

Database Processing

CS 451 / 551

Lecture 9: Query Processing



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Assignment 2 is Out!
Deadline: Nov 13, 2025 at 11:59pm

Quiz 2: Nov 6, 2025 (in class)

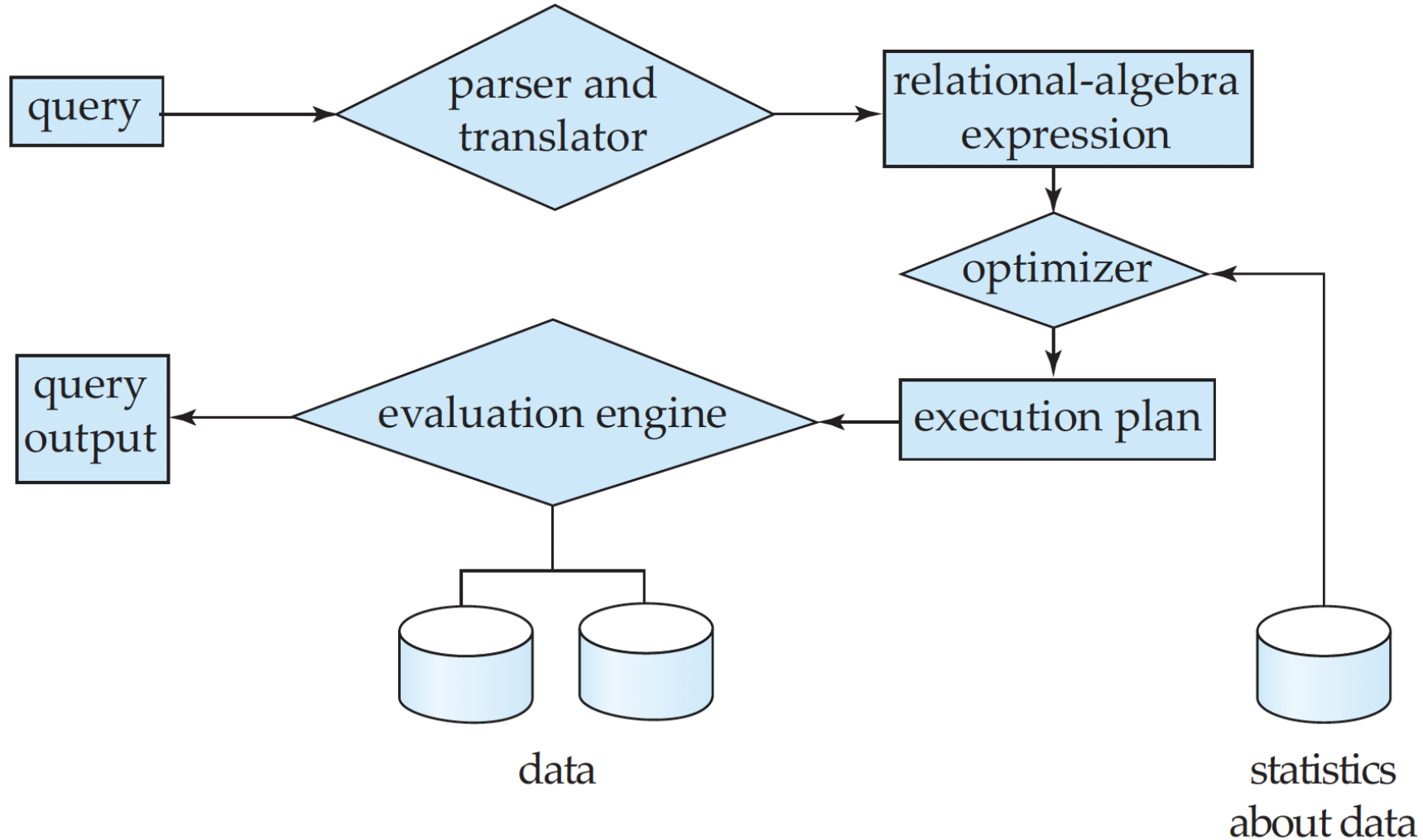
What is meant by Query Processing

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- We can sub-divide query processing into three tasks:
 - Parsing and translation.
 - Optimization.
 - Evaluation.

