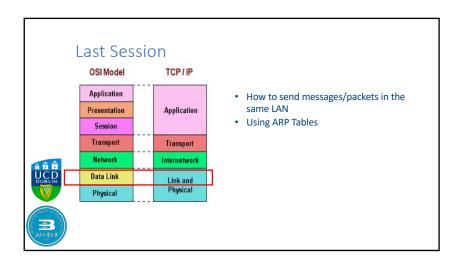
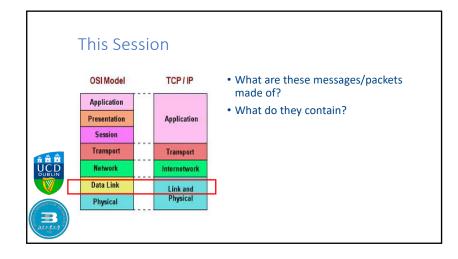
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Computer Networks

Link Layer



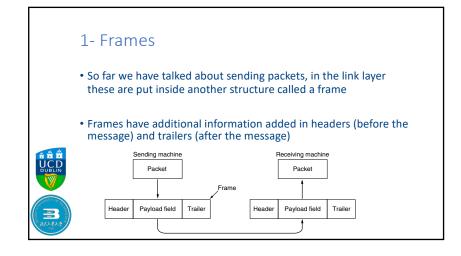


# The Link Layer

- In the physical layer we looked at how digital information is transferred between two machines
- In the link layer we are concerned with how to send messages between two machines
  - Messages are called frames



- The link layer has a number of functions, some important ones are
  - Framing messages
  - Dealing with transmission errors
  - Regulating the flow of data so slow receivers are not swamped

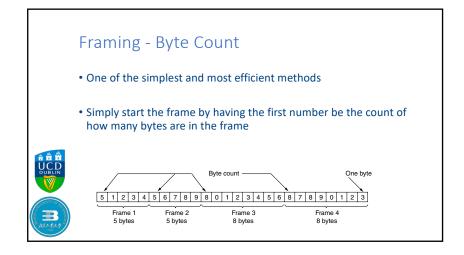


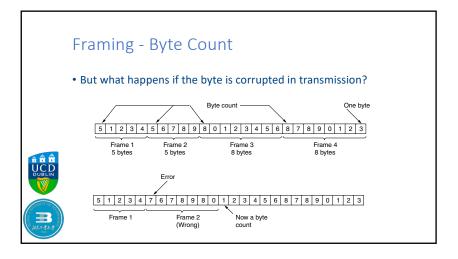
# Framing

- Breaking up the bit stream into frames is more difficult than it at first appears
- A good design must make it easy for a receiver to find the start of new frames while using little of the channel bandwidth



- We will look at three methods:
  - Byte count
  - Flag bytes with byte stuffing
  - Flag bits with bit stuffing





## Framing – Flag Byte

- The second framing method gets around the problem of resynchronization after an error by having each frame start and end with special bytes
- Often the same byte, called a **flag byte**, is used as both the starting and ending delimiter



- Two consecutive flag bytes indicate the end of one frame and the start of the next
- Thus, if the receiver ever loses synchronization it can just search for two flag bytes to find the end of the current frame and the start of the next frame



# Framing – Flag Byte

- What happens if the flag byte appears in the data being sent?
- One solution is to insert a special escape byte (ESC) before any accidental flag byte
- This way we can tell when a frame ends or the byte is just data



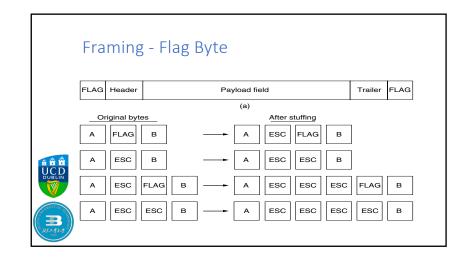
- The receiver then removes these flag and escape bytes from data it receives
- This process is called byte stuffing

# Framing – Escape Byte

- What happens if the escape byte appears in the data being sent?
- The simple solution is that another escape byte is stuffed before it







# Framing – Flag Bits

- Byte stuffing has a drawback, adding these bytes increases the size of the message a lot
  - Because each flag adds another byte
- The third method of framing uses single bits for stuffing so the increase in size is not as much





## Framing – Flag Bits

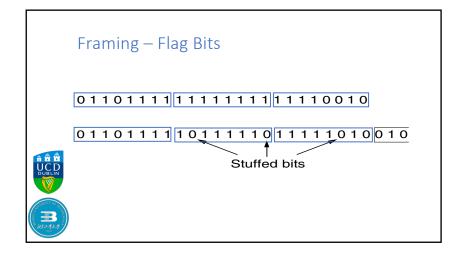
- Each frame begins with the bit pattern 011111110
  - six 1s

- Bit Stuffing
  - Sender: Whenever we see five 1s in our data we insert a 0
  - Receiver: Whenever we see five 1s we remove the following 0



- It is the same idea as byte stuffing but with less overhead
- The only problem is that the final frame could be of any number of bits but byte stuffing it is always a number of bytes

# 



## Physical Layer Framing

- · There exists other methods of framing that we are not studying closely
- Some of them exploit knowledge of what is happening in the physical layer
  - If the physical layer is using a protocol such as 4B/5B
  - It means that we know that certain byte sequences cannot appear in the
  - Therefore, we can use one of these Byte sequences to signal the start and end of frames

