

Notes on Riemann Surfaces

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Chapter 1

Generalities on Riemann Surfaces

1.1 The definition of a Riemann Surface

Definition 1.1.1. An n -dimensional *topological manifold* is a Hausdorff, second countable, topological space X such that every point $p \in X$ has an open neighbourhood homeomorphic to an open set of \mathbb{R}^n . A 1-dimensional topological manifold is called a (topological) *curve*. A 2-dimensional topological manifold is called a (topological) *surface*.

Definition 1.1.2. A *Riemann surface* is a surface admitting an open cover \mathcal{U} and homeomorphisms $\varphi_U : U \rightarrow \mathbb{C}$, for every $U \in \mathcal{U}$ such that $\varphi_U \circ \varphi_V^{-1} : \mathbb{C} \rightarrow \mathbb{C}$ is a biholomorphism (bijective, holomorphic and with an holomorphic inverse) for every $U, V \in \mathcal{U}$.

We say that a function $f : X \rightarrow \mathbb{C}$ is *holomorphic* at some point $p \in X$ if there exists an open set $U \in \mathcal{U}$ such that $f \circ \varphi_U^{-1} : \mathbb{C} \rightarrow \mathbb{C}$ is holomorphic at $\varphi_U(p)$. We say that f is holomorphic at a subset $S \subset X$ if it is holomorphic at p for every $p \in S$. In particular, we say that f is holomorphic at X if it is holomorphic for every $p \in X$. We denote by $\mathcal{O}_X(S)$ the set of holomorphic functions at S .

[dibujo]

Definition 1.1.3. A *holomorphic (or complex-analytic) structure* \mathcal{O}_X on a topological surface X assigns to every open set $U \subset X$ a set of continuous functions $\mathcal{O}_X(U) \subset C(U, \mathbb{C})$ in such a way that:

1. For every $p \in X$, there exists an open neighbourhood U of p and a homeomorphism $\varphi_U : U \rightarrow \mathbb{C}$ such that, for any open set $V \subset U$,

$$f \in \mathcal{O}_X(V) \text{ if and only if } f \circ \varphi_U^{-1} : \mathbb{C} \rightarrow \mathbb{C} \text{ is holomorphic.}$$

The pair (U, φ_U) is called a *holomorphic chart at p* .

2. If $f : U \rightarrow \mathbb{C}$, where $U = \bigcup_i U_i$ and U_i is open in X , then $f \in \mathcal{O}_X(U)$ if and only if $f|_{U_i} \in \mathcal{O}_X(U_i)$ for every i .

Of course, given a Riemann surface X , we have an holomorphic structure on X , namely, \mathcal{O}_X . The converse is also true, if we have an holomorphic structure \mathcal{O}_X on a topological surface X , we can take the open cover $\mathcal{U} = \{U_p | p \in X\}$, where U_p is the open neighbourhood of p whose existence is guaranteed by condition 1. Indeed, this open cover turns X into a Riemann surface: for every $U, V \in \mathcal{U}$, $\varphi_U \circ \varphi_V^{-1} : \mathbb{C} \rightarrow \mathbb{C}$ is a biholomorphism. This is true because, since $U \cap V \subset U$ and $\varphi_U \circ \varphi_U^{-1} = \text{id}_{\mathbb{C}}$, $\varphi_U \in \mathcal{O}_X(U \cap V)$, but this implies that $\varphi_U \circ \varphi_V^{-1}$ is holomorphic. The same argument shows that the inverse $(\varphi_U \circ \varphi_V^{-1})^{-1} = \varphi_V \circ \varphi_U^{-1}$ is holomorphic and we have a biholomorphism. Consequently, we can redefine a Riemann surface:

Definition 1.1.4. A *Riemann surface* is a pair (X, \mathcal{O}_X) , where X is a topological surface and \mathcal{O}_X is an holomorphic structure on X .

