Database Processing CS 451 / 551

Lecture 5:

Searching and Indexing: Part 2





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Assignment 1 is Out! Deadline: Oct 28, 2025 at 11:59pm

Start collaborating with your groups!

Quiz 1: Oct 16, 2025 (in class)

Last Class

- We discussed sequential indexes: sparse, dense, multi-level.
- What are the challenges with these indexes?
 - A lot of file reorganization is needed when adding or deleting a record.
 - Can we avoid the reorganization? Yes, but
 - Then records are no longer mapped sequentially on the disk.
- Can we do better?

How to determine a Good Index?

- A good index should help to search a record fast!
- Characteristics of a good index:
 - Access Types: Supports accessing a particular record (point query) and/or records within a specified range (range query).
 - Access Time: Time to find a particular record.
 - **Insertion Time:** Time to insert a new record in the index (includes time to find the right place to insert).
 - **Deletion Time:** Time to delete a new record in the index (includes time to find the item to be deleted).
 - Space Overhead: The space consumed by the index.

A More desirable Index Structure

• Should ensure minimal reorganization.

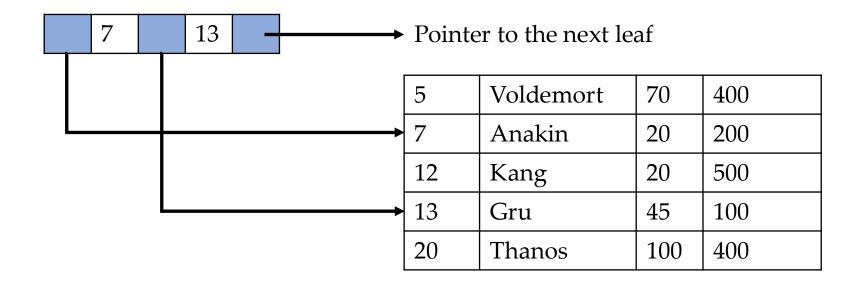
• Should support sequential data access from disk.

B⁺-Tree

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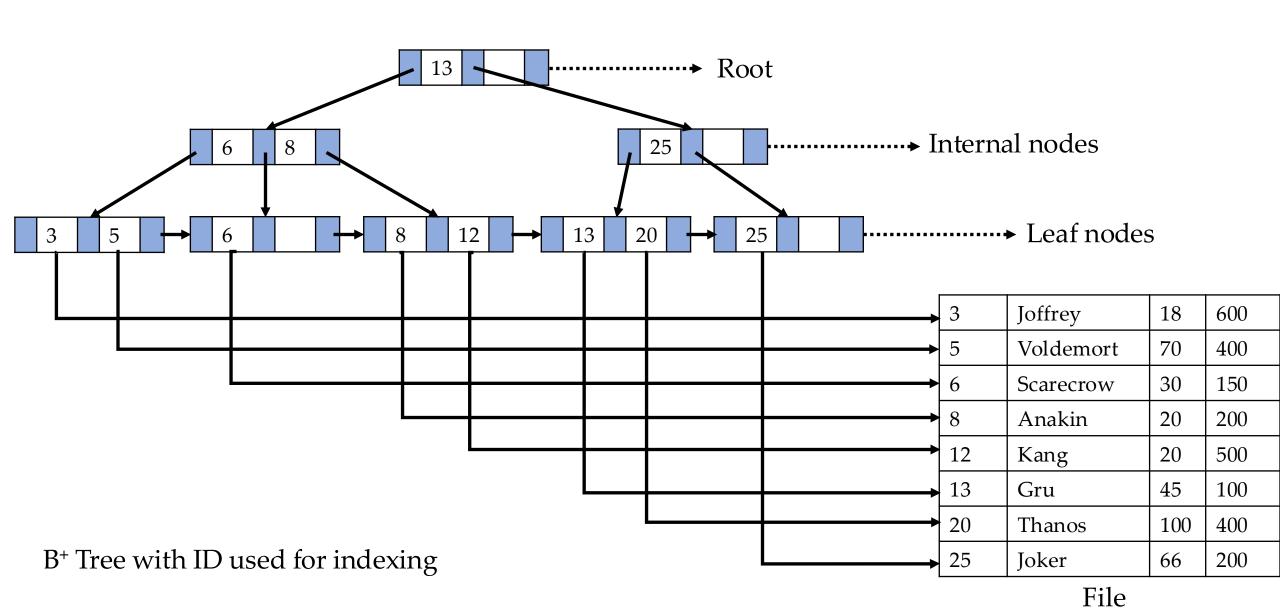
- Another tree from the family of Balanced Trees.
- Three types of nodes: root, internal nodes, and leaf nodes.
- Every leaf node is at the same height.
- Give a value **n**, each internal node has:
 - **k** children
 - k 1 search keys
 - where, k is between $\lfloor n/2 \rfloor$ to n.
- Root can have less than $\lceil n/2 \rceil$ children but should have at least 2 children if there are more than one node in the tree.