#### 2- Errors

- What the physical layer does is accept a raw bit stream and attempt to deliver it to the destination
- If the channel is noisy, the physical layer will add some redundancy to its signals to reduce the bit error rate
- However, the bit stream received by the data link layer is not guaranteed to be error free
- Some bits may have different values and the number of bits received may differ from the number of bits transmitted
- It is up to the data link layer to **detect** and, if necessary, **correct** errors





- The usual approach is for the data link layer to break up the bit stream into discrete frames, compute a short token called a checksum for each frame, and include the checksum in the frame when it is transmitted
- When a frame arrives at the destination, the checksum is recomputed
- If the newly computed checksum is different from the one contained in the frame, the data link layer knows that an error has occurred and takes steps to deal with it



#### **Error Control**

- As we know when a signal is transmitted by the physical layer attenuation and distortion can cause the signal to be read incorrectly
- There are a number of things we can do
  - Use codes to detect if errors have occurred
  - Use codes to correct errors when they occur
  - Retransmit any lost frames



• Reliability is a concern that appears in multiple layers







# Adding Redundancy

- If we add extra information to the frame we can use these to help detect or correct errors
- Error Detection
  - · Add check bits to messages that let some errors be detected



- Error Correction
  - Add more **check bits** to messages that let some errors be corrected
- The hardest problem is to structure the codes to detect as many errors with a small amount of extra bits and not too much calculation

# Simple Error Detection Example

- A simple code for detecting errors
  - Send two copies, if they are different there has been an error
- How good is this code?
  - How many errors can it detect/correct?
  - How many errors will make it fail?



How much overhead does it add?

# **Using Error Codes**

- Codeword consists of D data bits plus R check bits
- · Called systematic block code
- Number of check bits depends on the size of the data
- Check bits are computed based on the data and then added to the end



- When the receiver gets the package it recomputes the check bits based on the data bits
  - If there are no errors the check bits should match
- When an error is detected it can be difficult to tell if the error is in the data or in the check bits



- Use a single check bit such that the number of 1s in every codeword is
- If the number of 1s in the data is even we add a 0
- If the number of 1s in the data is odd we add a 1
- This is called single parity check



- If receiver gets a codeword with an odd number of 1's, it knows error(s) occurred
  - · can detect any odd number of bit errors
  - but: can't tell how many errors, or which bits are in error
  - even worse: any even number of bit errors is undetectable





## Single Parity Check - Example

- Data to be transmitted: 10110101
  - There are 5 1s in the data so the parity bit is 1
- We transmit: 101101011
  - If receiver gets 101101011 parity check is ok
  - If receiver gets 101100011 parity check fails
  - If receiver gets 101110011 parity check is ok but codeword is incorrect
  - If receiver gets 001100011 parity check is ok but codeword is incorrect



- Data to be transmitted: 10110001
  - There are 4 1s in the data so the parity bit is 0

# 2 Dimensional Parity Check

- In this scheme we form data into a 2-dimensional array and add single parity check bits to each row and each column
- If we have the data 1110001 1000111 0011001



- We form a 3x7 array and add row and column parity bits
  - 1 1 1 0 0 0 1 0 • 1 0 0 0 1 1 1 0
  - .00110011 .0101111



# 3

# 2 Dimensional Parity Check

- The receiver knows to form received bit string into 42x8 array, then check the row and column parity bits
- This scheme can detect any odd number of bit errors in a row or column
  - It can also detect an even number of bit errors if they're in a single row (using the column parity checks)
  - It can also detect an even number of bit errors if they're in a single column (using the row parity checks)



• This scheme can correct any single bit error

#### Example 1 - 1 Bit Error

- If we have the data 1110001 1000111 0011001
- And the receiver gets
  - ·11000010
  - ·10001110
  - .0011001**1**
  - .0101111



• The receiver can detect that the bit in position (1, 3) was in error and can correct it



#### Example 2 - 2 Bit Errors

- If we have the data 1110001 1000111 0011001
- And the receiver gets
  - 0 1 0 0 0 0 1 0
  - ·10001110
  - .0011001**1**
- .01011111



• The receiver can detect that the bit errors have occurred but it cannot correct them

## Example 3 - 2 Bit Errors

- If we have the data 1110001 1000111 0011001
- And the receiver gets
   0 1 1 0 0 0 1 0
- · 1 0 1 0 1 1 1 0 · 0 0 1 1 0 0 1 1 · 0 1 0 1 1 1 1 1



- The receiver can detect that the bit errors have occurred but it cannot correct them
- The same parity checks would be received if the errors were in positions (1, 3) and (2, 1)

# Example 4 - 3 Bit Errors

- If we have the data 1110001 1000111 0011001
- And the receiver gets 0 0 0 0 0 1 0

  - · 1 0 0 0 1 1 1 0
  - .0011001**1**
  - .01011111



- The receiver can detect that the bit errors have occurred but it cannot correct them
- Two of the bit errors could be on a single row with a correct parity so we cannot correct them



## Example 5 - 4 Bit Errors

- If we have the data 1110001 1000111 0011001
- And the receiver gets
  - 0 1 0 0 0 0 1 0
  - · 1 0 1 0 1 1 1 0
  - .00110011
  - .11011111



• The receiver can detect that the bit errors have occurred but cannot correct them



• Errors in (1,1), (1,3), (2,1) and (4,3) would have the same parity check