

모두의 딥러닝 (Deep learning)

Nambeom Kim (nbunkim@gmail.com)

Neural network to Deep learning (Perceptron)

Deep learning

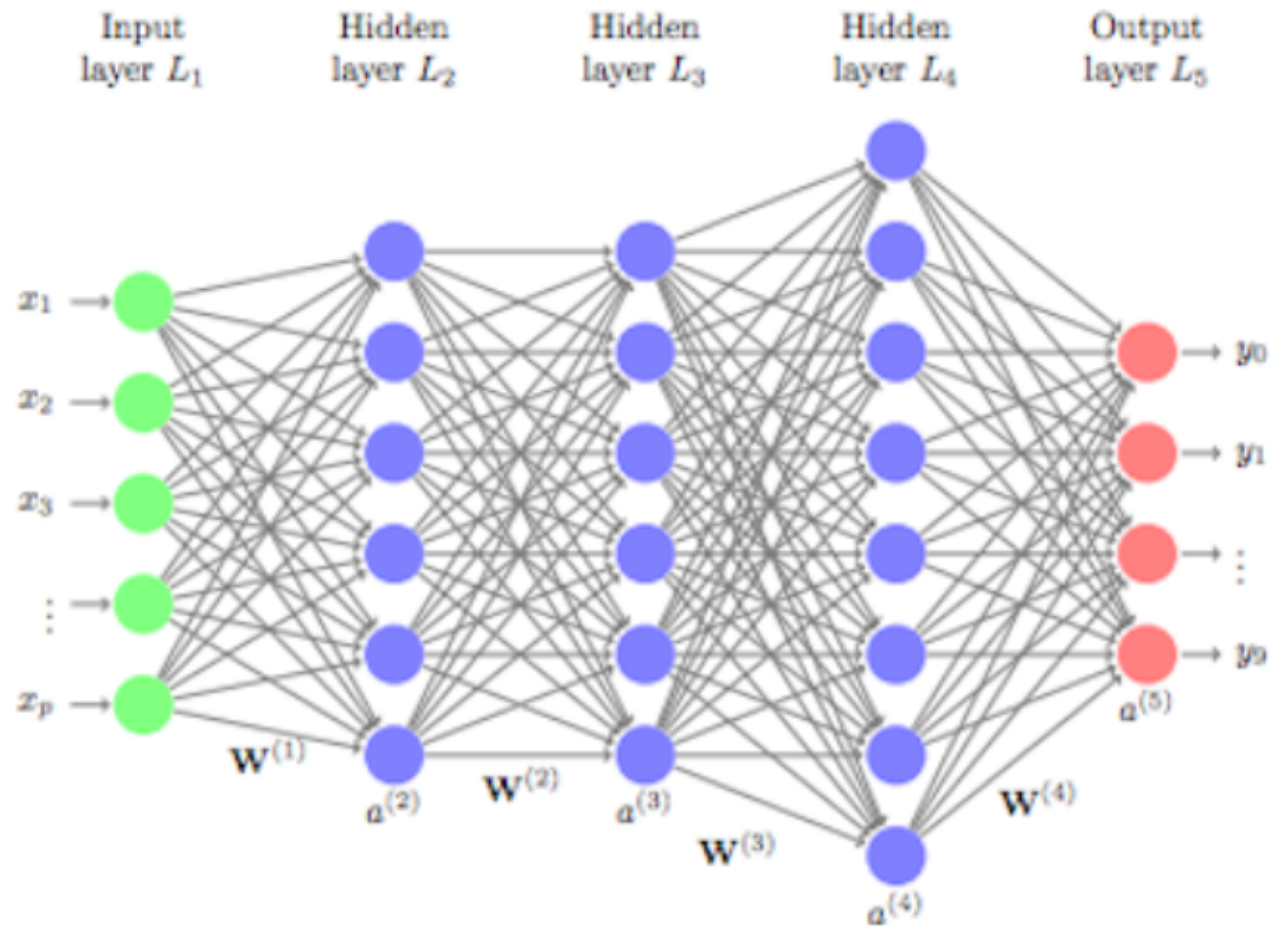
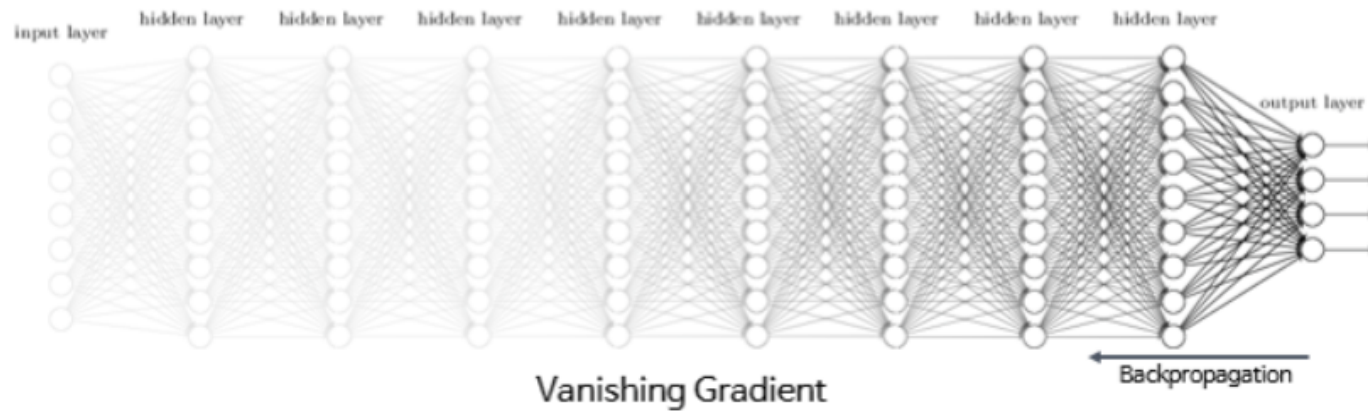
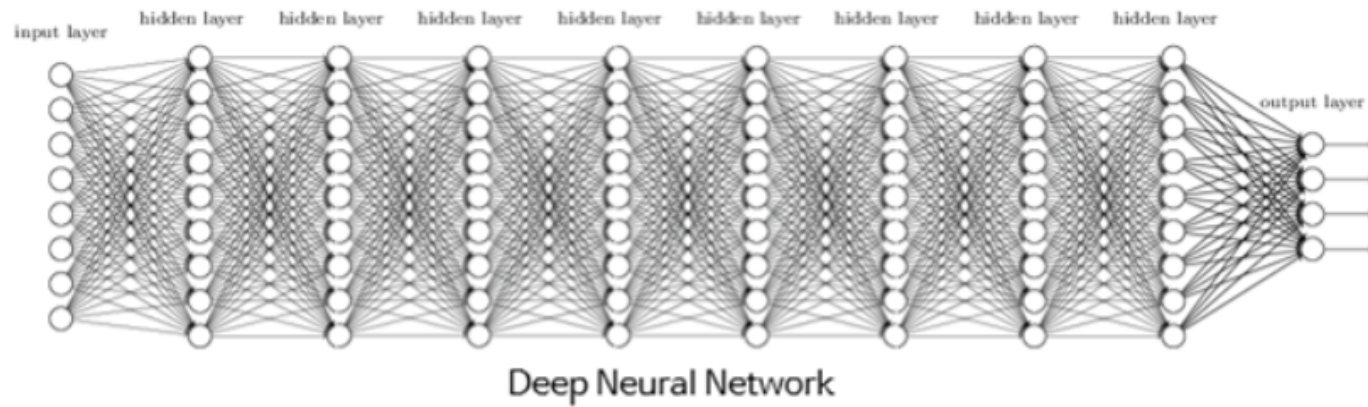