B⁺-Tree Leaf Node Structure



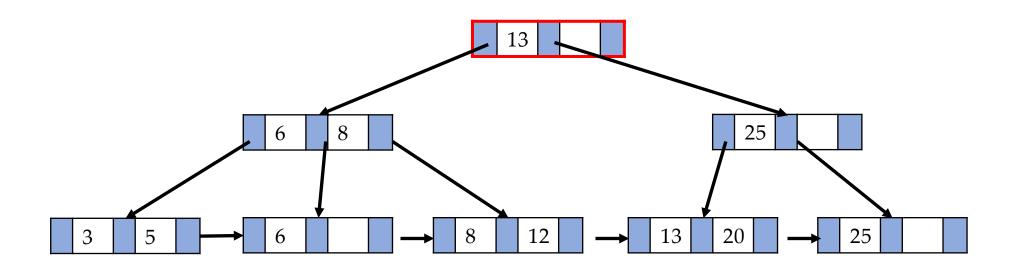
Internal nodes also have similar structure, except they point to other tree nodes

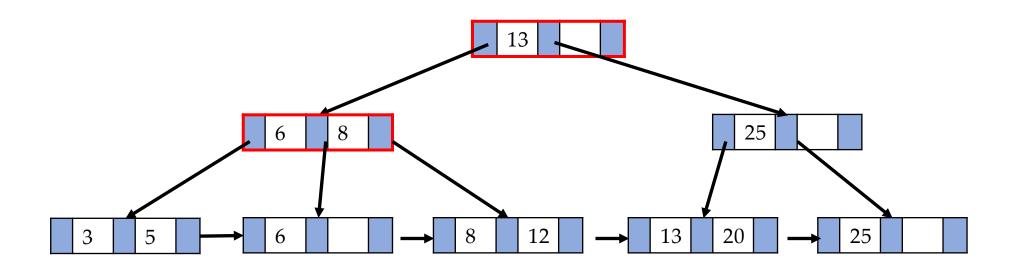
B⁺-Tree At a Glance

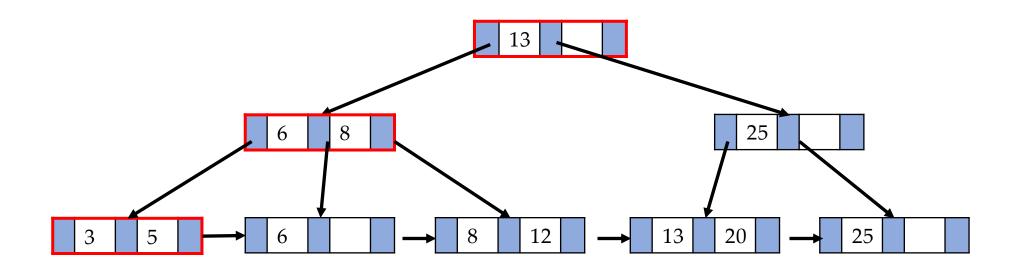


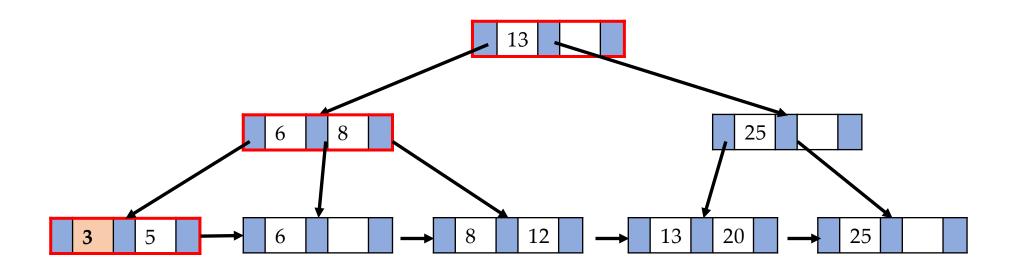
• Notice that the keys are stored in B+ tree in a **sorted manner**.

