GUOSONG YANG (杨国松)

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Position

University of California, Santa Barbara

Postdoctoral Scholar, Department of Electrical and Computer Engineering

Advisor: João P. Hespanha

Aug. 2017–present

Santa Barbara, CA

EDUCATION

University of Illinois at Urbana-Champaign

Urbana, IL Aug. 2013–Aug. 2017

Ph.D. in Electrical and Computer Engineering

Advisor: Daniel Liberzon

Dissertation: "Switched and hybrid systems with inputs: small-gain theorems, control with limited

information, and topological entropy"

University of Illinois at Urbana-Champaign

Urbana, IL

M.S. in Electrical and Computer Engineering

Aug. 2011-Aug. 2013

Advisor: Daniel Liberzon

Thesis: "A Lyapunov-based small-gain theorem for interconnected switched systems"

Hong Kong University of Science and Technology

Kowloon, Hong Kong Sep. 2007–May 2011

B.Eng. in Electronic Engineering (Honors Research Option)

Minor in Mathematics Advisor: Zexiang Li

RESEARCH INTERESTS

- Switched and hybrid systems
- Control with limited information
- Nonlinear systems and control theory

PUBLICATIONS

Journals:

- Guosong Yang and Daniel Liberzon, "Feedback stabilization of a switched linear system with an unknown disturbance under data-rate constraints," *IEEE Transactions on Automatic Control*, accepted
- Andrii Mironchenko, Guosong Yang, and Daniel Liberzon, "Lyapunov small-gain theorems for networks of not necessarily ISS hybrid systems," Automatica, accepted
- Kunihisa Okano, Masashi Wakaiki, Guosong Yang, and João P. Hespanha, "Stabilization of networked control systems under clock offsets and quantization," *IEEE Transactions on Automatic Control*, accepted

• Guosong Yang and Daniel Liberzon, "A Lyapunov-based small-gain theorem for interconnected switched systems," Systems & Control Letters, vol. 78, pp. 47–54, 2015

Conferences:

- Guosong Yang, Daniel Liberzon, and Zhong-Ping Jiang, "Stabilization of interconnected switched control-affine systems via a Lyapunov-based small-gain approach," in 2017 American Control Conference, 2017, pp. 5182–5187
- Guosong Yang, Daniel Liberzon, and Andrii Mironchenko, "Analysis of different Lyapunov function constructions for interconnected hybrid systems," in 55th IEEE Conference on Decision and Control, 2016, pp. 465–470
- Guosong Yang and Daniel Liberzon, "Finite data-rate stabilization of a switched linear system with unknown disturbance," in 10th IFAC Symposium on Nonlinear Control Systems, 2016, pp. 1085–1090
- Guosong Yang and Daniel Liberzon, "Stabilizing a switched linear system with disturbance by sampled-data quantized feedback," in 2015 American Control Conference, 2015, pp. 2193–2198
- Guosong Yang and Daniel Liberzon, "Input-to-state stability for switched systems with unstable subsystems: a hybrid Lyapunov construction," in 53rd IEEE Conference on Decision and Control, 2014, pp. 6240–6245
- Andrii Mironchenko, **Guosong Yang**, and Daniel Liberzon, "Lyapunov small-gain theorems for not necessarily ISS hybrid systems," in 21st International Symposium on Mathematical Theory of Networks and Systems, 2014, pp. 1001–1008

TEACHING EXPERIENCE

University of Illinois at Urbana-Champaign

Urbana, IL

- Teaching assistant, ECE517 Nonlinear and Adaptive Control, Fall 2015, Fall 2016
- Teaching assistant, ECE528 Analysis of Nonlinear Systems, Spring 2015

Professional activities

- Journal reviewer for IFAC Automatica, System & Control Letters, Nonlinear Analysis: Hybrid Systems, and IEEE Control Systems Letters
- Conference reviewer for MICNON 2015, HSCC 2017, and 2017 ACC

Honors and awards

- Best Poster Award, Coordinated Science Laboratory Student Conference, 2016
- HKUST University Scholarship, 2007–2011
- HKUST School of Engineering Scholarship, 2007–2011
- HKUST ECE Outstanding Freshmen Scholarship, 2007–2011
- HKUST The Joseph Lau Luen Hung Charitable Trust Scholarship, 2007–2011
- HKUST Dean's List Award, Fall 2007, Spring 2008, Fall 2008, Spring 2009, Fall 2009
- Gold medal for 8th Asian Physics Olympiad, 2007

Personal

• Citizenship: China

• Languages: Chinese (native), English (fluent)