

Scalable Bayesian seismic wavelet estimation

Guillermina Senn¹

Joint work with Matt Walker², Håkon Tjelmeland¹, and Andrew Holbrook³

¹Norwegian University of Science and Technology (NTNU)

²bp · ³University of California, Los Angeles

SINTEF Industri, Trondheim
May 27, 2025

Scalable Bayesian seismic wavelet estimation

Guillermina Senn¹

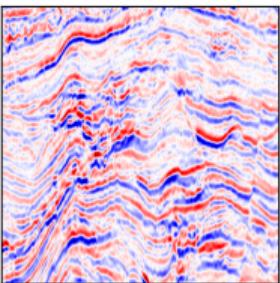
Joint work with Matt Walker², Håkon Tjelmeland¹, and Andrew Holbrook³

¹Norwegian University of Science and Technology (NTNU)
²bp · ³University of California, Los Angeles

SINTEF Industri, Trondheim
May 27, 2025

Summary

1. Seismic data



- Reflectivity \mathbf{c}
- Seismic wavelet \mathbf{w}
- Observational noise \mathbf{e}
- Seismic data \mathbf{d}

2. Model

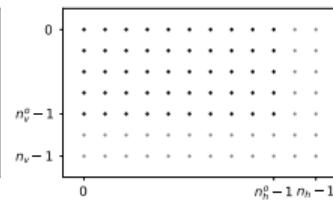
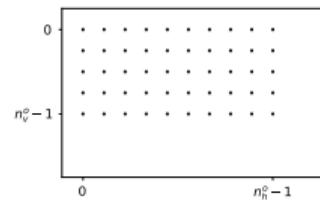
1D convolutional model:

$$\mathbf{d}_j = \mathbf{c}_j * \mathbf{w} + \mathbf{e}_j \quad \text{for column } j.$$

Probabilistic model:

- Gaussian reflectivity prior.
- Gaussian wavelet prior.
- Gaussian likelihood.
- Inverse-Gamma variances.

3. Scalability



4. Estimation

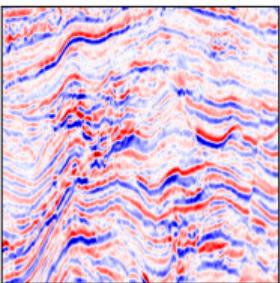
Sample posterior distribution

$$p(\mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \sigma_d^2 | \mathbf{d})$$

with Markov chain Monte Carlo (MCMC).

Summary

1. Seismic data



- Reflectivity \mathbf{c}
- Seismic wavelet \mathbf{w}
- Observational noise \mathbf{e}
- Seismic data \mathbf{d}

2. Model

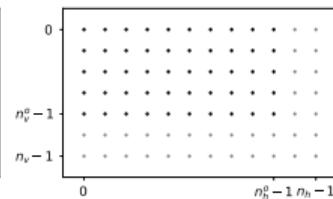
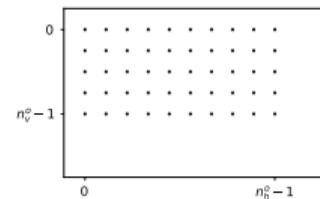
Convolutional model:

$$\mathbf{d}_j = \mathbf{c}_j * \mathbf{w} + \mathbf{e}_j \quad \text{for column } j.$$

Probabilistic model:

- Gaussian reflectivity prior.
- Gaussian wavelet prior.
- Gaussian likelihood.
- Inverse-Gamma variances.

3. Scalability



4. Estimation

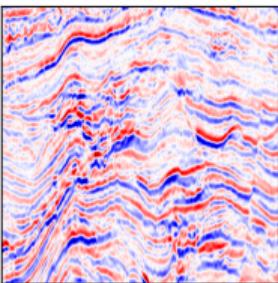
Sample posterior distribution

$$p(\mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \sigma_d^2 | \mathbf{d})$$

with Markov chain Monte Carlo (MCMC).

Summary

1. Seismic data



- Reflectivity \mathbf{c}
- Seismic wavelet \mathbf{w}
- Observational noise \mathbf{e}
- Seismic data \mathbf{d}

2. Model

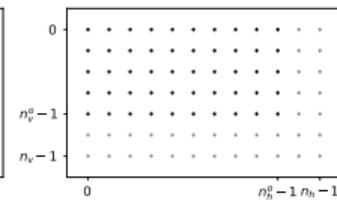
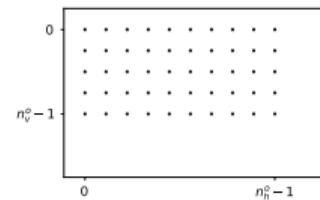
Convolutional model:

$$\mathbf{d}_j = \mathbf{c}_j * \mathbf{w} + \mathbf{e}_j \quad \text{for column } j.$$

Probabilistic model:

- Gaussian reflectivity prior.
- Gaussian wavelet prior.
- Gaussian likelihood.
- Inverse-Gamma variances.

3. Scalability



4. Estimation

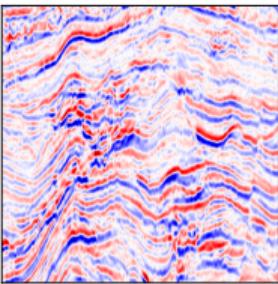
Sample posterior distribution

$$p(\mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \sigma_d^2 | \mathbf{d})$$

with Markov chain Monte Carlo (MCMC).

Summary

1. Seismic data



- Reflectivity \mathbf{c}
- Seismic wavelet \mathbf{w}
- Observational noise \mathbf{e}
- Seismic data \mathbf{d}

2. Model

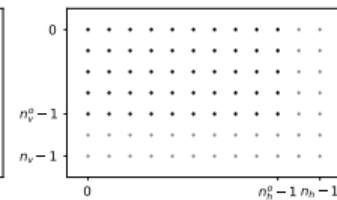
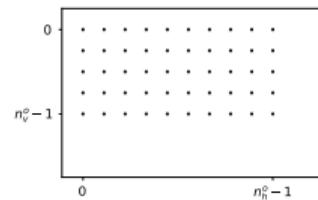
Convolutional model:

$$\mathbf{d}_j = \mathbf{c}_j * \mathbf{w} + \mathbf{e}_j \quad \text{for column } j.$$

Probabilistic model:

- Gaussian reflectivity prior.
- Gaussian wavelet prior.
- Gaussian likelihood.
- Inverse-Gamma variances.

3. Scalability



4. Estimation

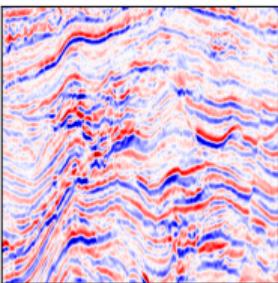
Sample posterior distribution

$$p(\mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \sigma_d^2 | \mathbf{d})$$

with Markov chain Monte Carlo (MCMC).

Summary

1. Seismic data



- Reflectivity \mathbf{c}
- Seismic wavelet \mathbf{w}
- Observational noise \mathbf{e}
- Seismic data \mathbf{d}

2. Model

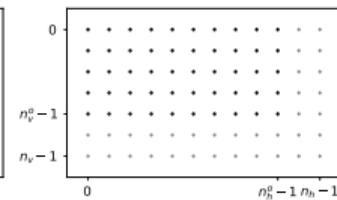
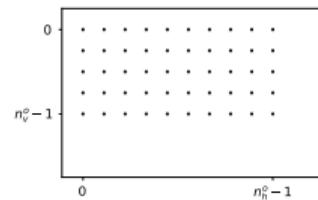
Convolutional model:

$$\mathbf{d}_j = \mathbf{c}_j * \mathbf{w} + \mathbf{e}_j \quad \text{for column } j.$$

Probabilistic model:

- Gaussian reflectivity prior.
- Gaussian wavelet prior.
- Gaussian likelihood.
- Inverse-Gamma variances.

3. Scalability



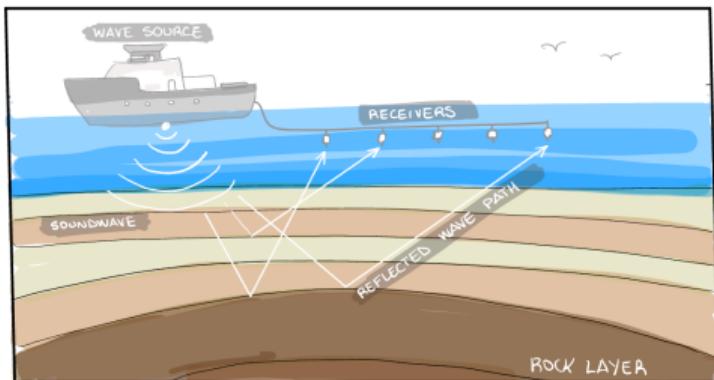
4. Estimation

Sample posterior distribution

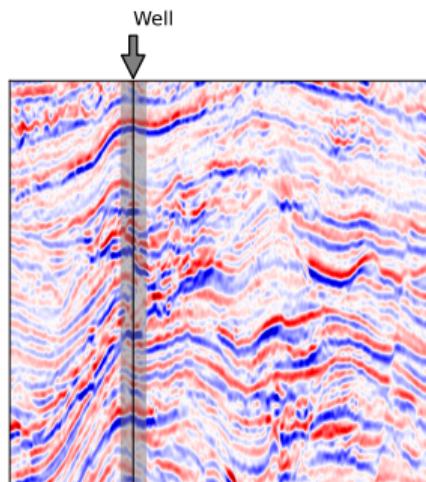
$$p(\mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \sigma_d^2 | \mathbf{d})$$

with Markov chain Monte Carlo (MCMC).

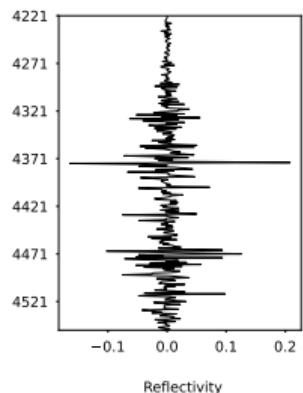
Seismic data acquisition and processing



(a) Data acquisition.

