Variational Learning for Gaussian Processes at Large Scale

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Joint GSoC work with Heiko Strathman (UCL) and Wu Lin (Univ of Waterloo)

The Big Picture

Joint density models for data with mixed data types

Bayesian models - principled and robust approach

Algorithms that are not only accurate and scalable, but are also easy to tune and implement.

Today's talk

Gaussian processes (GPs)
Variational algorithm

Gaussian Processes at Large Scale

- What are GPs? See Shogun Notebook on GPs!

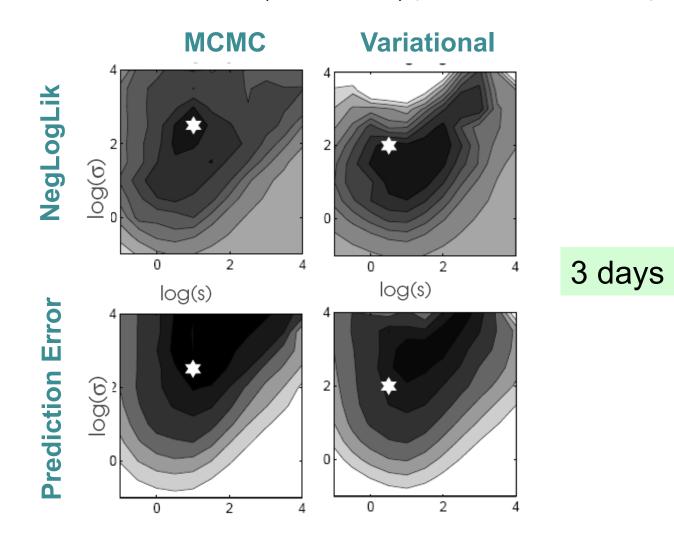
 http://www.shogun-toolbox.org/static/notebook/current/gaussian_processes.html
- Why GPs? For me, for uncertainty quantification.

 Applications: Recommendation systems, black-box optimization.
- Why large scale?
- Problems: Scalability problems due to big covariances
 - Inversion, storage, and optimization.
- Variational method is a promising solution.

MCMC vs Variational

Multiclass Gaussian Process: Glass dataset (N=143, K=6) (Khan et. al. Aistats 2012)

2 months



MCMC and its Scalability

On Netflix (for latent factor model with Gaussian likelihood)

	Time/iter (parallel)	Total Iters	Total Time	RMSE
MAP (D=100)	5 Mins	30	2.5 Hrs	0.93-0.90
Gibbs (D=30)	11 Mins	800	≈ 6 Days	0.89
Variational (D=30)	10 Mins	30	≈ 5 Hrs	0.89

Taken from Zhou et.al. 2010, Salakhutdinov & Mnih 2008

Outline

- Variational Gaussian approximation.
- A rough overview of algorithms.
- Future plans for large-scale implementation.
- Ipython notebook (GsoC 2014 code done by Wu Lin).

Variational Learning for GPs

$$\geq \max_{\mathbf{m}, \mathbf{V}} -D_{KL} \left(\left(\mathbf{M} \right) \right) + \sum_{n=1}^{N} \int \log p(y_n|z_n, \theta_y) \mathcal{N}(z_n|m_n, V_{nn}) dz_n$$

Optimization of the lower bound

Local bounds

NIPS 2012, ICML 2013, AISTATS 2014, NIPS 2014

NIPS 2010, ICML 2011, AISTATS 2012

Variational Gaussian Approximation

$$\geq \max_{\mathbf{m}, \mathbf{V}} -D_{KL} \left(\mathbf{M} \middle| \mathbf{M} \right) + \sum_{n=1}^{N} \int \log \mathbf{M} \left(\mathbf{M} \middle| \mathbf{M} \right) d\mathbf{M} \right)$$

- MAP assumes V = 0 (convex).
- Mean-Field (MF) assumes V is diagonal (convex).
- Cholesky method optimizes wrt Cholesky of V (convex).
- Kullback-Leibler (KL) method reparameterizes V (but not convex)

$$\mathbf{V} = (\mathbf{\Sigma}^{-1} + \operatorname{diag}(\boldsymbol{\lambda}))^{-1}$$

Dual method, similar as KL, but convex for some classes.

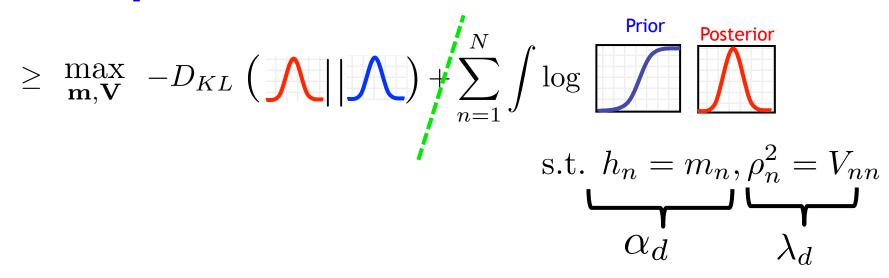
Less accurate More accurate

Accuracy MAP < MF < Dual < Decoupled = Cholesky = KL Computation MAP < MF < Dual = Decoupled < Cholesky ? KL

Less computation

More computation

Decoupled Variational Inference



GP Classification using GP Regression

Repeat

For all n, Given α and λ , find yPseudo (O(N)) predict yPseudo using GP regression (1 Inversion) For all n, compute (stochastic) gradient in parallel (O(N)).

Until convergence

A Rough Overview of Existing Methods

Less accurate
Less computation

MAP MF VG EP INLA MCMC

Generality
Accuracy
Speed
Scalability
Implement

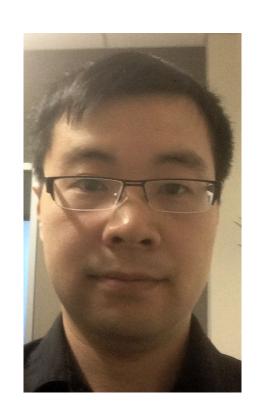
More accurate



MAP is maximum a-posteriori
MF is Mean field
VG is Variational Gaussian
EP is Expectation Propagation
INLA is Integrated Nested Laplace
MCMC is Monte Carlo Markov Chain

<u>Ipython</u> <u>Notebook</u>

Wu Lin (University of Waterloo)



Thanks Questions?