Signal Detection Theory (SDT)

Joachim Vandekerckhove

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- 1. **Sensitivity:** How well can the system separate signal from noise? (Information quality)
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Allows us to independently quantify sensitivity and bias, unlike simple accuracy.

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SDT introduced a probabilistic view:

- There is always noise: Internal and external random fluctuations.
- Decision is probabilistic: Based on internal evidence (a random variable).
- Strategy matters: Observers adopt criteria based on task demands (payoffs, instructions).

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Paradigm shift: From absolute thresholds to decision processes under uncertainty.

Common assumptions:

 Gaussian Distributions: Internal evidence for Noise (N) and Signal+Noise (S+N) follows Normal distributions.

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$$\sim \mathcal{N}(\mu_{\textit{N}}, \sigma_{\textit{N}}^2)$$

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- 3. Additivity: Signal shifts the mean $(\mu_{S+N} > \mu_N)$ but not the shape.

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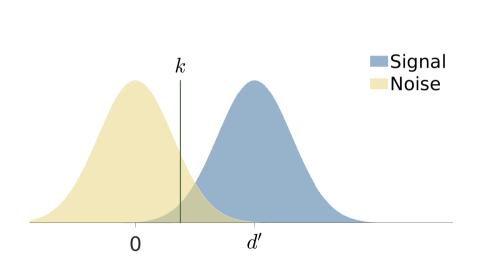
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- 3. **Additivity:** Signal shifts the mean $(\mu_{S+N} > \mu_N)$ but not the shape.
- 4. **Stable Criterion:** Observer uses a fixed decision criterion k. Respond "Yes" if Evidence > k.

Standard Model: Illustration



SDT: Model Parameters (d', c)

Key parameters under standard assumptions:

• **Sensitivity** (*d'*): Standardized difference between means.

$$d' = \frac{\mu_{S+N} - \mu_N}{\sigma}$$

Measures distribution separation (signal-to-noise ratio).

5

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• **Criterion** (c): Position relative to the midpoint between means.

$$c = \frac{k - (\mu_N + \mu_{S+N})/2}{\sigma}$$

Reflects response bias:

- c = 0: Neutral bias (relative to midpoint).
- c > 0: Conservative bias (need more evidence for "Yes").
- c < 0: Liberal bias (need less evidence for "Yes").

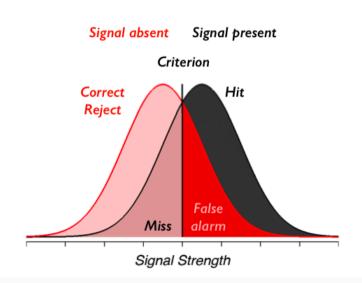
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• Convention: Often set $\mu_N = 0$ and $\sigma = 1$. Then:

Noise
$$\sim \mathcal{N}(0,1)$$

Signal $\sim \mathcal{N}(d',1)$
 $c=k-d'/2$
 $k=c+d'/2$ (Absolute criterion location)

Probabilities are areas



SDT: Linking Model to Data (HR, FAR)

The model links latent parameters (d',c) to observable data via Hit Rate (HR) and False Alarm Rate (FAR), using the standard normal CDF $\Phi(z) = P(Z \le z)$:

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• Hit Rate (HR): P("Yes" |Signal)

$$\begin{split} HR &= P(\mathsf{Evidence} > k | \mathsf{Signal}) \\ &= P(Z > \frac{k - \mu_{S+N}}{\sigma}) \quad (\mathsf{Standardize}) \\ &= P(Z > k - d') \quad (\mathsf{Using convention} \ \mu_{S+N} = d', \sigma = 1) \\ &= 1 - \Phi\left(k - d'\right) = \Phi\left(d' - k\right) \\ &= \Phi\left(d' - (c + d'/2)\right) = \Phi\left(d'/2 - c\right) \end{split}$$

