Notes for MATH 3210: Foundation of Analysis I

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1 Ring and Field

1.1 Ring

The set A has two binary operations, addition and multiplication. For any $a,b\in A,$

$$A * A \to A \tag{1}$$

$$a, b \to a + b$$
 (2)

Notations:

- Z: The set of integers (ring, not field, has no inverse);
- \mathbb{Q} : The set of rational numbers;
- \mathbb{R} : The set of real numbers (ring and field).

1.1.1 Addition Axiom

- 1. a + b = b + a (commutative)
- 2. (a + b) + c = a + (b + c) (associative)
- 3. There is an element 0 such that a + 0 = a (additive identity)
- 4. There exists -a (additive inverse) such that a + (-a) = 0

Multiplication Axiom

- 1. $a \cdot b = b \cdot a$
- 2. $(a \cdot b) \cdot c = a \cdot (b \cdot c)$
- 3. There is an element 1 such that $a \cdot 1 = a$ and $0 \neq 1$
- 4. $a \cdot (b+c) = a \cdot b + a \cdot c$ (distributive)

1.2 Field

A is a field if A is a ring for any $a \in A$ and $a \neq 0$, there exists a^{-1} (inverse of a) such that $a \cdot a^{-1} = 1$

Example: $x, y \in A, x \neq 0, y \neq 0, xy = 0$

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

2 Basic Topology

Metric (distance function) of x_0 and x: $d(x_0, x) = |x - x_0|$

Metric Space M2.1

$$d: M \times M \to \mathbb{R}$$

- 1. $d(x_0, x_1) \ge 0$ where $x_0, x_1 \in M$
- 2. $d(x_0, x_1) = 0 \iff x_0 = x_1$
- 3. $d(x_0, x_1) = d(x_1, x_0)$ (irrespective of order)
- 4. $d(x,z) \le d(x,y) + d(y,z)$ (triangular inequity)

Euclidean metric on \mathbb{R}^2 : $d(x,y) = \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2}$ Discrete metric: $d(x,y) = \begin{cases} 1 & \text{if } x \neq y \\ 0 & \text{if } x = y \end{cases}$

Open ball of radius ϵ : $B_{\epsilon}(x_0) = B(x_0, \epsilon) = \{y \in M \mid d(x_0, y) < \epsilon\}$

2.2 Open Sets

2.2.1 Metric Spaces X

 $U \subset X$ is open if for any $x \in U$ there exists $\epsilon > 0$ such that $B(x, \epsilon) \subset U$. Open interval is open set; closed interval is not open set.

2.2.2 Topological Spaces (X, U)

Let U be a family of all sets, X be a set. U is a **topology** on X if

- 1. \emptyset (Empty set) is always open; X is open. $\Leftrightarrow \emptyset$ and X itself belong to U.
- 2. F is a collection of open sets, then $\bigcup_{U \in F} U$ is open. \Leftrightarrow Any union of members of U still belongs to U. (Union)
- 3. F is a *finite* collection of open sets, then $\bigcap_{U \in F} U$ is open. \Leftrightarrow The intersection of any finite number of members of U belongs to U. (Intersection)

Finite case: $x \in \bigcap_{U \in F} U$, $x \in U$, hence $B(x, \epsilon_U) \subset U$

$$\delta = \min \epsilon_U > 0 \quad where \quad U \in F$$
$$B(x, \delta) \subset B(x, \epsilon_U) \subset U$$
$$\therefore B(x, \delta) \subset \bigcap_{U \in F} U$$

Infinite case: For example, the intersection of all intervals of $\left(-\frac{1}{n}, \frac{1}{n}\right)$, where n is a positive number, is the set $\{0\}$ which is not open in the real line.

2.3 Compact Sets

In metric space X, compact sets are <u>closed</u>.

Compact \Leftrightarrow closed and bounded (only for Euclidean metric, \mathbb{R}^n)