Chapter 33: Searching by Elimination.

In which we introduce a simple new search technique.

We are given a finite set W and a boolean function F defined on the elements of W. We are asked to construct a program to meet the following specification.

Pre:
$$\langle \exists w : w \in W : F.w \rangle$$

Post: F.x

We begin by defining

* (0) P.V =
$$\langle \exists v : v \in V : F.v \rangle$$
 , $V \subseteq W$

We can now rewrite the specification as

Pre: P.W

Post: $P.\{x\}$

We introduce a set variable V and propose the following invariants

$$P0 : P.V$$

 $P1 : V \subseteq W$

This is easily established by

$$V := W$$

We will choose the size of V as the variant which is written #.V

This leads us to the following program skeleton.

$$V := W \{P0 \land P1\}$$

$$; do \#.V \neq 1 \quad \Rightarrow \quad \{P0 \land P1 \land \#.V \neq 1\}$$

$$\text{``Decrease } \#.V \text{ but maintain } P0 \land P1\text{'`}$$

$$\{P0 \land P1\}$$
od
$$\{P0 \land P1 \land \#.V = 1\}$$

$$x := \text{``the unique elements in } V\text{'`}$$

Constructing the loop body.

As W is not the empty set, $P1 \land \#.V \neq 1$ leads us to conclude that $2 \leq \#.V$. Given that there are at least 2 elements in V we should be able to remove one of them without violating P0.

We propose the following structure. Note that α and β are as yet unknown guards.

```
V := W
;do \#.V \neq 1 \Rightarrow \{P0 \land P1 \land \#.V \neq 1\}
\text{"choose a, b } \epsilon V, \text{ where a } \neq b\text{"}
\text{if } \alpha \Rightarrow V := V \setminus \{a\}
[] \beta \Rightarrow V := V \setminus \{b\}
\text{fi}
\{P0 \land P1\}
od
x := \text{"the unique element in } V\text{"}
```

We must now determine α and β . Let us concentrate on α . The following must hold

$$\alpha \land (a \in V) \land (b \in V) \land (a \neq b) \land P.V \implies P.(V \setminus \{a\})$$

We calculate

$$P.V \Rightarrow P.(V \setminus \{a\})$$

$$= \{\text{definition of P, split off F.a, a } \epsilon V\}$$

$$F.a \vee P.(V \setminus \{a\}) \Rightarrow P.(V \setminus \{a\})$$

$$= \{P \vee Q \Rightarrow Q \equiv P \Rightarrow Q\}$$

$$F.a \Rightarrow P.(V \setminus \{a\})$$

$$= \{\text{split off b, b } \epsilon P.(V \setminus \{a\})\}$$

$$F.a \Rightarrow F.b \vee P.(V \setminus \{a,b\})$$

$$\leftarrow \{(P \Rightarrow Q) \Rightarrow (P \Rightarrow (Q \vee R))\}$$

$$F.a \Rightarrow F.b$$

So a candidate for α is F.a \Rightarrow F.b

Symmetrically, a candidate for β is F.b \Rightarrow F.a

Thus we have arrived at the program

```
V := W
;do \#.V \neq 1 \Rightarrow \{P0 \land P1 \land \#.V \neq 1\}
\text{"choose a, b } \epsilon V, \text{ where a } \neq b\text{"}
\text{if } F.a \Rightarrow F.b \Rightarrow V := V \setminus \{a\}
[] F.b \Rightarrow F.a \Rightarrow V := V \setminus \{b\}
\text{fi}
\{P0 \land P1\}
od
x := \text{"the unique element in } V\text{"}
```

This is the generic Searching by Elimination algorithm.