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• False Alarm Rate (FAR): P("Yes" | Noise)

$$\begin{aligned} \textit{FAR} &= P(\mathsf{Evidence} > k | \mathsf{Noise}) \\ &= P(Z > \frac{k - \mu_N}{\sigma}) \quad (\mathsf{Standardize}) \\ &= P(Z > k) \quad (\mathsf{Using convention} \ \mu_N = 0, \sigma = 1) \\ &= 1 - \Phi\left(k\right) = \Phi\left(-k\right) \\ &= \Phi\left(-(c + d'/2)\right) = \Phi\left(-d'/2 - c\right) \end{aligned}$$

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From:

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$$HR = \Phi(d'/2 - c) \implies \Phi^{-1}(HR) = d'/2 - c$$

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$$FAR = \Phi(-d'/2 - c) \implies \Phi^{-1}(FAR) = -d'/2 - c$$

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Solving this system yields:

$$d' = \Phi^{-1}(HR) - \Phi^{-1}(FAR)$$

 $c = -\frac{1}{2}[\Phi^{-1}(HR) + \Phi^{-1}(FAR)]$

SDT: ROC Curves

Receiver Operating Characteristic (ROC) Curve:

- Plots HR vs. FAR.
- Each point represents a (HR, FAR) pair achievable for a fixed sensitivity (d') by varying the criterion (c).
- Illustrates the trade-off: Increasing HR means increasing FAR for a given d'.

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- Properties:
 - Diagonal (HR = FAR) \implies Chance performance (d' = 0).
 - Bows towards upper-left corner (HR=1, FAR=0 = Perfect).
 - Degree of bowing reflects sensitivity (higher d' curves closer to top-left).

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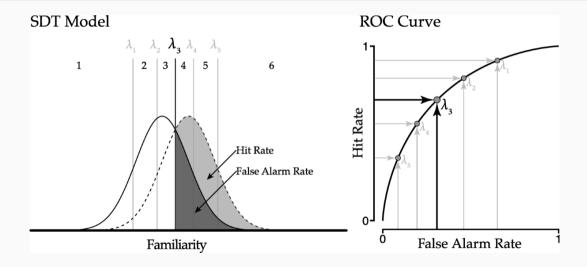
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• Area Under the ROC Curve (AUC):

- Non-parametric measure of sensitivity, independent of bias.
- AUC = $0.5 \implies$ Chance.
- AUC = $1.0 \implies \text{Perfect}$.
- For equal-variance Gaussian model: $AUC = \Phi(d'/\sqrt{2})$.

ROC Curve Illustration



SDT: Assumptions & Extensions

Standard model assumptions are often simplifications:

- Unequal Variances (UVSDT):
 - Often more realistic, but harder to estimate (needs more data, e.g., ratings).
- Non-Gaussian Distributions: Other evidence distributions (Poisson, Exponential) lead to different ROC shapes.
- **Criterion Variance:** Criterion might fluctuate across trials.
- Task Dependence: Model applies most directly to Yes/No tasks.
 - Rating Scales: Collect confidence ratings (e.g., 1-6). Allows plotting empirical ROC by collapsing ratings above different thresholds.
 - Forced-Choice (e.g., 2AFC): Choose interval/location with signal. Bias minimized. $PC = \Phi\left(d'/\sqrt{2}\right)$ for 2AFC.

SDT: Assumptions & Extensions

Limitations: SDT is a descriptive, static model. It doesn't typically explain:

- Underlying mechanisms generating distributions.
- Time course of decision (see DDM, etc.).
- Dynamic changes (learning).

First assignment: PyMC Implementation (Basic SDT)

The concepts discussed in this lecture (estimating d' and c for one observer/condition) are implemented using PyMC in a Python script in the class repository:

O-introduction/src/sdt/basic.py

This script demonstrates how to:

- Define priors for d' and c.
- Link parameters to observed Hits and False Alarms using a Binomial likelihood.
- Sample from the posterior distribution using MCMC.
- Analyze and visualize the results (parameter estimates, uncertainty).

Your assignment is to start the class container and run this script. Then, explore the code to study a practical application of Bayesian SDT modeling for the basic case.

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