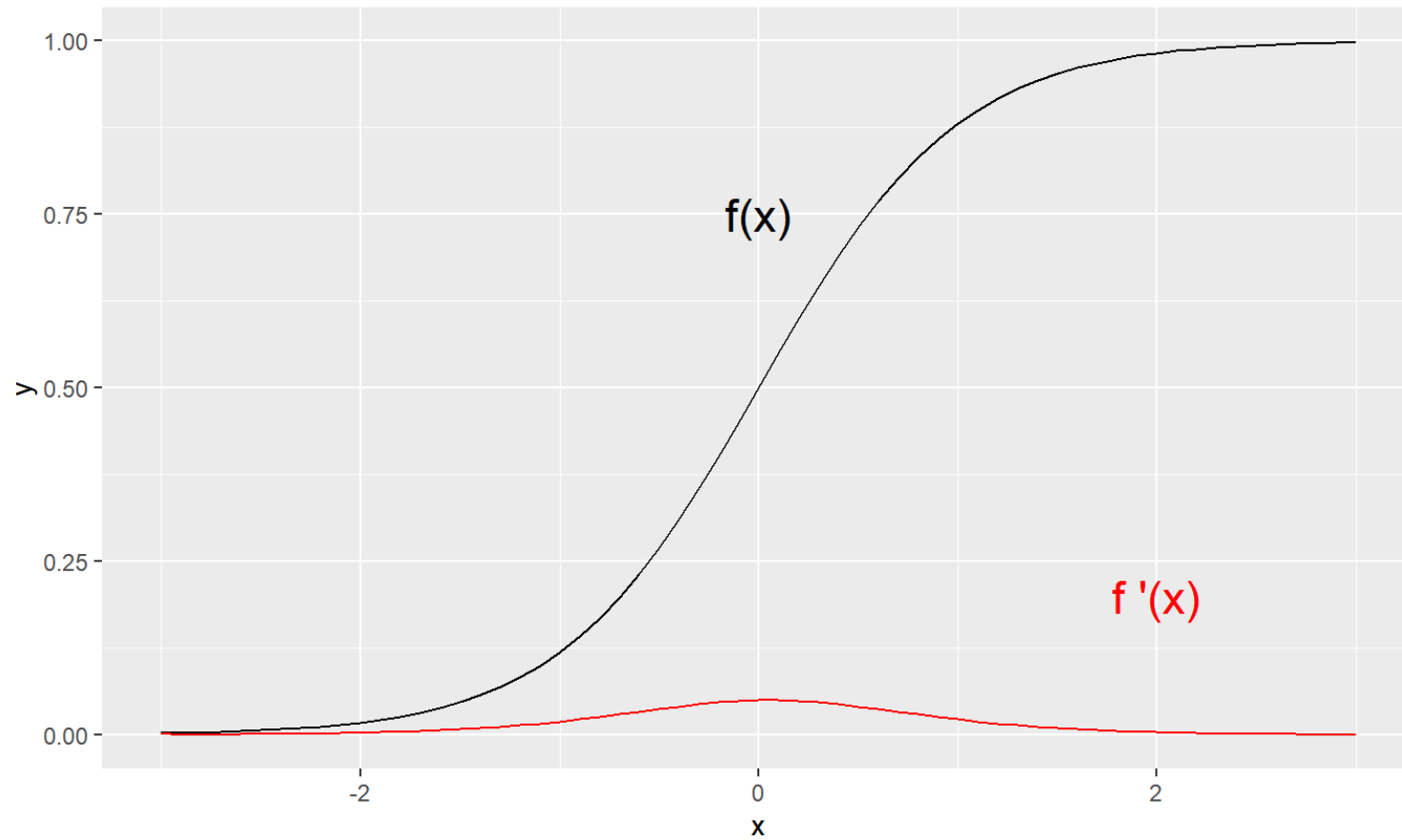
Figure 13.3: Representation of a deep feedforward neural network.

