

Guosong Yang

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RESEARCH INTERESTS

Switched and hybrid systems, networked control systems, learning in games, and their applications to cyber-physical systems (CPS) and network security.

POSITIONS

Rutgers, The State University of New Jersey, Piscataway, NJ, USA Sep. 2022–present
Assistant Professor, Department of Electrical and Computer Engineering

University of Illinois Urbana-Champaign, Urbana, IL, USA May 2022–Aug. 2022
Postdoctoral Research Associate, Coordinated Science Laboratory
Advisor: Daniel Liberzon

University of California, Santa Barbara, Santa Barbara, CA, USA Aug. 2017–May 2022
Postdoctoral Scholar, Center for Control, Dynamical Systems, and Computation
Advisor: João P. Hespanha

EDUCATION

University of Illinois at Urbana-Champaign, Urbana, IL, USA Oct. 2013–Jul. 2017
Doctor of Philosophy in Electrical and Computer Engineering
Dissertation: “Switched and hybrid systems with inputs: Small-gain theorems, control with limited information, and topological entropy”
Advisor: Daniel Liberzon

University of Illinois at Urbana-Champaign, Urbana, IL, USA Aug. 2011–Aug. 2013
Master of Science in Electrical and Computer Engineering
Thesis: “A Lyapunov-based small-gain theorem for interconnected switched systems”
Advisor: Daniel Liberzon

Hong Kong University of Science and Technology, Kowloon, Hong Kong Sep. 2007–Jun. 2011
Bachelor of Engineering in Electronic Engineering (First Class Honors), minor in Mathematics
Advisor: Zexiang Li

AWARDS AND HONORS

2019 *ACM SIGBED HSCC Best Paper Award*, 22nd ACM International Conference on Hybrid Systems: Computation and Control, Montreal, Canada

2016 *Best Poster Award*, 11th Coordinated Science Laboratory Student Conference, University of Illinois at Urbana-Champaign, Urbana, IL, USA

- 2016 *Graduate College Conference Travel Award*, University of Illinois at Urbana-Champaign, Urbana, IL, USA
- 2007–2011 *University Scholarship, School of Engineering Scholarship, The Joseph Lau Luen Hung Charitable Trust Scholarship, ECE Outstanding Freshmen Scholarship*, Hong Kong University of Science and Technology, Kowloon, Hong Kong
- 2007–2009 *Dean's List*, Hong Kong University of Science and Technology, Kowloon, Hong Kong
- 2007 *Gold medal*, 8th Asian Physics Olympiad, Shanghai, China

PUBLICATIONS

Working papers

- [W3] Raphael Chinchilla, **Guosong Yang**, and João P. Hespanha, “Newton and interior-point methods for (constrained) nonconvex-nonconcave minmax optimization with stability guarantees,” submitted for journal publication
- [W2] **Guosong Yang**, Daniel Liberzon, and João P. Hespanha, “Topological entropy of switched nonlinear and interconnected systems,” submitted for journal publication
- [W1] **Guosong Yang**, Radha Poovendran, and João P. Hespanha, “Adaptive learning in two-player Stackelberg games with application to network security,” submitted for journal publication

Journals

- [J6] João P. Hespanha, Raphael Chinchilla, Ramon R. Costa, Murat K. Erdal, and **Guosong Yang**, “Forecasting COVID-19 cases based on a parameter-varying stochastic SIR model,” *Annual Reviews in Control*, vol. 51, pp. 460–476, Apr. 2021
- [J5] **Guosong Yang**, A. James Schmidt, Daniel Liberzon, and João P. Hespanha, “Topological entropy of switched linear systems: General matrices and matrices with commutation relations,” *Mathematics of Control, Signals, and Systems*, vol. 32, no. 3, pp. 411–453, Sep. 2020
- [J4] **Guosong Yang** and Daniel Liberzon, “Feedback stabilization of switched linear systems with unknown disturbances under data-rate constraints,” *IEEE Transactions on Automatic Control*, vol. 63, no. 7, pp. 2107–2122, Jul. 2018
- [J3] Kuniyoshi Okano, Masashi Wakaiki, **Guosong Yang**, and João P. Hespanha, “Stabilization of networked control systems under clock offsets and quantization,” *IEEE Transactions on Automatic Control*, vol. 63, no. 6, pp. 1708–1723, Jun. 2018
- [J2] Andrii Mironchenko, **Guosong Yang**, and Daniel Liberzon, “Lyapunov small-gain theorems for networks of not necessarily ISS hybrid systems,” *Automatica*, vol. 88, pp. 10–20, Feb. 2018
- [J1] **Guosong Yang** and Daniel Liberzon, “A Lyapunov-based small-gain theorem for interconnected switched systems,” *Systems & Control Letters*, vol. 78, pp. 47–54, Apr. 2015

