Definition of Safety

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1 Language

We define our language over four sets of symbols: numerals, symbolic constants, variables, and aggregate names.

1.1 Term and Pools

We inductively define terms, tuples of terms, and pools:

- all numerals and variables are terms,
- f(t) is a term if f is a symbolic constant and t is a pool,
- $t_1 \star t_2$ is a term if t_1, t_2 are terms and $\star \in \{+, -, \times, \div, ..\}$,
- $\langle t \rangle$ is a term if t is a pool,
- t_1, \ldots, t_n is a tuple of terms if $n \ge 0$ and t_i is a term,
- $\dot{t_1}; \ldots; \dot{t_n}$ is a pool if $n \ge 1$ and each $\dot{t_i}$ is a tuple of terms.

We omit writing the parenthesis for terms of form f().

We inductively define a term to be evaluable if

- it is a numeral, or
- it has form $t_1 \star t_2$ where t_1 and t_2 are evaluable and $\star \in \{+, -, \times, \div\}$.

We then inductively define function *eval* mapping evaluable terms to sets of numerals:

- for numerals t, we let $eval(t) = \{t\}$, and
- for terms of form $t_1 \star t_2$, we let

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\begin{aligned} & eval(t_1+t_2) = \{s_1+s_2 \mid s_1 \in eval(t_1), s_2 \in eval(t_2)\}, \\ & eval(t_1-t_2) = \{s_1-s_2 \mid s_1 \in eval(t_1), s_2 \in eval(t_2)\}, \\ & eval(t_1 \times t_2) = \{s_1 \times s_2 \mid s_1 \in eval(t_1), s_2 \in eval(t_2)\}, \text{ and } \\ & eval(t_1 \div t_2) = \{s_1 \div s_2 \mid s_1 \in eval(t_1), s_2 \in eval(t_2), s_2 \neq 0\}. \end{aligned}
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We say that a term t is nonzero if it is evaluable and $0 \notin eval(t)$.

1.2 Atoms and Literals

An *atom* has form p(t) where p is a symbolic constant and t is a pool. We omit writing parenthesis for atoms of form p().

A comparison has form $t_1 \prec t_2$, where t_1, t_2 are terms and $\prec \in \{<, >, \leq, \geq, =, \neq\}$. Furthermore, we let negate be a function to negate relation symbols: $< \mapsto \geq$, $> \mapsto <, \leq \mapsto >, \geq \mapsto <, = \mapsto \neq$ and $\neq \mapsto =$.

A literal is either an atom or a comparison optionally preceded by the default negation symbol \neg .

A conditional literal has form $l: \dot{l}$, where l is a literal and \dot{l} is a (possibly empty) tuple of literals.

1.3 Aggregates

An aggregate has the form

$$\alpha\{\dot{t_1}:\dot{l_1};\ldots;\dot{t_n}:\dot{l_n}\} \prec s \tag{1}$$

where

- $n \geq 0$,
- α is an aggregate name,
- each \dot{t}_i is a tuple of terms,
- each \dot{l}_i is a (possible empty) tuple of literals,
- $\prec \in \{<,>,\leq,\geq,=,\neq\}$, and
- \bullet s is a term.

1.4 Rules

A rule has form

$$a_1 \vee \dots \vee a_m \leftarrow l_1 \wedge \dots \wedge l_n$$
 (2)

where $m, n \geq 0$, each a_i is an atom and each l_i is a literal, conditional literal or aggregate.

A choice rule has form

$$\{a_1; \dots; a_m\} \leftarrow l_1 \wedge \dots \wedge l_n$$
 (3)

where $m, n \geq 0$, each a_i is an atom and each l_i is a literal, conditional literal or aggregate.

We refer to the a_i and l_i in rules of form (2) and (3) as *head atoms* and *body literals*, respectively.

2 Safety

In the following, we use function vars(e) to obtain all variables occurring in an expression e. Furthermore, we say that a variable X occurs globally in

- a literal l if $X \in vars(l)$,
- a conditional literal $l : \dot{l} \text{ if } X \in vars(l) \setminus vars(\dot{l}),$
- an aggregate of form (1) if $X \in s$, and
- a rule of form (2) or (3) if it occurs globally in a head atom or body literal.

