state_interfaces:state_start_front_left_wheel/position → joint_state_broadcaster:state_end_front_left_wheel/position

state_interfaces:state_start_rear_left_wheel/velocity → joint_state_broadcaster:state_end_rear_left_wheel/velocity

state_interfaces:state_start_front_left_wheel/velocity → joint_state_broadcaster:state_end_front_left_wheel/velocity

state_interfaces:state_start_rear_left_wheel/position → joint_state_broadcaster:state_end_rear_left_wheel/position

state_interfaces:state_start_rear_right_wheel/position → joint_state_broadcaster:state_end_rear_right_wheel/position

state_interfaces:state_start_front_right_wheel/velocity → joint_state_broadcaster:state_end_front_right_wheel/velocity

state_interfaces:state_start_front_right_wheel/position → joint_state_broadcaster:state_end_front_right_wheel/position

state_interfaces:state_start_rear_right_wheel/velocity → joint_state_broadcaster:state_end_rear_right_wheel/velocity

command_interfaces
front_left_wheel/velocity
front_right_wheel/velocity
rear_left_wheel/velocity
rear_right_wheel/velocity
ridgeback_velocity_controller/angular/z/velocity
ridgeback_velocity_controller/linear/x/velocity
ridgeback_velocity_controller/linear/y/velocity

state_interfaces
front_left_wheel/position
front_left_wheel/velocity
front_right_wheel/position
front_right_wheel/velocity
rear_left_wheel/position
rear_left_wheel/velocity
rear_right_wheel/position
rear_right_wheel/velocity

ridgeback_velocity_controller	
angular/z/velocity	
linear/x/velocity	
linear/y/velocity	

joint_state_broadcaster	
front_left_wheel/position	
front_left_wheel/velocity	
front_right_wheel/position	
front_right_wheel/velocity	
rear_left_wheel/position	
rear_left_wheel/velocity	
rear_right_wheel/position	
rear_right_wheel/velocity	