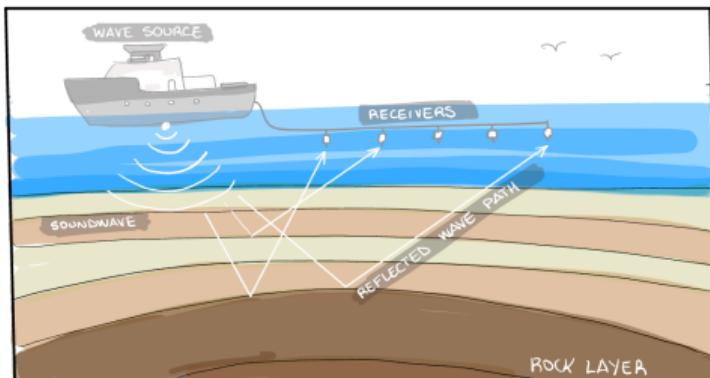


(b) Seismic data D

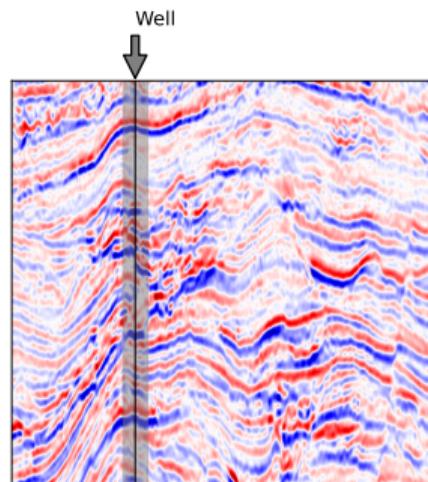


(c) Well log data
 c_{well} .

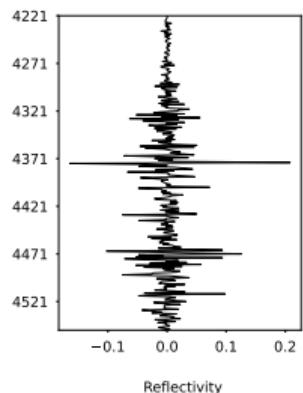
Seismic data acquisition and processing



(a) Data acquisition.

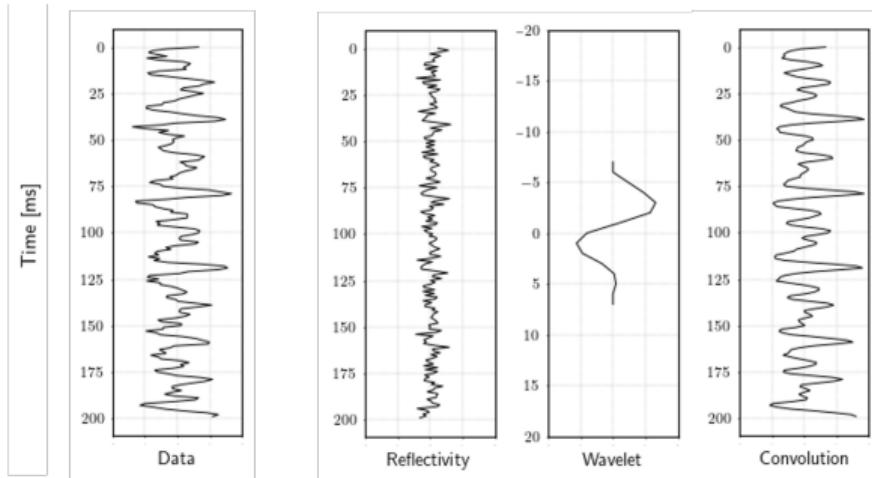


(b) Seismic data D



(c) Well log data
 c_{well} .

Model assumptions



1D convolutional model for column j :

$$\mathbf{d}_j = \mathbf{w} * \mathbf{c}_j + \mathbf{e}_j, \quad j = 1, \dots, m$$

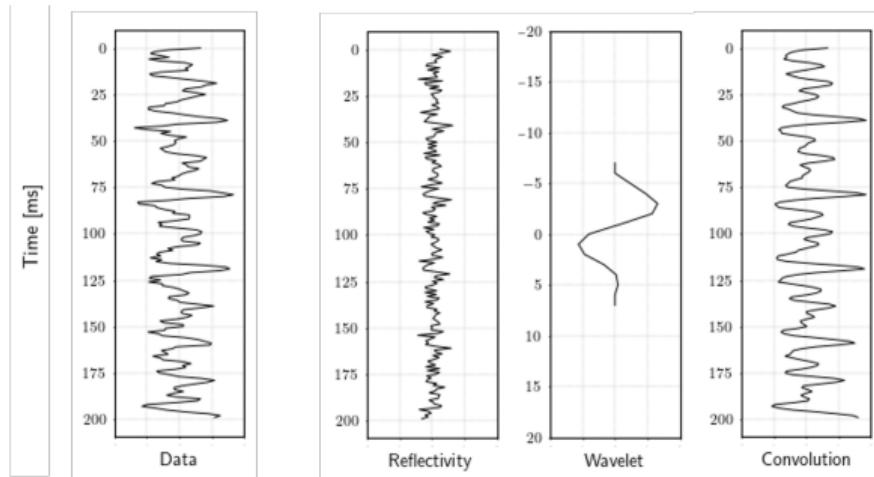
- Denote the data, reflectivity, and noise for all columns on the image by \mathbf{D} , \mathbf{C} , and \mathbf{E} .
- Denote their vectorized versions as $\mathbf{d} = \text{vec}(\mathbf{D})$, $\mathbf{c} = \text{vec}(\mathbf{C})$, and $\mathbf{e} = \text{vec}(\mathbf{E})$.
- The 1D convolutional model for the $n \times m$ image is

$$\mathbf{d} = \mathbf{W}\mathbf{c} + \mathbf{e}.$$

Assumptions:

- Same wavelet acts on each column.
- Stationary \mathbf{C} and \mathbf{E} .

Model assumptions



1D convolutional model for column j :

$$\mathbf{d}_j = \mathbf{w} * \mathbf{c}_j + \mathbf{e}_j, \quad j = 1, \dots, m$$

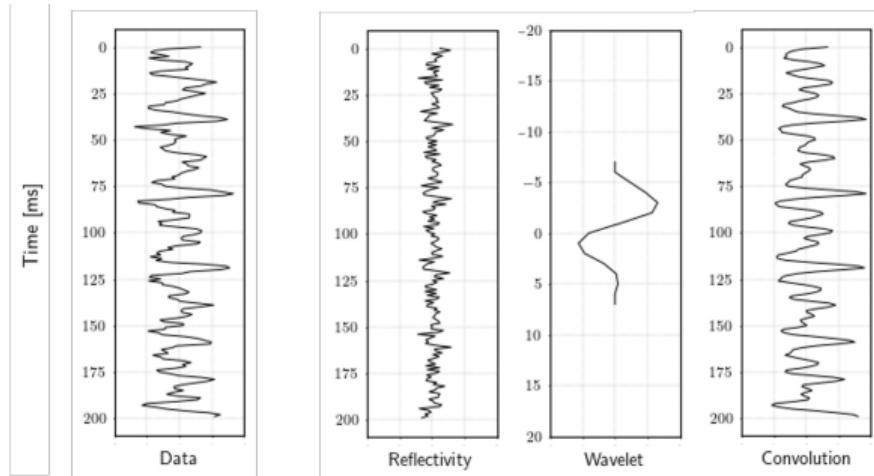
- Denote the data, reflectivity, and noise for all columns on the image by \mathbf{D} , \mathbf{C} , and \mathbf{E} .
- Denote their vectorized versions as $\mathbf{d} = \text{vec}(\mathbf{D})$, $\mathbf{c} = \text{vec}(\mathbf{C})$, and $\mathbf{e} = \text{vec}(\mathbf{E})$.
- The 1D convolutional model for the $n \times m$ image is

$$\mathbf{d} = \mathbf{W}\mathbf{c} + \mathbf{e}.$$

Assumptions:

- Same wavelet acts on each column.
- Stationary \mathbf{C} and \mathbf{E} .

Model assumptions



1D convolutional model for column j :

$$\mathbf{d}_j = \mathbf{w} * \mathbf{c}_j + \mathbf{e}_j, \quad j = 1, \dots, m$$

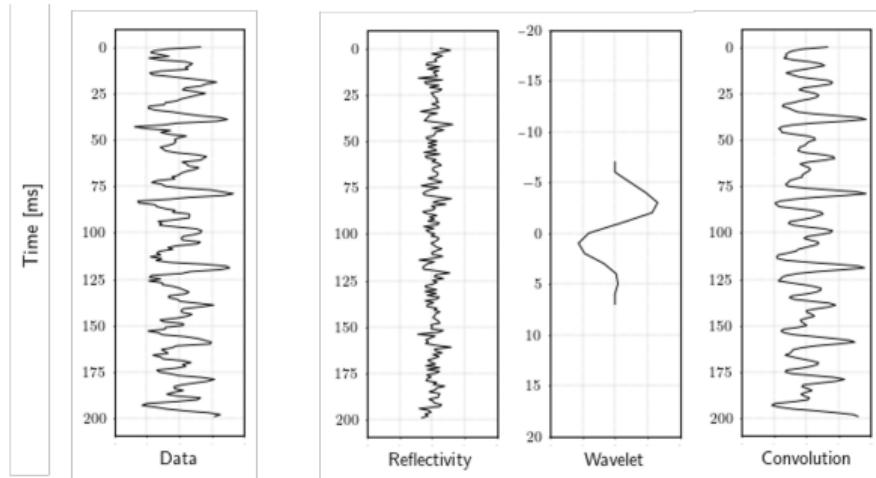
- Denote the data, reflectivity, and noise for all columns on the image by \mathbf{D} , \mathbf{C} , and \mathbf{E} .
- Denote their vectorized versions as $\mathbf{d} = \text{vec}(\mathbf{D})$, $\mathbf{c} = \text{vec}(\mathbf{C})$, and $\mathbf{e} = \text{vec}(\mathbf{E})$.
- The 1D convolutional model for the $n \times m$ image is

$$\mathbf{d} = \mathbf{W}\mathbf{c} + \mathbf{e}.$$

Assumptions:

- Same wavelet acts on each column.
- Stationary \mathbf{C} and \mathbf{E} .

