

Intelligent Systems



Lecture 1 Constraint Satisfaction Problems

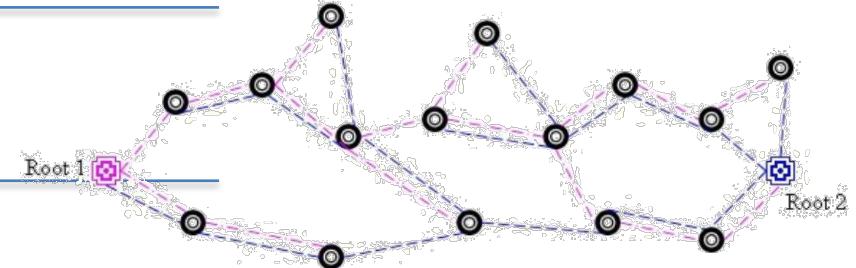
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Overview

1. Introduction to Constraint Satisfaction Problems
2. Problem Formulation
3. Backtracking for CSP
 1. MRV
 2. LCV
 3. Forward Checking
4. AC3
5. Local Search

1.1 Real World CSP Problems

Shortest path between several points



Optimal routing of data in Internet

Minimal cost planning for product shipping

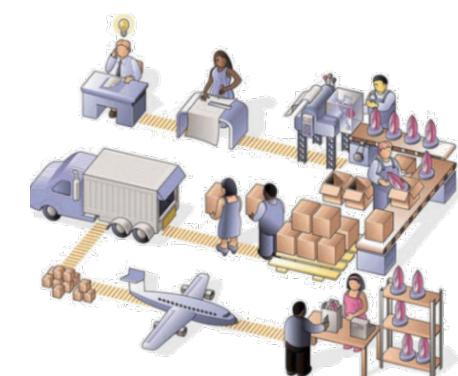


Optimal sequencing in process manufacturing

Task scheduling

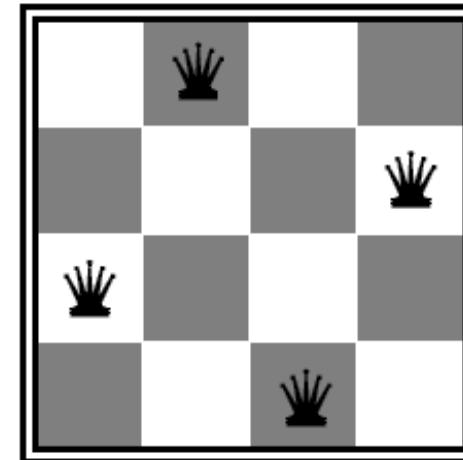
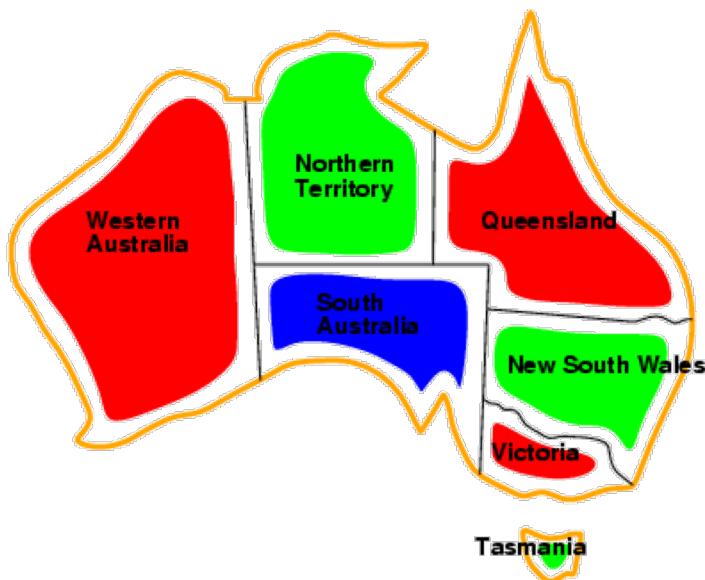
Optimal aircrew selection