Vanishing gradient



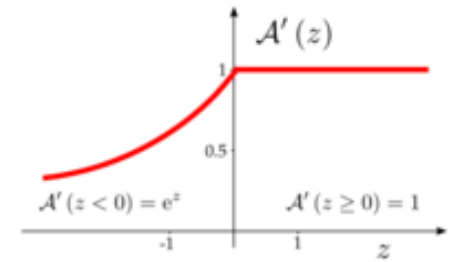
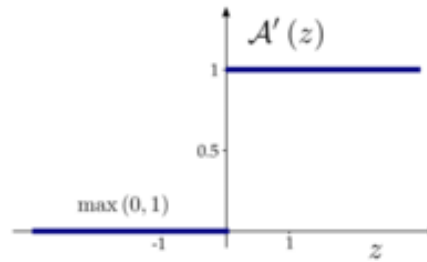
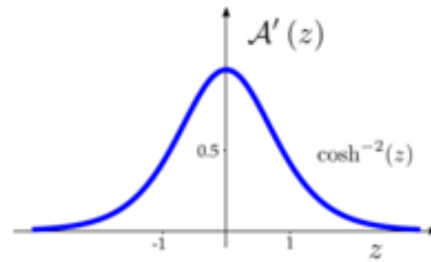
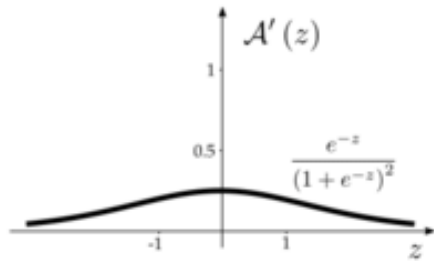
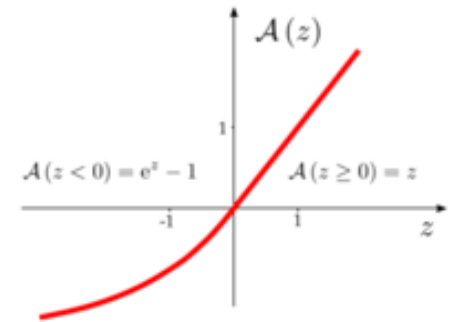
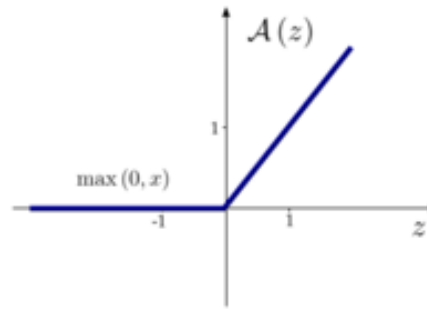
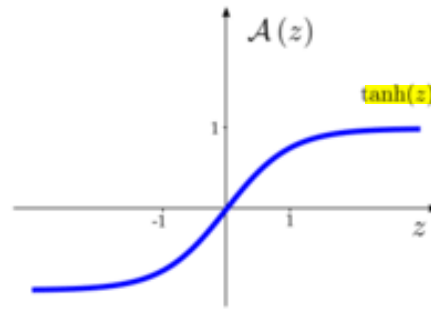
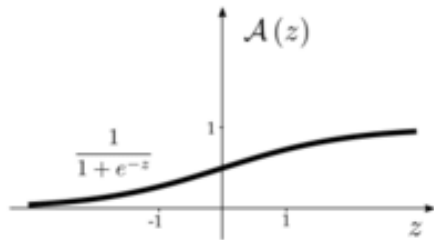
<https://trendy00develope.tistory.com/37>