Model assumptions



1D convolutional model for column j :

$$\mathbf{d}_j = \mathbf{w} * \mathbf{c}_j + \mathbf{e}_j, \quad j = 1, \dots, m$$

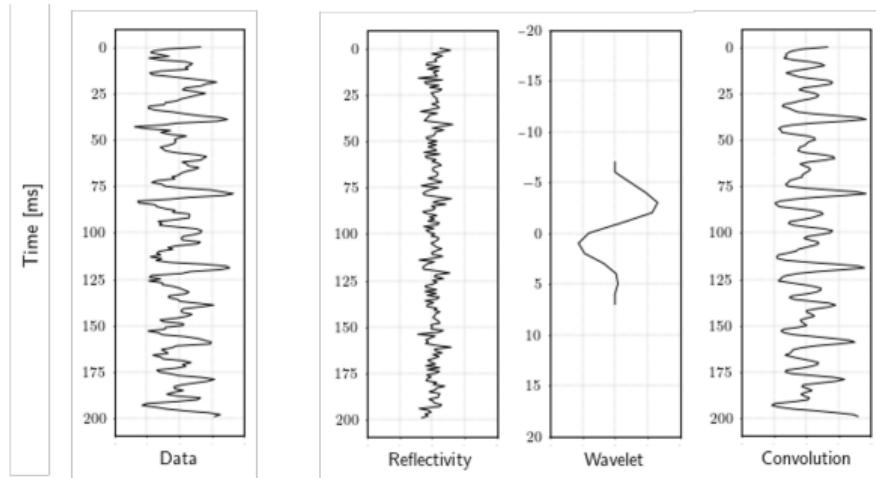
- Denote the data, reflectivity, and noise for all columns on the image by \mathbf{D} , \mathbf{C} , and \mathbf{E} .
- Denote their vectorized versions as $\mathbf{d} = \text{vec}(\mathbf{D})$, $\mathbf{c} = \text{vec}(\mathbf{C})$, and $\mathbf{e} = \text{vec}(\mathbf{E})$.
- The 1D convolutional model for the $n \times m$ image is

$$\mathbf{d} = \mathbf{W}\mathbf{c} + \mathbf{e}.$$

Assumptions:

- Same wavelet acts on each column.
- Stationary \mathbf{C} and \mathbf{E} .

Model assumptions



1D convolutional model for column j :

$$\mathbf{d}_j = \mathbf{w} * \mathbf{c}_j + \mathbf{e}_j, \quad j = 1, \dots, m$$

- Denote the data, reflectivity, and noise for all columns on the image by \mathbf{D} , \mathbf{C} , and \mathbf{E} .
- Denote their vectorized versions as $\mathbf{d} = \text{vec}(\mathbf{D})$, $\mathbf{c} = \text{vec}(\mathbf{C})$, and $\mathbf{e} = \text{vec}(\mathbf{E})$.
- The 1D convolutional model for the $n \times m$ image is

$$\mathbf{d} = \mathbf{W}\mathbf{c} + \mathbf{e}.$$

Assumptions:

- Same wavelet acts on each column.
- Stationary \mathbf{C} and \mathbf{E} .

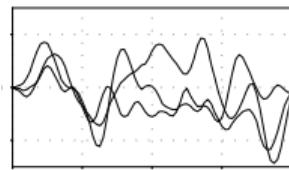
The probabilistic model (1)

- Represent the wavelet in the time domain as the sequence with k elements

$$\mathbf{w} = \{w_1, \dots, w_k\}.$$

- Define the $2 \times k$ constraint matrix \mathbf{A}_w that forces the endpoints of \mathbf{w} to be zero.
- Model the constrained sequence as a Gaussian process:

$$\mathbf{w} | \sigma_w^2 \sim N_k(0, \sigma_w^2 \mathbf{R}_w), \quad \mathbf{w}^* = \mathbf{w} | \mathbf{A}_w \mathbf{w} = 0, \quad \rightarrow \mathbf{w}^* | \sigma_w^2 \sim N_k(0, \sigma_w^2 \mathbf{R}_w^*)$$



Samples from (constrained) wavelet prior.

- Similarly, model the constrained reflectivity vector as a Gaussian field:

$$\mathbf{c} | \sigma_c^2 \sim N_{nm}(0, \sigma_c^2 \mathbf{R}_c), \quad \mathbf{c}^* = \mathbf{c} | \mathbf{A}_c \mathbf{c} = \mathbf{c}_{\text{well}} \quad \rightarrow \mathbf{c}^* | \sigma_c^2 \sim N_{nm}(\mu_c^*, \sigma_c^2 \mathbf{R}_c^*)$$

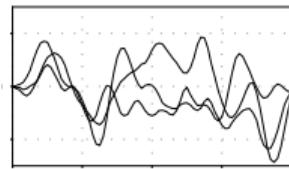
The probabilistic model (1)

- Represent the wavelet in the time domain as the sequence with k elements

$$\mathbf{w} = \{w_1, \dots, w_k\}.$$

- Define the $2 \times k$ constraint matrix \mathbf{A}_w that forces the endpoints of \mathbf{w} to be zero.
 - Model the constrained sequence as a Gaussian process:

$$w|\sigma_w^2 \sim N_k(0, \sigma_w^2 R_w), \quad w^* = w|\mathbf{A}_w w = 0, \quad \rightarrow w^*|\sigma_w^2 \sim N_k(0, \sigma_w^2 R_w^*)$$



Samples from (constrained) wavelet prior.

- Similarly, model the constrained reflectivity vector as a Gaussian field:

$$c|\sigma_c^2 \sim N_{nm}(0, \sigma_c^2 R_c), \quad c^* = c|\mathbf{A}_c c = c_{\text{well}} \quad \rightarrow c^*|\sigma_c^2 \sim N_{nm}(\mu_c^*, \sigma_c^2 R_c^*)$$

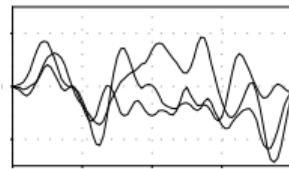
The probabilistic model (1)

- Represent the wavelet in the time domain as the sequence with k elements

$$\mathbf{w} = \{w_1, \dots, w_k\}.$$

- Define the $2 \times k$ constraint matrix \mathbf{A}_w that forces the endpoints of \mathbf{w} to be zero.
- Model the constrained sequence as a Gaussian process:

$$\mathbf{w} | \sigma_w^2 \sim N_k(0, \sigma_w^2 \mathbf{R}_w), \quad \mathbf{w}^* = \mathbf{w} | \mathbf{A}_w \mathbf{w} = 0, \quad \rightarrow \mathbf{w}^* | \sigma_w^2 \sim N_k(0, \sigma_w^2 \mathbf{R}_w^*)$$



Samples from (constrained) wavelet prior.

- Similarly, model the constrained reflectivity vector as a Gaussian field:

$$\mathbf{c} | \sigma_c^2 \sim N_{nm}(0, \sigma_c^2 \mathbf{R}_c), \quad \mathbf{c}^* = \mathbf{c} | \mathbf{A}_c \mathbf{c} = \mathbf{c}_{\text{well}} \quad \rightarrow \mathbf{c}^* | \sigma_c^2 \sim N_{nm}(\mu_c^*, \sigma_c^2 \mathbf{R}_c^*)$$

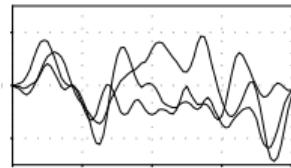
The probabilistic model (1)

- Represent the wavelet in the time domain as the sequence with k elements

$$\mathbf{w} = \{w_1, \dots, w_k\}.$$

- Define the $2 \times k$ constraint matrix \mathbf{A}_w that forces the endpoints of \mathbf{w} to be zero.
- Model the constrained sequence as a Gaussian process:

$$\mathbf{w} | \sigma_w^2 \sim N_k(0, \sigma_w^2 \mathbf{R}_w), \quad \mathbf{w}^* = \mathbf{w} | \mathbf{A}_w \mathbf{w} = 0, \quad \rightarrow \mathbf{w}^* | \sigma_w^2 \sim N_k(0, \sigma_w^2 \mathbf{R}_w^*)$$



Samples from (constrained) wavelet prior.

- Similarly, model the constrained reflectivity vector as a Gaussian field:

$$\mathbf{c} | \sigma_c^2 \sim N_{nm}(0, \sigma_c^2 \mathbf{R}_c), \quad \mathbf{c}^* = \mathbf{c} | \mathbf{A}_c \mathbf{c} = \mathbf{c}_{\text{well}} \quad \rightarrow \mathbf{c}^* | \sigma_c^2 \sim N_{nm}(\mu_c^*, \sigma_c^2 \mathbf{R}_c^*)$$

The probabilistic model (2)

- Assume Gaussian observational noise and obtain the Gaussian likelihood

$$\mathbf{d} | \mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \zeta \sim N_{nm}(\mathbf{W}\mathbf{c}, \sigma_d^2 \mathbf{R}_d), \quad \sigma_d^2 \propto \sigma_c^2 \sigma_w^2 \zeta, \quad \zeta^{-1} = \text{SNR}$$

- Model the spatial correlations as the product of the correlations in each direction (separability):

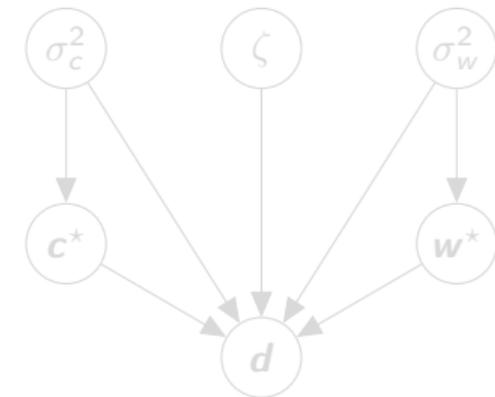
$$\mathbf{R}_d = \mathbf{R}_{d,h} \otimes \mathbf{R}_{d,v}, \quad \mathbf{R}_c = \mathbf{R}_{c,h} \otimes \mathbf{R}_{c,v}.$$

- Assign inverse-Gamma hyperpriors to the marginal variance parameters

$$\sigma_c^2 \sim IG(\alpha_c, \beta_c)$$

$$\sigma_w^2 \sim IG(\alpha_w, \beta_w)$$

$$\zeta \sim IG(\alpha_\zeta, \beta_\zeta)$$



The stochastic model represented by a DAG.

