On Topological Entropy of Switched Linear Systems with Pairwise Commuting Matrices

Guosong Yang and João P. Hespanha

Center for Control, Dynamical Systems, and Computation University of California, Santa Barbara

October 6, 2018

Motivation

Topological entropy in systems theory

- Originated from [Kolmogorov, 1958], defined by [Adler, Konheim, and McAndrew, 1965], [Bowen, 1971], and [Dinaburg, 1970].
- Essential idea:
 - The complexity growth of a system.
 - The information accumulation needed to approximate a trajectory.
- In control theory:
 - Topological feedback entropy [Nair, Evans, Mareels, and Moran, 2004]
 - Invariance entropy [Colonius and Kawan, 2009], exponential stabilization entropy [Colonius, 2012]
 - Estimation entropy [Savkin, 2006] and [Liberzon and Mitra]
- Minimal data rate for stabilizing linear time-invariant (LTI) system [Hespanha, Ortega, and Vasudevan, 2002], [Nair and Evans, 2003], and [Tatikonda and Mitter, 2004]

Motivation

Switched linear system with pairwise commuting matrices

- Switching is ubiquitous in realistic system models.
- Stability under arbitrary switching: pairwise commuting matrices [Narendra and Balakrishnan, 1994]
- Neither minimal data rate for stabilization nor topological entropy is well-understood:
 - Sufficient data rate [Liberzon, 2014], [Yang and Liberzon, 2018], and [Sibai and Mitra, 2017]
 - Topological entropy [Yang, Schmidt, and Liberzon]

Switched System

A finite family of continuous-time dynamical systems

$$\dot{x} = f_p(x), \qquad p \in \mathcal{P}$$

with the state $x \in \mathbb{R}^n$ and an index set \mathcal{P} .

A switched system

$$\dot{x} = f_{\sigma}(x), \qquad x(0) \in K.$$

- lacksquare Switching signal $\sigma:\mathbb{R}_+ o\mathcal{P}$ is right-continuous and piecewise constant
- lacktriangleright Initial set K is compact with a nonempty interior
- Modes $\{f_p : p \in \mathcal{P}\}$
- \blacksquare Denote by $\xi_\sigma(x,t)$ the solution at t with switching signal σ and initial state x

Entropy Definition

A switched system

$$\dot{x} = f_{\sigma}(x), \qquad x(0) \in K.$$

■ Given a time horizon $T \ge 0$ and a radius $\varepsilon > 0$, define the open ball:

$$B_{f_{\sigma}}(x,\varepsilon,T) := \Big\{ x' \in K : \max_{t \in [0,T]} \|\xi_{\sigma}(x',t) - \xi_{\sigma}(x,t)\| < \varepsilon \Big\}.$$

- A finite set $E \subset K$ is (T, ε) -spanning if $K = \bigcup_{\hat{x} \in E} B_{f_{\sigma}}(\hat{x}, \varepsilon, T)$.
- Let $S(f_{\sigma}, \varepsilon, T, K)$ be the minimal cardinality of a (T, ε) -spanning set.
- The topological entropy with initial set K and switching signal σ is defined in terms of the exponential growth rate of $S(f_{\sigma}, \varepsilon, T, K)$ by

$$h(f_{\sigma}, K) := \lim_{\varepsilon \searrow 0} \limsup_{T \to \infty} \frac{1}{T} \log S(f_{\sigma}, \varepsilon, T, K).$$

Alternative Entropy Definition

A switched system

$$\dot{x} = f_{\sigma}(x), \qquad x(0) \in K.$$

■ The topological entropy is defined by

$$h(f_{\sigma}, K) := \lim_{\varepsilon \searrow 0} \limsup_{T \to \infty} \frac{1}{T} \log S(f_{\sigma}, \varepsilon, T, K).$$

■ A finite set of points $E \subset K$ is (T, ε) -separated if for all $\hat{x}, \hat{x}' \in E$,

$$\hat{x}' \notin B_{f_\sigma}(\hat{x}, \varepsilon, T) = \Big\{ x \in K : \max_{t \in [0, T]} \|\xi_\sigma(x, t) - \xi_\sigma(\hat{x}, t)\| < \varepsilon \Big\}.$$

- Let $N(f_{\sigma}, \varepsilon, T, K)$ be the maximal cardinality of a (T, ε) -separated set.
- Proposition 1. The topological entropy satisfies

$$h(f_{\sigma}, K) = \lim_{\varepsilon \searrow 0} \limsup_{T \to \infty} \frac{1}{T} \log N(f_{\sigma}, \varepsilon, T, K).$$

Proof.
$$N(f_{\sigma}, 2\varepsilon, T, K) \leq S(f_{\sigma}, \varepsilon, T, K) \leq N(f_{\sigma}, \varepsilon, T, K)$$
.

