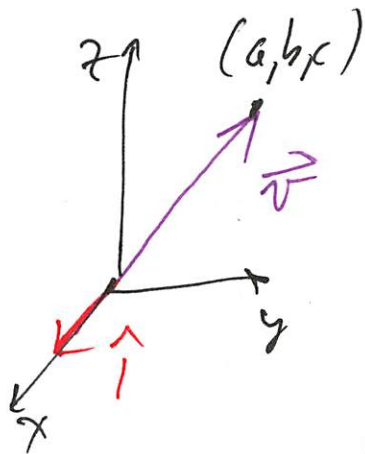


Last hour: vectors.

$$\vec{v} = \langle a, b, c \rangle$$

$$\vec{w} = \langle d, e, f \rangle$$



α scalar

$$\alpha \vec{v} = \langle \alpha a, \alpha b, \alpha c \rangle, \quad \vec{0} = \langle 0, 0, 0 \rangle$$

$$\vec{v} + \vec{w} = \langle a+d, b+e, c+f \rangle$$

$$\vec{v} - \vec{w} = \langle a-d, b-e, c-f \rangle$$

$$|\vec{v}| = \text{length} = \sqrt{a^2 + b^2 + c^2}$$

$\hat{v} \iff$ vector of length 1
 $|\hat{v}| = 1.$

$$|\vec{v}| = 0 \iff \vec{v} = \vec{0}$$

if $\vec{v} \neq \vec{0}$, then $\frac{1}{|\vec{v}|} \vec{v}$ is a
unit vector in direction of \vec{v}

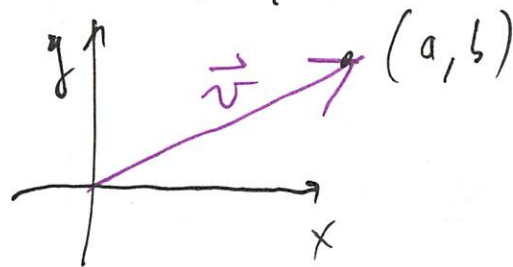
$$\begin{aligned}\hat{i} &= \langle 1, 0, 0 \rangle \\ \hat{j} &= \langle 0, 1, 0 \rangle \\ \hat{k} &= \langle 0, 0, 1 \rangle\end{aligned}$$

"standard
basis
vectors"

$$\begin{aligned}\vec{v} &= \langle a, b, c \rangle \\ &= a\hat{i} + b\hat{j} + c\hat{k} \\ &= \langle a, 0, 0 \rangle + \langle 0, b, 0 \rangle \\ &\quad + \langle 0, 0, c \rangle\end{aligned}$$

2D vectors too:

$$\vec{v} = \langle a, b \rangle$$



Have 3 different kinds of multiplication. one is scalar mult. 2 others that take 2 vectors as input.

	Input	Output
dot product	2 vectors	scalar
cross product	2 vectors	vector.

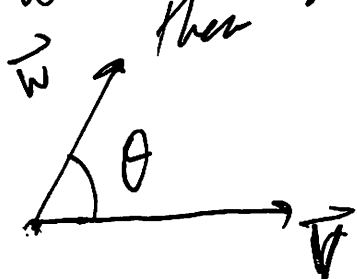
Dot product.

$$\vec{v}, \vec{w} \Rightarrow \vec{v} \cdot \vec{w}$$

Def $\vec{v} \cdot \vec{w}$ is the scalar

$$|\vec{v}| |\vec{w}| \cos \theta$$

where θ is angle between



if $\vec{v} = \langle a, b, c \rangle$, ②
 $\vec{w} = \langle d, e, f \rangle$, then

$$\vec{v} \cdot \vec{w} = ad + be + cf$$

Fact: same number!

e.g. $\vec{v} = \langle 1, -1, 0 \rangle$

$$\vec{w} = \langle 0, 1, -1 \rangle$$

$$\begin{aligned} \vec{v} \cdot \vec{w} &= 1 \cdot 0 + (-1) \cdot 1 + 0 \cdot (-1) \\ &= -1 \end{aligned}$$

Properties

$$\vec{v} \cdot \vec{w} = \vec{w} \cdot \vec{v}$$

$$\vec{v} \cdot (\vec{u} + \vec{w}) = \vec{v} \cdot \vec{u} + \vec{v} \cdot \vec{w}$$

$$(\alpha \vec{v}) \cdot \vec{w} = \alpha (\vec{v} \cdot \vec{w})$$

We can use the dot product to understand the angle θ

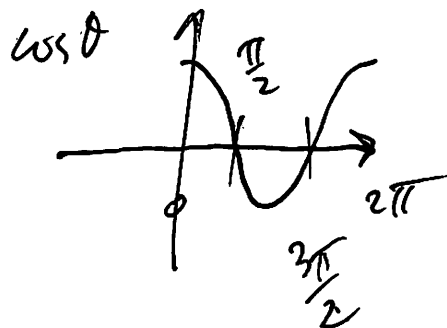
e.g. 2 vectors are $\perp \iff$

$$\vec{v} \cdot \vec{w} = 0$$

(assume $\vec{v}, \vec{w} \neq \vec{0}$)