What is meant by Query Processing



*Diagram from Database Systems Concepts book.

Parser

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- Parsing helps to translate the query into a usable form.
- SQL is suitable for human to write queries, but not suited for system's internal representation of a query.
- Relational algebra is a more suited representation.
- So, the first step for the system, on receiving a query is to translate it into an understandable format.

Parser

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- Does this remind you of some other component that you have used/heard?
- Compilers!
 - A compiler also includes a parser to parse your programs.
- To generate an understandable format, query parser needs to:
 - Check the syntax of the user's query.
 - Verify that the relation names appearing in the query are names of the relations in the database, and
 - Many more tasks...
- Post this, the system constructs a parse-tree representation of the query.

Parser

- We are not covering parsing as it is part of standard compilers course!

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Query Evaluation

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- You need to evaluate the query (compute the result of the query).

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Say, we selected the following relational algebra translation for the earlier query.

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How will you execute this query?

- 1) Search every tuple in instructor to find tuples with salary less than 75000.

What are the challenges with Evaluating a Query

Say, we selected the following relational algebra translation for the earlier query.

- $\sigma_{\text{salary} < 7500} (\pi_{\text{salary}} (\text{instructor}))$;

How will you execute this query?

- 1) Search every tuple in instructor to find tuples with salary less than 75000.
- 2) Say you have a B⁺-tree index on salary, we can use that index to locate the tuples.

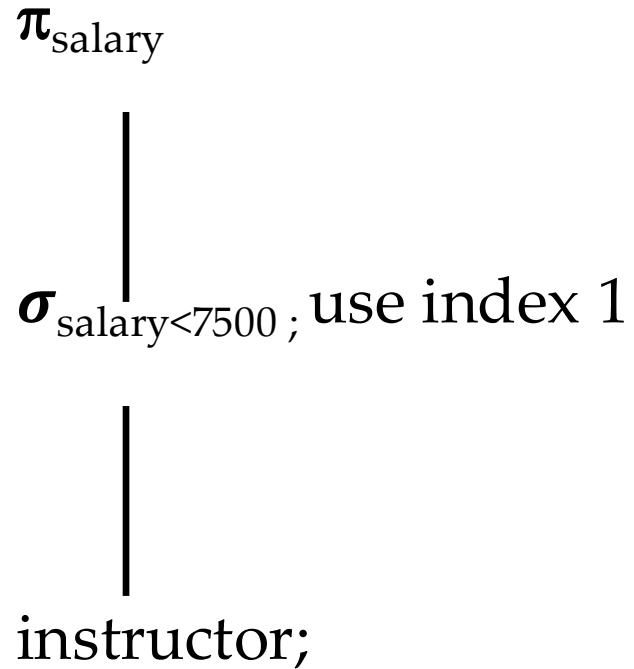
Evaluation Plan

- Query translation should specify two things:
 - The corresponding relational-algebra expression
 - Annotate it with instructions stating how to evaluate each operation.
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- Query translation should specify two things:
 - The corresponding relational-algebra expression
 - Annotate it with instructions stating how to evaluate each operation.
- **Annotations** can state the algorithm to be used, or one or more indices to use.
- **Evaluation Primitive:**
 - A relational algebra operation annotated with instructions on how to evaluate it.
- **Query-Execution plan:**
 - A sequence of primitive operations that help to evaluate a query.

A simple query Evaluation Plan



→ Here, index 1 could be an index on salary; internally numbered as 1.

Cost Optimization

- Different evaluation plans for a given query can have different costs.