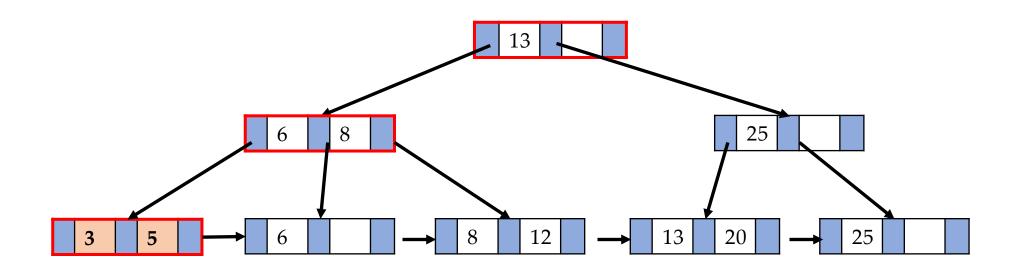
• We claim that the data is stored in B+ tree in sorted order because if you perform an in-order traversal, then you will get a sorted list.

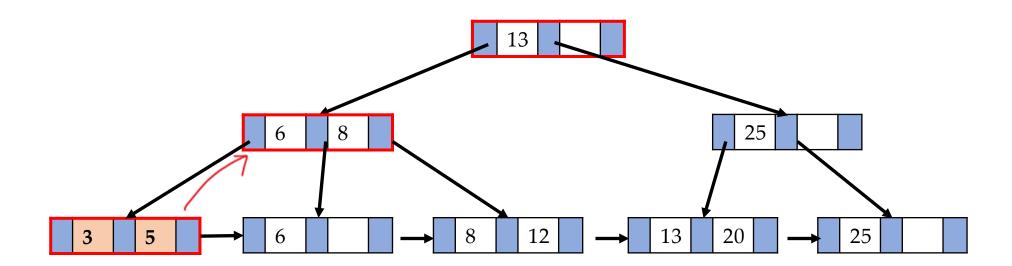


