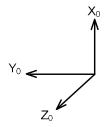
MCE4101 1/2020

## MCE4101 Introduction to Robotics Quiz1 (5%) –SET 10

- 1. (25 Marks). The original frame is given. The following transformation steps for fixed frames are
  - i. Rotate -90° in the current x axis then
  - ii. Translate 2 in the current z axis then
  - iii. Rotate 90° in the current y axis then
  - iv. Translate -2 in the current x axis then
  - a. (10) Find the  $T_4^0$  transformation matrix.
- b. (5) If a point is fixed on the z axis at (0,0,1), obtain the coordinate  $P_4$  with reference to origin.
- c. (10) Plot all the transformation frames and mark P<sub>4</sub> location with reference to origin



MCE4101 1/2020

2. (25 Marks). The original frame is given. The following transformation steps for fixed frames are

- i. Rotate -90° in the fixed x axis then
- ii. Translate 2 in the fixed z axis then
- iii. Rotate 90° in the fixed y axis then
- iv. Translate -2 in the fixed x axis then
- a. (10) Find the  $T_4^0$  transformation matrix.
- b. (5) If a point is fixed on the z axis at (0,0,1), obtain the coordinate  $P_4$  with reference to origin.
- c. (10) Plot all the transformation frames and mark  $P_4$  location with reference to origin

