

Embedded System & Embedded Linux Development Part 6

Index of today's topic



- ⌘ Use libraries in development

- ⌘ Use libjpeg to display/save jpeg image

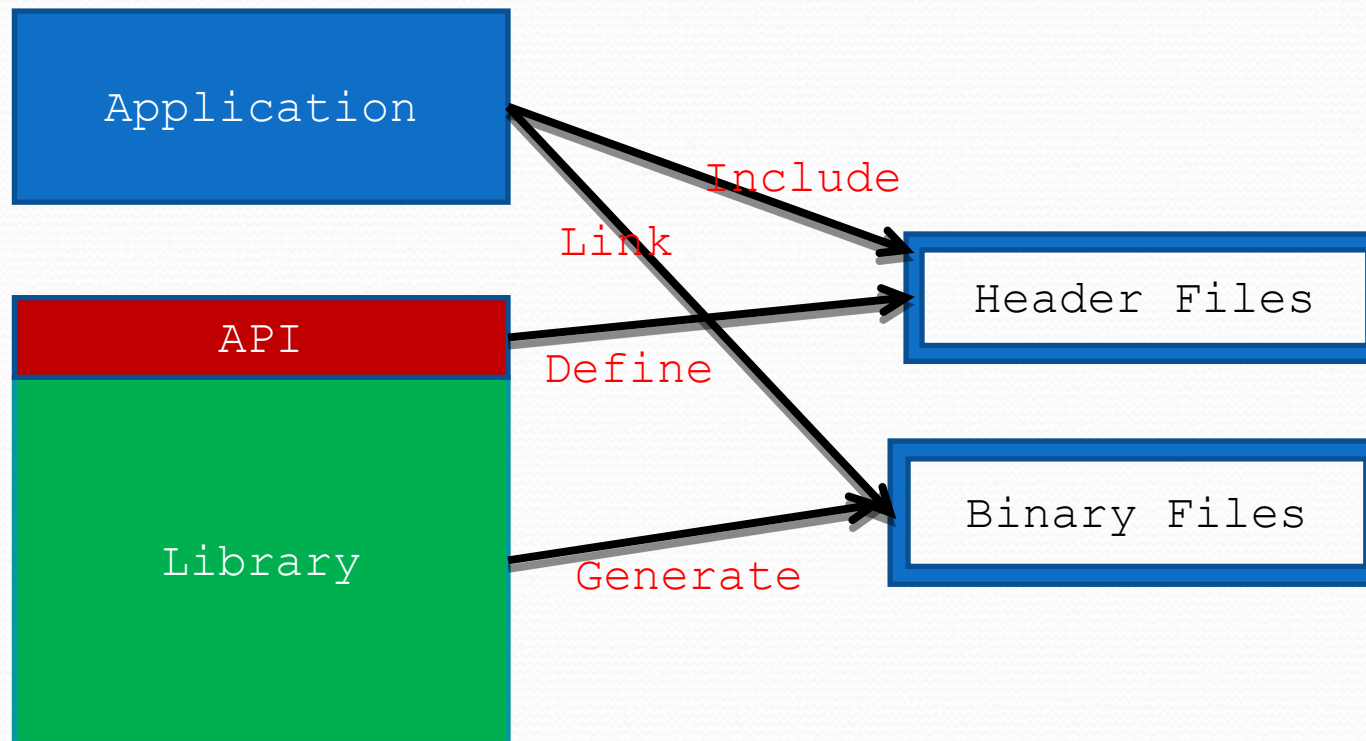
- ⌘ Use camera on FL6410

- ⌘ Exercise

What is library?

- ⌘ a collection of resources used to develop software
- ⌘ contain code and data that provide services to independent programs
- ⌘ Code reuse

Application/Library/API



C Library

- ⌘ Standard Library

 - ⌘ Philosophies between C & Python

- ⌘ GNU C Library (glibc)

- ⌘ Math Library (libm)

C standard library

- ✂ <assert.h>
- ✂ <ctype.h>
- ✂ <errno.h>
- ✂ <float.h>
- ✂ <limits.h>
- ✂ <locale.h>
- ✂ <math.h>
- ✂ <setjmp.h>
- ✂ <signal.h>
- ✂ <stdarg.h>
- ✂ <stddef.h>
- ✂ <stdio.h>
- ✂ <stdlib.h>
- ✂ <string.h>
- ✂ <time.h>

