

Information Technology Project Project proposal March 7, 2024

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Context (a)

- Talos, the mythological automaton
- Surveillance & security
- Autonomy



Idea



Autonomous Robot

Talos is able to guard a perimeter and provide the data to the user.



User Interface

The user interacts with the robot and is able to understand the data provided.

Innovation potential



Machine learning



Video streaming



Energy efficient



Market analysis <u>~</u>





It is a financially prosperous market with a great future prospect.



Target market

Two main markets: autonomous system & surveillance.

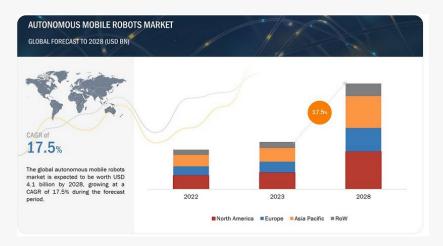


Competitive landscape

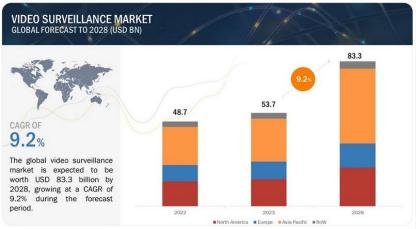
It is a fragmented, young not crowded market which is still in the early phases of its life cycle.

Market analysis 🗠

Future growth







Basic components



Mobile Application

Shares identical characteristics with the Web Application. Incorporates an authentication mechanism to only allow authorized owners to view data from their robot.



Backend & Monitoring

Establish a communication between the surveillance robots and the server.



Web Application

Handle the visualization of all the results. Present the data gathered by Talos in a user-friendly manner.



Autonomous Robot

Featured with several sensors for data acquisition and monitoring.

Basic components - Mobile application

- Tools: Flutter and Dart
- Support for iOS and Android
- Intuitive and aesthetically pleasing







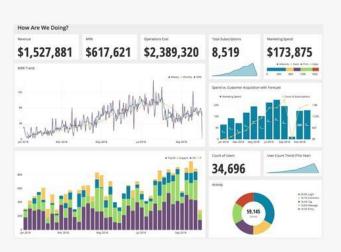
Flutter

Basic components - Mobile application

- Authentication Mechanisms
- Data visualization
- UI Development

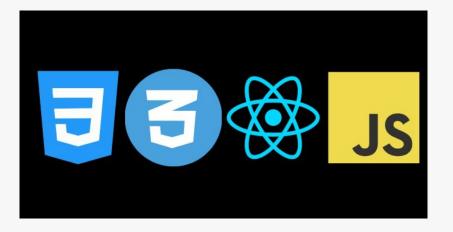






Basic components - Web Application

- Tools: HTML5, CSS, JavaScript and React
- Mobile and Desktop Compatibility
- Unique functionalities



Basic components - Web Application

- Authentication Mechanisms
- Video Streaming
- Dashboard







Basic components - Backend & Database

Tools: MongoDB

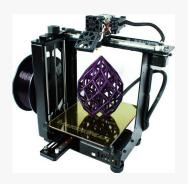
Data Transmitting and Receiving

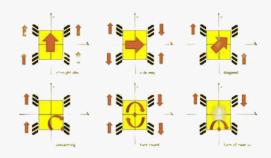


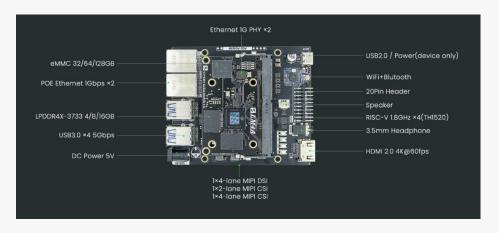


Basic components - Autonomous robot

- 3D printed
- Mecanum wheels
- Lichee Pi 4A (RISC-V core)
- WiFi

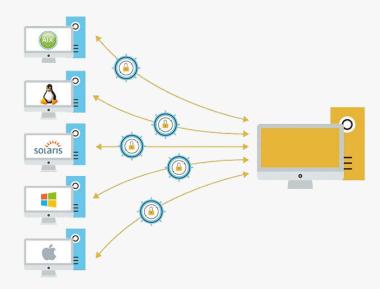


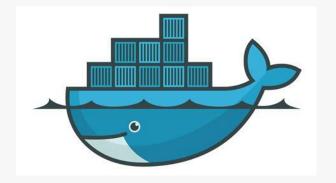




Basic components - Dockerization

- Isolation and portability for distribution
- Replicated environment





Further Development

- Monitoring: Grafana and Prometheus
- Trained machine learning model
- Enhanced security mechanisms
- Enhanced maneuverability





Cost Analysis (approximation)

| Item | Units | Cost (€) |
|---|-------|----------|
| Lichee Pi $4A (16 + 128GB) [5]$ | 1 | 222.17 |
| Temperature & humidity sensor [6] | 1 | 6.49 |
| Speed sensor [7] | 1 | 3.88 |
| USB Camera [5] | 1 | 9.29 |
| GNSS/GPS Module [8] | 1 | 12.18 |
| 3D Printer filament [9] | 1 | 30.49 |
| Hosting services | 1 | free |
| Engineer salary (2 month equivalent) [10] | 4 | 6073.83 |
| Total $(\sum_{n=1}^{8} Units_n \cdot Cost_n)$ | -: | 24567.32 |

Table 1: Estimated cost of the project [own compilation].

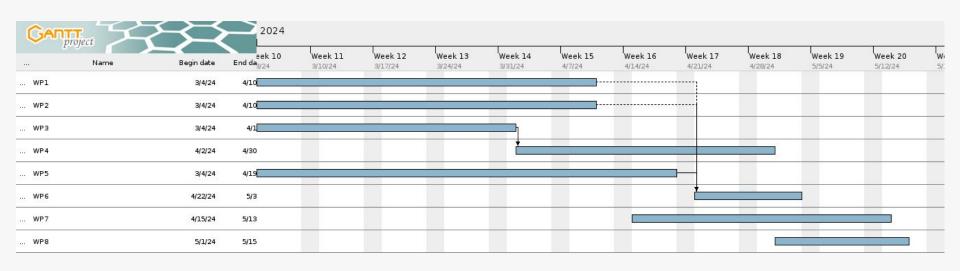
Package Assignment

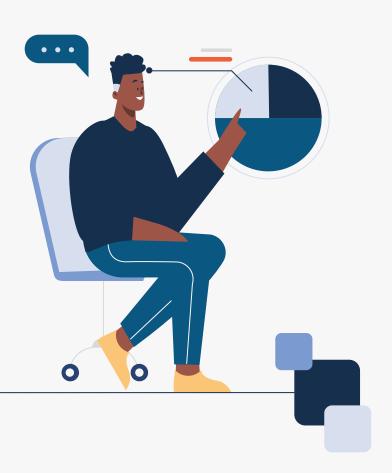
| Nombres / Work Package |
|------------------------------|
| Joan Llonch Majó |
| Luis Jesús Valverde Zavaleta |
| Guillermo Vidal Sulé |
| Oriol Vilella Jam |

| WP1 | WP2 | WP3 | WP4 | WP5 | WP6 | WP7 | WP8 |
|-----|-----|-----|-----|-----|------|-----|-----|
| | R | | C | | 11.7 | C | C |
| | | R | C | | C | C | C |
| | | | | R | R | C | R |
| R | | | R | | | R | C |

Table 1: Work packages assigned to each member, being either responsible (R) or contributor (C).

Gantt Diagram





Thanks!