<https://www.youtube.com/watch?v=y4RAYQjKb5Y>



1.1 CSP problems

- N-Queens
- Map Colouring
- Cryptography



$$\begin{array}{r}
 T \quad W \quad O \\
 + \\
 T \quad W \quad O \\
 \hline
 F \quad O \quad U \quad R
 \end{array}$$

1.1 CSP definition

Constraint Satisfaction Problem (CSP)

the solution is a correct assignment of values to each variable according to a set of constraints that must be satisfied

1.2 CSP formulation

Set of Variables $X_1 \dots X_n$

- whose values belong to a domain D_i

Set of Constraints $C_1 \dots C_m$

- the set of allowed values
- rules or properties that each variable must satisfy

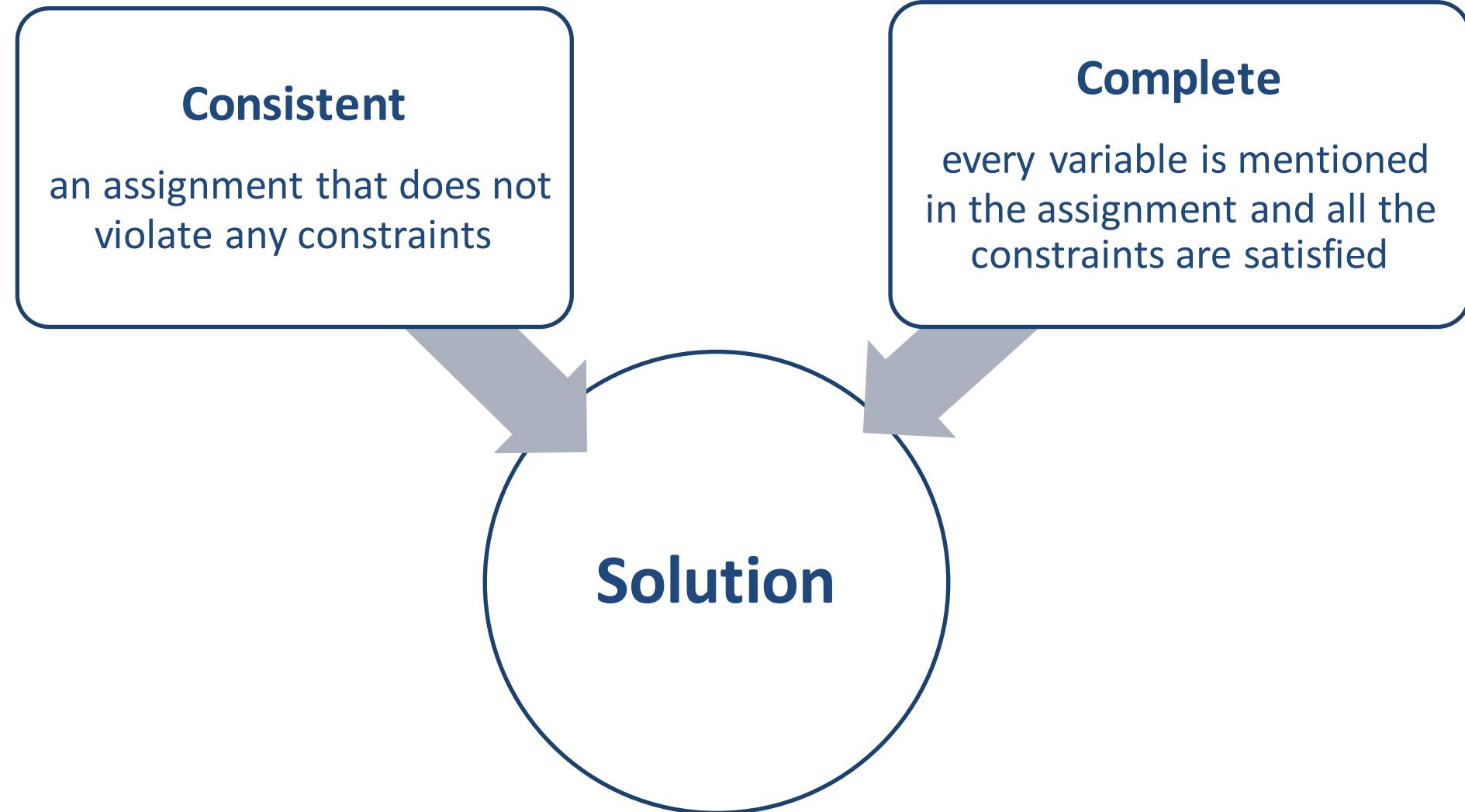
State:

