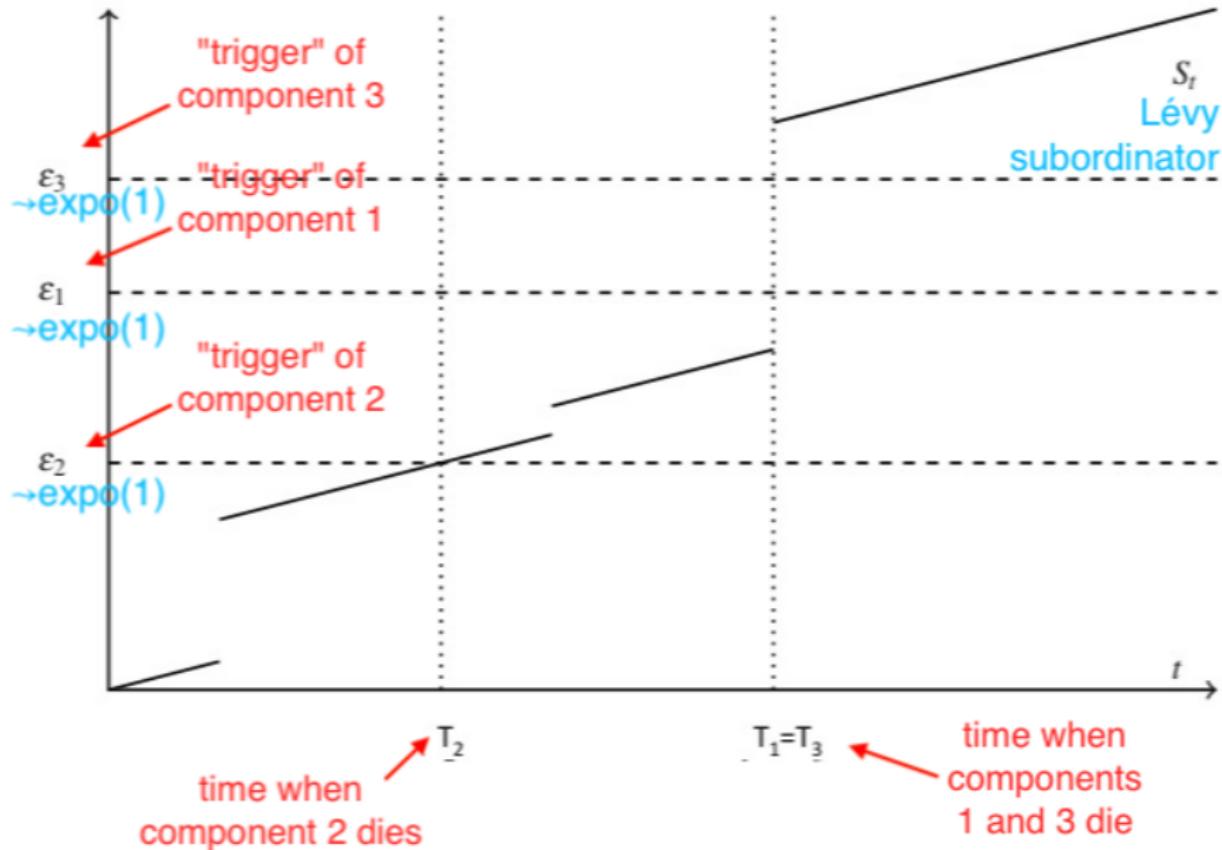
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## Setting, part 2: times of failure (dynamic)

Consider a system with  $n$  components subject to failures.

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Define  $T_i = \text{time of failure of component } i$  as

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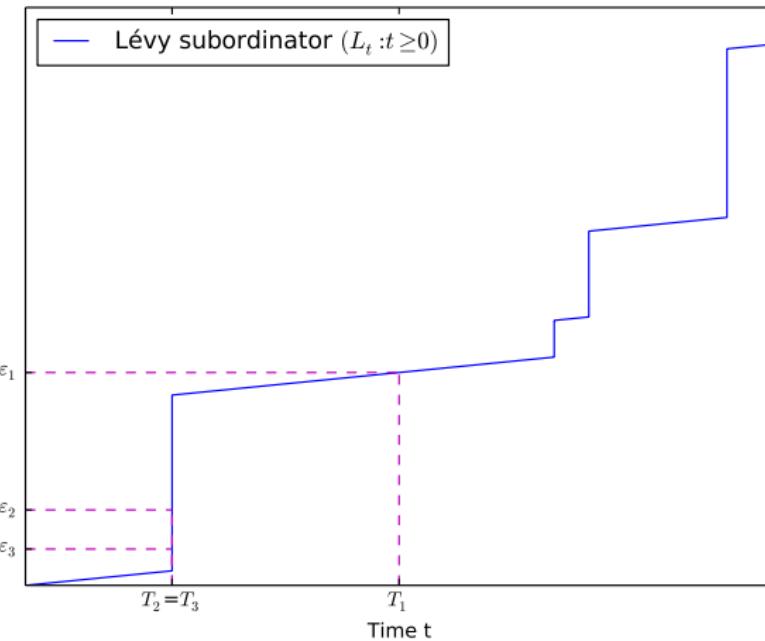
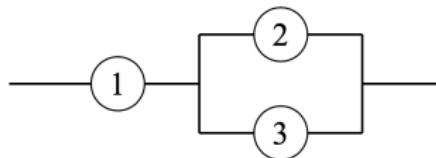
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☺ Markovian structure!    ☺ A Marshall-Olkin (shock) model!    ☺ **Very few parameters!**

