GUNSHI GUPTA

✉ gunshigupta9@gmail.com 🌐 https://gunshigupta.netlify.app/ 🌐 linkedin.com/in/gunshi-gupta/

Areas of Interest : Policy Learning (IL/RL/LfD), Causal Inference, Robotics, Lifelong Learning

Education

OATML Lab, University of Oxford **Oxford, UK**
D.Phil, Machine Learning (sup. by Prof. Yarin Gal, Dr. Rowan McAllister, Dr. Adrien Gaidon) *Sept. 2021-Present*

Montreal Institute of Learning Algorithms (MILA) **Montreal, Quebec**
Research Master's, Machine Learning | GPA: 4.0/4.0 *Sept. 2018-Aug. 2020*

Delhi Technological University (DTU) **New Delhi, India**
Bachelor of Technology, Mathematics and Computing, Aplied Math | GPA: 8.05/10 *Sept. 2012-May 2016*

Work Experience (Previous 3 yrs)

Wayve Technologies (End-to-End Autonomous Driving Startup) **London, UK**
Deep Learning Researcher, Policy Learning Team *July. 2020-August 2021*

- Researched Offline RL methods for learning safe driving policies from imbalanced data. Efforts include extending the framework to incorporate sparse feedback signals like corrective actions into the learning loop.

Robotics Research Center, IIIT Hyderabad **Hyderabad, India**
Graduate Research Assistant (under Dr. K. Madhava Krishna) *Jan. 2017-May 2018*

- Project for Center of Artificial Intelligence and Robotics : Developed Multi Robot SLAM framework facilitating Incremental/Batch Optimization, Centralized/Distributed map merging, Dense point cloud registration, Robot Encounters with Visual Odometry based front-end [Nonlinear Convex optimisation, Multi-View Geometry]
- Tested framework successfully on Husky UGV Robot Platform for complex trajectories.

Research

- *Can Active Sampling Reduce Causal Confusion in Offline Reinforcement Learning* : **Gunshi Gupta**, Tim G.J. Rudner, Rowan McAllister, Adrien Gaidon and Yarin Gal [Under Review]
- *La-MAML: Look-Ahead Meta Learning for Continual Learning* (NeurIPS 2020 Oral) : **Gunshi Gupta***, Karmesh Yadav* and Liam Paull [ArXiV][NeurIPS] [Code]
- *Probabilistic object detection: Strengths, Weaknesses, and Opportunities* (ICML AIAD 2020 Workshop) : Dhaivat Bhatt*, Dishank Bansal*, **Gunshi Gupta***, Hanju Lee, Krishna Murthy Jatavallabhula, Liam Paull
- *Unifying Variational Inference and PAC-Bayes for Generalisation Bounds in Imitation Learning* : Sanjay Thakur, Herke Van Hoof, **Gunshi Gupta** and David Meger [Preprint].
- *Stein Variational Methods for Robot Navigation* (Poster at ICML 2019 Workshop): Stein Methods in Machine Learning.
- *Viewpoint Invariant Junction Recognition using Deep Network Ensembles* (IROS 2018) : Abhijeet Kumar*, **Gunshi Gupta***, Avinash Sharma and K. Madhava Krishna. [Link].
- *Geometric Consistency for Self-Supervised End-to-End Visual Odometry* (1st International Workshop on Deep Learning for Visual SLAM, CVPR 2018) : Ganesh Iyer*, J. Krishna Murthy*, **Gunshi Gupta**, and Liam Paull. [Link].

Outreach

- Invited Talk: "Deep learning for Autonomous Driving" at OxBridge Women in Computer Science 2021 conference.
- Panelist at ICML Women in Machine Learning Social organised by OxWoCS 2022.
- Appointed as an ED&I Fellow with MPLS (Maths, Physics, Life-Sciences) department at Oxford (2022-2023)
- LatinX-in-AI Mentor - 2021 cohort