Definition 1.1.5. Let $F : X \rightarrow Y$ be a continuous mapping between two surfaces, and \mathcal{O}_X a holomorphic structure on X . We define the *pushforward holomorphic structure* $F_*\mathcal{O}_X$ as the holomorphic structure on Y that assigns to every open set $U \subset Y$ the set $F_*\mathcal{O}_X(U)$ such that

$$f \in F_*\mathcal{O}_X(U) \text{ if and only if } f \circ F \in \mathcal{O}_X(F^{-1}U).$$

Definition 1.1.6. Let (X, \mathcal{O}_X) and (Y, \mathcal{O}_Y) be Riemann surfaces and $F : X \rightarrow Y$ a continuous mapping. We say that F is a *holomorphism* or a *morphism of Riemann surfaces* if $F_*\mathcal{O}_X = \mathcal{O}_Y$. We say that F is a *biholomorphism* or an *isomorphism of Riemann surfaces* if it is bijective, a holomorphism and F^{-1} is a holomorphism. We can then define the *category of Riemann surfaces* whose objects are Riemann surfaces and whose morphisms are the holomorphisms between Riemann surfaces.

Remark. Since this work will be mainly centered in the study of Riemann surfaces, we have only considered Riemann surfaces in our definitions. Nevertheless, all these notions can be easily generalized to define *n-dimensional complex manifolds*, just changing \mathbb{C} by \mathbb{C}^n in the definition of Riemann surface (for a reference on what a multivariable holomorphic map is and on other generalities of complex calculus on several variables, such as the Hartogs theorem, check out [Griffiths-Harris]). The definition of a holomorphic structure \mathcal{O}_X can be immediately generalized to an *n-dimensional topological manifold* X and we can see a complex manifold as a pair (X, \mathcal{O}_X) . The equivalence of the two definitions is analogous to the case of Riemann surfaces, although in this case we have to consider the coordinate projections $\text{pr}_i : \mathbb{C}^n \rightarrow \mathbb{C}$. This way, Riemann surfaces can be thought just as 1-dimensional complex manifolds, that is, complex curves.

Note also that changing the word “holomorphic” by “smooth” and \mathbb{C}^n by \mathbb{R}^{2n} , we can define *smooth manifolds* and *differentiable structures* on a similar fashion.

1.2 The tangent space

Let X be a Riemann surface and $p \in X$. We define the *set of germs of holomorphic functions at p* as

$$\mathcal{O}_{X,p} = \varinjlim_{p \in U \subset X \text{ open}} \mathcal{O}_X(U).$$

That is, $\mathcal{O}_{X,p}$ is the quotient of set of functions that are holomorphic on some neighbourhood of p by the equivalence relation that identifies two functions if they coincide on some other neighbourhood of p . We define $\mathbb{T}_p X$ the *holomorphic tangent space of X at p* as the space of derivations on $\mathcal{O}_{X,p}$; i.e. \mathbb{C} -linear maps $D : \mathcal{O}_{X,p} \rightarrow \mathbb{C}$ satisfying the Leibniz rule

$$D(fg) = D(f)g(z) + f(z)D(g),$$

for all $f, g \in \mathcal{O}_{X,p}$. This tangent space is a 1-dimensional complex vector space. To give a basis of this space, we can fix a holomorphic chart (U, φ_U) at p so that $\mathbb{T}_p X$ is generated by the derivation

$$\begin{aligned} \partial_z|_p : \mathcal{O}_{X,p} &\longrightarrow \mathbb{C} \\ f &\longmapsto \frac{\partial(f \circ \varphi_U^{-1})}{\partial z}(z), \end{aligned}$$

with $z = \varphi_U(p) \in \mathbb{C}$.

Every holomorphic function $f : \mathbb{C} \rightarrow \mathbb{C}$ is in particular a smooth mapping $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, thus a holomorphic structure on a topological surface X gives in particular a differentiable structure, turning X into a 2-dimensional smooth manifold. By means of the germs of smooth functions, we can define in a similar way the “usual” tangent space at p , $T_p X$. Taking the same holomorphic chart (U, φ_U) and writing $\varphi_U(p) = z = x + iy$, we see that $T_p X_{\mathbb{C}}$ is a 2-dimensional real vector space generated by $\{\partial_x|_p, \partial_y|_p\}$. In order to relate $T_p X$ with $T_p X$, we consider the complexification

$$T_p X_{\mathbb{C}} = T_p X \otimes_{\mathbb{R}} \mathbb{C},$$

and introduce the derivations

$$\partial_z|_p = \frac{1}{2}(\partial_x|_p - i\partial_y|_p), \quad \partial_{\bar{z}}|_p = \frac{1}{2}(\partial_x|_p + i\partial_y|_p).$$