Book chapter

- [Ch1] **Guosong Yang** and João P. Hespanha, “Modeling and mitigating link-flooding distributed denial-of-service attacks via learning in Stackelberg games,” in *Handbook of Reinforcement Learning and Control*, Kyriakos G. Vamvoudakis, Yan Wan, Frank L. Lewis, and Derya Cansever, Eds. Cham, Switzerland: Springer, 2021, pp. 433–463

Conferences

- [C14] Sharad C. Shankar, **Guosong Yang**, and João P. Hespanha, “State estimation for asynchronously switched sampled-data systems,” in *61st IEEE Conference on Decision and Control*, Cancún, Mexico, 2022, to be published
- [C13] Raphael Chinchilla, **Guosong Yang**, Murat K. Erdal, Ramon R. Costa, and João P. Hespanha, “A tale of two doses: Model identification and optimal vaccination for COVID-19,” in *60th IEEE Conference on Decision and Control*, Austin, TX, USA, 2021, pp. 3544–3550 (invited paper)
- [C12] **Guosong Yang**, Daniel Liberzon, and João P. Hespanha, “Topological entropy of switched nonlinear systems,” in *24th ACM International Conference on Hybrid Systems: Computation and Control*, Nashville, TN, USA, 2021, 11 pages
- [C11] **Guosong Yang**, Radha Poovendran, and João P. Hespanha, “Adaptive learning in two-player Stackelberg games with continuous action sets,” in *58th IEEE Conference on Decision and Control*, Nice, France, 2019, pp. 6905–6911
- [C10] **Guosong Yang**, João P. Hespanha, and Daniel Liberzon, “On topological entropy and stability of switched linear systems,” in *22nd ACM International Conference on Hybrid Systems: Computation and Control*, Montreal, Canada, 2019, pp. 119–127 (24% acceptance rate, **Best Paper Award winner**)
- [C9] **Guosong Yang** and João P. Hespanha, “On topological entropy of switched linear systems with pairwise commuting matrices,” in *56th Annual Allerton Conference on Communication, Control, and Computing*, Monticello, IL, USA, 2018, pp. 429–436 (invited paper)
- [C8] **Guosong Yang**, A. James Schmidt, and Daniel Liberzon, “On topological entropy of switched linear systems with diagonal, triangular, and general matrices,” in *57th IEEE Conference on Decision and Control*, Miami Beach, FL, USA, 2018, pp. 5682–5687
- [C7] **Guosong Yang**, Hossein Hosseini, Dinuka Sahabandu, Andrew Clark, João P. Hespanha, and Radha Poovendran, “Modeling and mitigating the Coremelt attack,” in *2018 American Control Conference*, Milwaukee, WI, USA, 2018, pp. 3410–3416
- [C6] **Guosong Yang**, Daniel Liberzon, and Zhong-Ping Jiang, “Stabilization of interconnected switched control-affine systems via a Lyapunov-based small-gain approach,” in *2017 American Control Conference*, Seattle, WA, USA, 2017, pp. 5182–5187
- [C5] **Guosong Yang**, Daniel Liberzon, and Andrii Mironchenko, “Analysis of different Lyapunov function constructions for interconnected hybrid systems,” in *55th IEEE Conference on Decision and Control*, Las Vegas, NV, USA, 2016, pp. 465–470 (invited paper)
- [C4] **Guosong Yang** and Daniel Liberzon, “Finite data-rate stabilization of a switched linear system with unknown disturbance,” in *10th IFAC Symposium on Nonlinear Control Systems*, vol. 49, no. 18, Monterey, CA, USA, 2016, pp. 1085–1090
- [C3] **Guosong Yang** and Daniel Liberzon, “Stabilizing a switched linear system with disturbance by sampled-data quantized feedback,” in *2015 American Control Conference*, Chicago, IL, USA, 2015, pp. 2193–2198
- [C2] **Guosong Yang** and Daniel Liberzon, “Input-to-state stability for switched systems with unstable subsystems: A hybrid Lyapunov construction,” in *53rd IEEE Conference on Decision and Control*, Los Angeles, CA, USA, 2014, pp. 6240–6245
- [C1] Andrii Mironchenko, **Guosong Yang**, and Daniel Liberzon, “Lyapunov small-gain theorems for not necessarily ISS hybrid systems,” in *21st International Symposium on Mathematical Theory of Networks and Systems*, Groningen, Netherlands, 2014, pp. 1001–1008

GRANT-APPLICATION EXPERIENCE

- Coauthor of the National Science Foundation grant CMMI-1662708: “Switched control systems with limited information: An entropy approach to stabilization and disturbance attenuation,” PI: Daniel Liberzon, Jul. 2017–Jun. 2020, Award: \$349,540

