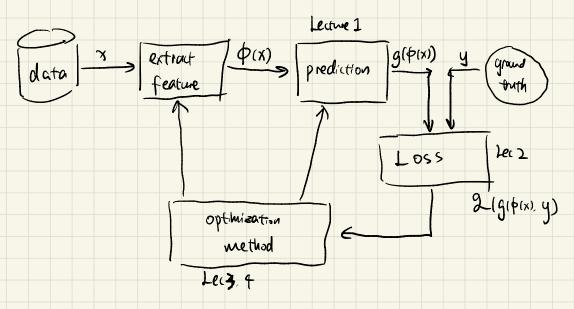
Livear Regulation



Notation
a.b.c ER

$$\vec{a} \cdot \vec{b} \cdot \vec{c} \in \mathbb{R}^d$$

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$$\vec{a} \cdot \vec{c} = \begin{bmatrix} a_1 \\ a_2 \\ a_4 \end{bmatrix}$$

A.B. C. ERN×a aij. [A]

$$A = \begin{bmatrix} (\vec{x}')^T \\ (\vec{x}')^T \\ (\vec{x}d)^T \end{bmatrix}$$

T. 
$$\vec{1} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
 ith

Likeur Regression Formulation

Regression:

Given measurement  $y^n$ .  $n = 1 \dots N$ 

Given imputs:  $\vec{1}^n$ 

Given model:  $g_0(\vec{x}^n)$ 
 $y^n \approx g_0(\vec{x}^n)$ 

Likeur Regression:

 $g_0(\vec{x}^n) = \int_{0}^{\infty} x_1 g_1$ 

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 $g_0(\vec{x}^n) = \int_{0}^{\infty} x_1 g_1$ 

Solution
$$y^{n} \approx S_{\theta}(\tilde{x}^{n})$$
Loss function:

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$$J(\vec{\theta}) = \sum_{n=1}^{N} (g_{\theta}(x^n) - y^n)^2$$

$$\sum_{n=1}^{N} |g_0(x^n) - y^n| \quad 1 - norm losses$$

Goal: 
$$\hat{\theta} = \underset{\hat{0}}{\operatorname{arg min}} J(\hat{0})$$

For 
$$\vec{x}$$
 new  $= g_{\vec{\theta}}(\vec{x}^{new}) = \vec{x}^{new} T_{\vec{\theta}}$ 

$$J(\vec{\theta}) = \sum_{n=1}^{N} (g_{\theta}(\vec{x}^{n}) - g_{\theta})^{2}$$

$$= \sum_{n=1}^{N} (\hat{\theta} T_{\vec{x}}^{n} - g_{\theta})^{2} = ||A\vec{\theta} - \hat{g}||^{2}$$

$$\begin{bmatrix} -(\vec{x}')^{T} \\ -(\vec{x}')^{T} \\ -(\vec{x}')^{T} \end{bmatrix} \vec{y} = \begin{bmatrix} \vec{y}' \\ \vec{y}' \end{bmatrix}$$

$$\nabla_{\vec{\theta}} \vec{J} (\vec{\theta}) = 0 = 2 (A)^{T} (A\vec{\theta} - \vec{y})$$

 $\partial = (A^TA)^T A^T Y$ 

Theorem:
For
the n

For a linear regression problem:

$$\hat{\vec{\theta}} = \underset{\vec{\theta}}{\text{argmin}} J(\hat{\vec{\theta}}) = ||A\vec{\theta} - \hat{\vec{y}}||^{L}$$

the muhimizer 
$$\delta = (A^TA)^TA^Ty$$
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