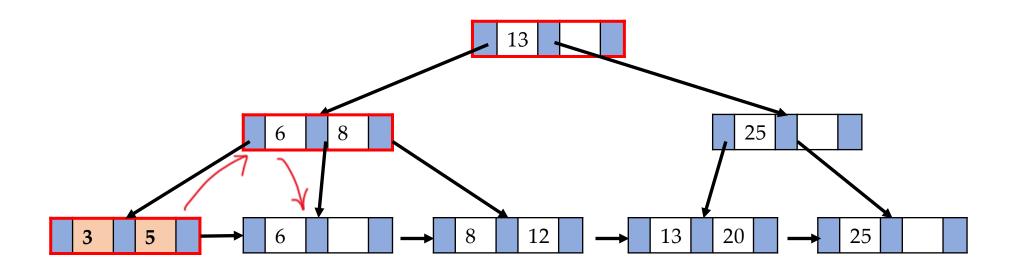


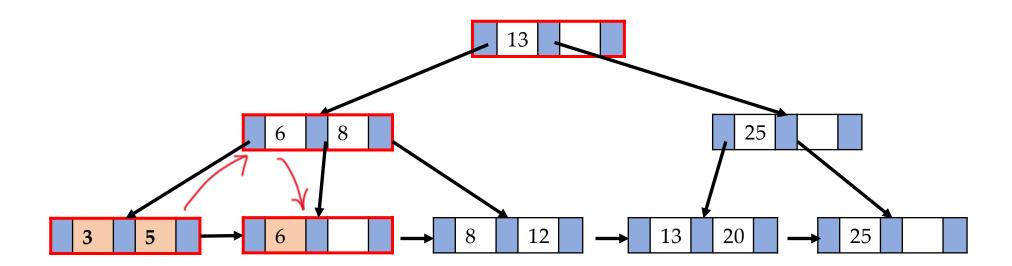


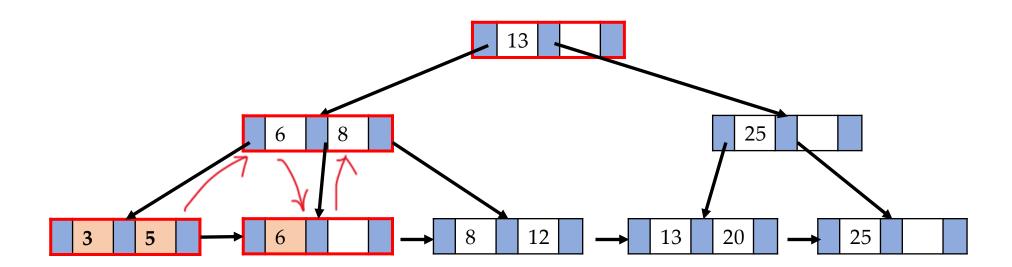


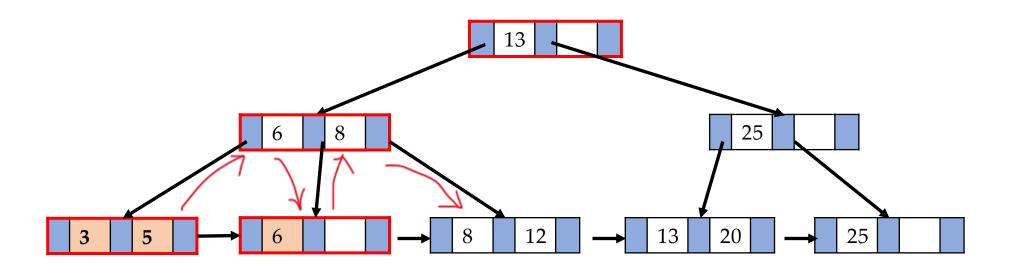


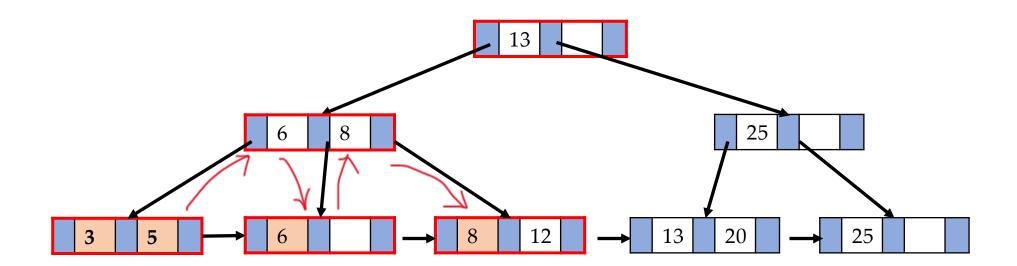


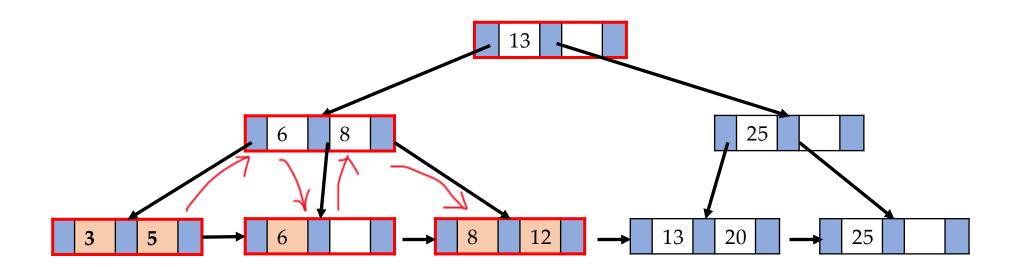