C POSIX library header files

⌘ <cpio.h>	Magic numbers for the cpio archive format.
⌘ <dirent.h>	Allows the opening and listing of directories.
⌘ <fcntl.h>	File opening, locking and other operations.
⌘ <grp.h>	User group information and control.
⌘ <pthread.h>	Defines an API for creating and manipulating POSIX threads.
⌘ <pwd.h>	passwd (user information) access and control.
⌘ <sys/ipc.h>	Inter-process communication (IPC).
⌘ <sys/msg.h>	POSIX message queues.
⌘ <sys/sem.h>	POSIX semaphores.
⌘ <sys/stat.h>	File information (stat et al.).
⌘ <sys/time.h>	Time and date functions and structures.
⌘ <sys/types.h>	Various data types used elsewhere.
⌘ <sys/utsname.h>	uname and related structures.
⌘ <sys/wait.h>	Status of terminated child processes (see wait)
⌘ <tar.h>	Magic numbers for the tar archive format.
⌘ <termios.h>	Allows terminal I/O interfaces.
⌘ <unistd.h>	Various essential POSIX functions and constants.
⌘ <utime.h>	inode access and modification times.

Library

- ⌘ Static Libraries

- ⌘ *.a

- ⌘ Shared Libraries

- ⌘ *.so

- ⌘ Dynamic Linking

- ⌘ Dll/so (Shared Object)

Link Library in Linux

⌘ Include the header files in .c

⌘ `#include <library_file_header.h>`

⌘ Compile

⌘ `gcc -c <object file> <source file> -
I<library_header_path>`

⌘ Link Shared Library

⌘ `gcc -o <output> <object files> -l<library_name>
-L<library_file_path>`

⌘ Link Static Library

⌘ `gcc -o <output> <object files>
<library_file_name.a>`

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libjpeg

⌘ a library to decode & encode the jpeg file

⌘ installed in most of the Linux distribution

⌘ Official website:

⌘ <http://sourceforge.net/projects/libjpeg/>

Use libjpeg in your code

⌘ include the jpeglib.h

⌘ **#include <jpeglib.h>**

⌘ add **-ljpeg** to the linking options

⌘ **gcc -o test.o -c test.c**

⌘ **gcc -o test.out test.o -ljpeg**



Example:

<http://www.cim.mcgill.ca/~junaed/libjpegeg.php>

Key point in writing a JPEG file

⌘ Convert RGB565 buffer to RGB888 buffer

⌘ Write the jpeg file line by line

```
while (cinfo.next_scanline <  
    cinfo.image_height) {  
    row_pointer[0] =  
        &image_buffer[cinfo.next_scanline *  
            image_width * 3];  
    (void) jpeg_write_scanlines(&cinfo,  
row_pointer, 1);  
}
```


Key point in displaying a JPEG file

- ⌘ Read the jpeg file line by line
- ⌘ Convert RGB888 pixel to RGB565 pixel
- ⌘ Draw pixel by pixel

```
y = 0;
while (cinfo.output_scanline < cinfo.output_height)
{
    jpeg_read_scanlines(&cinfo, buffer, 1);
    for(x=0; x<cinfo.output_width||
        x<SCREEN_WIDTH; x++)
    {
        draw_pixel(x, y, COLOR(buffer[0][x*3],
                                buffer[0][x*3+1], buffer[0][x*3+2]));
    }
    y++;
}
```

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Camera on FL6410



Camera connection

**Shut down
power
before
plug/unplug
camera!**

The use of the camera: camera outward, frame angle alignment, then energized.

Camera driver in Linux

⌘ device name **/dev/video0**

⌘ `read()` on this device will get the screen pixels with resolution=320*240 in RGB565 format

`read(camerafd, cambuf, VIDEO_WIDTH * VIDEO_HEIGHT * VIDEO_DEPTH / 8)`

⌘ you need a buffer with size=320*240*2

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Exercise tips

Read JPEG

Decompression procedure

- 1 allocates space for the object and
 initialize JPEG
- 2 Specify the decompressed data source
- 3 Getting file information
- 4 To decompress setting parameters,
 including image size, color space
- 5 Start decompression
- 6 Remove the data
- 7 decompression is completed
- 8 release resources

```
/* LCD pixel : 480x272 */  
/* Camera    : 320x240 */  
#define VIDEO_WIDTH 320  
#define VIDEO_HEIGHT 240  
#define VIDEO_DEPTH 16
```