Cost Optimization

- Different evaluation plans for a given query can have different costs.
- You cannot expect users to write queries in a way that it results in the most efficient evaluation plan.
- Responsibility of the DBMS to construct a query evaluation plan that minimizes the cost of query evaluation.
 - This task is called as **query optimization**.

How to Measure cost of a Query?

- Recall that the cost to access data from disk is the most expensive as disk accesses are slow compared to in-memory operations.
- **Cost of Query Evaluation plan =**
 - Number of block transfers from disk + Number of disk seeks.
- Say;
 - **D** \rightarrow Time to transfer a block from disk.
 - **A** \rightarrow Block access time (Seek time + Rotational Latency)
 - To transfer **b** blocks and perform **s** disk seeks would take = **$b * D + s * A$**

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How to Measure cost of a Query?

- Several other factors also contribute to query cost:
 - **Writes are twice expensive as reads.** Why?
Because disk systems read sectors back after they are written to verify that the write was successful.
 - You may have to even estimate the **cost of writing the final result** of an operation back to the disk.

Scans and Searching

- We will now spend time on estimating the cost of search and scans.
- What are the important factors to consider when estimating the cost of a search or scan?

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- We will now spend time on estimating the cost of search and scans.
- What are the important factors to consider when estimating the cost of a search or scan?
 - Is the search on a primary key?
 - Is the search equal to primary key?
 - Do you have access to indexes on primary key?
 - Do you have access to secondary indexes?

File Scans: Linear Search

- Let's assume we have a query like the following:
select * from instructors;
- This is going to scan over all the records in the table.
- A query similar to scan is where you have to search a key and you do not have any index → You are forced to perform linear search.
- So, what do you think is the cost of this query?

File Scans: Linear Search

- Given,
 - $D \rightarrow$ Time to transfer a block from disk.
 - $A \rightarrow$ Block access time (Seek time + Rotational Latency)
 - Say, you have to transfer b blocks.
- What is the cost of linear search or scan?

File Scans: Linear Search

- Given,
 - $D \rightarrow$ Time to transfer a block from disk.
 - $A \rightarrow$ Block access time (Seek time + Rotational Latency)
 - Say, you have to transfer b blocks.
- What is the cost of linear search or scan?
 - $A + b * D$
 - One initial seek (A) to reach the correct block/sector.
 - Then, transferring b blocks.

Equality Search on Primary Key

- Let's assume we have a query like the following:
select * from instructors where id = 10;
- The difference between this query and the previous query is that this query wants us to search a specific record.
- Further, assume that the attribute “id” is the primary key.
- And, suppose we have a B⁺-tree index built over the attribute “id”.

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Equality Search on Primary Key

- Let's assume the **height of the tree** (total levels from root to leaf) = **h** .
- Given,
 - **D** \rightarrow Time to transfer a block from disk.
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- What is the cost of Equality Search on Primary Key?

Equality Search on Primary Key

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- Given,
 - **D** \rightarrow Time to transfer a block from disk.
 - **A** \rightarrow Block access time (Seek time + Rotational Latency)
- What is the cost of Equality Search on Primary Key?
 - **$(h+1) * (A + D)$**
 - Why this?

