

# GUNSHI GUPTA

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## Education

### OATML Lab, University of Oxford

*D.Phil, Machine Learning (sup. by Prof. Yarin Gal, Dr. Rowan McAllister, Dr. Adrien Gaidon)*

**Oxford, UK**

*Sept. 2021-Present*

### Montreal Institute of Learning Algorithms (MILA)

*Research Master's, Machine Learning | GPA: 4.0/4.0*

**Montreal, Quebec**

*Sept. 2018-Aug. 2020*

### Delhi Technological University (DTU)

*Bachelor of Technology, Mathematics and Computing, Applied Math | GPA: 8.05/10*

**New Delhi, India**

*Sept. 2012-May 2016*

## Recent Work Experience

### Microsoft Research (MSR)

*Deep Learning Intern, Gaming Intelligence Team*

**Cambridge, UK**

*April 2023-July 2023*

- Contributed to two conference submissions on developing a VQGAN-Transformer-based world-and-action model trained on sequences from 3 years of gameplay data from a high-fidelity collaborative multi-agent Xbox game.
- Developed an evaluation suite for mechanistic interpretability of transformer representations, probing for concepts related to emergent game-state and multi-agent awareness.

### Wayve Technologies (End-to-End Autonomous Driving Startup)

*Deep Learning Researcher, Policy Learning Team*

**London, UK**

*July. 2020-August 2021*

- Researched Offline RL methods for learning safe driving policies from imbalanced data. Efforts include extending the framework to incorporate sparse feedback signals like corrective actions into the learning loop.

### Robotics Research Center, IIIT Hyderabad

*Graduate Research Assistant (under Dr. K. Madhava Krishna)*

**Hyderabad, India**

*Jan. 2017-May 2018*

- Project for Center of Artificial Intelligence and Robotics : Developed Multi Robot SLAM framework facilitating Incremental/Batch Optimization, Centralized/Distributed map merging, Dense point cloud registration, Robot Encounters with Visual Odometry based front-end [Nonlinear Convex optimisation, Multi-View Geometry]
- Tested framework successfully on Husky UGV Robot Platform for complex trajectories.

## Research

- *Memo: Training Memory-Efficient Transformer-Based Agents with Reinforcement Learning*  
**Gunshi Gupta**, Karmesh Yadav, Zsolt Kira, Yarin Gal, Rahaf Aljundi [Under Review]
- *WHAM! World and Human Action Modelling in a Modern Xbox Game*  
Gaming Intelligence, MSR [Under Review]
- *Architecting Generative AI Capabilities To Support Human Creative Ideation*  
Gaming Intelligence, MSR [To appear in Nature]
- *Pre-trained Text-to-Image Diffusion Models Are Versatile Representation Learners for Control*  
**Gunshi Gupta**, Karmesh Yadav, Yarin Gal, Dhruv Batra, Zsolt Kira, Cong Lu and Tim G.J. Rudner [NeurIPS 2024 spotlight, Oral talk at Generative AI for Decision Making Workshop at ICLR 2024]
- *Can Active Sampling Reduce Causal Confusion in Offline Reinforcement Learning?*  
**Gunshi Gupta**, Tim G.J. Rudner, Rowan McAllister, Adrien Gaidon and Yarin Gal [CleaR 2023, Neurips OfflineRL Workshop 2022]
- *ReLU to the Rescue: Improve Your On-Policy Actor-Critic with Positive Advantages*  
Andrew Jesson, Chris Lu, **Gunshi Gupta**, Jakob Foerster and Yarin Gal [ICML 2024]
- *La-MAML: Look-Ahead Meta Learning for Continual Learning*  
**Gunshi Gupta\***, Karmesh Yadav\* and Liam Paull [NeurIPS 2020 Oral] [ArXiv][NeurIPS] [Code]

- *Probabilistic object detection: Strengths, Weaknesses, and Opportunities* [ICML AIAD 2020 Workshop]  
Dhaivat Bhatt\*, Dishank Bansal\*, **Gunshi Gupta\***, Hanju Lee, Krishna Murthy J., Liam Paull
- *Unifying Variational Inference and PAC-Bayes for Generalisation Bounds in Imitation Learning*  
Sanjay Thakur, Herke Van Hoof, **Gunshi Gupta** and David Meger [Preprint].
- *Stein Variational Methods for Robot Navigation* [ICML 2019 Workshop: Stein Methods in Machine Learning]
- *Viewpoint Invariant Junction Recognition using Deep Network Ensembles* (IROS 2018) [Link]  
Abhijeet Kumar\*, **Gunshi Gupta\***, Avinash Sharma and K. Madhava Krishna.
- *Geometric Consistency for Self-Supervised End-to-End Visual Odometry* [Link][CVPR 2018 Workshop: Deep Learning for Visual SLAM]: Ganesh Iyer\*, J. Krishna Murthy\*, **Gunshi Gupta**, and Liam Paull.

## Outreach

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- Invited Talk: "Deep learning for Autonomous Driving" at OxBridge Women in Computer Science 2021 conference.
- Panelist at ICML Women in Machine Learning Social organised by OxWoCS 2022.
- Appointed as an ED&I Fellow with MPLS (Maths, Physics, Life-Sciences) department at Oxford (2022-2023)
- LatinX-in-AI Mentor - 2021 cohort