Active Time and Active Rates

For a switching signal σ , define the following quantities.

lacktriangle The active time of each mode over an interval [0,t] is

$$\tau_p(t) := \int_0^t \mathbb{1}_p(\sigma(s)) \, \mathrm{d}s, \qquad p \in \mathcal{P}$$

with the indicator function 1. Then $\sum_{p\in\mathcal{P}} \tau_p(t) = t$.

lacktriangle The active rate of each mode over [0,t] is

$$\rho_p(t) := \tau_p(t)/t, \qquad p \in \mathcal{P}$$

with
$$\rho_p(0) := \mathbb{1}_p(\sigma(0))$$
. Then $\sum_{p \in \mathcal{P}} \rho_p(t) = 1$.

■ The asymptotic active rate of each mode is

$$\hat{\rho}_p := \limsup_{t \to \infty} \rho_p(t), \qquad p \in \mathcal{P}.$$

It is possible that $\sum_{p \in \mathcal{P}} \hat{\rho}_p > 1$.

Entropy of Switched Linear Systems

A switched linear system

$$\dot{x} = A_{\sigma}x, \qquad x(0) \in K.$$

Results from [Yang, Schmidt, and Liberzon]:

- **Proposition 2.** The topological entropy of the switched linear system is independent of the choice of the initial set K.
- Proposition 3. The topological entropy of the switched linear system is upper bounded by

$$\limsup_{t \to \infty} \sum_{p \in \mathcal{P}} \operatorname{tr}(A_p) \rho_p(t) \le h(A_\sigma) \le \limsup_{t \to \infty} \sum_{p \in \mathcal{P}} n \|A_p\| \rho_p(t)$$

with the active rates ρ_p .

Proof for the upper bound.

- 1. The solutions satisfy $\|\xi_{\sigma}(x',t) \xi_{\sigma}(x,t)\| \le e^{\sum_{p} \|A_{p}\|\tau_{p}(t)} \|x' x\|$.
- 2. Construct a (T, ε) -spanning set using a grid.

Lack of "independence" between eigenspaces of different modes!

Switched Commuting Linear Systems

A switched linear system

$$\dot{x} = A_{\sigma}x, \qquad x(0) \in K$$

with a commuting family $\{A_p : p \in \mathcal{P}\}.$

- If all A_p are diagonalizable, then there is a change of basis under which all A_p are diagonal.
- Every scalar component evolves independently (under the same switching signal).
- A formula for the entropy was established in [Yang, Schmidt, and Liberzon].

Switched Commuting Linear Systems

A switched linear system

$$\dot{x} = A_{\sigma}x, \qquad x(0) \in K$$

with a commuting family $\{A_p : p \in \mathcal{P}\}.$

- lacksquare A well-known result: in general, there is a change of basis under which all A_p are upper triangular.
- Each scalar component evolves in a "strict-feedback" fashion.
- An upper bound for the entropy was established in [Yang, Schmidt, and Liberzon].
- Being simultaneously triangularizable is weaker than being pairwise commuting!

Switched Commuting Linear Systems

A switched linear system

$$\dot{x} = A_{\sigma}x, \qquad x(0) \in K$$

with a commuting family $\{A_p : p \in \mathcal{P}\}.$

- First goal: a suitable change of basis for pairwise commuting matrices.
- Jordan–Chevalley Decomposition [Humphreys, 1972]. For each matrix A, there exist polynomials f and g, without constant term, such that f(A) is a diagonalizable matrix, g(A) is a nilpotent matrix, and

$$A = f(A) + g(A).$$

lacksquare A polynomial of a matrix A commutes with all matrices that commute with A.

A Change of Basis

Proposition 5

For the commuting family $\{A_p:p\in\mathcal{P}\}$, there exists an invertible matrix $\Gamma\in\mathbb{C}^{n\times n}$ such that

$$\Gamma A_p \Gamma^{-1} = D_p + N_p \qquad \forall \, p \in \mathcal{P},$$

where all $D_p \in \mathbb{C}^{n \times n}$ are diagonal matrices, all $N_p \in \mathbb{C}^{n \times n}$ are nilpotent matrices, and $\{D_p, N_p : p \in \mathcal{P}\}$ is a commuting family.

Proof.

- 1. For each p, there are polynomials f_p and g_p such that $f_p(A_p)$ is diagonalizable, $g_p(A_p)$ is nilpotent, and $A_p = f_p(A_p) + g_p(A_p)$.
- 2. The set $\{f_p(A_p), g_p(A_p) : p \in \mathcal{P}\}$ is a commuting family.
- 3. There is an invertible $\Gamma\in\mathbb{C}^{n\times n}$ such that all $D_p:=\Gamma f_p(A_p)\Gamma^{-1}$ are invertible.
- 4. All $N_p:=\Gamma g_p(A_p)\Gamma^{-1}$ are nilpotent, and $\{D_p,N_p:p\in\mathcal{P}\}$ is a commuting family.

