GUOSONG YANG

Department of Electrical and Computer Engineering
University of California, Santa Barbara
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Position

University of California, Santa Barbara (UCSB)

Santa Barbara, CA Aug. 2017-present

Postdoctoral Scholar

Center for Control, Dynamical Systems, and Computation Department of Electrical and Computer Engineering

Advisor: João P. Hespanha

EDUCATION

University of Illinois at Urbana-Champaign (UIUC)

Urbana, IL

Ph.D. in Electrical and Computer Engineering

Aug. 2013-Aug. 2017

Advisor: Daniel Liberzon

Dissertation: "Switched and hybrid systems with inputs: small-gain theorems, control with lim-

ited information, and topological entropy"

University of Illinois at Urbana-Champaign (UIUC)

Urbana, IL

M.S. in Electrical and Computer Engineering

Aug. 2011-Aug. 2013

Advisor: Daniel Liberzon

Thesis: "A Lyapunov-based small-gain theorem for interconnected switched systems"

Hong Kong University of Science and Technology (HKUST)

Hong Kong

B.Eng. in Electronic Engineering (Honors Research Option)

Sep. 2007-May 2011

Minor in Mathematics Advisor: Zexiang Li

RESEARCH INTERESTS

- Switched and hybrid systems
- Networked systems
- Control with limited information
- Network security

PUBLICATIONS

Journals

• Guosong Yang and Daniel Liberzon, "Feedback stabilization of a switched linear system with an unknown disturbance under data-rate constraints," *IEEE Transactions on Automatic Control*, vol. 63, no. 7, pp. 2107–2122, 2018

- Kunihisa Okano, Masashi Wakaiki, **Guosong Yang**, and João P. Hespanha, "Stabilization of networked control systems under clock offsets and quantization," *IEEE Transactions on Automatic Control*, vol. 63, no. 6, pp. 1708–1723, 2018
- Andrii Mironchenko, **Guosong Yang**, and Daniel Liberzon, "Lyapunov small-gain theorems for networks of not necessarily ISS hybrid systems," *Automatica*, vol. 88, pp. 10–20, 2018
- Guosong Yang and Daniel Liberzon, "A Lyapunov-based small-gain theorem for interconnected switched systems," Systems & Control Letters, vol. 78, pp. 47–54, 2015

Conferences

- Guosong Yang, João P. Hespanha, and Daniel Liberzon, "On topological entropy and stability of switched linear systems," in 22nd International Conference on Hybrid Systems: Computation and Control, 2019, to be published
- Guosong Yang and João P. Hespanha, "On topological entropy of switched linear systems with pairwise commuting matrices," in 56th Annual Allerton Conference on Communication, Control, and Computing, 2018, to be published (Invited Paper)
- Guosong Yang, A. James Schmidt, and Daniel Liberzon, "On topological entropy of switched linear systems with diagonal, triangular, and general matrices," in 57th IEEE Conference on Decision and Control, 2018, pp. 5682–5687
- Guosong Yang, Hossein Hosseini, Dinuka Sahabandu, Andrew Clark, João P. Hespanha, and Radha Poovendran, "Modeling and mitigating the Coremelt attack," in 2018 American Control Conference, 2018, pp. 3410–3416
- Guosong Yang, Daniel Liberzon, and Zhong-Ping Jiang, "Stabilization of interconnected switched control-affine systems via a Lyapunov-based small-gain approach," in 2017 American Control Conference, 2017, pp. 5182–5187
- Guosong Yang, Daniel Liberzon, and Andrii Mironchenko, "Analysis of different Lyapunov function constructions for interconnected hybrid systems," in 55th IEEE Conference on Decision and Control, 2016, pp. 465–470 (Invited Paper)
- Guosong Yang and Daniel Liberzon, "Finite data-rate stabilization of a switched linear system with unknown disturbance," in 10th IFAC Symposium on Nonlinear Control Systems, vol. 49, no. 18, 2016, pp. 1085–1090
- Guosong Yang and Daniel Liberzon, "Stabilizing a switched linear system with disturbance by sampled-data quantized feedback," in 2015 American Control Conference, 2015, pp. 2193–2198
- Guosong Yang and Daniel Liberzon, "Input-to-state stability for switched systems with unstable subsystems: A hybrid Lyapunov construction," in 53rd IEEE Conference on Decision and Control, 2014, pp. 6240–6245
- Andrii Mironchenko, Guosong Yang, and Daniel Liberzon, "Lyapunov small-gain theorems for not necessarily ISS hybrid systems," in 21st International Symposium on Mathematical Theory of Networks and Systems, 2014, pp. 1001–1008