Why? $\vec{v} \cdot \vec{w} = |\vec{v}| |\vec{w}| \cos \theta$

" $\Rightarrow \cos \theta = 0$
 $\theta = \frac{\pi}{2}, \frac{3\pi}{2}$
 $\frac{\pi}{2} = 90^\circ$



e.g. $\langle 1, 1, 1 \rangle \cdot \langle 1, 0, -1 \rangle$

e.g. can find angle between \vec{v}, \vec{w} .

e.g. $\vec{v} = \langle 1, -1, 0 \rangle$

$\vec{w} = \langle 0, 1, -1 \rangle$

want θ .

$$\begin{cases} \vec{v} \cdot \vec{w} = -1 \\ = |\vec{v}| |\vec{w}| \cos \theta \end{cases}$$

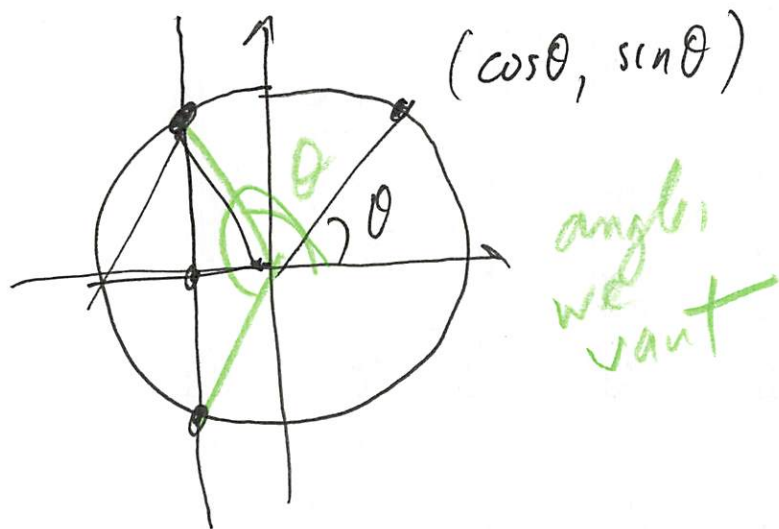
$$|\vec{v}| = \sqrt{1^2 + (-1)^2 + 0^2} = \sqrt{2}$$

$$|\vec{w}| = \sqrt{\dots} = \sqrt{2}$$

$$\Rightarrow -\frac{1}{\sqrt{2}\sqrt{2}} = \cos \theta$$

$$\text{or } \cos \theta = -\frac{1}{2}$$

use
unit
circle



$$\Rightarrow \theta = \frac{2\pi}{3}$$

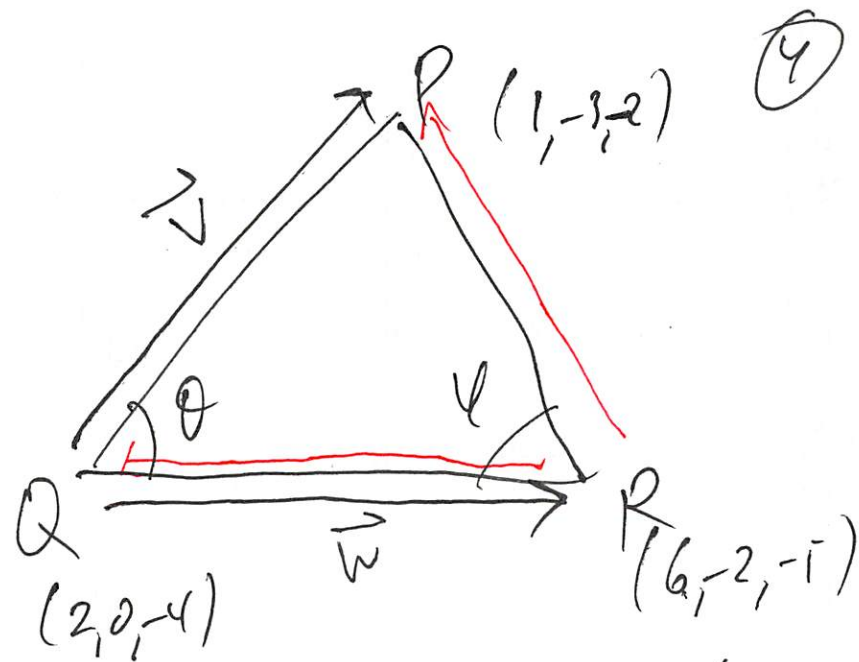
$$\cos \theta = \frac{\vec{v} \cdot \vec{w}}{|\vec{v}| |\vec{w}|}$$

e.g. $P = (1, -3, -2)$

$Q = (2, 0, -4)$

$R = (6, -2, -1)$

they determine a \triangle
is this a right \triangle ?