- assignment of values to variables

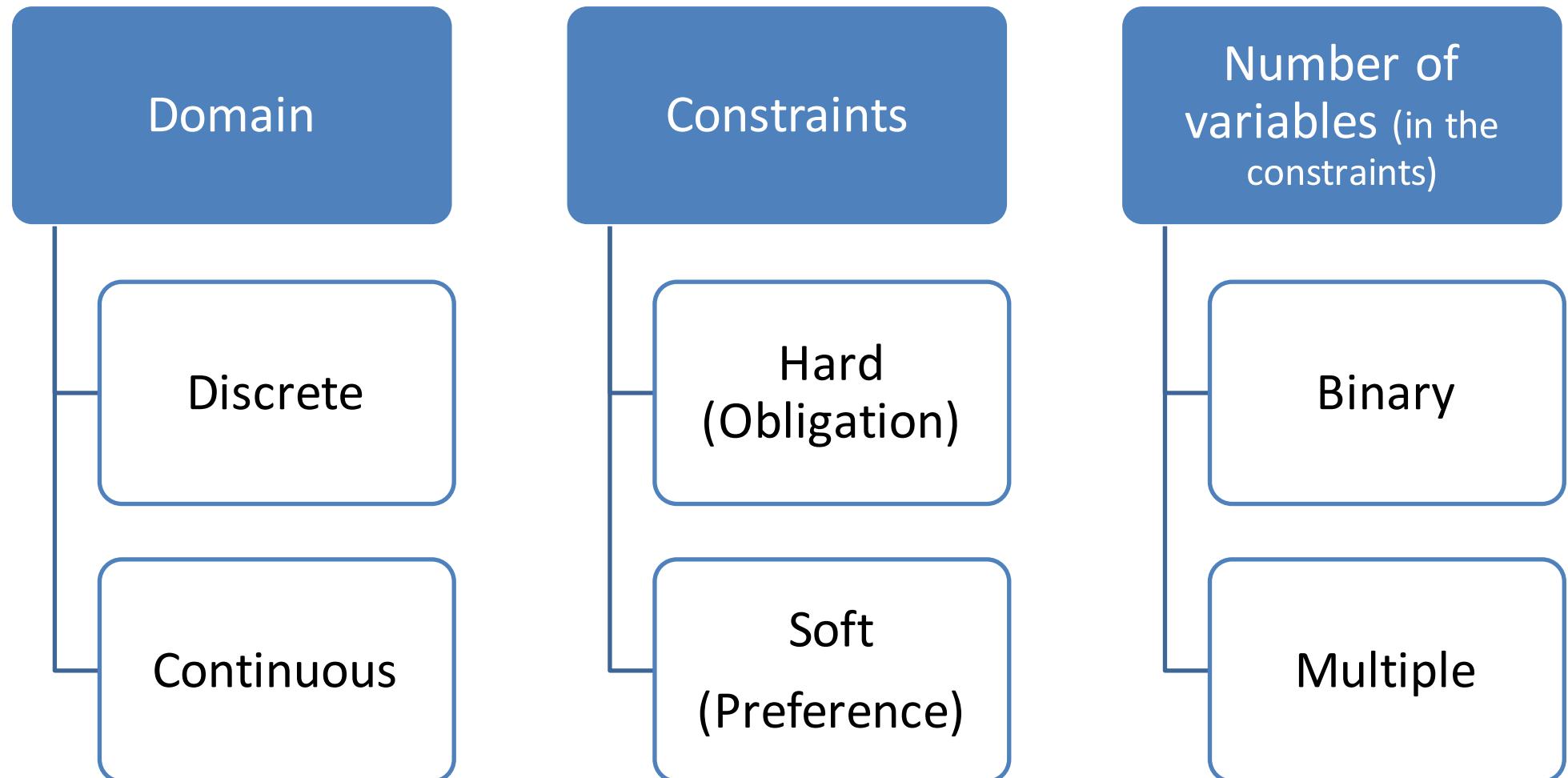
Solution:

- complete assignment that satisfies all the constraints

1.3 Assignments



1.4 CSP classification



1.5 CSP formulation example: Graph-colouring

- **GOAL:** Assign different colours to adjacent regions
- **Variables:** $R_1 \dots R_7$ each region
 - **Domain** of each variable: set of colours {red, green, blue}
 - **Constraints:**
 - Two adjacent regions must have different colours
 - $R_i \neq R_j$ If R_i and R_j are adjacent
 - **State:** any assignment, $R_1=\text{red}$
 - **Solution:** Consistent and complete assignment

$\{R_1=\text{red}, R_2=\text{green}, R_3=\text{red}, R_4=\text{blue},$
 $R_5=\text{green}, R_6=\text{red}, R_7=\text{green}\}$



1.5 CSP formulation example: Graph-colouring

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Discrete Domain

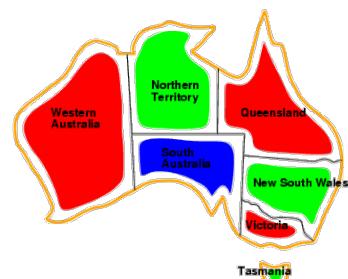
Hard Constraints

Binary Constraints

- **State:** any assignment, $R_1=\text{red}$

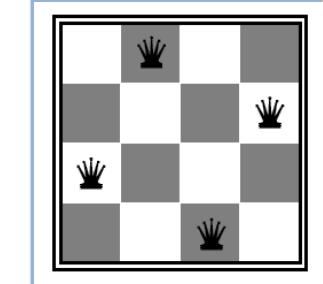
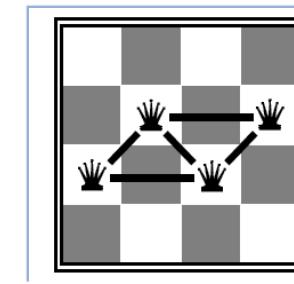
- **Solution:** Consistent and complete

$\{R_1=\text{red}, R_2=\text{green}, R_3=\text{red}, R_4=\text{blue},$
 $R_5=\text{green}, R_6=\text{red}, R_7=\text{green}\}$



1.5 CSP formulation example: N-Queens

- GOAL: Place N queens on an NxN chess board so that no queen can attack any other queen
 - **Variables:** Q_1, Q_2, Q_3, Q_4 representing each queen position (Queen 1 is always in column 1, Queen 2 in column 2, ...)
 - **Domain:** row numbers {1, 2, 3 y 4}
 - **Constraints:**
 - Different Row: $Q_i \neq Q_j$
 - Different Diagonal: $|Q_i - Q_j| \neq |i - j|$
 - **State:** Any assignment
 - **Solution:** $Q_1=3\ Q_2=1\ Q_3=4\ Q_4=2$



Discrete Domains, Hard Constraints, Binary Constraints

1.5 CSP formulation example: Criptoarithmetic

■ GOAL: assign different digits to the letters

■ **Variables:** each letter is a different variable, and two more variables are needed:

$$\{T, W, O, F, U, R, X_1, X_2\}$$

■ **Domain** for the letters: values from 0 to 9, for the carrying variables, values from 0 to 1

■ **Constraints:**

- Sum1: $O+O=R + 10 * X_1$
- Sum2: $X_1 + W + W = U + 10 * X_2$
- Sum3: $X_2 + T + T = O + 10 * F$