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Presentations and seminars

- Presentation at the 57th IEEE Conference on Decision and Control, Miami Beach, FL, Dec. 2018
- Presentation at the 35th Southern California Control Workshop, University of California, Los Angeles, CA, Nov. 2018
- Invited presentation at the 56th Annual Allerton Conference on Communication, Control, and Computing, Monticello, IL, Oct. 2018
- Presentation at the 2018 American Control Conference, Milwaukee, WI, Jun. 2018
- Presentation at the 2017 American Control Conference, Seattle, WA, May. 2017
- Seminar at the Multi-Agent Robotics Lab, University of California, San Diego, CA, Mar. 2017
- Seminar at the Hybrid Systems Laboratory, University of California, Santa Cruz, CA, Feb. 2017
- Invited presentation at the 55th IEEE Conference on Decision and Control, Las Vegas, NV, Dec. 2016
- Seminar at the *Center for Control, Dynamical Systems, and Computation*, University of California, Santa Barbara, CA, Nov. 2016
- Seminar at the *Cyber-Physical Systems Laboratory*, University of California, Los Angeles, CA, Oct. 2016
- Presentation at the 10th IFAC Symposium on Nonlinear Control Systems, Monterey, CA, Aug. 2016
- Presentation at the 2015 American Control Conference, Chicago, IL, Jul. 2015
- Presentation at the 53rd IEEE Conference on Decision and Control, Los Angeles, CA, Dec. 2014
- Presentation at the 2nd Midwest Workshop on Control and Game Theory, University of Notre Dame, Notre Dame, IN, Apr. 2013

Grant-writing experience

• Coauthor of National Science Foundation grant CMMI-1662708: "Switched control systems with limited information: An entropy approach to stabilization and disturbance attenuation," PI: Daniel Liberzon, 2017–2020, Amount: \$349,540

AWARDS AND HONORS

• Best Poster Award, 11th CSL Student Conference, UIUC	2016
• Graduate College Conference Travel Award, UIUC	2016
• University Scholarship, HKUST	2007 – 2011
• School of Engineering Scholarship, HKUST	2007 – 2011
• ECE Outstanding Freshmen Scholarship, HKUST	2007 – 2011
• The Joseph Lau Luen Hung Charitable Trust Scholarship, HKUST	2007 – 2011
• Gold medal, 8th Asian Physics Olympiad	2007

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Teaching

University of Illinois at Urbana-Champaign

Urbana, IL

- Teaching assistant, ECE517 Nonlinear and Adaptive Control

Fall 2015, Fall 2016

- Teaching assistant, ECE528 Analysis of Nonlinear Systems

Spring 2015

SERVICE

Journal reviewer

- IEEE Transactions on Automatic Control
- IFAC Automatica
- System & Control Letters
- Nonlinear Analysis: Hybrid Systems
- IEEE Control Systems Letters

Conference reviewer

- American Control Conference: ACC 2017 and ACC 2018
- ACM International Conference on Hybrid Systems: Computation and Control: HSCC 2016 and HSCC 2017
- IFAC Conference on Modelling, Identification and Control of Nonlinear Systems: MICNON 2015

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