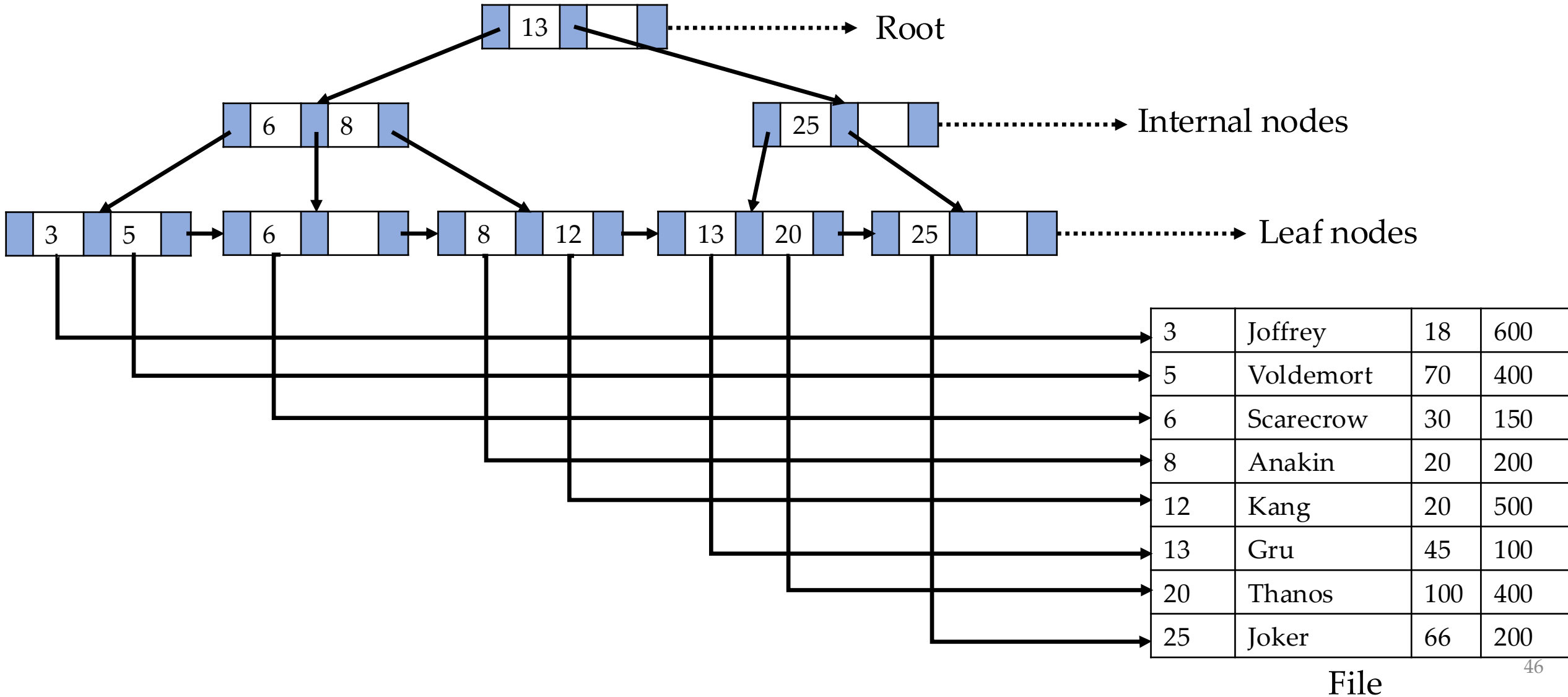
Equality Search on Primary Key

- These are worst-case cost estimates and the assumption is that the B⁺-tree is large and cannot be stored in-memory.
 - So, every node in the B⁺-tree has to be fetched from the disk.

Equality Search on Primary Key

- These are worst-case cost estimates and the assumption is that the B⁺-tree is large and cannot be stored in-memory.
 - So, every node in the B⁺-tree has to be fetched from the disk.
- All the keys in a B⁺-tree are at the leaf nodes. So,
 - First, you need to traverse all the way to leaf node.
 - During this traversal, you will access B⁺-tree nodes to determine which path to take.
 - Fetching each of these nodes is a disk access and requires seek time.
 - And, then once you reach the desired node, you need to also fetch the actual record.

Equality Search on Primary Key



Equality Search on Non-Key

- Let's assume we have a query like the following:
select * from instructors where age = 45;
- The difference between this query and the previous query is that this query wants us to search a specific record on a non-key.
- Here, the attribute “age” is not the primary key.
- So, what is the challenge with estimating the cost of this query?

Equality Search on Non-Key

- B⁺-tree index is built over the primary key attribute.
- For non-key attributes, we do not have an available index.
- So, we need to fetch multiple records and blocks as the index is not much useful.