Write JPEG

Compression procedure

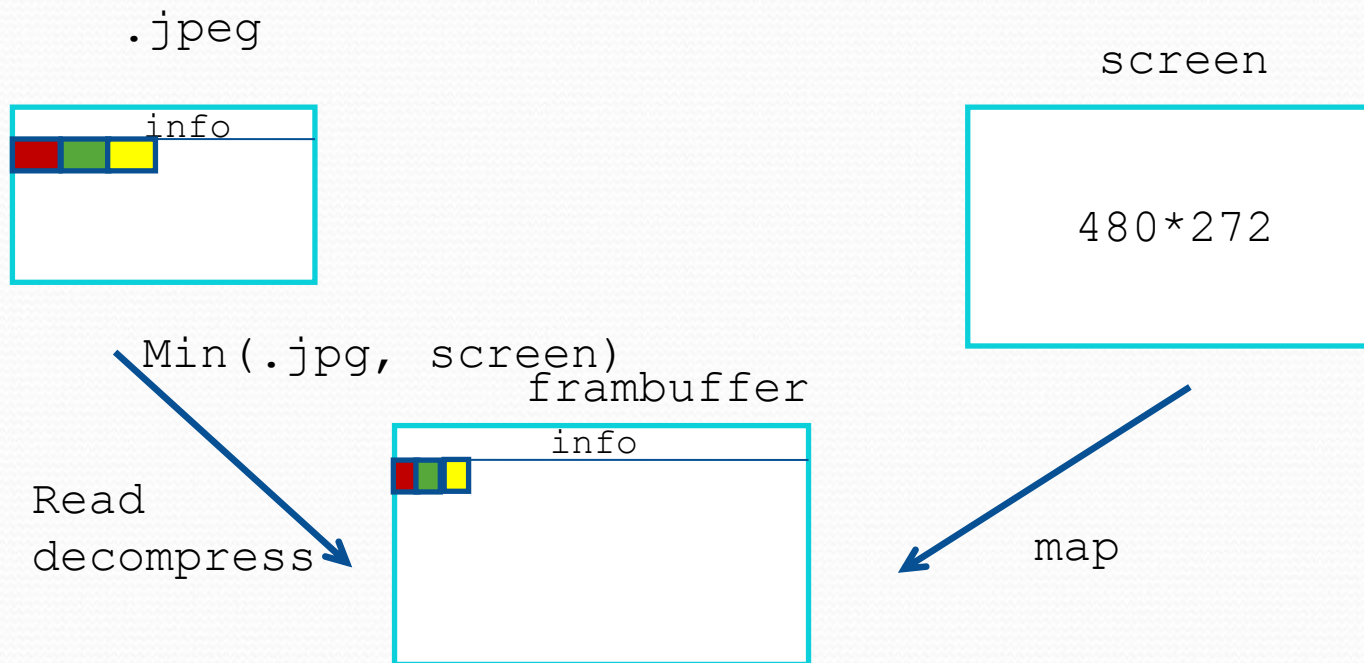
- 1 allocates space for the object and initialize JPEG
- 2 Specify the image output target
- 3 the compression set parameters,
 including the image size, color space
- 4 compression begins
- 5 write data
- 6 compression is completed
- 7 release resources

```
JSAMPROW row_pointer[1];  
/* libjpeg data structure  
for storing one row, that  
is, scanline of an image  
*/
```


Exercise 1

⌘ Display a JPEG image file in the LCD screen

Processing sketch



Exercise 2

- ⌘ display camera video in the screen

- ⌘ open Framebuffer device

- ⌘ get screen size, do mmap

- ⌘ open camera device

- ⌘ while(1)

- ⌘ read camera data to buffer

- ⌘ copy data to framebuffer

- ⌘ you can see what you get in LCD

Tips

```
⌘ struct v4l2_format fmt; //Frame format, such  
                           //as width, height
```

```
⌘ int type = V4L2_BUF_TYPE_VIDEO_CAPTURE;
```

```
⌘ fmt.type = V4L2_BUF_TYPE_VIDEO_CAPTURE;
```

```
⌘ fmt.fmt.pix.width = VIDEO_WIDTH;
```

```
⌘ fmt.fmt.pix.height = VIDEO_HEIGHT;
```

```
⌘ fmt.fmt.pix.depth = VIDEO_DEPTH;
```

```
⌘ fmt.fmt.pix.pixelformat= V4L2_PIX_FMT_RGB565;
```


Tips

```
/*open camera */
```

```
❧camerafd = open("/dev/video0",  
    O_RDWR);
```

```
/*Set video capture formats*/
```

```
❧ioctl(camerafd, VIDIOC_S_FMT, &fmt)
```

```
/*Start a video display functions*/
```

```
❧ioctl(camerafd, VIDIOC_STREAMON,  
    &type)
```

Exercise 3

⌘ Display Video on Screen

⌘ When user press a button, save current picture to a JPEG file

Processing sketch