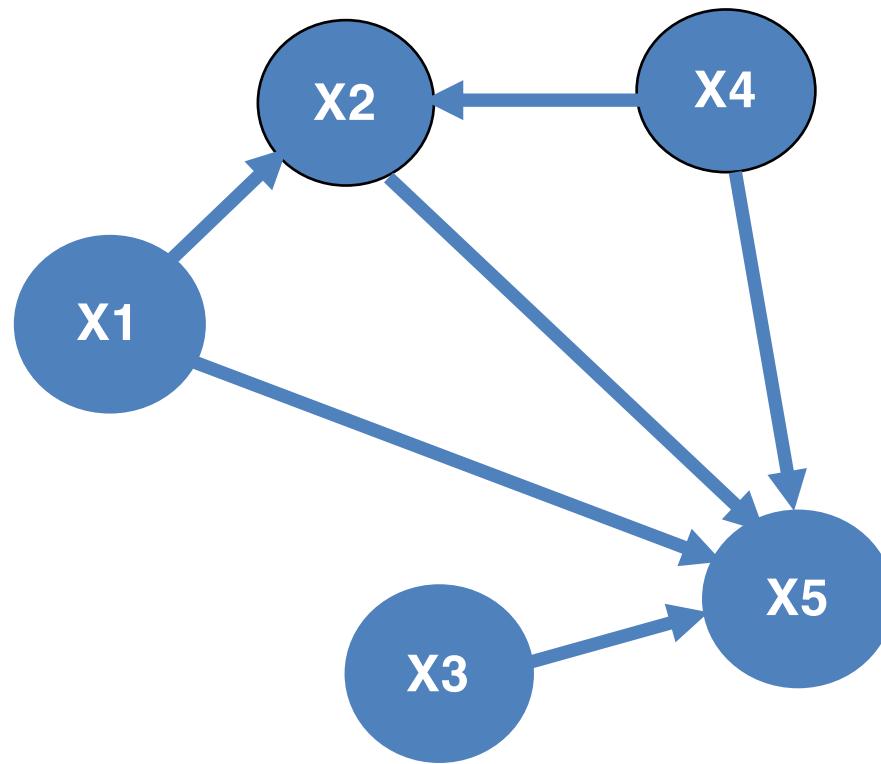
X_2	X_1			
T	W	O		
T	W	O		+
F	O	U	R	
0	1			
8	3	6		
8	3	6		+
1	6	7	2	

Hard and Multiple Constraints

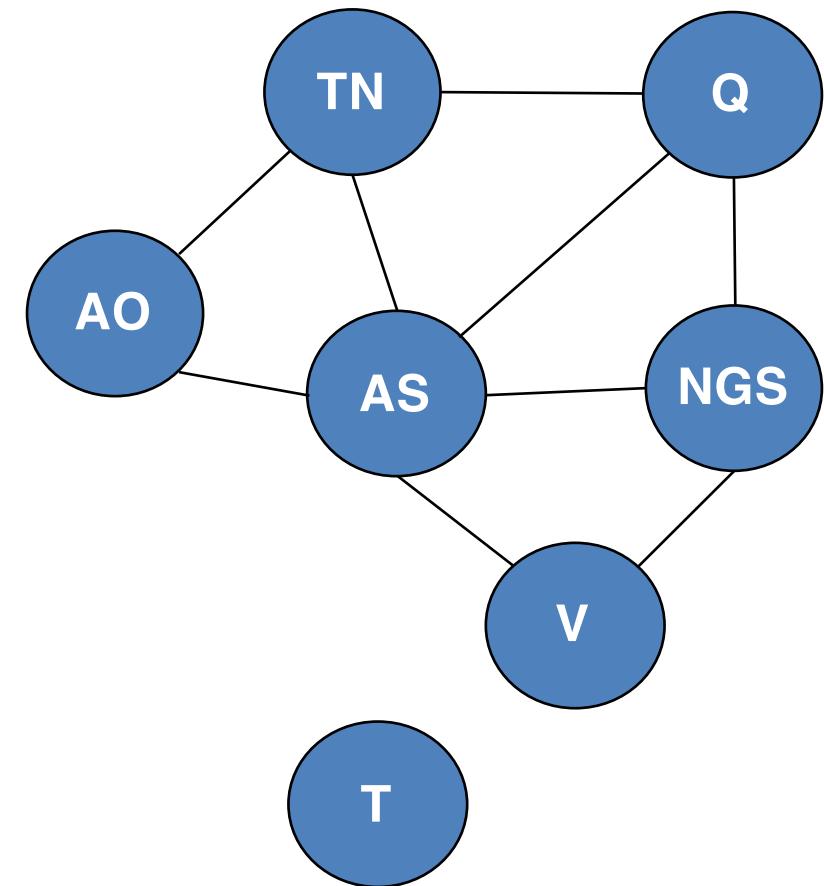
1.6 CSP representation

■ Binary constraint graph:

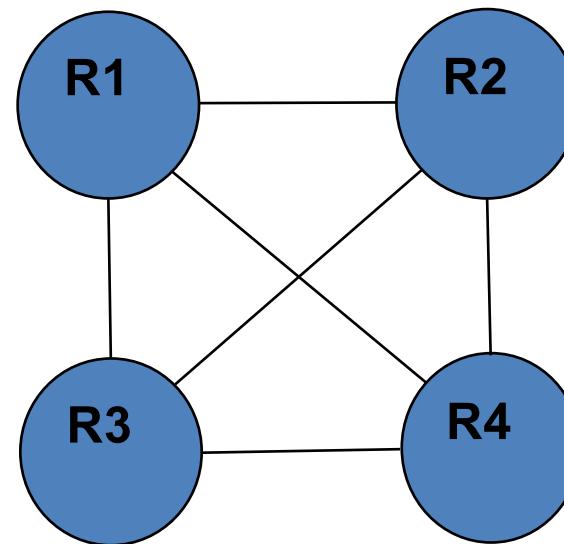
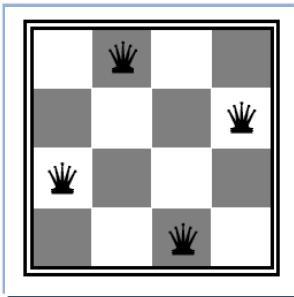
- **Nodes :** Variables
- **Arcs or edges:** Binary relations between variables