Differentiation of sigmoid



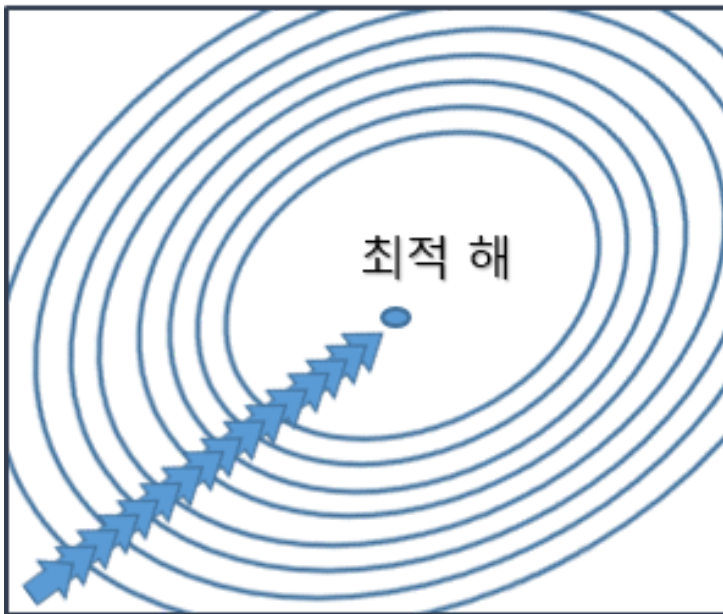
안드레이 카패시 미디어 블로그

Differentiation of activation functions

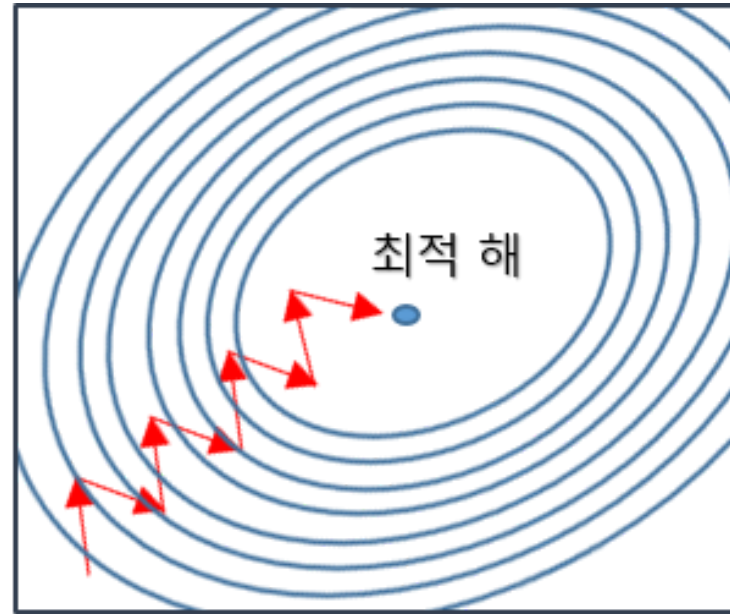


경사하강 vs 확률적 경사하강

$$\theta_j^{(n+1)} = \theta_j^{(n)} - \gamma \frac{\partial}{\partial \theta_j} J(\theta^{(n)})$$