This gives us a decomposition

$$T_p X_{\mathbb{C}} = T_p^{1,0} X \oplus T_p^{0,1} X,$$

where $T_p^{1,0} X$ is the subspace spanned by $\partial_z|_p$ and $T_p^{0,1} X$ the one spanned by $\partial_{\bar{z}}|_p$. Lets consider now a smooth mapping $f : X \rightarrow \mathbb{C}$ of the form

$$\begin{aligned} f \circ \varphi_U^{-1} : \mathbb{C} &\longrightarrow \mathbb{C} \\ x + iy &\longmapsto u(x, y) + iv(x, y). \end{aligned}$$

Then

$$\begin{aligned} \partial_{\bar{z}}|_p f &= \frac{1}{2} \left[\left(\frac{\partial u}{\partial x}(z) + i \frac{\partial v}{\partial x}(z) \right) + i \left(\frac{\partial u}{\partial y}(z) + i \frac{\partial v}{\partial y}(z) \right) \right] \\ &= \frac{1}{2} \left[\left(\frac{\partial u}{\partial x}(z) - \frac{\partial v}{\partial y}(z) \right) + i \left(\frac{\partial u}{\partial y}(z) + \frac{\partial v}{\partial x}(z) \right) \right]. \end{aligned}$$

Now, if f is also holomorphic at p , it must satisfy the Cauchy-Riemann equations:

$$\begin{aligned} \frac{\partial u}{\partial x}(z) &= \frac{\partial v}{\partial y}(z), \\ \frac{\partial u}{\partial y}(z) &= -\frac{\partial v}{\partial x}(z). \end{aligned}$$

Thus, we have that $\partial_{\bar{z}}|_p f = 0$. In conclusion, we get that

$$T_p X = T_p^{1,0} X = \text{span}(\partial_z|_p).$$

Passing to differential forms, let us consider the complexified cotangent space $T_p^* X_{\mathbb{C}} = T_p^* X \otimes_{\mathbb{R}} \mathbb{C}$. Taking the dual elements of the basis $\{\partial_z|_p, \partial_{\bar{z}}|_p\}$ we get the 1-forms $\{dz_p, d\bar{z}_p\}$. Thus, from the set of (real-valued) differential 1-forms in a chart (U, φ_U) , $\Omega^1(U, \mathbb{R})$, we can define the set of *complex-valued differential 1-forms in U* ,

$$\Omega^1(U) = \Omega^1(U, \mathbb{C}) = \Omega^1(U, \mathbb{R}) \otimes_{\mathbb{R}} \mathbb{C}.$$

In general, we define $\Omega^k(U) = \Omega^k(U, \mathbb{C}) = \Omega^k(U, \mathbb{R}) \otimes_{\mathbb{R}} \mathbb{C}$. Of course, $\Omega^k(U) = \bigwedge^k \Omega^1(U)$. Dually to what we did with the complexified tangent space, we can decompose $T_p^* X_{\mathbb{C}} = (T_p^{1,0} X)^* \oplus (T_p^{0,1} X)^*$, thus getting

$$\Omega^1(U) = \Omega^{1,0}(U) \oplus \Omega^{0,1}(U).$$

Equivalently, what we are saying is that every complex 1-form $\omega \in \Omega^1(U)$ can be written as

$$\omega = \omega_{1,0}dz + \omega_{0,1}d\bar{z},$$

with $\omega_{1,0}, \omega_{0,1} : U \rightarrow \mathbb{C}$ smooth functions. Taking exterior powers we can extend this decomposition to higher degree forms, getting a bigraduation

$$\Omega^k(U) = \bigoplus_{p+q=k} \Omega^{p,q}(U),$$

with

$$\Omega^{p,q}(U) = \left(\bigwedge^p \Omega^{1,0}(U) \right) \wedge \left(\bigwedge^q \Omega^{0,1}(U) \right).$$

Anyway, recall that X is a Riemann surface, so $\Omega^k(U) = 0$ for $k > 2$. Thus, the only non-trivial case for this decomposition that we have not studied yet is the case of 2-forms,

$$\Omega^2(U) = \Omega^{2,0}(U) \oplus \Omega^{1,1}(U) \oplus \Omega^{0,2}(U) = \Omega^{1,1}(U),$$

since $dz \wedge dz = d\bar{z} \wedge d\bar{z} = 0$. That is, every 2-form $\omega \in \Omega^2(U)$ can be written as

$$\omega = \omega_{1,1}dz \wedge d\bar{z},$$

with $\omega_{1,1} : U \rightarrow \mathbb{C}$ an smooth function.