The probabilistic model (2)

- Assume Gaussian observational noise and obtain the Gaussian likelihood

$$\mathbf{d} | \mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \zeta \sim N_{nm}(\mathbf{W}\mathbf{c}, \sigma_d^2 \mathbf{R}_d), \quad \sigma_d^2 \propto \sigma_c^2 \sigma_w^2 \zeta, \quad \zeta^{-1} = \text{SNR}$$

- Model the spatial correlations as the product of the correlations in each direction (separability):

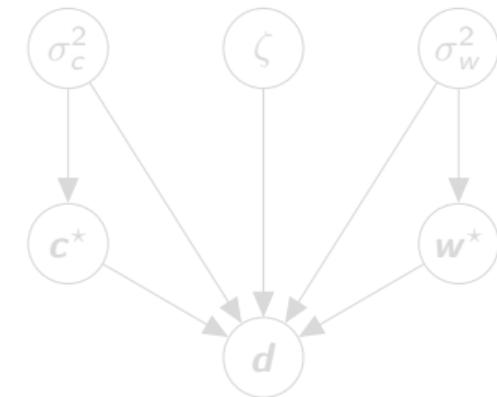
$$\mathbf{R}_d = \mathbf{R}_{d,h} \otimes \mathbf{R}_{d,v}, \quad \mathbf{R}_c = \mathbf{R}_{c,h} \otimes \mathbf{R}_{c,v}.$$

- Assign inverse-Gamma hyperpriors to the marginal variance parameters

$$\sigma_c^2 \sim IG(\alpha_c, \beta_c)$$

$$\sigma_w^2 \sim IG(\alpha_w, \beta_w)$$

$$\zeta \sim IG(\alpha_\zeta, \beta_\zeta)$$



The stochastic model represented by a DAG.

The probabilistic model (2)

- Assume Gaussian observational noise and obtain the Gaussian likelihood

$$\mathbf{d} | \mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \zeta \sim N_{nm}(\mathbf{W}\mathbf{c}, \sigma_d^2 \mathbf{R}_d), \quad \sigma_d^2 \propto \sigma_c^2 \sigma_w^2 \zeta, \quad \zeta^{-1} = \text{SNR}$$

- Model the spatial correlations as the product of the correlations in each direction (separability):

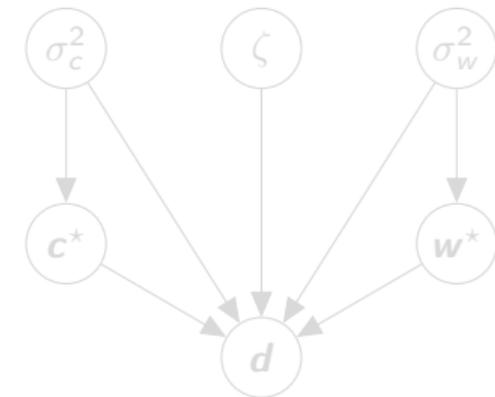
$$\mathbf{R}_d = \mathbf{R}_{d,h} \otimes \mathbf{R}_{d,v}, \quad \mathbf{R}_c = \mathbf{R}_{c,h} \otimes \mathbf{R}_{c,v}.$$

- Assign inverse-Gamma hyperpriors to the marginal variance parameters

$$\sigma_c^2 \sim IG(\alpha_c, \beta_c)$$

$$\sigma_w^2 \sim IG(\alpha_w, \beta_w)$$

$$\zeta \sim IG(\alpha_\zeta, \beta_\zeta)$$



The stochastic model represented by a DAG.

The probabilistic model (2)

- Assume Gaussian observational noise and obtain the Gaussian likelihood

$$\mathbf{d} | \mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \zeta \sim N_{nm}(\mathbf{W}\mathbf{c}, \sigma_d^2 \mathbf{R}_d), \quad \sigma_d^2 \propto \sigma_c^2 \sigma_w^2 \zeta, \quad \zeta^{-1} = \text{SNR}$$

- Model the spatial correlations as the product of the correlations in each direction (separability):

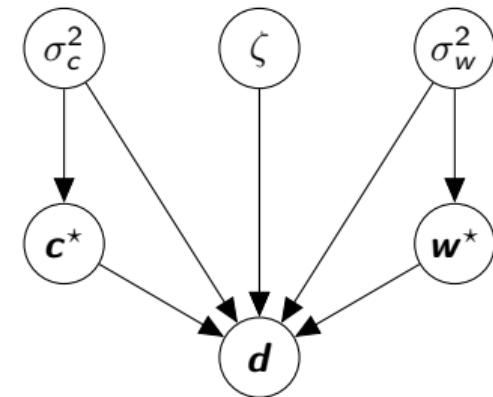
$$\mathbf{R}_d = \mathbf{R}_{d,h} \otimes \mathbf{R}_{d,v}, \quad \mathbf{R}_c = \mathbf{R}_{c,h} \otimes \mathbf{R}_{c,v}.$$

- Assign inverse-Gamma hyperpriors to the marginal variance parameters

$$\sigma_c^2 \sim IG(\alpha_c, \beta_c)$$

$$\sigma_w^2 \sim IG(\alpha_w, \beta_w)$$

$$\zeta \sim IG(\alpha_\zeta, \beta_\zeta)$$



The stochastic model represented by a DAG.

Posterior distribution of the model

- Denote: data $\mathbf{y} = (\mathbf{d}, \mathbf{c}_{well})$ and unknown parameters $\boldsymbol{\theta} = (\mathbf{w}^*, \mathbf{c}^*, \sigma_w^2, \sigma_c^2, \zeta)$.
- Use Bayes' rule

$$p(\boldsymbol{\theta}|\mathbf{y}) = \frac{p(\boldsymbol{\theta}, \mathbf{y})}{p(\mathbf{y})} \propto p(\mathbf{y}, \boldsymbol{\theta})$$

to find the joint distribution

$$p(\mathbf{c}^*, \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta | \mathbf{d}) = p(\mathbf{d} | \mathbf{c}^*, \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta) p(\mathbf{c}^* | \sigma_c^2) p(\mathbf{w}^* | \sigma_w^2) p(\sigma_c^2) p(\sigma_w^2) p(\zeta).$$

- Conjugate distributions in the model (Gaussian-Gaussian and Gaussian-inverse-Gamma) let us write a Gibbs sampler.

Posterior distribution of the model

- Denote: data $\mathbf{y} = (\mathbf{d}, \mathbf{c}_{well})$ and unknown parameters $\boldsymbol{\theta} = (\mathbf{w}^*, \mathbf{c}^*, \sigma_w^2, \sigma_c^2, \zeta)$.
- Use Bayes' rule

$$p(\boldsymbol{\theta}|\mathbf{y}) = \frac{p(\boldsymbol{\theta}, \mathbf{y})}{p(\mathbf{y})} \propto p(\mathbf{y}, \boldsymbol{\theta})$$

to find the joint distribution

$$p(\mathbf{c}^*, \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta | \mathbf{d}) = p(\mathbf{d} | \mathbf{c}^*, \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta) p(\mathbf{c}^* | \sigma_c^2) p(\mathbf{w}^* | \sigma_w^2) p(\sigma_c^2) p(\sigma_w^2) p(\zeta).$$

- Conjugate distributions in the model (Gaussian-Gaussian and Gaussian-inverse-Gamma) let us write a Gibbs sampler.

Posterior distribution of the model

- Denote: data $\mathbf{y} = (\mathbf{d}, \mathbf{c}_{\text{well}})$ and unknown parameters $\boldsymbol{\theta} = (\mathbf{w}^*, \mathbf{c}^*, \sigma_w^2, \sigma_c^2, \zeta)$.
- Use Bayes' rule

$$p(\boldsymbol{\theta}|\mathbf{y}) = \frac{p(\boldsymbol{\theta}, \mathbf{y})}{p(\mathbf{y})} \propto p(\mathbf{y}, \boldsymbol{\theta})$$

to find the joint distribution

$$p(\mathbf{c}^*, \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta | \mathbf{d}) = p(\mathbf{d} | \mathbf{c}^*, \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta) p(\mathbf{c}^* | \sigma_c^2) p(\mathbf{w}^* | \sigma_w^2) p(\sigma_c^2) p(\sigma_w^2) p(\zeta).$$

- Conjugate distributions in the model (Gaussian-Gaussian and Gaussian-inverse-Gamma) let us write a Gibbs sampler.

