

Methodology Development: Nuchal Translucency measurement and thickness detection

Submitted by:

Ananya Gupta

Dayananda Sagar College Of Engineering

Submitted by:

Ananya Gupta

Dayananda Sagar College Of Engineering

1. Objective

1. Data Collection and Preparation

1.1 Dataset Acquisition

1.2 Data Preprocessing

2. Model Development

2.1 Baseline Models

2.2 Deep Learning Architectures

2.2.1 Segmentation Models

2.2.2 Classification Models

2.3 Generative Models

2.4 Attention Mechanisms

3. Training and Validation

3.1 Data Splitting and Augmentation

3.2 Training Strategy

3.3 Validation and Cross-Validation

4. Evaluation Metrics and Benchmarking

4.1 Segmentation Metrics

4.2 Classification Metrics

4.3 Computational Efficiency

4.4 Clinical Benchmarking

5. Deployment Pipeline

5.1 End-to-End System

5.2 Real-World Validation

5.3 Deployment Formats

6. Iterative Refinement and Feedback Loop

6.1 Continuous Learning

1. Objective

To design, develop, and evaluate a state-of-the-art AI-driven pipeline capable of accurately detecting and measuring NT thickness from fetal ultrasound images, ensuring clinical-grade performance for real-world use.

1. Data Collection and Preparation

1.1 Dataset Acquisition

- **Clinical Collaborations:** Establish partnerships with hospitals and diagnostic centers to collect fetal ultrasound images taken between 11–14 weeks of gestation.
- **Public Data:** Source data from publicly available repositories such as Kaggle, MURA, or specialized obstetric datasets if accessible.
- **Ethical Clearance:** Ensure compliance with HIPAA or GDPR regulations for patient confidentiality, obtaining necessary permissions for clinical data usage.

1.2 Data Preprocessing

- **Normalization:** Normalize image intensities to account for varying ultrasound machine settings.
- **Contrast Enhancement:** Employ adaptive histogram equalization or CLAHE to enhance NT visibility.
- **Noise Reduction:**
 - Apply Gaussian filters or wavelet-based denoising techniques.
 - Use anisotropic diffusion for edge-preserving noise suppression.
- **ROI Extraction:**
 - Use bounding box annotations (manual or automated) to isolate NT regions.

- Employ sliding window methods or patch-based segmentation to focus on critical areas.
- **Artifact Removal:** Remove speckle noise and irrelevant artifacts using domain-specific techniques like median filtering or deep-learning-based despeckling models.

2. Model Development

2.1 Baseline Models

- Extract hand-crafted features (e.g., texture, edge, and geometric features) using HOG, Gabor filters, or wavelet transforms.
- Train and evaluate traditional classifiers such as:
 - **Support Vector Machines (SVM)** for binary classification.
 - **Random Forests** for feature importance analysis.

2.2 Deep Learning Architectures

2.2.1 Segmentation Models

- **U-Net:** Use as a baseline for NT segmentation due to its success in biomedical image processing.
- **Refinements:** Incorporate residual connections or multi-scale attention to improve NT boundary detection.
- **Variants:**
 - ResU-Net: Integrate ResNet blocks for better feature representation.
 - Attention U-Net: Embed attention gates for precise NT region delineation in noisy images.

2.2.2 Classification Models

- **EfficientNet:** Utilize this lightweight and scalable architecture for NT thickness classification.

- **Vision Transformers (ViT):** Fine-tune for high-resolution images and capture long-range dependencies in ultrasound images.

2.3 Generative Models

- **GANs (Generative Adversarial Networks):**
 - Generate synthetic NT images to balance dataset class distribution.
 - Use StyleGAN for high-quality image generation with domain-specific adjustments.
- **Data Augmentation GANs:** Augment existing datasets to simulate variations in image quality, orientation, and fetal positioning.

2.4 Attention Mechanisms

- Integrate attention modules to prioritize NT regions:
 - Use **Squeeze-and-Excitation Networks** to enhance feature importance adaptively.
 - Incorporate **Transformer-Based Architectures** for learning from low-quality or noisy images.
-

3. Training and Validation

3.1 Data Splitting and Augmentation

- Divide dataset into:
 - **Training Set:** 70%
 - **Validation Set:** 15%
 - **Testing Set:** 15%
- Apply robust data augmentation strategies:
 - Geometric: Random rotations, flipping, and scaling.
 - Color: Intensity shifting and gamma correction.
 - Noise Injection: Simulate real-world ultrasound conditions.

3.2 Training Strategy

- **Optimizer:** Use AdamW or SGD with learning rate warm-up and cosine annealing.
- **Loss Functions:**
 - **Segmentation:** Combined loss of Dice and Binary Cross-Entropy (BCE) for balanced segmentation.
 - **Classification:** Weighted cross-entropy to handle class imbalances.
- **Regularization:**
 - Dropout and weight decay to mitigate overfitting.
 - Use early stopping based on validation loss.

3.3 Validation and Cross-Validation

- Perform K-fold cross-validation to evaluate model robustness.
 - Monitor metrics like Dice Score, IoU, AUROC, sensitivity, and specificity across folds.
-

4. Evaluation Metrics and Benchmarking

4.1 Segmentation Metrics

- Dice Similarity Coefficient (DSC): Evaluate overlap between predicted and ground-truth NT regions.
- Intersection over Union (IoU): Measure accuracy of segmentation boundaries.

4.2 Classification Metrics

- Area Under Receiver Operating Characteristic Curve (AUROC).
- Sensitivity and specificity for identifying abnormal NT values.

4.3 Computational Efficiency

- Inference time on real-time ultrasound images.
- Resource utilization (e.g., GPU/CPU memory, latency).

4.4 Clinical Benchmarking

- Compare automated measurements against clinician-annotated NT thickness using Bland-Altman analysis or similar statistical tests.
-

5. Deployment Pipeline

5.1 End-to-End System

- Integrate modules for preprocessing, segmentation, classification, and post-processing in a unified pipeline.
- Optimize for edge devices to enable deployment in clinical ultrasound machines.

5.2 Real-World Validation

- Evaluate system on unseen clinical datasets to ensure robustness across varied demographics and equipment.
- Conduct usability studies with radiologists to refine user interface and workflow integration.

5.3 Deployment Formats

- Develop as a standalone desktop/mobile application.
 - Collaborate with ultrasound device manufacturers to integrate as a plug-in or firmware update.
-

6. Iterative Refinement and Feedback Loop

6.1 Continuous Learning

- Use active learning to incorporate edge cases and mislabeled instances into retraining pipelines.
- Employ federated learning for privacy-preserving model updates using clinical feedback.

6.2 Collaboration with Clinicians

- Regularly gather qualitative feedback from radiologists and obstetricians.
- Address interpretability concerns using explainable AI (XAI) techniques to highlight NT region predictions.

6.3 Enhancements

- Investigate multi-task learning to predict additional markers (e.g., nasal bone length) simultaneously.
 - Explore self-supervised learning to maximize utility of unlabeled ultrasound data.
-