

## Chapter 2

### List of exercises

#### 2.1 Sampling random points within D- dimensional domains by hit and miss

**Rectangle** Generate random points uniformly distributed within a rectangle  $[a, b] \times [c, d]$  and compare the analytic value of the area  $A = L_{ab}L_{cd}$  with the Monte Carlo estimate based on the hit-miss method as a function of the number of “throws”.

**Disk** Do the same for a unit radius disk.

#### 2.2 Sampling random numbers from a given distribution

##### 2.2.1 Inversion method

**Exercise** Use the inversion method to design an algorithm that samples random numbers according to the power law probability distribution

$$\rho(x) = c x^n, \quad \text{with } x \in [0, 1] \quad (2.1)$$

for some constant  $c$  that normalise  $\rho(x)$ . Simulate the cases  $n = 3, 4$  and compare the histograms with the analytical expressions.

**Exercise** Use the inversion method to sample random numbers according to the probability distribution  $\rho(x) = cx^2$  with  $x \in [0, 2]$

**Additional exercises** Use the inversion method to generate random numbers with the following PDF

1.  $\rho(x) = \mu e^{-\mu x}$ , for  $x \geq 0$ ;
2.  $\rho(x) = 2x e^{-x^2}$ , for  $x \geq 0$ .
3.  $\rho(x) = \frac{1}{(a+bx)^n}$  for  $x \geq 0$  and  $n > 1$

**Note.** For all the exercises proposed above first compute the  $F$ ,  $F^{-1}$  and the map  $x_i = f(\xi_i)$  and then implement and run the corresponding algorithm. Compute the histogram of the sampled points and compare it with the expected PDF.

## 2.3 Sampling via transformation of coordinates

**Exercise Sampling uniformly points within a unit radius disk** The obvious approach to sample points within the unit disk corresponds to considering  $r = \xi_1$  and  $\theta = 2\pi\xi_2$  with  $\xi_1, \xi_2$  uniformly distributed in  $[0, 1]$ .

- Show by simulation that this algorithm does not sample points uniformly within the disk. Explain which is the conceptual mistake of this algorithm.
- Design an algorithm that does it correctly. (**Hint:** One way is to first perform the transformation into polar coordinates and then use the marginal  $p(r)$  and the conditional  $p(\theta|r)$  PDFs to do the sampling by applying in turn the 1D inversion method. )

**Exercise** A way to generate numbers from a 2D (normalised) 2D Gaussian PDF,  $\mathcal{N}(0, 1)$  is the so-called Box-Muller transformation. This is based on the idea presented during the lecture in which one first makes a coordinate transformation to factorize the 2-point PDF

$$\rho(x, y) = \frac{1}{2\pi} e^{-(x^2+y^2)/2} \quad (2.2)$$

into a product of two one-point PDFs and then performs two separate samplings, one for each PDF.

- Write an algorithm that does this sampling by first performing the analytical calculations necessary to find the correct transformation;
- How one can extend the algorithm to sample from  $\mathcal{N}(\mu, \sigma^2)$  ?

### 2.3.1 Rejection method

**Exercise** Use the rejection method to generate random numbers that are distributed according to the pdf

$$f(x) = \sqrt{2/\pi} e^{-x^2}. \quad (2.3)$$

Hint: One may use a function  $g(x) = A$  for  $0 \leq x \leq p$  and  $g(x) = (A/p) x \exp(p^2 - x^2)$  for  $x > p$ . See how good the performance is for a few values of  $p$  (use a reasonable value  $N$  of “darts”).

## 2.4 Importance sampling

**Exercise** Let us consider the following function  $f(x) = e^{-x^2}g(x)$  in  $[0, \infty]$  where  $g(x)$  is a slowly varying function. Compute the integral both with the crude method and by using the importance sampling technique. Hint: For the importance sampling method use a Gaussian random number generator with density  $W(x) = \sqrt{2/\pi} e^{-x^2}$ . With this choice one has

$$I = \int_0^\infty f(x) dx \sim \frac{1}{N} \sum_{i=1}^N \frac{f(x_i)}{W(x_i)} = \frac{1}{N} \sqrt{\pi/2} \sum_{i=1}^N g(x_i). \quad (2.4)$$

**Exercise** Estimate the integral

$$\int_0^{\pi/2} \cos x dx \quad (2.5)$$

using the importance sampling technique with  $g(x)$  proportional to  $a + bx^2$ . Determine the optimal values of the parameters  $a$  and  $b$  to generate samples according to  $g(x)$  and establish the number of iterations needed to get an accuracy of %1.