Gibbs sampler for joint reflectivity and wavelet estimation

Algorithm Gibbs sampler

Input: Seismic data \mathbf{d} , well log \mathbf{c}_{well} , priors, initial values

Output: Samples from posterior $p(\mathbf{c}^*, \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta | \mathbf{d})$

Initialize $\mathbf{c}^{(0)}, \mathbf{w}^{(0)}, (\sigma_c^2)^{(0)}, (\sigma_w^2)^{(0)}, \zeta^{(0)}$

for $t = 1, 2, \dots, T$ **do**

Update reflectivity: Sample $\mathbf{c}^{(t)} \sim p(\mathbf{c}^* | \mathbf{w}^{(t-1)}, (\sigma_c^2)^{(t-1)}, (\sigma_w^2)^{(t-1)}, \zeta^{(t-1)}, \mathbf{d})$

Update wavelet: Sample $\mathbf{w}^{(t)} \sim p(\mathbf{w}^* | \mathbf{c}^{(t)}, (\sigma_c^2)^{(t-1)}, (\sigma_w^2)^{(t-1)}, \zeta^{(t-1)}, \mathbf{d})$

Update reflectivity variance: Sample $(\sigma_c^2)^{(t)} \sim p(\sigma_c^2 | \mathbf{c}^{(t)}, \mathbf{w}^{(t)}, (\sigma_w^2)^{(t-1)}, \zeta^{(t-1)}, \mathbf{d})$

Update wavelet variance: Sample $(\sigma_w^2)^{(t)} \sim p(\sigma_w^2 | \mathbf{c}^{(t)}, \mathbf{w}^{(t)}, (\sigma_c^2)^{(t)}, \zeta^{(t-1)}, \mathbf{d})$

Update SNR: Sample $\zeta^{(t)} \sim p(\zeta | \mathbf{c}^{(t)}, \mathbf{w}^{(t)}, (\sigma_c^2)^{(t)}, (\sigma_w^2)^{(t)}, \mathbf{d})$

Return: $\{\mathbf{c}^{(t)}, \mathbf{w}^{(t)}, (\sigma_c^2)^{(t)}, (\sigma_w^2)^{(t)}, \zeta^{(t)}\}_{t=B+1}^T$ after burn-in B

The problem is that the full conditionals $p(\theta_j | \theta_{-j}, \mathbf{d})$ involve operations with computational complexity $\mathcal{O}(l^3)$, $l = nm$.

Gibbs sampler for joint reflectivity and wavelet estimation

Algorithm Gibbs sampler

Input: Seismic data \mathbf{d} , well log \mathbf{c}_{well} , priors, initial values

Output: Samples from posterior $p(\mathbf{c}^*, \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta | \mathbf{d})$

Initialize $\mathbf{c}^{(0)}, \mathbf{w}^{(0)}, (\sigma_c^2)^{(0)}, (\sigma_w^2)^{(0)}, \zeta^{(0)}$

for $t = 1, 2, \dots, T$ **do**

Update reflectivity: Sample $\mathbf{c}^{(t)} \sim p(\mathbf{c}^* | \mathbf{w}^{(t-1)}, (\sigma_c^2)^{(t-1)}, (\sigma_w^2)^{(t-1)}, \zeta^{(t-1)}, \mathbf{d})$

Update wavelet: Sample $\mathbf{w}^{(t)} \sim p(\mathbf{w}^* | \mathbf{c}^{(t)}, (\sigma_c^2)^{(t-1)}, (\sigma_w^2)^{(t-1)}, \zeta^{(t-1)}, \mathbf{d})$

Update reflectivity variance: Sample $(\sigma_c^2)^{(t)} \sim p(\sigma_c^2 | \mathbf{c}^{(t)}, \mathbf{w}^{(t)}, (\sigma_w^2)^{(t-1)}, \zeta^{(t-1)}, \mathbf{d})$

Update wavelet variance: Sample $(\sigma_w^2)^{(t)} \sim p(\sigma_w^2 | \mathbf{c}^{(t)}, \mathbf{w}^{(t)}, (\sigma_c^2)^{(t)}, \zeta^{(t-1)}, \mathbf{d})$

Update SNR: Sample $\zeta^{(t)} \sim p(\zeta | \mathbf{c}^{(t)}, \mathbf{w}^{(t)}, (\sigma_c^2)^{(t)}, (\sigma_w^2)^{(t)}, \mathbf{d})$

Return: $\{\mathbf{c}^{(t)}, \mathbf{w}^{(t)}, (\sigma_c^2)^{(t)}, (\sigma_w^2)^{(t)}, \zeta^{(t)}\}_{t=B+1}^T$ after burn-in B

The problem is that the full conditionals $p(\theta_j | \boldsymbol{\theta}_{-j}, \mathbf{d})$ involve operations with computational complexity $\mathcal{O}(l^3)$, $l = nm$.

A possible solution

- Matrix multiplication, inversion, and decomposition for arbitrary $s \times s$ matrices scale \sim cubic with s .
- For matrices with special structures we have efficient multiplication/inversion algorithms.
- For example, take the circulant matrix

$$\underline{R} = \text{circ}(\underline{r}) = \begin{pmatrix} r_0 & r_1 & r_2 & \cdots & r_{s-1} \\ r_{s-1} & r_0 & r_1 & \cdots & r_{s-2} \\ r_{s-2} & r_{s-1} & r_0 & \cdots & r_{s-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_1 & r_2 & r_3 & \cdots & r_0 \end{pmatrix}, \quad \underline{r} = (r_0, \dots, r_{s-1})^T.$$

- We can represent it by its base \underline{r} .
- We can find its eigenvalues with the DFT in $\mathcal{O}(s \log(s))$.
- Multiplication/inversion/decomposition are eigenvalue-based operations.

Can we make our correlation matrices circulant?

A possible solution

- Matrix multiplication, inversion, and decomposition for arbitrary $s \times s$ matrices scale \sim cubic with s .
- For matrices with special structures we have efficient multiplication/inversion algorithms.
- For example, take the circulant matrix

$$\underline{R} = \text{circ}(\underline{r}) = \begin{pmatrix} r_0 & r_1 & r_2 & \cdots & r_{s-1} \\ r_{s-1} & r_0 & r_1 & \cdots & r_{s-2} \\ r_{s-2} & r_{s-1} & r_0 & \cdots & r_{s-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_1 & r_2 & r_3 & \cdots & r_0 \end{pmatrix}, \quad \underline{r} = (r_0, \dots, r_{s-1})^T.$$

- We can represent it by its base \underline{r} .
- We can find its eigenvalues with the DFT in $\mathcal{O}(s \log(s))$.
- Multiplication/inversion/decomposition are eigenvalue-based operations.

Can we make our correlation matrices circulant?

A possible solution

- Matrix multiplication, inversion, and decomposition for arbitrary $s \times s$ matrices scale \sim cubic with s .
- For matrices with special structures we have efficient multiplication/inversion algorithms.
- For example, take the circulant matrix

$$\underline{R} = \text{circ}(\underline{r}) = \begin{pmatrix} r_0 & r_1 & r_2 & \cdots & r_{s-1} \\ r_{s-1} & r_0 & r_1 & \cdots & r_{s-2} \\ r_{s-2} & r_{s-1} & r_0 & \cdots & r_{s-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_1 & r_2 & r_3 & \cdots & r_0 \end{pmatrix}, \quad \underline{r} = (r_0, \dots, r_{s-1})^T.$$

- We can represent it by its base \underline{r} .
- We can find its eigenvalues with the DFT in $\mathcal{O}(s \log(s))$.
- Multiplication/inversion/decomposition are eigenvalue-based operations.

Can we make our correlation matrices circulant?

A possible solution

- Matrix multiplication, inversion, and decomposition for arbitrary $s \times s$ matrices scale \sim cubic with s .
- For matrices with special structures we have efficient multiplication/inversion algorithms.
- For example, take the circulant matrix

$$\underline{R} = \text{circ}(\mathbf{r}) = \begin{pmatrix} r_0 & r_1 & r_2 & \cdots & r_{s-1} \\ r_{s-1} & r_0 & r_1 & \cdots & r_{s-2} \\ r_{s-2} & r_{s-1} & r_0 & \cdots & r_{s-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_1 & r_2 & r_3 & \cdots & r_0 \end{pmatrix}, \quad \mathbf{r} = (r_0, \dots, r_{s-1})^T.$$

- We can represent it by its base \mathbf{r} .
- We can find its eigenvalues with the DFT in $\mathcal{O}(s \log(s))$.
- Multiplication/inversion/decomposition are eigenvalue-based operations.

Can we make our correlation matrices circulant?

A possible solution

- Matrix multiplication, inversion, and decomposition for arbitrary $s \times s$ matrices scale \sim cubic with s .
- For matrices with special structures we have efficient multiplication/inversion algorithms.
- For example, take the circulant matrix

$$\underline{R} = \text{circ}(\mathbf{r}) = \begin{pmatrix} r_0 & r_1 & r_2 & \cdots & r_{s-1} \\ r_{s-1} & r_0 & r_1 & \cdots & r_{s-2} \\ r_{s-2} & r_{s-1} & r_0 & \cdots & r_{s-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_1 & r_2 & r_3 & \cdots & r_0 \end{pmatrix}, \quad \mathbf{r} = (r_0, \dots, r_{s-1})^T.$$

- We can represent it by its base \mathbf{r} .
- We can find its eigenvalues with the DFT in $\mathcal{O}(s \log(s))$.
- Multiplication/inversion/decomposition are eigenvalue-based operations.

Can we make our correlation matrices circulant?

A possible solution

- Matrix multiplication, inversion, and decomposition for arbitrary $s \times s$ matrices scale \sim cubic with s .
- For matrices with special structures we have efficient multiplication/inversion algorithms.
- For example, take the circulant matrix

$$\underline{R} = \text{circ}(\mathbf{r}) = \begin{pmatrix} r_0 & r_1 & r_2 & \cdots & r_{s-1} \\ r_{s-1} & r_0 & r_1 & \cdots & r_{s-2} \\ r_{s-2} & r_{s-1} & r_0 & \cdots & r_{s-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_1 & r_2 & r_3 & \cdots & r_0 \end{pmatrix}, \quad \mathbf{r} = (r_0, \dots, r_{s-1})^T.$$

- We can represent it by its base \mathbf{r} .
- We can find its eigenvalues with the DFT in $\mathcal{O}(s \log(s))$.
- Multiplication/inversion/decomposition are eigenvalue-based operations.