A Formula for Entropy

The switched commuting linear system becomes

$$\dot{x} = (D_{\sigma} + N_{\sigma})x, \qquad x(0) \in K,$$

where $D_p=\mathrm{diag}(a_p^1,\dots,a_p^n)$ are diagonal, N_p are nilpotent, and $\{D_p,N_p:p\in\mathcal{P}\}$ is a commuting family.

Theorem 6

The topological entropy of the switched commuting system satisfies

$$h(D_{\sigma} + N_{\sigma}) = \limsup_{T \to \infty} \sum_{i=1}^{n} \frac{1}{T} \max_{t \in [0,T]} \sum_{p \in \mathcal{P}} \operatorname{Re}(a_{p}^{i}) \tau_{p}(t)$$

with the active times τ_p .

■ The entropy only depends on the diagonal part, i.e., $h(D_{\sigma}+N_{\sigma})=h(D_{\sigma}).$

A Formula for Entropy

Proof.

1. The solutions satisfy

$$\|\xi_{\sigma}(x',t) - \xi_{\sigma}(x,t)\| = \left\| e^{\sum_{p \in \mathcal{P}} N_p \tau_p(t)} e^{\sum_{p \in \mathcal{P}} D_p \tau_p(t)} (x'-x) \right\|.$$

2. Lemma 2. Consider the commuting family of nilpotent matrices $\{N_p:p\in\mathcal{P}\}$. For each $\delta>0$, there is a constant $c_\delta>0$ such that for all $v\in\mathbb{C}^n$,

$$c_{\delta}^{-1}e^{-\delta t}\|v\| \le \left\|e^{\sum_{p\in\mathcal{P}}N_p\tau_p(t)}v\right\| \le c_{\delta}e^{\delta t}\|v\|$$

for all $t \geq 0$ with the active times τ_p .

3. Given a radius $\varepsilon > 0$, there is a constant $c_{\varepsilon} > 0$ such that

$$\cdots \leq \|\xi_{\sigma}(x',t) - \xi_{\sigma}(x,t)\| \leq c_{\varepsilon} e^{\varepsilon t} \max_{i=1,\ldots,n} e^{\sum_{p \in \mathcal{P}} \operatorname{Re}(a_{p}^{i}) \tau_{p}(t)} |x'_{i} - x_{i}|.$$

4. For the upper/lower bound, construct a (T,ε) -spanning/separated set using a grid.

The Non-Switched Case

The formula for entropy yields the following well-known result Bowen [1971]:

Corollary 7

The topological entropy of the linear time-invariant (LTI) system

$$\dot{x} = Ax, \qquad x(0) \in K$$

equals the sum of the positive real parts of the eigenvalues of A, that is,

$$h(A) = \sum_{\lambda \in \operatorname{spec}(A)} \max \{ \operatorname{Re}(\lambda), \, 0 \}.$$

Proof.

- 1. The spectrum $\operatorname{spec}(A) = \{a^1, \dots, a^n\}.$
- 2. The entropy

$$h(A) = \limsup_{T \to \infty} \sum_{i=1}^{n} \frac{1}{T} \max_{t \in [0,T]} \text{Re}(a^{i})t = \sum_{i=1}^{n} \max\{\text{Re}(a^{i}), 0\}. \quad \Box$$

More General Upper and Lower Bounds for Entropy

#	Formula/upper bounds	Sw	СоВ
(1)	$= \limsup_{T \to \infty} \sum_{i=1}^{n} \frac{1}{T} \max_{t \in [0,T]} \sum_{p \in \mathcal{P}} \operatorname{Re}(a_{p}^{i}) \tau_{p}(t)$	$ au_p$	Yes
(2)	$\leq \sum_{i=1}^{n} \max \left\{ \limsup_{t \to \infty} \sum_{p \in \mathcal{P}} \operatorname{Re}(a_p^i) \rho_p(t), 0 \right\}$	$ ho_p$	Yes
(3)	$\leq \limsup_{t \to \infty} \sum_{p \in \mathcal{P}} h(D_p) \rho_p(t)$	$ ho_p$	No
(4)	$\leq \sum_{p \in \mathcal{P}} h(D_p) \hat{ ho}_p$	$\hat{ ho}_p$	No
(5)	$\leq \max_{p\in\mathcal{P}} h(D_p)$	N/A	No
(6)	$\leq \limsup_{t \to \infty} \sum_{p \in \mathcal{P}} n \ A_p\ \rho_p(t)$	$ ho_p$	No
(7)	$\geq \limsup_{t \to \infty} \sum_{p \in \mathcal{P}} \operatorname{tr}(A_p) \rho_p(t)$	$ ho_p$	No