2.1 Terms

We inductively define function pt for terms, tuples of terms and pools:

- for numerals n, we let $pt(n) = \emptyset$,
- for variables X, we let $pt(X) = \{X\}$,
- for term tuples $\dot{t} = t_1, \dots, t_n$, we let $pt(\dot{t}) = pt(t_1) \cup \dots \cup pt(t_n)$,
- for pools $\mathbf{t} = \dot{t_1}; \dots; \dot{t_n}$, we let $pt(\mathbf{t}) = pt(\dot{t_1}) \cap \dots \cap pt(\dot{t_n})$,
- for terms of form f(t), we let pt(f(t)) = pt(t),
- for terms of form $t_1 \star t_2$, we let

$$pt(t_1 \star t_2) = \begin{cases} pt(t_2) & t_1 \text{ is evaluable and } \star \in \{+, -\}, \text{ or} \\ & t_1 \text{ is nonzero and } \star = \times, \\ pt(t_1) & t_2 \text{ is evaluable and } \star \in \{+, -\}, \text{ or} \\ & t_2 \text{ is nonzero and } \star = \times, \\ \emptyset & \text{otherwise} \end{cases}$$

We define function dt for terms t as $dt(t) = vars(t) \setminus pt(t)$.

2.2 Body Literals and Rules

Next, we define function dep for body literals and rules:

- for an atom a of form p(t), we let $dep(a) = \{(pt(t), \emptyset), (\emptyset, dt(t))\},\$
- for a comparison a of form $t_1 \prec t_2$ with $\prec \notin \{=\}$, we let $dep(a) = \{(\emptyset, vars(a))\},$
- for a comparison a of form $t_1 = t_2$, we let $dep(a) = \{(pt(t_1), vars(t_2)), (pt(t_2), vars(t_1)), (\emptyset, dt(t_1) \cup dt(t_2))\},$
- for a literal l of form $\neg a$ where a is an atom, we let $dep(l) = \{(\emptyset, vars(l))\},\$

- for a literal l of form $\neg t_1 \prec t_2$, we let $dep(l) = dep(t_1 \ negate(\prec) \ t_2)$,
- for conditional literal l, we let $dep(l) = \{(\emptyset, vars(l))\},\$
- for an aggregate l of form (1) with $\prec \notin \{=\}$, we let $dep(l) = \{(\emptyset, vars(l))\}$,
- for an aggregate l of form (1) with $\prec \in \{=\}$, we let $dep(l) = \{(pt(s), vars(\dot{t_1}: \dot{l_1}; \ldots; \dot{t_n}: \dot{l_n})), (\emptyset, dt(s))\}.$

Furthermore, we let $dep_{|X}(l) = \{(D \cap X, P \cap X) \mid (D, P) \in dep(l)\}$ to restrict variables in the dependency to the given set X of variables.

2.3 Gathering Dependencies

Next, we define function *analyze* to gather dependencies in rules, conditional literals, and aggregate elements:

• for a rule r of form (2) or (3), we let

$$analyze(r) = \bigcup_{0 \le i \le m} \{(\emptyset, vars(a_i))\} \cup \bigcup_{0 \le i \le n} dep(l_i),$$

• for a conditional literal l of form $l_0: l_1, \ldots, l_n$, we let

$$\mathit{analyze}(l) = \{(\emptyset, \mathit{vars}(l_0))\} \cup \bigcup_{1 \leq i \leq n} \mathit{dep}(l_i),$$

• for an aggregate element e of form $\dot{t}: l_1, \ldots, l_n$, we let

$$\mathit{analyze}(e) = \{(\emptyset, \mathit{vars}(\dot{t}))\} \cup \bigcup_{1 \leq i \leq n} \mathit{dep}(l_i).$$

Given a set PD of pairs of sets of variables and a set of variables V, we let $PD_{|V} = \{(P \cap V, D \cap V) \mid (P, D) \in PD\}.$

2.4 Safety Definition

We define operator C_{PD} parametrized with a set PD of pairs of sets of variables applied to a set V of variables as

$$C_{PD}(V) = \bigcup_{(P,D)\in PD, D\subseteq V} P.$$

Let r be a rule with global variables G. We say that a rule r is globally safe if G is the least fixed point of $C_{PD|G}$ with PD = analyze(r). Furthermore, we say that a conditional literal or aggregate element e occurring in rule r is locally safe if $L = vars(e) \setminus G$ is the least fixed point of $C_{PD|G}$ with PD = analyze(e).

A rule is *safe* if it is globally safe and all occurrences of conditional literals and aggregate elements in it are locally safe.

3 Other Examples

$$\begin{split} dep(p(X,Y+Y)) &= \{(pt(X,Y+Y),\emptyset), (\emptyset, dt(X,Y+Y))\} \\ &= \{(pt(X) \cup pt(Y+Y),\emptyset), (\emptyset, dt(X) \cup dt(Y+Y))\} \\ &= \{(\{X\} \cup \emptyset,\emptyset), (\emptyset,\emptyset \cup vars(Y+Y))\} \\ &= \{(\{X\},\emptyset), (\emptyset,\{Y\})\} \end{split}$$

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