Can we make our correlation matrices circulant?

A possible solution

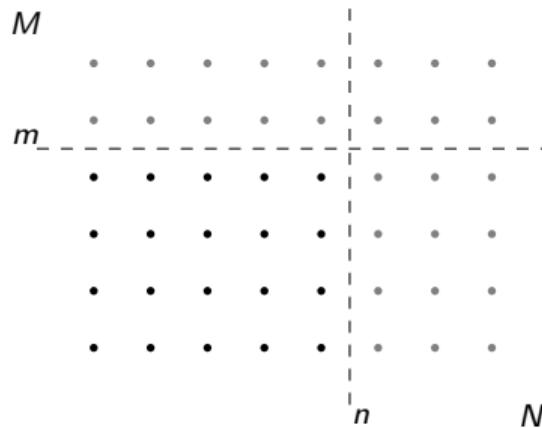
- Matrix multiplication, inversion, and decomposition for arbitrary $s \times s$ matrices scale \sim cubic with s .
- For matrices with special structures we have efficient multiplication/inversion algorithms.
- For example, take the circulant matrix

$$\underline{R} = \text{circ}(\underline{r}) = \begin{pmatrix} r_0 & r_1 & r_2 & \cdots & r_{s-1} \\ r_{s-1} & r_0 & r_1 & \cdots & r_{s-2} \\ r_{s-2} & r_{s-1} & r_0 & \cdots & r_{s-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ r_1 & r_2 & r_3 & \cdots & r_0 \end{pmatrix}, \quad \underline{r} = (r_0, \dots, r_{s-1})^T.$$

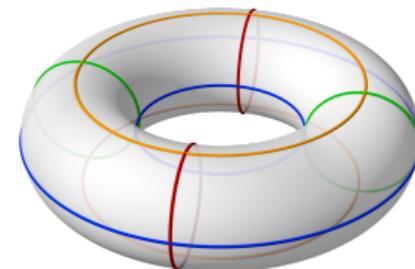
- We can represent it by its base \underline{r} .
- We can find its eigenvalues with the DFT in $\mathcal{O}(s \log(s))$.
- Multiplication/inversion/decomposition are eigenvalue-based operations.

Can we make our correlation matrices circulant?

Scalability



(a) The extended lattice.



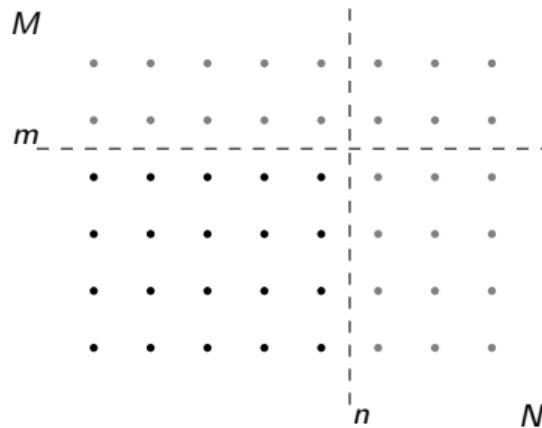
(b) The cyclic lattice.

- Separability on the cyclic lattice gives circulant or block-circulant with circulant blocks correlation matrices:

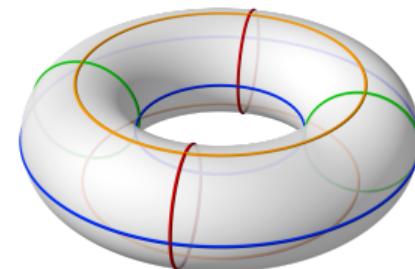
$$\underline{\underline{R}}_{w,v}, \quad \underline{\underline{R}}_c = \underline{\underline{R}}_{c,h} \otimes \underline{\underline{R}}_{c,v}, \quad \underline{\underline{R}}_d = \underline{\underline{R}}_{d,h} \otimes \underline{\underline{R}}_{d,v},$$

- Convolutional matrix $\underline{\underline{\underline{W}}}$ is BCCB.

Scalability



(a) The extended lattice.



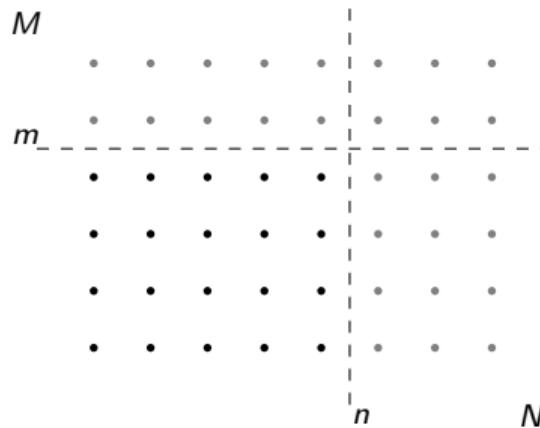
(b) The cyclic lattice.

- Separability on the cyclic lattice gives circulant or block-circulant with circulant blocks correlation matrices:

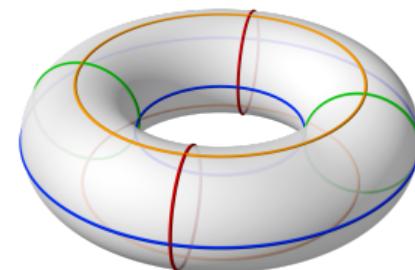
$$\underline{\underline{R}}_{w,v}, \quad \underline{\underline{R}}_c = \underline{\underline{R}}_{c,h} \otimes \underline{\underline{R}}_{c,v}, \quad \underline{\underline{R}}_d = \underline{\underline{R}}_{d,h} \otimes \underline{\underline{R}}_{d,v},$$

- Convolutional matrix $\underline{\underline{\underline{W}}}$ is BCCB.

Scalability



(a) The extended lattice.



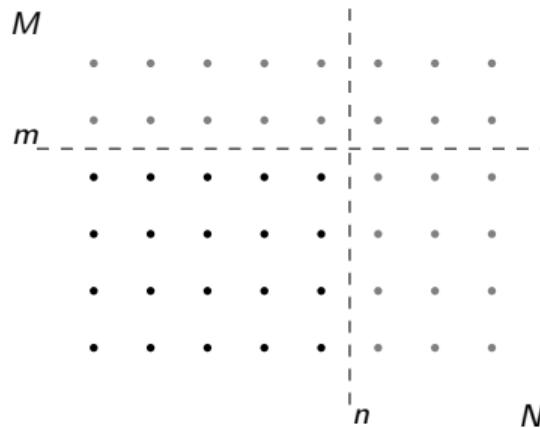
(b) The cyclic lattice.

- Separability on the cyclic lattice gives circulant or block-circulant with circulant blocks correlation matrices:

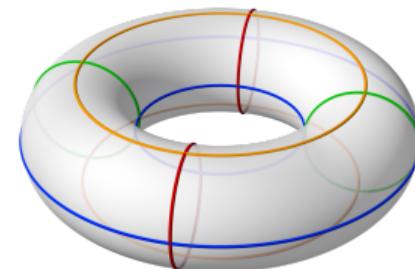
$$\underline{R}_{w,v}, \quad \underline{\underline{R}}_c = \underline{R}_{c,h} \otimes \underline{R}_{c,v}, \quad \underline{\underline{R}}_d = \underline{R}_{d,h} \otimes \underline{R}_{d,v},$$

- Convolutional matrix $\underline{\underline{\underline{W}}}$ is BCCB.

Scalability



(a) The extended lattice.



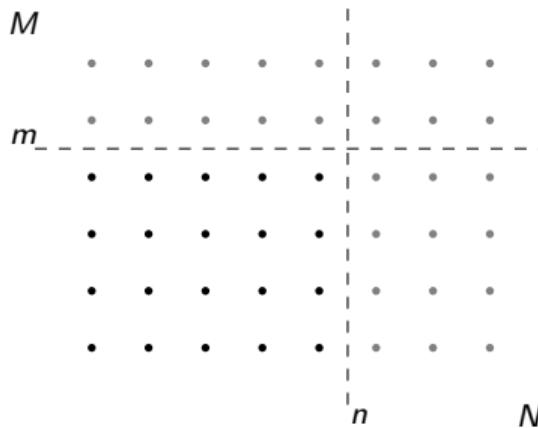
(b) The cyclic lattice.

- Separability on the cyclic lattice gives circulant or block-circulant with circulant blocks correlation matrices:

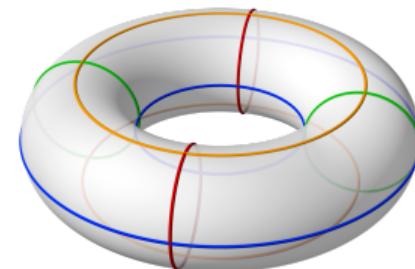
$$\underline{\underline{R}}_{w,v}, \quad \underline{\underline{R}}_c = \underline{\underline{R}}_{c,h} \otimes \underline{\underline{R}}_{c,v}, \quad \underline{\underline{R}}_d = \underline{\underline{R}}_{d,h} \otimes \underline{\underline{R}}_{d,v},$$

- Convolutional matrix $\underline{\underline{W}}$ is BCCB.

Scalability



(a) The extended lattice.



(b) The cyclic lattice.

- Separability on the cyclic lattice gives circulant or block-circulant with circulant blocks correlation matrices:

$$\underline{\underline{R}}_{w,v}, \quad \underline{\underline{R}}_c = \underline{\underline{R}}_{c,h} \otimes \underline{\underline{R}}_{c,v}, \quad \underline{\underline{R}}_d = \underline{\underline{R}}_{d,h} \otimes \underline{\underline{R}}_{d,v},$$

- Convolutional matrix $\underline{\underline{\underline{W}}}$ is BCCB.

Gibbs sampling on the cyclic lattice

Algorithm Gibbs sampler on the cyclic lattice

Input: ...**Output:** Samples from posterior $p(\mathbf{c}^*, \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}} | \mathbf{d})$

Initialize ...