Numerical Example

Let
$$\mathcal{P}=\{1,\,2\}$$
 and

$$D_1 = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}, \quad D_2 = \begin{bmatrix} 3 & 0 \\ 0 & 0 \end{bmatrix}.$$

	$(\hat{ ho}_1,\hat{ ho}_2)$	(1)	(2)	(3)	(4)	(5)	(6)	(7)
No switch	(1,0)	2	2	2	2	3	4	1
Periodic switches	(0.5, 0.5)	2	2	2.5	2.5	3	5	2
Switches w/ set-points	(0.9, 0.9)	2.8	4.4	2.9	4.5	3	5.8	2.8

Conclusion

Contributions:

- Switched linear systems with pairwise commuting matrices.
- A change of basis under which each of the matrices can be decomposed into a diagonal part and a nilpotent part, and all the diagonal and nilpotent parts are pairwise commuting.
- A formula for the topological entropy, which only depends on the diagonal part.
- More general upper bounds for the entropy.

Future research:

- Reconcile the switching characterizations for entropy computation and for stability analysis and control design
 - Stability and stabilization: slow-switching conditions such as the average dwell-time
 - Entropy: the active time (rarely seen in the literature)

References I

- R. L. Adler, A. G. Konheim, and M. H. McAndrew, "Topological entropy," Transactions of the American Mathematical Society, vol. 114, no. 2, pp. 309–319, 1965.
- R. Bowen, "Entropy for group endomorphisms and homogeneous spaces," Transactions of the American Mathematical Society, vol. 153, pp. 401–414, 1971.
- F. Colonius, "Minimal bit rates and entropy for exponential stabilization," SIAM Journal on Control and Optimization, vol. 50, no. 5, pp. 2988–3010, 2012.
- F. Colonius and C. Kawan, "Invariance entropy for control systems," SIAM Journal on Control and Optimization, vol. 48, no. 3, pp. 1701–1721, 2009.
- E. I. Dinaburg, "The relation between topological entropy and metric entropy," Doklady Akademii Nauk SSSR, vol. 190, no. 1, pp. 19–22, 1970, in Russian.
- J. P. Hespanha, A. Ortega, and L. Vasudevan, "Towards the control of linear systems with minimum bit-rate," in 15th International Symposium on Mathematical Theory of Networks and Systems, 2002, pp. 1–15.
- J. E. Humphreys, Introduction to Lie Algebras and Representation Theory. Springer New York, 1972, vol. 9.
- A. N. Kolmogorov, "A new metric invariant of transitive dynamical systems and automorphisms of Lebesgue spaces," *Doklady Akademii Nauk SSSR*, vol. 119, no. 5, pp. 861–864, 1958, in Russian.
- D. Liberzon, "Finite data-rate feedback stabilization of switched and hybrid linear systems," Automatica, vol. 50, no. 2, pp. 409–420, 2014.
- D. Liberzon and S. Mitra, "Entropy and minimal bit rates for state estimation and model detection," IEEE Transactions on Automatic Control, to appear.
- G. N. Nair and R. J. Evans, "Exponential stabilisability of finite-dimensional linear systems with limited data rates," Automatica, vol. 39, no. 4, pp. 585–593, 2003.

References II

- G. N. Nair, R. J. Evans, I. M. Y. Mareels, and W. Moran, "Topological feedback entropy and nonlinear stabilization," *IEEE Transactions on Automatic Control*, vol. 49, no. 9, pp. 1585–1597, 2004.
- K. S. Narendra and J. Balakrishnan, "A common Lyapunov function for stable LTI systems with commuting A-matrices," *IEEE Transactions on Automatic Control*, vol. 39, no. 12, pp. 2469–2471, 1994.
- A. V. Savkin, "Analysis and synthesis of networked control systems: topological entropy, observability, robustness and optimal control," *Automatica*, vol. 42, no. 1, pp. 51–62, 2006.
- H. Sibai and S. Mitra, "Optimal data rate for state estimation of switched nonlinear systems," in 20th International Conference on Hybrid Systems: Computation and Control, 2017, pp. 71–80.
- S. Tatikonda and S. Mitter, "Control under communication constraints," *IEEE Transactions on Automatic Control*, vol. 49, no. 7, pp. 1056–1068, 2004.
- G. Yang and D. Liberzon, "Feedback stabilization of a switched linear system with an unknown disturbance under data-rate constraints," *IEEE Transactions on Automatic Control*, vol. 63, no. 7, pp. 2107–2122, 2018.
- G. Yang, A. J. Schmidt, and D. Liberzon, "On topological entropy of switched linear systems with diagonal, triangular, and general matrices," in 57th IEEE Conference on Decision and Control, to appear.