PRESENTATIONS AND SEMINARS

1. Seminar at the *e-TEC Talks @SNU Summer 2021*, Seoul National University, Seoul, Korea, Aug. 2021
2. Presentation at the *24th ACM International Conference on Hybrid Systems: Computation and Control*, Nashville, TN, USA, May 2021
3. Presentation at the *37th Southern California Control Workshop*, University of California, San Diego, San Diego, CA, USA, Jan. 2020
4. Presentation at the *22nd ACM International Conference on Hybrid Systems: Computation and Control*, Montreal, Canada, Apr. 2019 (24% acceptance rate, Best Paper Award winner)
5. Presentation at the *57th IEEE Conference on Decision and Control*, Miami Beach, FL, USA, Dec. 2018
6. Presentation at the *35th Southern California Control Workshop*, University of California, Los Angeles, Los Angeles, CA, USA, Nov. 2018
7. Invited presentation at the *56th Annual Allerton Conference on Communication, Control, and Computing*, Monticello, IL, USA, Oct. 2018
8. Presentation at the *2018 American Control Conference*, Milwaukee, WI, USA, Jun. 2018
9. Presentation at the *2017 American Control Conference*, Seattle, WA, USA, May 2017
10. Seminar at the *Multi-Agent Robotics Lab*, University of California, San Diego, San Diego, CA, USA, Mar. 2017 (Host: Jorge Cortés and Sonia Martínez)
11. Seminar at the *Arcak Lab*, University of California, Berkeley, Berkeley, CA, USA, Mar. 2017 (Host: Murat Arcak)
12. Seminar at the *Hybrid Systems Laboratory*, University of California, Santa Cruz, Santa Cruz, CA, USA, Feb. 2017 (Host: Ricardo G. Sanfelice)
13. Invited presentation at the *55th IEEE Conference on Decision and Control*, Las Vegas, NV, USA, Dec. 2016
14. Seminar at the *Center for Control, Dynamical Systems, and Computation*, University of California, Santa Barbara, Santa Barbara, CA, USA, Nov. 2016 (Host: Andrew R. Teel)
15. Seminar at the *Cyber-Physical Systems Laboratory*, University of California, Los Angeles, Los Angeles, CA, USA, Oct. 2016 (Host: Paulo Tabuada)
16. Presentation at the *10th IFAC Symposium on Nonlinear Control Systems*, Monterey, CA, USA, Aug. 2016
17. Poster presentation at the *11th Coordinated Science Laboratory Student Conference*, University of Illinois at Urbana-Champaign, Urbana, IL, USA, Feb. 2016 (Best Poster Award winner)
18. Presentation at the *2015 American Control Conference*, Chicago, IL, USA, Jul. 2015
19. Presentation at the *53rd IEEE Conference on Decision and Control*, Los Angeles, CA, USA, Dec. 2014

20. Presentation at the *2nd Midwest Workshop on Control and Game Theory*, University of Notre Dame, Notre Dame, IN, USA, Apr. 2013

TEACHING AND MENTORING

University of California, Santa Barbara, Santa Barbara, CA, USA

- *Mentor* for undergraduate student internship: “Remote Tracking of Unmanned Ground Vehicles”
- *Mentor* for high school student internship: “Motion Planning for Unmanned Ground Vehicles”

University of Illinois at Urbana-Champaign, Urbana, IL, USA

- *Teaching assistant* for graduate course: “ECE517 Nonlinear and Adaptive Control”
- *Teaching assistant* for graduate course: “ECE528 Analysis of Nonlinear Systems”

SERVICE TO THE PROFESSION

Journal review

- *IEEE Transactions on Automatic Control* (8)
- *Automatica* (7)
- *Nonlinear Analysis: Hybrid Systems* (3)
- *System & Control Letters* (2)
- *IEEE Transactions on Control of Network Systems* (1)
- *IEEE Control Systems Letters* (1)
- *Communications in Nonlinear Science and Numerical Simulation* (1)
- *Mathematics of Control, Signals, and Systems* (1)

Conference review

- *American Control Conference* (2017, 2018, and 2021)
- *IEEE Conference on Decision and Control* (2019 and 2020)
- *IFAC World Congress* (2020)
- *IFAC Workshop on Distributed Estimation and Control in Networked Systems* (2019)
- *ACM International Conference on Hybrid Systems: Computation and Control* (2016 and 2017)
- *IFAC Conference on Modelling, Identification and Control of Nonlinear Systems* (2015)

Conference organization

- *Program committees* for “Repeatability Evaluation” and “Posters and Demos” at the *25th ACM International Conference on Hybrid Systems: Computation and Control*, May 2022
- *Program committees* for “Repeatability Evaluation” and “Posters and Demos” at the *24th ACM International Conference on Hybrid Systems: Computation and Control*, May 2021

- *Session chair* for “Switched Systems I” at the *57th IEEE Conference on Decision and Control*, Miami Beach, FL, USA, Dec. 2018