1.6 Binary constraint graph



1.7 N-Queens Example



2. CSP solving

■ Search strategies

Systematic search: Exploration of the state space

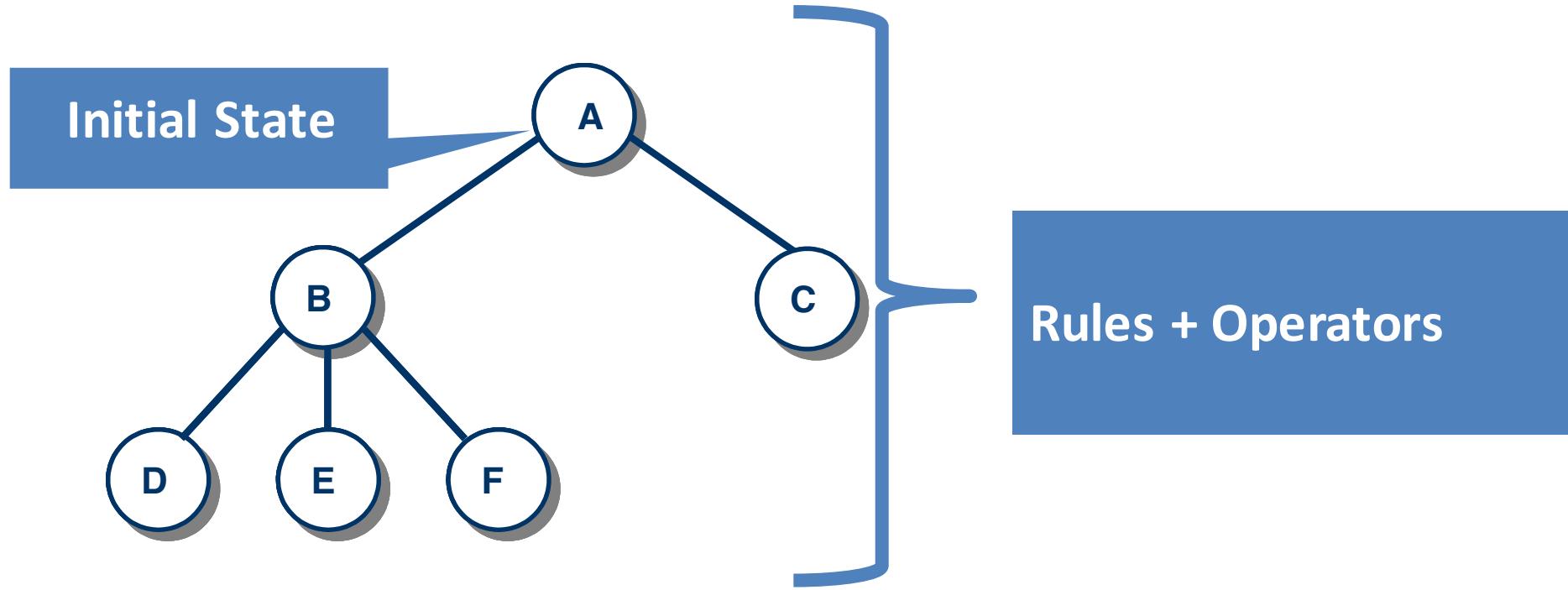
■ Consistency approaches

Inconsistent values are removed from variables domains

Help to reduce the state space

2. Search Strategies

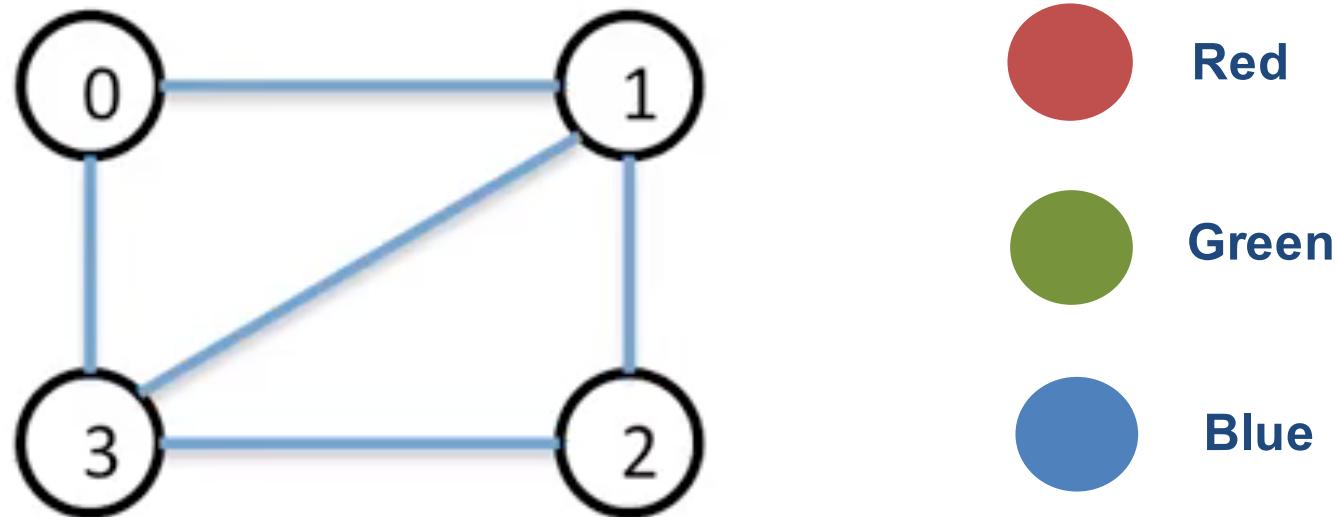
State Space



- Goal Test
- Path or Solution
- Solution Cost

2.1 Example

■ Graph colouring problem



2.1 CSP as state space search

Incremental formulation as a standard search problem:

- **Initial State:** empty assignment

{ V0, V1, V2, V3}

{ , , , }

- **List of Actions:** Assign a color: Red, Green or Blue

- **Successor Function:** assignment of a value v to an unassigned variable when this action does not conflict with previous assignments
 - **isSafe** function to guarantee consistent assignments