$$\vec{v} = \overrightarrow{QP}$$

to get \vec{v} take difference of coords.

$$\vec{v} = \langle 1-2, -3-0, -2-(-4) \rangle$$

$$= \langle -1, -3, 2 \rangle$$

$$\vec{w} = \overrightarrow{QR} = \langle 4, -2, -1 \rangle$$

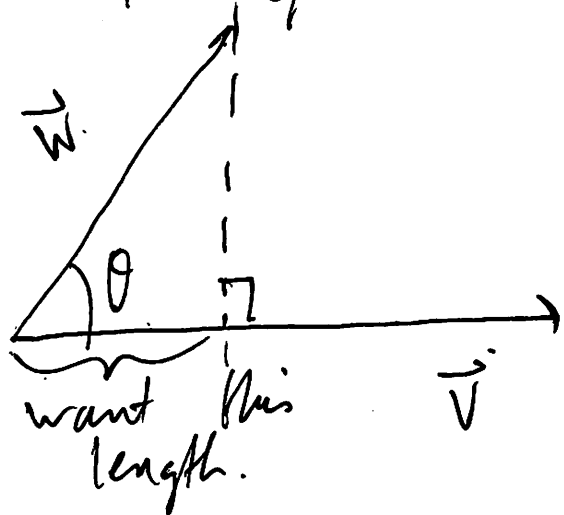
$$\vec{v} \cdot \vec{w} = \langle -1, -3, 2 \rangle \cdot \langle 4, -2, -1 \rangle$$

$$= -4 + 6 - 2 = 0$$

$\Rightarrow \vec{v} \perp \vec{w} \Rightarrow \theta$ is right angle.

p.g. finding the component of \vec{w} in direction of \vec{v}

this means finding how far \vec{w} projects in the direction of \vec{v} .



desired distance is

$$|\vec{w}| \cos \theta$$

almost $\vec{v} \cdot \vec{w}$, missing $|\vec{v}|$

\Rightarrow this component equals

$$\frac{1}{|\vec{v}|} \vec{v} \cdot \vec{w}$$

can also think of it as

$$\left(\frac{1}{|\vec{v}|} \vec{v} \right) \cdot \vec{w}$$

$$= \hat{\vec{v}} \cdot \vec{w}$$

p.g. find component of $\vec{w} = \langle 1, -1, 3 \rangle$ in direction of $\langle 6, 3, 2 \rangle = \vec{v}$

(5)

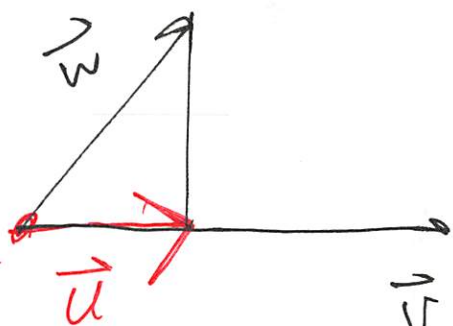
want $\vec{w} \cdot \hat{v}$.

$$|\vec{v}| = \sqrt{36+9+4} = \sqrt{49} = 7$$

$$\Rightarrow \hat{v} = \left\langle \frac{6}{7}, \frac{3}{7}, \frac{2}{7} \right\rangle$$

$$\vec{w} \cdot \hat{v} = \frac{6}{7} - \frac{3}{7} + \frac{6}{7} = \boxed{\frac{9}{7}}$$

e.g. vector projection of \vec{w} along \vec{v} means the vector \vec{u}



has
length
 $\hat{v} \cdot \vec{w}$.

direction is \hat{v} .

$$\Rightarrow \vec{u} = (\hat{v} \cdot \vec{w}) \hat{v}$$

previous example:

$$\hat{v} \cdot \vec{w} = \frac{9}{7}$$

$$\hat{v} = \left\langle \frac{6}{7}, \frac{3}{7}, \frac{2}{7} \right\rangle$$

$$\Rightarrow \vec{u} = \left\langle \frac{54}{49}, \frac{27}{49}, \frac{18}{49} \right\rangle$$