Equality Search on Non-Key

- Let's assume the **height of the tree** (total levels from root to leaf) = **h** .
- Given,
 - **D** \rightarrow Time to transfer a block from disk.
 - **A** \rightarrow Block access time (Seek time + Rotational Latency)
 - **b** \rightarrow Number of blocks to fetch
- What is the cost of Equality Search on Non-Key?

Equality Search on Non-Key

- Given,
 - $D \rightarrow$ Time to transfer a block from disk.
 - $A \rightarrow$ Block access time (Seek time + Rotational Latency)
 - $b \rightarrow$ Number of blocks to fetch
- What is the cost of Equality Search on Non-Key?
 - $A + n * D$

Equality Search on Non-Key

- $A + n * D$, Why?
- Because, we lack an index and the best way is to simply do a linear scan over all.
- Assumption \rightarrow Data is stored sequentially.

Equality Search on Secondary Key

- Let's assume we have a query like the following:
select * from instructors where age = 45;
- But, now assume we have a second index on the attribute “age”.
- Further, assume that our secondary index is also a B⁺-tree.
- So, what is cost of this query?

Equality Search on Secondary Key

- Let's assume the **height of the tree** (total levels from root to leaf) = **h** .
- Given,
 - **D** \rightarrow Time to transfer a block from disk.
 - **A** \rightarrow Block access time (Seek time + Rotational Latency)
- What is the cost of Equality Search on Secondary Key?
 - **$(h+1) * (A + D)$**
 - Why is this same as Equality Search on Primary Key?

Equality Search on Secondary Key

- The cost is same as equality on primary key because we have a B⁺-tree and we are doing an exact match!
 - No extra blocks accessed.

Equality Search on Secondary Non-Key

- Let's assume we have a query like the following:

select * from instructors where salary = 10000;

- But, now assume that we have a
 - Primary index on “Id”.
 - Secondary index on “age”.
 - But, **no index for “salary”**.
- So, what is cost of this query?

Equality Search on Secondary Non-Key

- Let's assume the **height of the tree** (total levels from root to leaf) = **h** .
- Given,
 - **D** \rightarrow Time to transfer a block from disk.
 - **A** \rightarrow Block access time (Seek time + Rotational Latency)
 - **n** \rightarrow Number of records to fetch
- What is the cost of Equality Search on Non-Key?
 - **$A + n * D$**

Comparative Search on Primary Key

- Let's assume we have the following queries:

select * from instructors where id < 10;

select * from instructors where id <= 10;

- For these queries, we need to decide whether we want to use a B⁺-tree index or linear scan.
 - Why do we need to decide?

Comparative Search on Primary Key

- Let's assume we have the following queries:

select * from instructors where id < 10;

select * from instructors where id <= 10;

- For these queries, we need to decide whether we want to use a B⁺-tree index or linear scan.
 - Why do we need to decide?
- Because linear scan will often result in cheaper estimate as we have to get all the values less or less than equal to the primary key.

Comparative Search on Primary Key

- Let's assume we have the following queries:

select * from instructors where id > 10;

select * from instructors where id >= 10;

Comparative Search on Primary Key

- Let's assume we have the following queries:

select * from instructors where id > 10;

select * from instructors where id >= 10;

- For these queries, we will make use of a B+-tree index , followed by a file scan.
 - Why?

Comparative Search on Primary Key

- Let's assume we have the following queries:

select * from instructors where id > 10;

select * from instructors where id >= 10;

- For these queries, we will make use of a B+-tree index, followed by a file scan.
 - Why?
- Because the last record to access is the end of the file.
- What is the cost?

Comparative Search on Primary Key

- Let's assume the **height of the tree** (total levels from root to leaf) = **h**.
- Given,
 - **D** \rightarrow Time to transfer a block from disk.
 - **A** \rightarrow Block access time (Seek time + Rotational Latency)
 - **b** \rightarrow Number of blocks to fetch
- What is the cost of Equality Search on Non-Key?
 - **$(h+1) * (A+D) + b * D$**