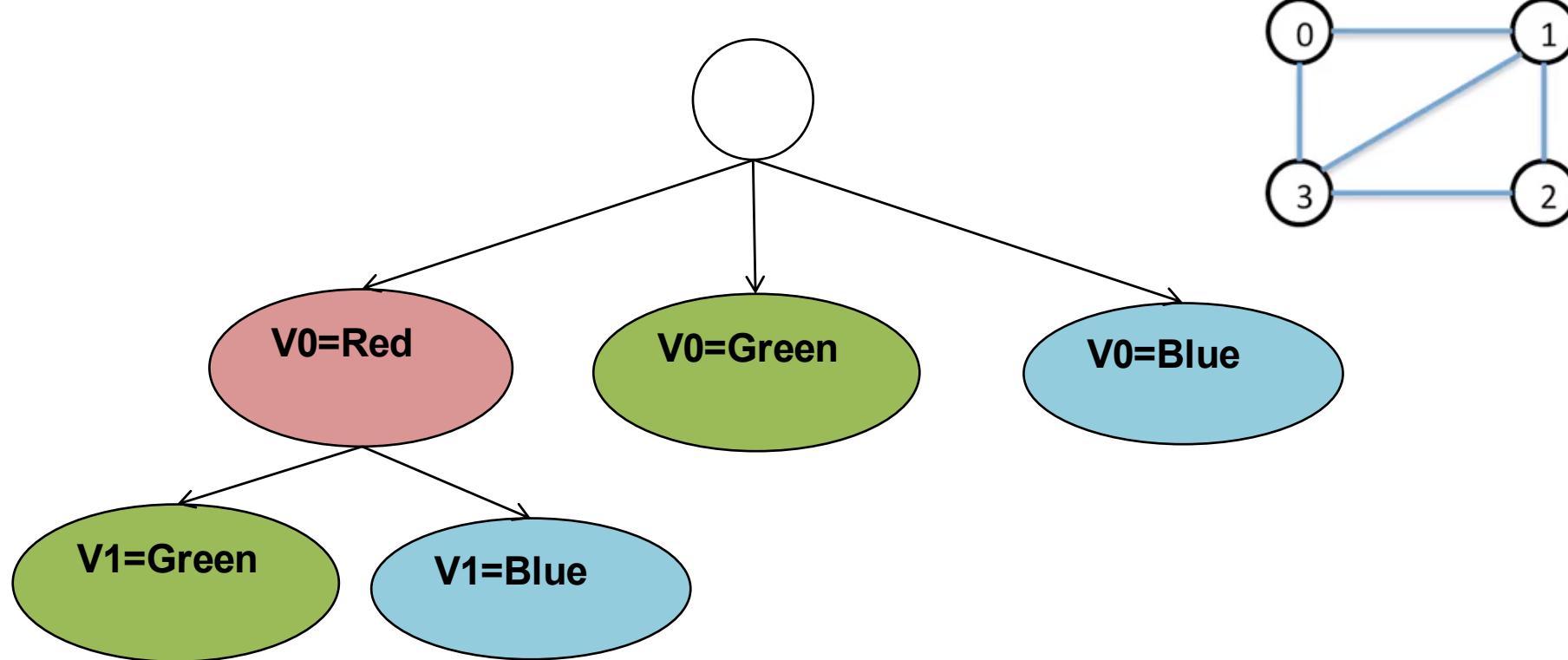
{**Red** , , , }

{ **Red** , **Green**, , }

- **Goal Test:** the current assignment is complete

2.1 CSP as state space search

Incremental formulation as a standard search problem:



¿Depth or Breadth Search?

2.2 Some considerations

- FINITE DEPTH: the number of variables determines the solution depth
- COMMUTATIVITY: assignment order is irrelevant
 - Depth-first search for CSPs with single-variable assignments is called backtracking search
- CONTROL OF REPEATED STATES is unnecessary

2.3 Backtracking

Special depth search ...

- Consider the variables in some order
- Pick an unassigned variable and give it a provisional value such that it is consistent with all of the constraints
 - If no such assignment can be made, we've reached a dead end and we need to backtrack to the previous variable
- Continue this process until a solution is found or all possible assignments have been exhausted

2.3 Backtracking Algorithm

```

function BacktrackingSearch(csp) returns solution or failure
    return Recursive-Backtracking(csp)
function [csp]= Recursive-Backtracking(csp)
//returns solution/failure and the assignment
    var←SELECT-UNASSIGNED-VARIABLE(csp)
    if Notempty(var)
        values_list←ORDER-DOMAIN-VALUES(var,csp)
        while Not complete(csp.assignment) & Not empty(values_list)
            value←next(values_list)
            if consistent (csp,value,vari) then
                add {var←value} to csp.assignment
                [csp]=Recursive_Backtracking(csp)
            end
        end %while
    end
end %function

```