

Large Margin Nearest Neighbours in Shogun

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Mahalanobis distance

- Euclidean distance.

$$\mathcal{D}(\vec{x}_i, \vec{x}_j) = \|\vec{x}_i - \vec{x}_j\|_2^2 = (\vec{x}_i - \vec{x}_j)^T (\vec{x}_i - \vec{x}_j) \quad \vec{x}_i, \vec{x}_j \in \mathbb{R}^n$$

- Mahalanobis distance.

$$\mathcal{D}_M(\vec{x}_i, \vec{x}_j) = (\vec{x}_i - \vec{x}_j)^T M (\vec{x}_i - \vec{x}_j) \quad \vec{x}_i, \vec{x}_j \in \mathbb{R}^n, M \in \mathbb{R}^{n \times n}$$

$$\vec{x}^T M \vec{x} \geq 0 \quad \forall \vec{x} \in \mathbb{R}^n$$

k-nearest neighbours classification

- What distance to use?
 - Amplify the most informative dimensions,
 - while shrinking the least informative ones.
- Distance adapted to the data.
- LMNN: find a Mahalanobis distance that maximises k-NN classification.

LMNN

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- *Impostors* are avoided, that is

$$\nexists \vec{x}_l \mid \mathcal{D}_M(\vec{x}_i, \vec{x}_l) \leq \mathcal{D}_M(\vec{x}_i, \vec{x}_j) \quad \forall i, j, l \mid j \rightsquigarrow i, y_l \neq y_i.$$

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- Introducing a *margin*,

$$\nexists \vec{x}_l \mid \mathcal{D}_M(\vec{x}_i, \vec{x}_l) \leq \mathcal{D}_M(\vec{x}_i, \vec{x}_j) + 1 \quad \forall i, j, l \mid j \rightsquigarrow i, y_l \neq y_i.$$

LMNN – SDP formulation

$$\forall i, j, l \mid j \rightsquigarrow i, y_l \neq y_i$$

$$\mathcal{D}_M(\vec{x}_i, \vec{x}_j) \leq \mathcal{D}_M(\vec{x}_i, \vec{x}_l)$$

$$\mathcal{D}_M(\vec{x}_i, \vec{x}_j) + 1 \leq \mathcal{D}_M(\vec{x}_i, \vec{x}_l)$$

$$\mathcal{D}_M(\vec{x}_i, \vec{x}_j) + 1 \leq \mathcal{D}_M(\vec{x}_i, \vec{x}_l) + \xi_{ijl}$$

$$\min_M \sum_{i, j \rightsquigarrow i} \mathcal{D}_M(\vec{x}_i, \vec{x}_j) + \mu \sum_{i, j \rightsquigarrow i, l} \xi_{ijl}$$

subject to:

$$\mathcal{D}_M(\vec{x}_i, \vec{x}_j) + 1 \leq \mathcal{D}_M(\vec{x}_i, \vec{x}_l) + \xi_{ijl}$$

$$\xi_{ijl} \geq 0$$

$$\vec{x}^T M \vec{x} \geq 0$$

LMNN – Linear metric learning interpretation

$$\vec{x}^T \mathbf{M} \vec{x} \geq 0 \quad \forall \vec{x} \in \mathbb{R}^n \Rightarrow \mathbf{M} = \mathbf{L}^T \mathbf{L}$$

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$$\begin{aligned} \mathcal{D}_{\mathbf{M}}(\vec{x}_i, \vec{x}_j) &= (\vec{x}_i - \vec{x}_j)^T \mathbf{M} (\vec{x}_i - \vec{x}_j) = \\ &= (\vec{x}_i - \vec{x}_j)^T \mathbf{L}^T \mathbf{L} (\vec{x}_i - \vec{x}_j) = \mathcal{D}(\mathbf{L}\vec{x}_i, \mathbf{L}\vec{x}_j) \end{aligned}$$

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■ Beyond classification:

- **Dimension reduction** with **rectangular** \mathbf{L} (i.e. $\mathbf{L} \in \mathbb{R}^{r \times n} | r < n$).
- **Feature selection** with **diagonal** \mathbf{L} .