경사 하강법

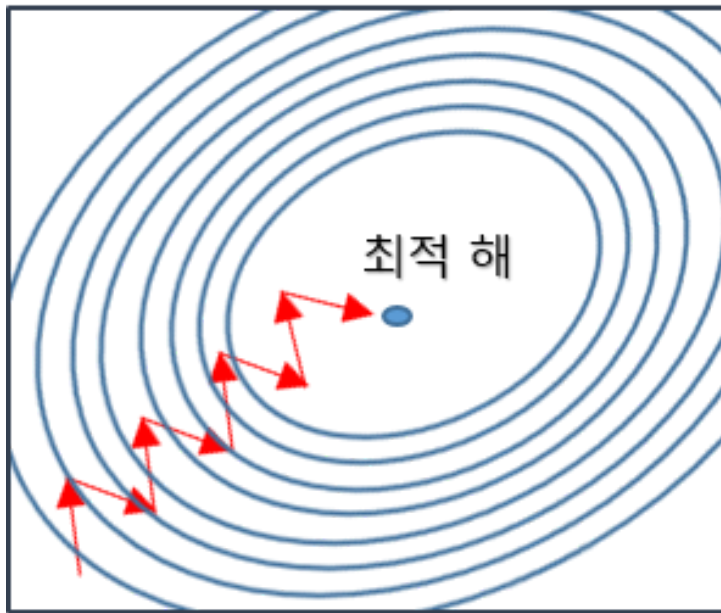


확률적 경사 하강법

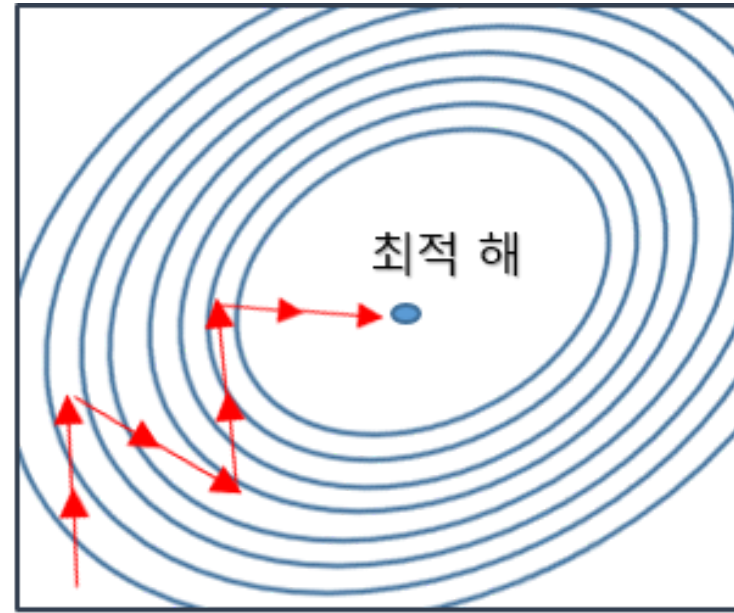
<https://twinw.tistory.com/247>

모멘텀 (Momentum)

$$\theta_j^{(n+1)} = \theta_j^{(n)} + v_{n-1} - \gamma \frac{\partial}{\partial \theta_j} J(\theta^{(n)})$$
$$v_n = \sum_{i=0}^n \rho^{n-i} [-\gamma \frac{\partial}{\partial \theta_j} J(\theta^{(i)})]$$



