cmake\_minimum\_required(VERSION 2.8.3)

project(aro\_slam)

find\_package(catkin REQUIRED)

# For aro\_slam package

catkin\_python\_setup()

catkin\_package(

CATKIN\_DEPENDS

geometry\_msgs

message\_runtime

nav\_msgs

point\_cloud\_color

ros\_numpy

rospy

sensor\_msgs

tf2\_ros

)

catkin\_install\_python(

PROGRAMS scripts/icp\_slam\_2d

DESTINATION ${CATKIN\_PACKAGE\_BIN\_DESTINATION}

)