

Yijie Guo

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Research Interests

My research interest lies in deep reinforcement learning, especially balancing the exploration and exploitation in difficult domains, and representation learning to improve sample efficiency and performance of RL algorithms.

EDUCATION

University of Michigan Ph.D. in <i>Computer Science & Engineering</i> Advisor: Honglak Lee	Ann Arbor, Michigan <i>Sep. 2017 – Present</i>
University of Michigan B.S. in <i>Honors Mathematics & Data Science</i> , GPA: 3.9/4.0	Ann Arbor, Michigan <i>Jul. 2015 – Apr. 2017</i>
Peking University Major in <i>Applied Mathematics</i> , GPA: 3.75/4.0	Beijing, China <i>Sep. 2012 – Jun. 2015</i>

RESEARCH EXPERIENCE

Research Assistant at University of Michigan	Ann Arbor, Michigan <i>Sep. 2017 – Present</i>
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- Propose a trajectory-conditioned policy to imitate diverse trajectories from the agent's past experience reinforcement learning problems with sparse reward to help exploration to find the (near)-optimal solution
- Implement self-imitation learning, generative adversarial self-imitation learning, and related baseline models; Conduct experiments on Atari and Mujoco tasks to get better performance against baseline
- Conduct experiments across various image datasets for unsupervised landmark discovery; Implement the regression model for quantitative evaluation and generation model for qualitative evaluation

Research Intern at Google Brain Advisor: Minmin Chen, Honglak Lee	MTV, California <i>Jun. 2019 – Present</i>
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- Improve the policy-based method in batch reinforcement learning problems by constraining the divergence between target policy and behavior policy in a curriculum way

Research Intern at Google Brain Advisor: Honglak Lee, Samy Bengio	MTV, California <i>Jun. 2018 – Aug. 2018</i>
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- Build a model to learn representation about controllable and uncontrollable dynamics in RL; Capture the location information of multiple moving entities in the 2D video games to improve count-based exploration
- Augment the agent's past good experience using the learnt representation to help one-shot imitation learning

PUBLICATION

Contingency-Aware Exploration in Reinforcement Learning

Jongwook Choi*, **Yijie Guo***, Marcin Moczulski*, Junhyuk Oh, Neal Wu, Mohammad Norouzi, Honglak Lee
International Conference on Learning Representations (ICLR), 2019

Generative Adversarial Self-Imitation Learning

Junhyuk Oh*, **Yijie Guo***, Satinder Singh, Honglak Lee

In *Advances in Neural Information Processing Systems, Deep Reinforcement Learning Workshop*, 2018

Self-Imitation Learning

Junhyuk Oh*, **Yijie Guo***, Satinder Singh, Honglak Lee

In *International Conference on Machine Learning (ICML)*, 2018.

Unsupervised Discovery of Landmarks as Structural Representations

Yuting Zhang, **Yijie Guo**, Yixin Jin, Yijun Luo, Zhiyuan He, Honglak Lee.

In *Conference on Computer Vision and Pattern Recognition (CVPR)*, 2018. **Oral presentation**

Discriminative Bimodal Networks for Visual Localization and Detection with Natural Language Queries

Yuting Zhang, Luyao Yuan, **Yijie Guo**, Zhiyuan He, I-An Huang, Honglak Lee

In *Conference on Computer Vision and Pattern Recognition (CVPR)*, 2017. **Spotlight**

Perspective Transformer Nets: Learning Single-View 3D Object Reconstruction without 3D Supervision

Xinchen Yan, Jimei Yang, Ersin Yumer, **Yijie Guo**, Honglak Lee

In *Advances in Neural Information Processing Systems (NeurIPS)*, 2016.