# Examples of systems



## Setting, part 3: repair policy

Assume that:

- Repairing one component costs  $c_{comp}$
- Repairing failed system costs  $c_{sys}$ , plus  $c_{comp}$  for each failed component
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**Question: what's the optimal value of  $r$ ?**

# Main result

## Theorem (idea)

Setting:

- 1 A fixed monotone system with  $n$  components
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- Ingredients of proof: Samaniego decomposition + Markov chain analysis

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- $C[0, t]$  = total cost up to time  $t$
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it holds that

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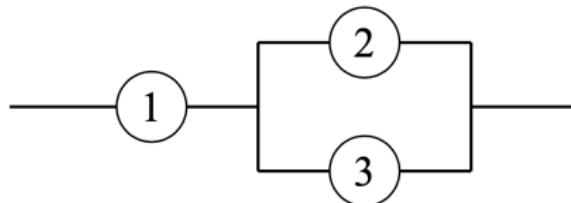
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# Example I

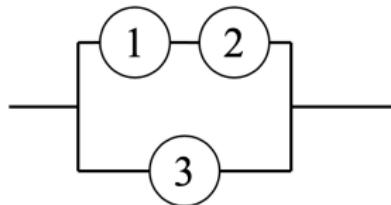
3 components,  $c_{comp} = 1$ ,  $c_{sys} = 10$



r	Probab. of failure before repair	Rate of component failures	Expected time to system failure	Long-term average cost
1	0.42	4.50	0.632	20.33
2	1.00	3.83	0.483	24.52
3	1.00	3.83	0.483	24.52

## Example II

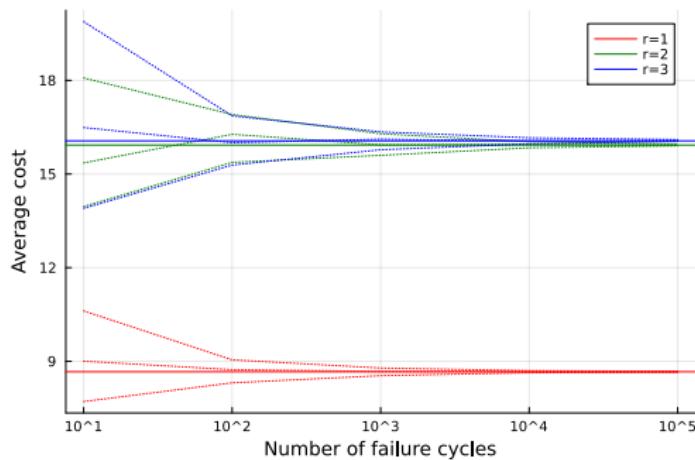
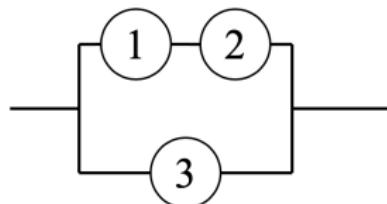
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r	Probab. of failure before repair	Rate of component failures	Expected time to system failure	Long-term average cost
1	0.111	4.50	2.40	8.66
2	0.725	3.68	0.816	15.93
3	1.0	3.16	0.775	16.06

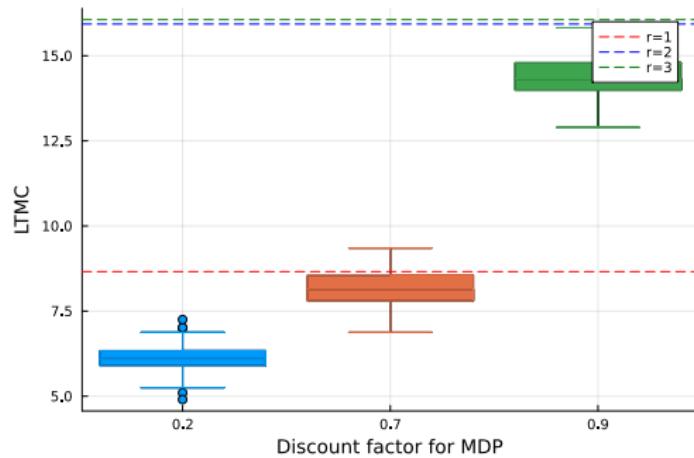
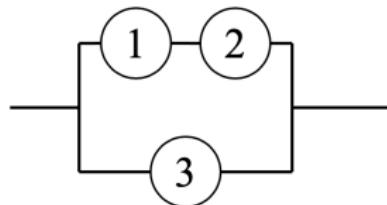
## Example II — simulations