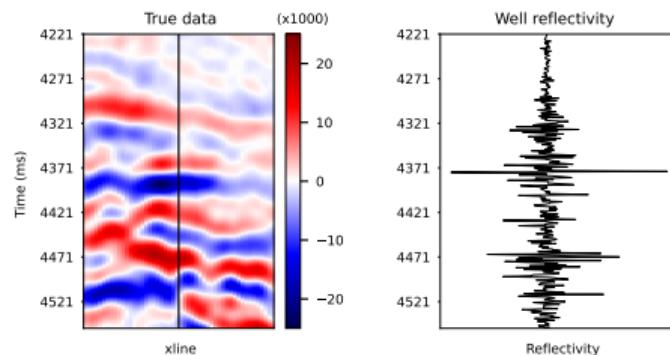
for $t = 1, 2, \dots, T$ **do** **Update reflectivity** **Update wavelet** **Update reflectivity variance** **Update wavelet variance** **Update SNR** **Update auxiliary seismic data \mathbf{d}_{aux}** **Return:** $\{\mathbf{c}^{(t)}, \mathbf{w}^{(t)}, (\sigma_c^2)^{(t)}, (\sigma_w^2)^{(t)}, \zeta^{(t)}, \mathbf{d}_{\text{aux}}^{(t)}\}_{t=B+1}^T$ after burn-in B

Some advantages:

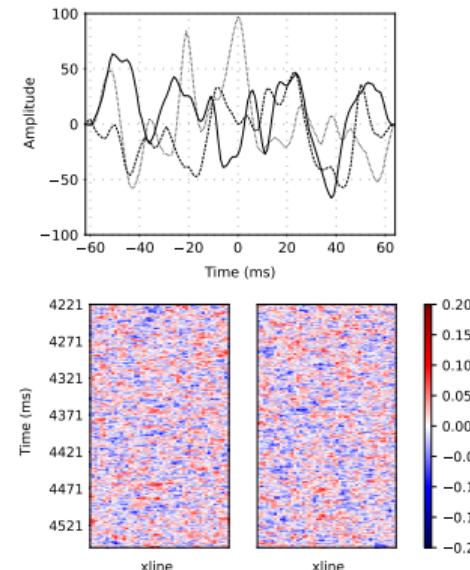
- Store only bases of $\underline{\mathbf{R}}_{\cdot, h}$, $\underline{\mathbf{R}}_{\cdot, v}$, $\underline{\mathbf{R}}$.
- Use DFT to compute full conditional parameters and sample from Gaussians in $\mathcal{O}(S \log(S))$, $S = NM$.

Real application: Gas reservoir in offshore Egypt

We extract a 330×50 s window from the AVO data for a fixed inline, centered around the well.

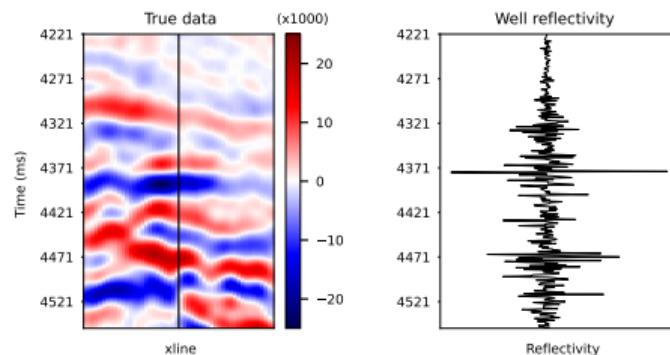


We choose high correlation in the wavelet prior and moderate correlation in the reflectivity prior. Some prior samples:

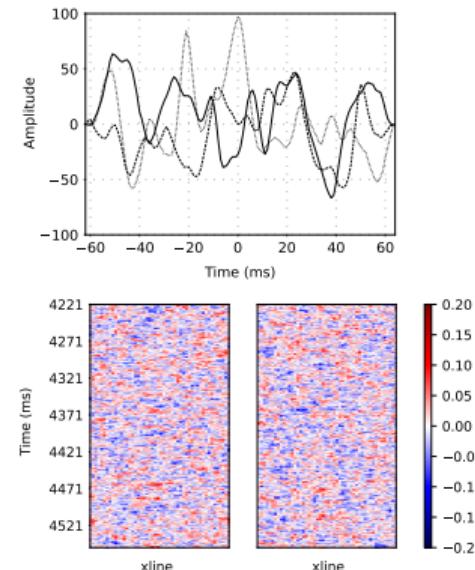


Real application: Gas reservoir in offshore Egypt

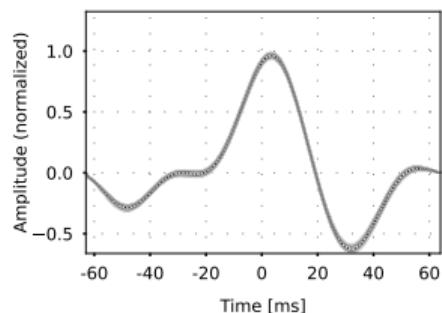
We extract a 330×50 s window from the AVO data for a fixed inline, centered around the well.



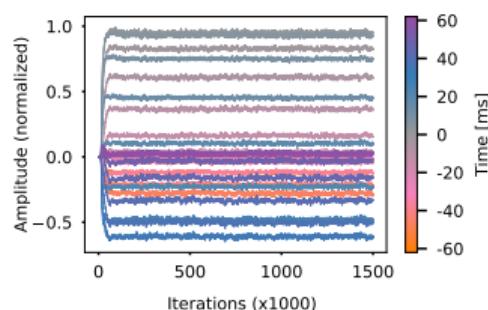
We choose high correlation in the wavelet prior and moderate correlation in the reflectivity prior. Some prior samples:



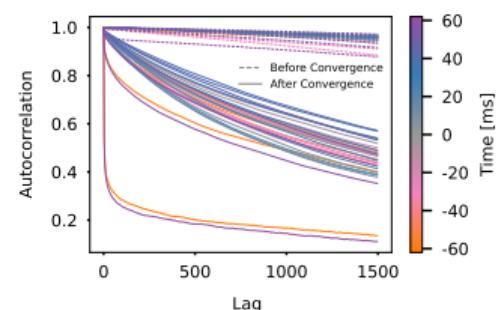
Wavelet posterior exploration



(a) Posterior samples



(b) Traceplots

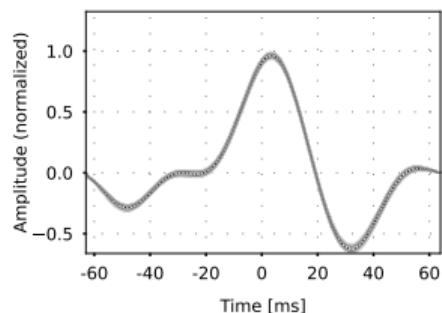


(c) Sample autocorrelation

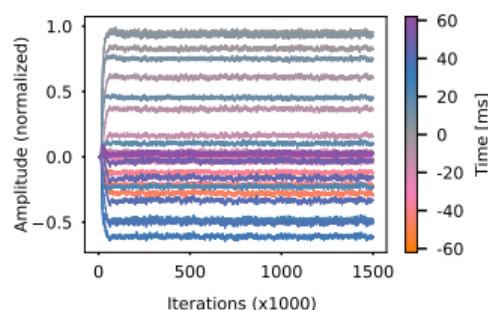
MCMC sampling results for wavelet posterior distribution.

Question: Can we sample more efficiently from the same posterior distribution?

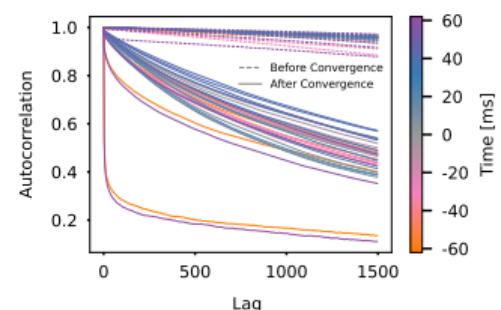
Wavelet posterior exploration



(a) Posterior samples



(b) Traceplots

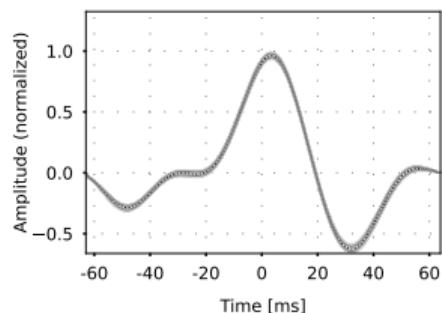


(c) Sample autocorrelation

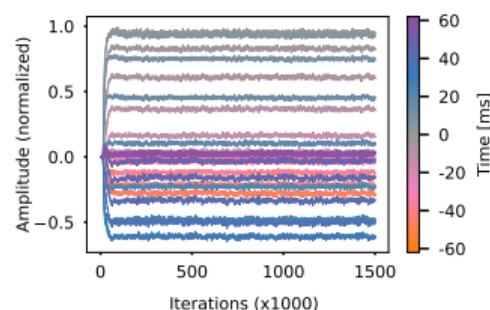
MCMC sampling results for wavelet posterior distribution.

Question: Can we sample more efficiently from the same posterior distribution?

