GUOSONG YANG (杨国松)

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Position

University of California, Santa Barbara

Santa Barbara, CA May 2017–Jul. 2017

Visiting Scholar, Department of Electrical and Computer Engineering

Advisor: João P. Hespanha

EDUCATION

University of Illinois at Urbana-Champaign

Urbana, IL

Ph.D. candidate in Electrical and Computer Engineering Aug. 2013–Jul. 2017 (expected)

Advisor: Daniel Liberzon

Tentative dissertation title: "Switched and hybrid systems with inputs: small-gain theorems and control

with limited information"

University of Illinois at Urbana-Champaign

Urbana, IL

M.S. in Electrical and Computer Engineering

Aug. 2011-Aug. 2013

Advisor: Daniel Liberzon

Thesis: "A Lyapunov-based small-gain theorem for interconnected switched systems"

Hong Kong University of Science and Technology

Kowloon, Hong Kong

B.Eng. in Electronic Engineering (Honors Research Option)

Sep. 2007– May 2011

Minor in Mathematics Advisor: Zexiang Li

RESEARCH INTERESTS

- Switched and hybrid systems
- Control with limited information
- Nonlinear systems and control theory

PUBLICATIONS

Journals:

- Guosong Yang and Daniel Liberzon, "Feedback stabilization of a switched linear system with an unknown disturbance under data-rate constraints," *IEEE Transactions on Automatic Control*, submitted for publication
- Andrii Mironchenko, **Guosong Yang**, and Daniel Liberzon, "Lyapunov small-gain theorems for networks of not necessarily ISS hybrid systems," *Automatica*, submitted for publication
- Guosong Yang and Daniel Liberzon, "A Lyapunov-based small-gain theorem for interconnected switched systems," Systems & Control Letters, vol. 78, pp. 47–54, 2015

Conferences:

- Guosong Yang, Daniel Liberzon, and Zhong-Ping Jiang, "Stabilization of interconnected switched control-affine systems via a Lyapunov-based small-gain approach," in 2017 American Control Conference, 2017, pp. 5182–5187
- Guosong Yang, Daniel Liberzon, and Andrii Mironchenko, "Analysis of different Lyapunov function constructions for interconnected hybrid systems," in 55th IEEE Conference on Decision and Control, 2016, pp. 465–470
- Guosong Yang and Daniel Liberzon, "Finite data-rate stabilization of a switched linear system with unknown disturbance," in 10th IFAC Symposium on Nonlinear Control Systems, 2016, pp. 1085–1090
- Guosong Yang and Daniel Liberzon, "Stabilizing a switched linear system with disturbance by sampled-data quantized feedback," in 2015 American Control Conference, 2015, pp. 2193–2198
- Guosong Yang and Daniel Liberzon, "Input-to-state stability for switched systems with unstable subsystems: a hybrid Lyapunov construction," in 53rd IEEE Conference on Decision and Control, 2014, pp. 6240–6245
- Andrii Mironchenko, **Guosong Yang**, and Daniel Liberzon, "Lyapunov small-gain theorems for not necessarily ISS hybrid systems," in *21st International Symposium on Mathematical Theory of Networks and Systems*, 2014, pp. 1001–1008

TEACHING EXPERIENCE

University of Illinois at Urbana-Champaign

Urbana, IL

- Teaching assistant, ECE517 Nonlinear and Adaptive Control, Fall 2015, Fall 2016
- Teaching assistant, ECE528 Analysis of Nonlinear Systems, Spring 2015

Professional activities

- Journal reviewer for IFAC Automatica, System & Control Letters, and Nonlinear Analysis: Hybrid Systems
- Conference reviewer for MICNON 2015, HSCC 2017, and 2017 ACC

Honors and awards

- Best Poster Award, Coordinated Science Laboratory Student Conference, 2016
- HKUST University Scholarship, 2007–2011
- HKUST School of Engineering Scholarship, 2007–2011
- HKUST ECE Outstanding Freshmen Scholarship, 2007–2011
- HKUST The Joseph Lau Luen Hung Charitable Trust Scholarship, 2007–2011
- HKUST Dean's List Award, Fall 2007, Spring 2008, Fall 2008, Spring 2009, Fall 2009
- Gold medal for 8th Asian Physics Olympiad, 2007

Personal

- Citizenship: China
- Languages: Chinese (native), English (fluent)