This decomposition also gives a splitting of the exterior differential $d : \Omega^k(U) \rightarrow \Omega^{k+1}(U)$. For a 0-form $f \in \Omega^0(U) = \Omega^{0,0}(U) = C^\infty(U, \mathbb{C})$, we have

$$df = \partial_z f dz + \partial_{\bar{z}} f d\bar{z}.$$

We can define then the operators

$$\begin{aligned} \partial : \Omega^0(U) &\longrightarrow \Omega^{1,0}(U) \\ f &\longmapsto \partial_z f dz, \end{aligned}$$

and

$$\begin{aligned} \bar{\partial} : \Omega^0(U) &\longrightarrow \Omega^{0,1}(U) \\ f &\longmapsto \partial_{\bar{z}} f d\bar{z}, \end{aligned}$$

so that

$$df = \partial f + \bar{\partial} f.$$

For a 1-form $\omega = \omega_{1,0}dz + \omega_{0,1}d\bar{z}$, we get

$$d\omega = \partial_{\bar{z}}\omega_{1,0}d\bar{z} \wedge dz + \partial_z\omega_{0,1}dz \wedge d\bar{z} = (\partial_z\omega_{0,1} - \partial_{\bar{z}}\omega_{1,0})dz \wedge d\bar{z}.$$

We can define then the operators

$$\begin{aligned} \bar{\partial} : \Omega^{1,0}(U) &\longrightarrow \Omega^{1,1}(U) \\ \omega dz &\longmapsto \partial_{\bar{z}}\omega d\bar{z} \wedge dz \end{aligned}$$

and

$$\begin{aligned} \partial : \Omega^{0,1}(U) &\longrightarrow \Omega^{1,1}(U) \\ \omega d\bar{z} &\longmapsto \partial_z\omega dz \wedge d\bar{z}, \end{aligned}$$

and the projections

$$\begin{aligned} \text{pr}_{1,0} : \Omega^1(U) &\longrightarrow \Omega^{1,0}(U) \\ \omega_{1,0}dz + \omega_{0,1}d\bar{z} &\longmapsto \omega_{1,0}dz \end{aligned}$$

and

$$\begin{aligned} \text{pr}_{0,1} : \Omega^1(U) &\longrightarrow \Omega^{0,1}(U) \\ \omega_{1,0}dz + \omega_{0,1}d\bar{z} &\longmapsto \omega_{0,1}d\bar{z}, \end{aligned}$$

so that

$$d\omega = \bar{\partial}\text{pr}_{1,0}\omega + \partial\text{pr}_{0,1}\omega.$$

Diagrammatically, we have

$$\begin{array}{ccccccc} 0 & \longrightarrow & \mathbb{C} & \hookrightarrow & \Omega^0(U) & \xrightarrow{d} & \Omega^1(U) \xrightarrow{d} \Omega^2(U) \xrightarrow{d} 0 \\ & & & & \nearrow \partial & & \searrow \bar{\partial} \\ & & & & \Omega^{0,0}(U) & & \Omega^{1,0}(U) \xrightarrow{\partial} \Omega^{1,1}(U) \xrightarrow{\partial} 0 \\ & & & & \searrow \bar{\partial} & & \nearrow \partial \\ & & & & \Omega^{0,1}(U) & & \Omega^{1,1}(U) \xrightarrow{\bar{\partial}} 0 \end{array}$$

Note in particular the segment

$$\Omega^{1,0}(U) \xrightarrow{\bar{\partial}} \Omega^{1,1}(U) \xrightarrow{\bar{\partial}} 0,$$

and consider the set of holomorphic differential 1-forms in U :

$$\Omega^1(U) = \ker(\bar{\partial} : \Omega^{1,0} \rightarrow \Omega^{1,1}).$$

In particular, an element in $\Omega^1(U)$ is of the form

$$\omega dz,$$

where $\omega : U \rightarrow \mathbb{C}$ is a holomorphic function (so that $\partial_{\bar{z}}\omega = 0$). We also have the following result [Griffiths-Harris]:

Proposition 1.2.1 ($\bar{\partial}$ -Poincaré Lemma). *Let $D \subset \mathbb{C}$ be an open disk and $\omega \in C^\infty(\bar{D})$ a function. The function*

$$\alpha(z) = \frac{1}{2\pi i} \int_D \frac{\omega(w)}{w - z} dw \wedge d\bar{w},$$

is in $C^\infty(D)$ and satisfies

$$\frac{\partial \alpha}{\partial \bar{z}} = \omega.$$

Therefore, for every $\omega d\bar{z} \wedge dz \in \Omega^{1,1}(U)$ we can choose a disk $D \subset U$ and the function

$$\alpha(z) = \frac{1}{2\pi i} \int_D \frac{\omega(w)}{w-z} dw \wedge d\bar{w}$$

satisfies $\partial_{\bar{z}}\alpha = \omega$, so that

$$\omega d\bar{z} \wedge dz = \bar{\partial}(\alpha dz),$$

in D . In conclusion, the mapping $\bar{\partial} : \Omega^{1,0}(D) \rightarrow \Omega^{1,1}(D)$ is surjective and the sequence

$$0 \longrightarrow \Omega^1(D) \hookrightarrow \Omega^{1,0}(D) \xrightarrow{\bar{\partial}} \Omega^{1,1}(D) \xrightarrow{\bar{\partial}} 0$$

is exact.

1.3 Sheaves and cohomology

1.3.1 Presheaves and sheaves

Let X be a topological space and consider the category $\mathbf{Op}(X)$ whose objects are the nonempty open sets in X and such that, if $U, V \subset X$ are open sets

$$\mathrm{Hom}_{\mathbf{Op}(X)}(U, V) = \begin{cases} U \hookrightarrow V, & \text{if } U \subset V, \\ \emptyset, & \text{otherwise.} \end{cases}$$

Definition 1.3.1. A *presheaf* over a category \mathcal{C} is a contravariant functor $\mathcal{F} : \mathbf{Op}(X) \rightarrow \mathcal{C}$.

In other words, a presheaf assigns to every nonempty open set $U \subset X$ an object $\mathcal{F}(U)$ and, to every pair of sets U and V such that $V \subset U$, a morphism

$$r_V^U : \mathcal{F}(U) \rightarrow \mathcal{F}(V),$$

satisfying that $r_U^U = \mathrm{id}_U$ and, if $W \subset V \subset U$, $r_W^U = r_W^V \circ r_V^U$. If $\mathcal{C} = \mathbf{Ring}, \mathbf{Grp}, \mathbf{Set}$ or \mathbf{Ab} , we say that \mathcal{F} is a presheaf of rings, groups, sets or abelian groups, respectively. From now on \mathcal{C} will be a category of sets like one of the list that we just stated. In this case, the elements of a set $\mathcal{F}(U)$ will be called *sections of \mathcal{F} over U* and, if $s \in \mathcal{F}(U)$ and $V \subset U$, we will write $s|_V = r_V^U(s)$.

Definition 1.3.2. A presheaf \mathcal{F} is called a *sheaf* if for every open cover \mathcal{U} of any open set $U \subset X$, the following conditions are satisfied:

1. *Axiom of locality:* If $s, t \in \mathcal{F}(U)$ and $s|_V = t|_V$ for every $V \in \mathcal{U}$, then $s = t$.
2. *Axiom of gluing:* Consider a family of sections $\{s_V : V \in \mathcal{U}\}$. If for every $V, W \in \mathcal{U}$ such that $V \cap W \neq \emptyset$ we have

$$s_V|_{V \cap W} = s_W|_{V \cap W},$$

then there exists an $s \in \mathcal{F}(U)$ such that $s|_V = s_V$ for all $V \in \mathcal{U}$.

Definition 1.3.3. If \mathcal{F} and \mathcal{G} are two presheaves (respectively, two sheaves), a morphism of presheaves (sheaves) is a natural transformation $h : \mathcal{F} \rightarrow \mathcal{G}$.

In other words, if \mathcal{F} and \mathcal{G} are two sheaves or two presheaves a morphism $h : \mathcal{F} \rightarrow \mathcal{G}$ is a collection of morphisms $h_U : \mathcal{F}(U) \rightarrow \mathcal{G}(U)$ for each open set $U \subset X$ such that the following diagram commutes

$$\begin{array}{ccc}
\mathcal{F}(U) & \xrightarrow{h_U} & \mathcal{G}(U) \\
\downarrow r_V^U & & \downarrow r_V^U \\
\mathcal{F}(V) & \xrightarrow{h_V} & \mathcal{G}(V),
\end{array}$$

for any $V \subset U \subset X$ open sets. If the maps h_U are inclusions, \mathcal{F} is said to be a *subpresheaf* or a *subsheaf* of \mathcal{G} .

