

GUOSONG YANG

Center for Control, Dynamical Systems, and Computation
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POSITION

University of California, Santa Barbara (UCSB)	Santa Barbara, CA
Postdoctoral Scholar	Aug. 2017–present
Center for Control, Dynamical Systems, and Computation	
Advisor: João P. Hespanha	

EDUCATION

University of Illinois at Urbana-Champaign (UIUC)	Urbana, IL
Ph.D. in Electrical and Computer Engineering	Aug. 2013–Aug. 2017
Advisor: Daniel Liberzon	
Dissertation: “Switched and hybrid systems with inputs: small-gain theorems, control with limited information, and topological entropy”	

University of Illinois at Urbana-Champaign (UIUC)	Urbana, IL
M.S. in Electrical and Computer Engineering	Aug. 2011–Aug. 2013
Advisor: Daniel Liberzon	
Thesis: “A Lyapunov-based small-gain theorem for interconnected switched systems”	

Hong Kong University of Science and Technology (HKUST)	Hong Kong
B.Eng. in Electronic Engineering (Honors Research Option)	Sep. 2007–May 2011
Minor in Mathematics	
Advisor: Zexiang Li	

RESEARCH INTERESTS

- Switched and hybrid systems
- Networked systems
- Control with limited information
- Network security

PUBLICATIONS

Journals

- **Guosong Yang** and Daniel Liberzon, “Feedback stabilization of a switched linear system with an unknown disturbance under data-rate constraints,” *IEEE Transactions on Automatic Control*, vol. 63, no. 7, pp. 2107–2122, 2018
- Kuniyoshi Okano, Masashi Wakaiki, **Guosong Yang**, and João P. Hespanha, “Stabilization of networked control systems under clock offsets and quantization,” *IEEE Transactions on Automatic Control*, vol. 63, no. 6, pp. 1708–1723, 2018

- Andrii Mironchenko, **Guosong Yang**, and Daniel Liberzon, “Lyapunov small-gain theorems for networks of not necessarily ISS hybrid systems,” *Automatica*, vol. 88, pp. 10–20, 2018
- **Guosong Yang** and Daniel Liberzon, “A Lyapunov-based small-gain theorem for interconnected switched systems,” *Systems & Control Letters*, vol. 78, pp. 47–54, 2015

Conferences

- **Guosong Yang**, João P. Hespanha, and Daniel Liberzon, “On topological entropy and stability of switched linear systems,” in *22nd International Conference on Hybrid Systems: Computation and Control*, 2019, to appear
- **Guosong Yang** and João P. Hespanha, “On topological entropy of switched linear systems with pairwise commuting matrices,” in *56th Annual Allerton Conference on Communication, Control, and Computing*, 2018, to appear (Invited Paper)
- **Guosong Yang**, A. James Schmidt, and Daniel Liberzon, “On topological entropy of switched linear systems with diagonal, triangular, and general matrices,” in *57th IEEE Conference on Decision and Control*, 2018, pp. 5682–5687
- **Guosong Yang**, Hossein Hosseini, Dinuka Sahabandu, Andrew Clark, João P. Hespanha, and Radha Poovendran, “Modeling and mitigating the Coremelt attack,” in *2018 American Control Conference*, 2018, pp. 3410–3416
- **Guosong Yang**, Daniel Liberzon, and Zhong-Ping Jiang, “Stabilization of interconnected switched control-affine systems via a Lyapunov-based small-gain approach,” in *2017 American Control Conference*, 2017, pp. 5182–5187
- **Guosong Yang**, Daniel Liberzon, and Andrii Mironchenko, “Analysis of different Lyapunov function constructions for interconnected hybrid systems,” in *55th IEEE Conference on Decision and Control*, 2016, pp. 465–470 (Invited Paper)
- **Guosong Yang** and Daniel Liberzon, “Finite data-rate stabilization of a switched linear system with unknown disturbance,” in *10th IFAC Symposium on Nonlinear Control Systems*, vol. 49, no. 18, 2016, pp. 1085–1090
- **Guosong Yang** and Daniel Liberzon, “Stabilizing a switched linear system with disturbance by sampled-data quantized feedback,” in *2015 American Control Conference*, 2015, pp. 2193–2198
- **Guosong Yang** and Daniel Liberzon, “Input-to-state stability for switched systems with unstable subsystems: A hybrid Lyapunov construction,” in *53rd IEEE Conference on Decision and Control*, 2014, pp. 6240–6245
- Andrii Mironchenko, **Guosong Yang**, and Daniel Liberzon, “Lyapunov small-gain theorems for not necessarily ISS hybrid systems,” in *21st International Symposium on Mathematical Theory of Networks and Systems*, 2014, pp. 1001–1008