확률적 경사 하강법



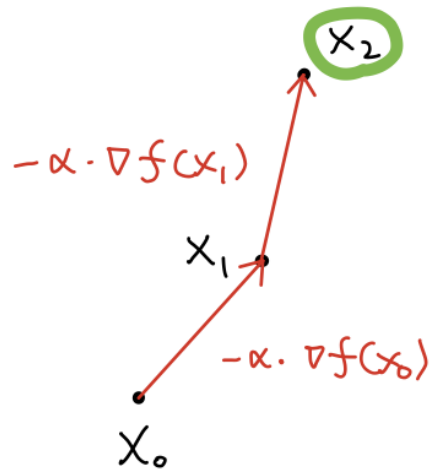
모멘텀

<https://twinw.tistory.com/247>

이전 방향을 고려하여 비슷한 방향으로 진행

이전 방향과 완전히 다른 방향으로 움직이는 것 = 확률적 경사 하강법

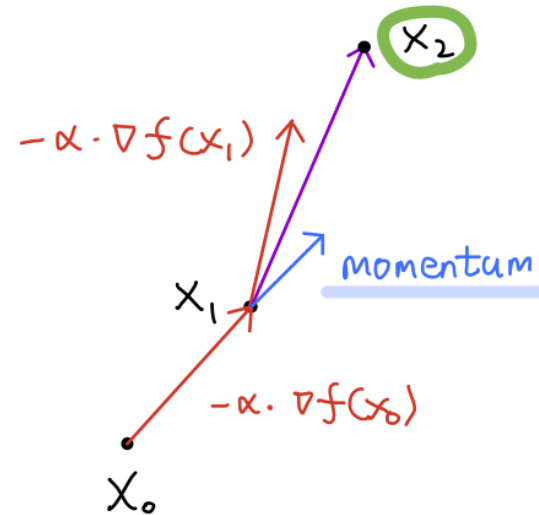
Gradient Descent



$$x_1 = x_0 - \alpha \cdot f(x_0)$$

$$x_2 = x_1 - \alpha \cdot f(x_1)$$

Momentum



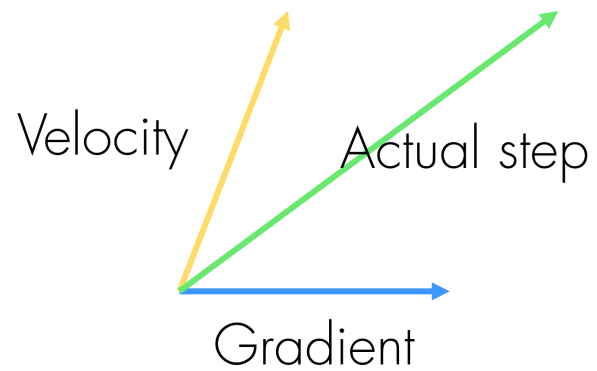
$$x_1 = x_0 - \alpha \cdot f(x_0)$$

$$x_2 = x_1 - \alpha \cdot f(x_1) + \text{momentum}$$

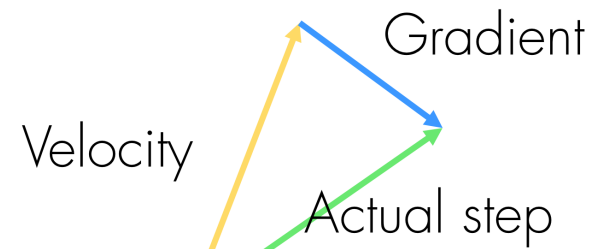
<https://icim.nims.re.kr/post/easyMath/428>

Nesterov Momentum

Plain momentum



Nesterov momentum



<https://hyunw.kim/blog/2017/11/01/Optimization.html>

Adagrad and RMSProp

Update

$$\theta_j^{(n+1)} = \theta_j^{(n)} - \frac{\gamma}{\sqrt{\mathbf{h}}} \frac{\partial}{\partial \theta_j} J(\theta^{(n)})$$

너무 빨리 움직이는 것은 제외, 잘 움직이지 않는 것을 움직이기 위해 사용하는 \mathbf{h}

Adagrad

$$\mathbf{h} = \sum_{i=0}^{n-1} \left(\frac{\partial}{\partial \theta_j} J(\theta^{(i)}) \right)^2$$