Cross product $\vec{v} \times \vec{w}$

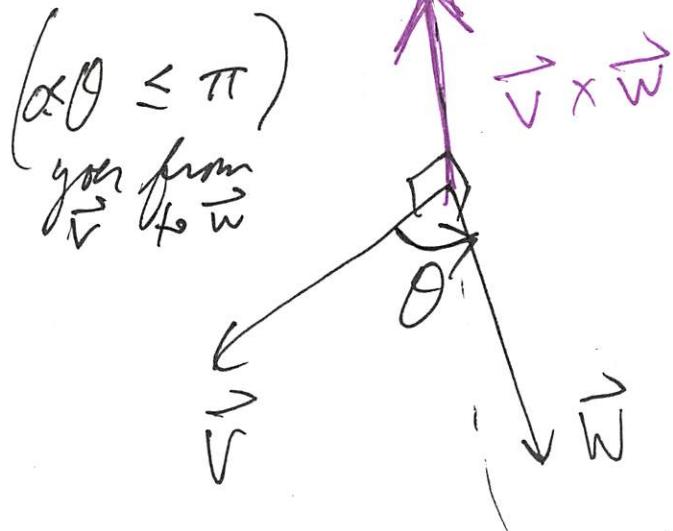
input 2 vectors
output vector

only makes sense for
vectors in 3D.

geometric def.

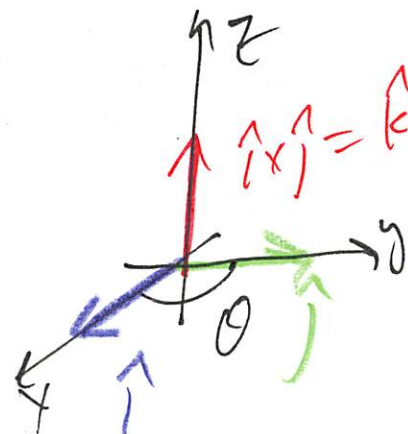
$\vec{v} \times \vec{w}$ is the vector with

length = $|\vec{v}|/|\vec{w}| \sin \theta$
 direction = \perp to both \vec{v}, \vec{w}
 and determined using
 R.H. rule.



push \vec{w} into \vec{v} along θ .
 R.H. Thumb points in
 direction of $\vec{v} \times \vec{w}$.

e.g. $\hat{i} \times \hat{j} = ?$ (7)



$$\theta = \frac{\pi}{2}$$

$$\sin \frac{\pi}{2} = 1$$

$$|\hat{i}| = |\hat{j}| = 1$$

$\hat{i} \times \hat{j} \perp$ to \hat{i}, \hat{j}
 and has length 1.

$$\Rightarrow \hat{k} \text{ or } -\hat{k}$$

$$\hat{j} \times \hat{i} = \hat{k} \text{ or } -\hat{k}$$

$$= -\hat{k}$$

$$\Rightarrow \boxed{\vec{v} \times \vec{w} = -\vec{w} \times \vec{v}}$$

NOT COMMUTATIVE

algebraic def

use determinants.

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc$$

2x2

need determinant of
3x3 matrix

$$\det \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

$$= aei + bfg + cdh - ceg - afh - bdi$$

can also compute
in terms of 2x2 det

$$\det \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

$$= +a \det \begin{pmatrix} e & f \\ h & i \end{pmatrix}$$

$$- b \det \begin{pmatrix} d & f \\ g & i \end{pmatrix}$$

$$+ c \det \begin{pmatrix} d & e \\ g & h \end{pmatrix}$$

get same thing

⑧

to use to compute $\vec{v} \times \vec{w}$.

$$\vec{v} = \langle a, b, c \rangle$$

$$\vec{w} = \langle d, e, f \rangle$$

- ① make 3×3 matrix
- Ⓐ 1st row $\hat{i} \hat{j} \hat{k}$
 - Ⓑ 2nd row \vec{v}
 - Ⓒ 3rd row \vec{w}

- ② take determinant,
interpret result
as a vector.

p.g. $\vec{v} = \langle 1, -1, 0 \rangle$ ⑨

$$\vec{w} = \langle 0, 1, -1 \rangle$$

$$\vec{v} \times \vec{w} = ?$$

$$\det \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & -1 & 0 \\ 0 & 1 & -1 \end{pmatrix} \quad \left| \begin{array}{l} \text{can} \\ \text{check} \\ \vec{v} \times \vec{w} \\ \perp \vec{v}, \vec{w} \end{array} \right.$$

$$= +\hat{i} \det \begin{pmatrix} -1 & 0 \\ 1 & -1 \end{pmatrix} - \hat{j} \det \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} + \hat{k} \det \begin{pmatrix} 1 & -1 \\ 0 & 1 \end{pmatrix}$$

$$= 1\hat{i} - (-1)\hat{j} + 1\hat{k} \\ = \langle 1, 1, 1 \rangle$$