PRESENTATIONS AND SEMINARS

- Presentation at the *57th IEEE Conference on Decision and Control*, Miami Beach, FL, Dec. 2018
- Presentation at the *35th Southern California Control Workshop*, University of California, Los Angeles, CA, Nov. 2018
- Invited presentation at the *56th Annual Allerton Conference on Communication, Control, and Computing*, Monticello, IL, Oct. 2018

- Presentation at the *2018 American Control Conference*, Milwaukee, WI, Jun. 2018
- Presentation at the *2017 American Control Conference*, Seattle, WA, May. 2017
- Seminar at the *Multi-Agent Robotics Lab*, University of California, San Diego, CA, Mar. 2017
- Seminar at the *Hybrid Systems Laboratory*, University of California, Santa Cruz, CA, Feb. 2017
- Invited presentation at the *55th IEEE Conference on Decision and Control*, Las Vegas, NV, Dec. 2016
- Seminar at the *Center for Control, Dynamical Systems, and Computation*, University of California, Santa Barbara, CA, Nov. 2016
- Seminar at the *Cyber-Physical Systems Laboratory*, University of California, Los Angeles, CA, Oct. 2016
- Presentation at the *10th IFAC Symposium on Nonlinear Control Systems*, Monterey, CA, Aug. 2016
- Presentation at the *2015 American Control Conference*, Chicago, IL, Jul. 2015
- Presentation at the *53rd IEEE Conference on Decision and Control*, Los Angeles, CA, Dec. 2014
- Presentation at the *2nd Midwest Workshop on Control and Game Theory*, University of Notre Dame, Notre Dame, IN, Apr. 2013

GRANT-WRITING EXPERIENCE

- Coauthor of National Science Foundation grant [CMMI-1662708](#): “Switched control systems with limited information: An entropy approach to stabilization and disturbance attenuation,” PI: [Daniel Liberzon](#), 2017–2020, Amount: \$349,540

AWARDS AND HONORS

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| • Best Poster Award, 11th CSL Student Conference, UIUC | 2016 |
| • Graduate College Conference Travel Award, UIUC | 2016 |
| • University Scholarship, HKUST | 2007–2011 |
| • School of Engineering Scholarship, HKUST | 2007–2011 |
| • ECE Outstanding Freshmen Scholarship, HKUST | 2007–2011 |
| • The Joseph Lau Luen Hung Charitable Trust Scholarship, HKUST | 2007–2011 |
| • Gold medal, 8th Asian Physics Olympiad | 2007 |

TEACHING

University of Illinois at Urbana-Champaign	Urbana, IL
– Teaching assistant, ECE517 Nonlinear and Adaptive Control	Fall 2015, Fall 2016
– Teaching assistant, ECE528 Analysis of Nonlinear Systems	Spring 2015

Journal reviewer

- [IEEE Transactions on Automatic Control](#)
- [IFAC Automatica](#)
- [System & Control Letters](#)
- [Nonlinear Analysis: Hybrid Systems](#)
- [IEEE Control Systems Letters](#)

Conference reviewer

- American Control Conference: [ACC 2017](#) and [ACC 2018](#)
- ACM International Conference on Hybrid Systems: Computation and Control: [HSCC 2016](#) and [HSCC 2017](#)
- IFAC Conference on Modelling, Identification and Control of Nonlinear Systems: [MICNON 2015](#)