Example 1.3.4. Let us define some of the sheaves that we are going to consider during these notes.

1. If X is any topological space, we can consider the *presheaf of Y -valued continuous mappings on X* , denoted by $C_X(-, Y)$, where Y is any topological space: for every open set $U \subset X$, $C_X(U, Y)$ is the set of continuous mappings $U \rightarrow Y$ and the morphisms r_V^U are just the restrictions of functions. This presheaf clearly satisfies the axioms of locality and gluing, so it is a sheaf. If $Y = \mathbb{R}$ or \mathbb{C} , $C_X(-, Y)$ is called the *sheaf of real-valued (respectively, complex-valued) continuous functions*.
2. If X is a smooth manifold, we can consider the *sheaf of Y -valued smooth mappings on X* , denoted by $C_X^\infty(-, Y)$, where Y is any smooth manifold as the subsheaf of $C_X(-, Y)$ of continuous mappings that are smooth. If $Y = \mathbb{R}$ or \mathbb{C} , this is called the *sheaf of real-valued (respectively, complex-valued) smooth functions*.
3. If X is a complex manifold, we consider the *sheaf of holomorphic functions on X* , denoted by \mathcal{O}_X as the subsheaf of $C_X^\infty(-, \mathbb{C})$ of functions that are holomorphic. Note that this sheaf is precisely the holomorphic structure on X , this is why it is also called the *structure sheaf on X* . We can also consider the subsheaf \mathcal{O}_X^* of \mathcal{O}_X of nonzero holomorphic functions.
4. If X is a Riemann surface, we consider the *sheaf of smooth complex differential forms of type (p, q)* , denoted by $\Omega_X^{p,q}$: to any open subset $U \subset X$ we assign the set $\Omega_X^{p,q}(U) = \Omega^{p,q}(U)$.
5. If X is a Riemann surface, we consider the *sheaf of holomorphic differential 1-forms*, denoted by Ω_X^1 as the subsheaf of $\Omega_X^{1,0}$ of 1-forms that are holomorphic. \square

Example 1.3.5 (Presheaves that are not sheaves). Consider $\mathbb{C}^* = \mathbb{C} \setminus \{0\}$ and the morphism of sheaves $\exp : \mathcal{O}_{\mathbb{C}^*} \rightarrow \mathcal{O}_{\mathbb{C}^*}^*$ defined by

$$\begin{aligned}
\exp_U : \mathcal{O}_{\mathbb{C}^*}(U) &\longrightarrow \mathcal{O}_{\mathbb{C}^*}^*(U) \\
f &\longmapsto e^{2\pi i f}.
\end{aligned}$$

Note now that the complex logarithm is not globally defined on \mathbb{C}^* but it is defined on every simply connected open subset $U \subset \mathbb{C}^*$. Thus, if we consider the function $f(z) = z$, $f \in \mathcal{O}_{\mathbb{C}^*}^*(\mathbb{C}^*)$ and $f \notin \exp(\mathcal{O}_{\mathbb{C}^*}(\mathbb{C}^*))$, but $f|_U \in \exp(\mathcal{O}_{\mathbb{C}^*}(U))$ if $U \subset \mathbb{C}^*$ is simply connected. We can define then the presheaf $\exp(\mathcal{O}_{\mathbb{C}^*}(-))$ with the natural restriction morphisms but we can cover \mathbb{C}^* by simply connected open sets U where f has a logarithm, so that $f|_U \in \exp(\mathcal{O}_{\mathbb{C}^*}(U))$ but these $f|_U$ are not restrictions of a globally defined $f \in \exp(\mathcal{O}_{\mathbb{C}^*}(\mathbb{C}^*))$. Therefore, this presheaf violates the axiom of gluing, so it is not a sheaf. Dually, we can consider the presheaf $\text{coker}(\exp)$ defined by

$$\text{coker}(\exp)(U) = \mathcal{O}_{\mathbb{C}^*}^*(U) / \exp(\mathcal{O}_{\mathbb{C}^*}(U)).$$

By the same argument as before, $f|_U = 0 \in \text{coker}(\exp)(U)$ for every $U \subset \mathbb{C}^*$ simply connected, but $f \neq 0$ in $\text{coker}(\exp)(\mathbb{C}^*)$. In this case, we have that $\text{coker}(\exp)$ violates the axiom of locality so we conclude that it is not a sheaf. \square

Sheafification