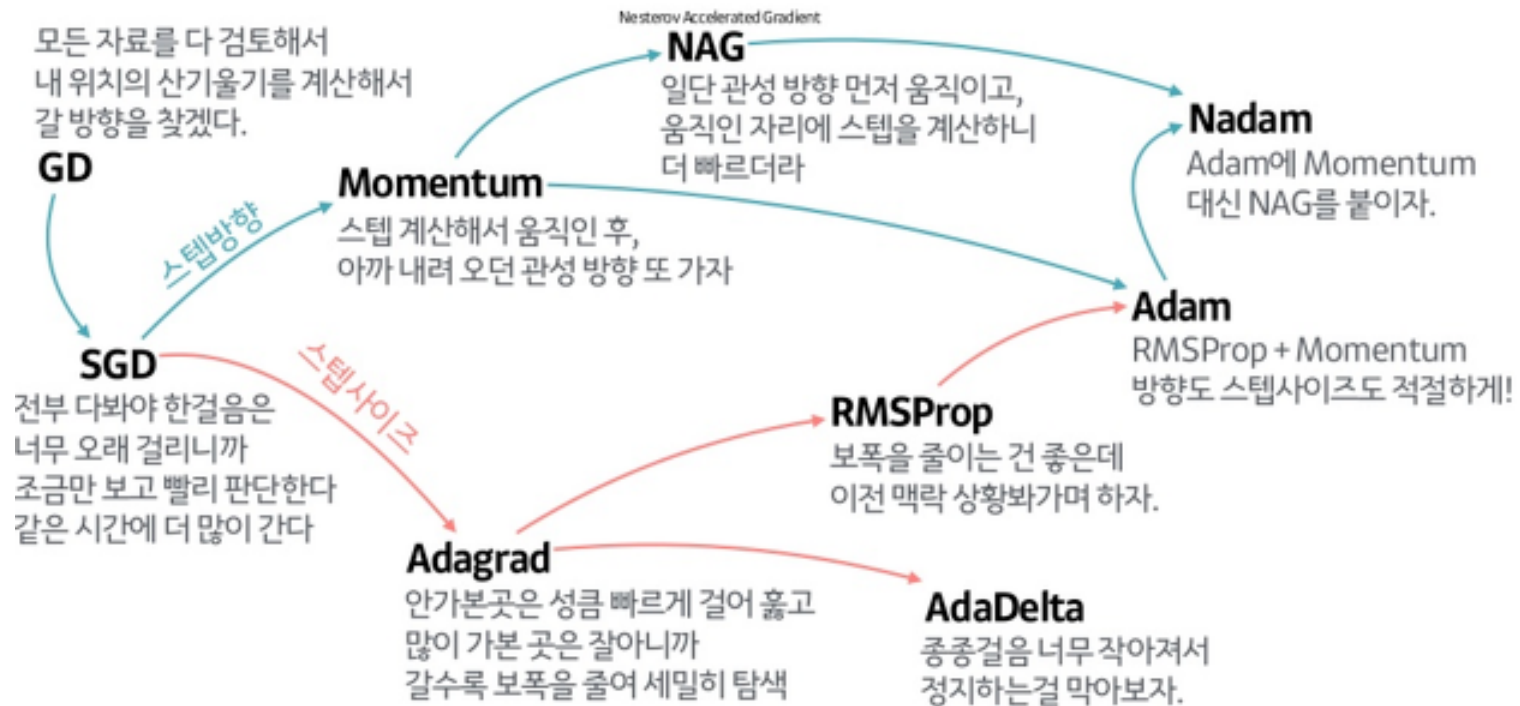
RMSProp

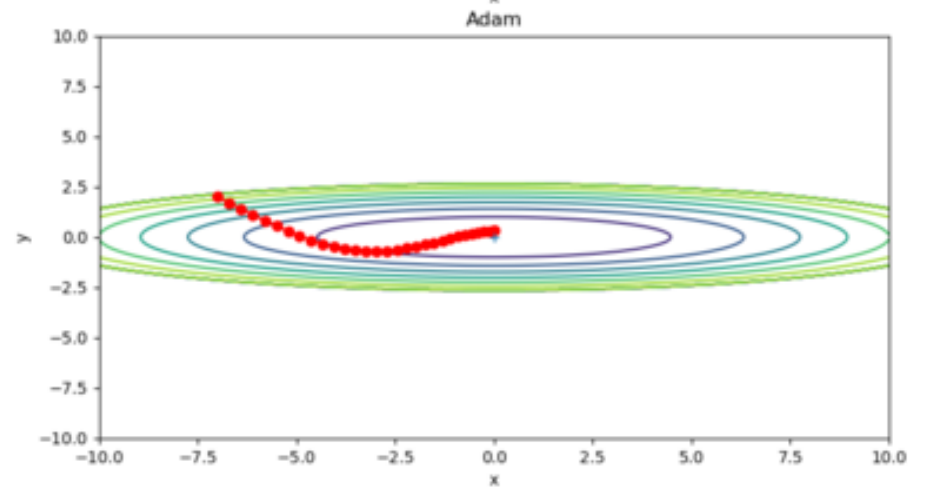
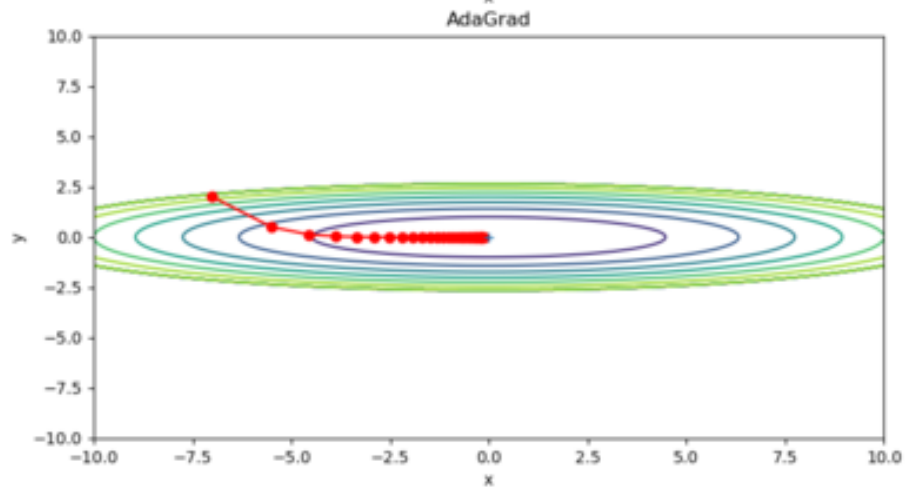
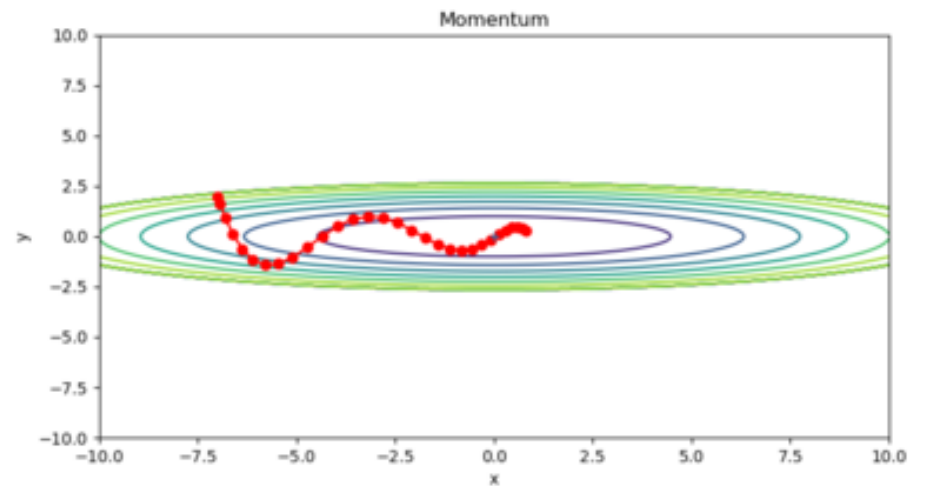
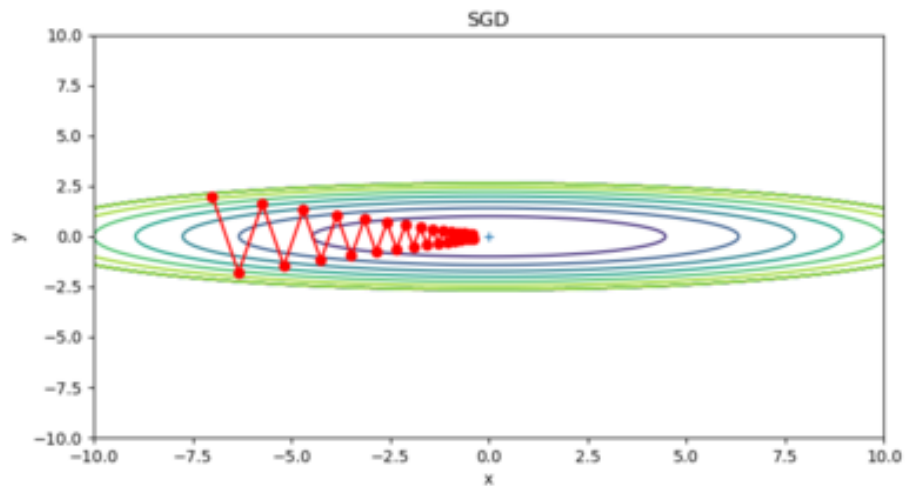
$$\mathbf{h} = \rho \mathbf{h}_{n-1} + (1 - \rho) \left(\frac{\partial}{\partial \theta_j} J(\theta^{(i)}) \right)^2$$

Adam

- Momentum + RMSProp

최적화 기법 (Optimization)





<https://m.blog.naver.com/PostView.naver?isHttpsRedirect=true&blogId=tinz6461&logNo=221589073944>