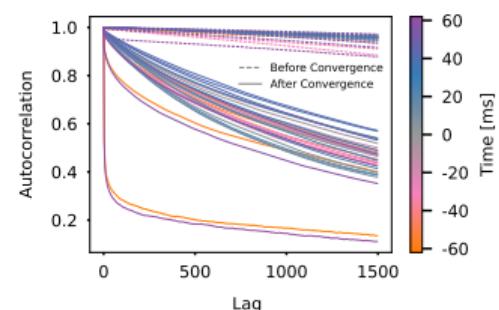
Wavelet posterior exploration



(a) Posterior samples



(b) Traceplots

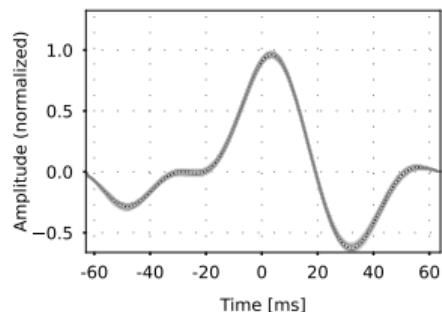


(c) Sample autocorrelation

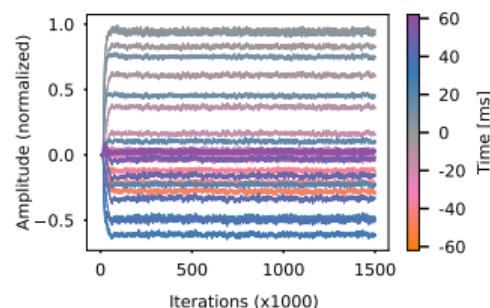
MCMC sampling results for wavelet posterior distribution.

Question: Can we sample more efficiently from the same posterior distribution?

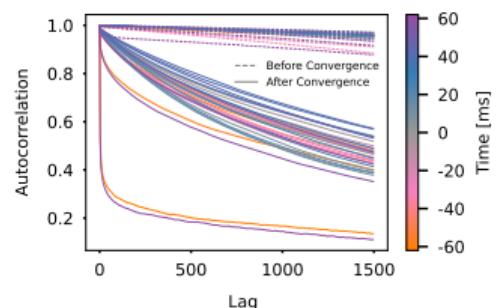
Wavelet posterior exploration



(a) Posterior samples



(b) Traceplots



(c) Sample autocorrelation

MCMC sampling results for wavelet posterior distribution.

Question: Can we sample more efficiently from the same posterior distribution?

Marginal seismic wavelet estimation with Hamiltonian Monte Carlo

- The joint reflectivity and wavelet estimation is mathematically equivalent to sampling from the joint $p(\mathbf{w}^*, \mathbf{c}^* | \mathbf{d}, \sigma_c^2, \sigma_c^2, \zeta)$.
- We instead want a marginal wavelet estimation, i.e. to sample from $p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_c^2, \zeta)$.
- This new marginal posterior looks like

$$p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) \propto p(\mathbf{w}^* | \sigma_w^2) p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}),$$

with

$$p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) = \int p(\mathbf{d}, \mathbf{c}^* | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta) d\mathbf{c}^* \quad (1)$$

- This integral can be done analytically.
- Using HMC might be better because it's a gradient-based algorithm.
- Evaluating gradients and densities at each iteration is $\mathcal{O}(s^{1.5})$ on the cyclic lattice.

Marginal seismic wavelet estimation with Hamiltonian Monte Carlo

- The joint reflectivity and wavelet estimation is mathematically equivalent to sampling from the joint $p(\mathbf{w}^*, \mathbf{c}^* | \mathbf{d}, \sigma_c^2, \sigma_c^2, \zeta)$.
- We instead want a marginal wavelet estimation, i.e. to sample from $p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_c^2, \zeta)$.
- This new marginal posterior looks like

$$p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) \propto p(\mathbf{w}^* | \sigma_w^2) p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}),$$

with

$$p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) = \int p(\mathbf{d}, \mathbf{c}^* | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta) d\mathbf{c}^* \quad (1)$$

- This integral can be done analytically.
- Using HMC might be better because it's a gradient-based algorithm.
- Evaluating gradients and densities at each iteration is $\mathcal{O}(s^{1.5})$ on the cyclic lattice.

Marginal seismic wavelet estimation with Hamiltonian Monte Carlo

- The joint reflectivity and wavelet estimation is mathematically equivalent to sampling from the joint $p(\mathbf{w}^*, \mathbf{c}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta)$.
- We instead want a marginal wavelet estimation, i.e. to sample from $p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta)$.
- This new marginal posterior looks like

$$p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) \propto p(\mathbf{w}^* | \sigma_w^2) p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}),$$

with

$$p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) = \int p(\mathbf{d}, \mathbf{c}^* | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta) d\mathbf{c}^* \quad (1)$$

- This integral can be done analytically.
- Using HMC might be better because it's a gradient-based algorithm.
- Evaluating gradients and densities at each iteration is $\mathcal{O}(s^{1.5})$ on the cyclic lattice.

Marginal seismic wavelet estimation with Hamiltonian Monte Carlo

- The joint reflectivity and wavelet estimation is mathematically equivalent to sampling from the joint $p(\mathbf{w}^*, \mathbf{c}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta)$.
- We instead want a marginal wavelet estimation, i.e. to sample from $p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta)$.
- This new marginal posterior looks like

$$p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) \propto p(\mathbf{w}^* | \sigma_w^2) p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}),$$

with

$$p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) = \int p(\mathbf{d}, \mathbf{c}^* | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta) d\mathbf{c}^* \quad (1)$$

- This integral can be done analytically.
 - Using HMC might be better because it's a gradient-based algorithm.
 - Evaluating gradients and densities at each iteration is $\mathcal{O}(s^{1.5})$ on the cyclic lattice.

Marginal seismic wavelet estimation with Hamiltonian Monte Carlo

- The joint reflectivity and wavelet estimation is mathematically equivalent to sampling from the joint $p(\mathbf{w}^*, \mathbf{c}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta)$.
- We instead want a marginal wavelet estimation, i.e. to sample from $p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta)$.
- This new marginal posterior looks like

$$p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) \propto p(\mathbf{w}^* | \sigma_w^2) p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}),$$

with

$$p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) = \int p(\mathbf{d}, \mathbf{c}^* | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta) d\mathbf{c}^* \quad (1)$$

- This integral can be done analytically.
- Using HMC might be better because it's a gradient-based algorithm.
- Evaluating gradients and densities at each iteration is $\mathcal{O}(s^{1.5})$ on the cyclic lattice.

Marginal seismic wavelet estimation with Hamiltonian Monte Carlo

- The joint reflectivity and wavelet estimation is mathematically equivalent to sampling from the joint $p(\mathbf{w}^*, \mathbf{c}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta)$.
- We instead want a marginal wavelet estimation, i.e. to sample from $p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta)$.
- This new marginal posterior looks like

$$p(\mathbf{w}^* | \mathbf{d}, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) \propto p(\mathbf{w}^* | \sigma_w^2) p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}),$$

with

$$p(\mathbf{d} | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta, \mathbf{d}_{\text{aux}}) = \int p(\mathbf{d}, \mathbf{c}^* | \mathbf{w}^*, \sigma_c^2, \sigma_w^2, \zeta) d\mathbf{c}^* \quad (1)$$

- This integral can be done analytically.
- Using HMC might be better because it's a gradient-based algorithm.
- Evaluating gradients and densities at each iteration is $\mathcal{O}(s^{1.5})$ on the cyclic lattice.

Conclusions

- We proposed an approach for estimating a seismic wavelet with full UQ.
- Gibbs sampler allows joint wavelet and reflectivity estimation but is slow.
- Collapsed HMC allows efficient marginal wavelet estimation.

References

- Buland, A. and Omre, H. (2003). Bayesian wavelet estimation from seismic and well data. *Geophysics*, 68, 2000–2009.
- Buland, A. and Omre, H. (2003). Joint AVO inversion, wavelet estimation and noise-level estimation using a spatially coupled hierarchical Bayesian model. *Geophysical Prospecting*, 51(6).
- Senn, G., Walker, M. and Tjelmeland, H. (2025). Scalable Bayesian seismic wavelet estimation. *Geophysical Prospecting*, 73(5), 1635–1650.

Conclusions

- We proposed an approach for estimating a seismic wavelet with full UQ.
- Gibbs sampler allows joint wavelet and reflectivity estimation but is slow.
- Collapsed HMC allows efficient marginal wavelet estimation.

References

- Buland, A. and Omre, H. (2003). Bayesian wavelet estimation from seismic and well data. *Geophysics*, 68, 2000–2009.
- Buland, A. and Omre, H. (2003). Joint AVO inversion, wavelet estimation and noise-level estimation using a spatially coupled hierarchical Bayesian model. *Geophysical Prospecting*, 51(6).
- Senn, G., Walker, M. and Tjelmeland, H. (2025). Scalable Bayesian seismic wavelet estimation. *Geophysical Prospecting*, 73(5), 1635–1650.

Conclusions

- We proposed an approach for estimating a seismic wavelet with full UQ.
- Gibbs sampler allows joint wavelet and reflectivity estimation but is slow.
- Collapsed HMC allows efficient marginal wavelet estimation.

References

- Buland, A. and Omre, H. (2003). Bayesian wavelet estimation from seismic and well data. *Geophysics*, 68, 2000–2009.
- Buland, A. and Omre, H. (2003). Joint AVO inversion, wavelet estimation and noise-level estimation using a spatially coupled hierarchical Bayesian model. *Geophysical Prospecting*, 51(6).
- Senn, G., Walker, M. and Tjelmeland, H. (2025). Scalable Bayesian seismic wavelet estimation. *Geophysical Prospecting*, 73(5), 1635–1650.

Conclusions

- We proposed an approach for estimating a seismic wavelet with full UQ.
- Gibbs sampler allows joint wavelet and reflectivity estimation but is slow.
- Collapsed HMC allows efficient marginal wavelet estimation.

References

- Buland, A. and Omre, H. (2003). Bayesian wavelet estimation from seismic and well data. *Geophysics*, 68, 2000–2009.
- Buland, A. and Omre, H. (2003). Joint AVO inversion, wavelet estimation and noise-level estimation using a spatially coupled hierarchical Bayesian model. *Geophysical Prospecting*, 51(6).
- Senn, G., Walker, M. and Tjelmeland, H. (2025). Scalable Bayesian seismic wavelet estimation. *Geophysical Prospecting*, 73(5), 1635–1650.