3 components,  $c_{comp} = 1$ ,  $c_{sys} = 10$



## Example II — comparison with MDP solutions

3 components,  $c_{comp} = 1$ ,  $c_{sys} = 10$



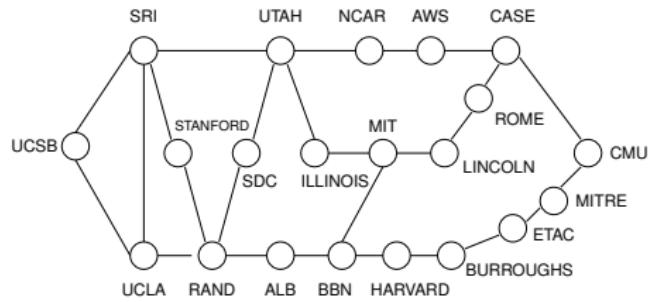
## Example III

A random mixed monotone system with 10 components.

r	Probab. of failure before repair	Rate of component failures	Expected time to system failure	Long-term average cost
1	0.183	15.0	17.5	34.9
2	0.254	14.3	19.7	29.1
3	0.387	13.6	18.8	29.1
4	0.492	12.9	18.4	28.3
5	0.614	12.2	17.7	28.1
6	0.734	11.6	17.0	28.2
7	0.776	11.1	16.9	26.9
8	0.835	10.5	16.8	25.9
9	0.897	9.8	16.5	24.9
10	1.0	8.9	15.9	24.0

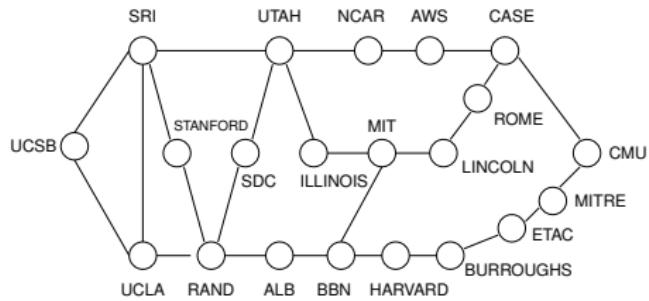
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RAND network: arcs fail and system works when there is path UCSB→CMU:



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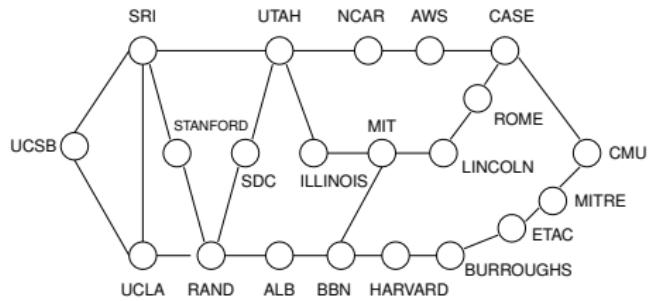
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$$2^n = 67\,108\,864 \text{ states}$$

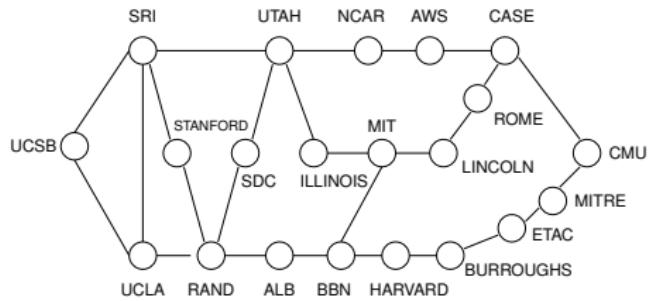
First state (“all components working”) has  $2^n - 1$  successors

$$\text{Total: } 3^n - 2^n = 2\,541\,798\,719\,465 \text{ transitions}$$

**Computer can't do it!**

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- Trivial computation for best  $r$ -out-of- $n$  policy

# Summary & main takeaways

- Setting considered:
  - **Failure times:** components fail according to *Lévy-frailty Marshall-Olkin* (LFMO) model for **simultaneous failures**
  - **System structure:** **monotone system**
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- Comparison with MDP-obtained policies:
  - Competitive, depending on choice of discount factor
  - Bypasses exponential number of states and transitions



# MMR 2025

## 13th International Conference On **Mathematical Methods In Reliability**

June 23–27th, 2025, Viña Del Mar, Chile

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