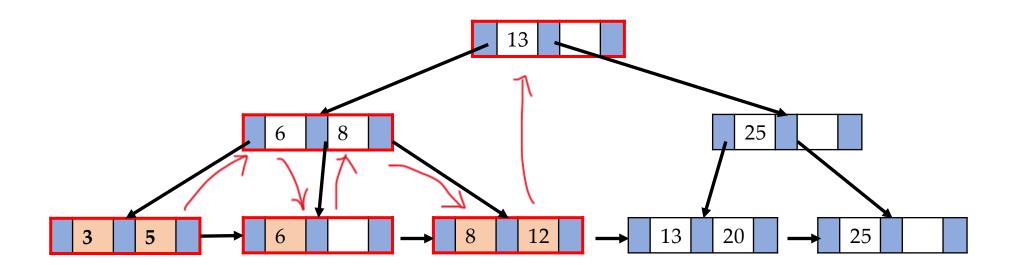


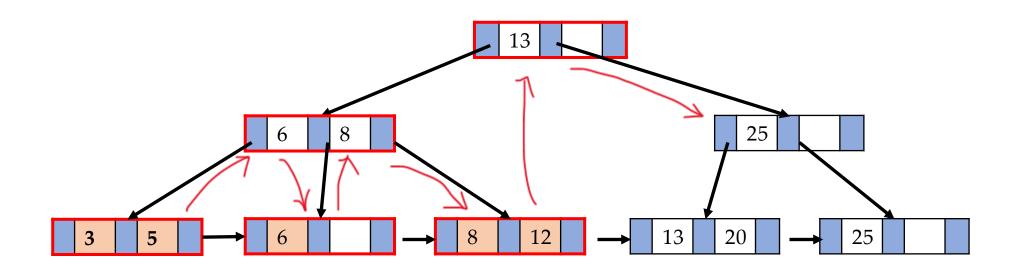


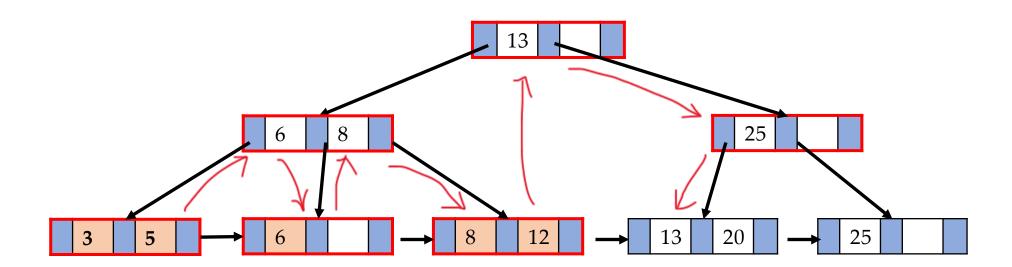


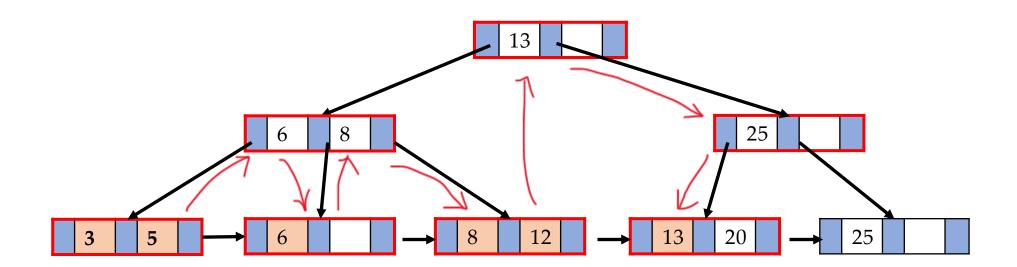


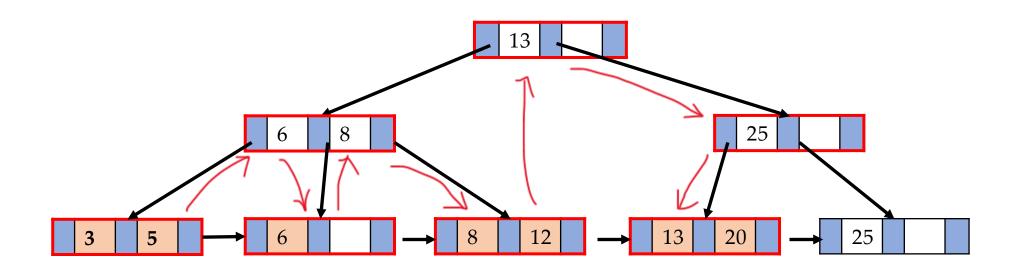


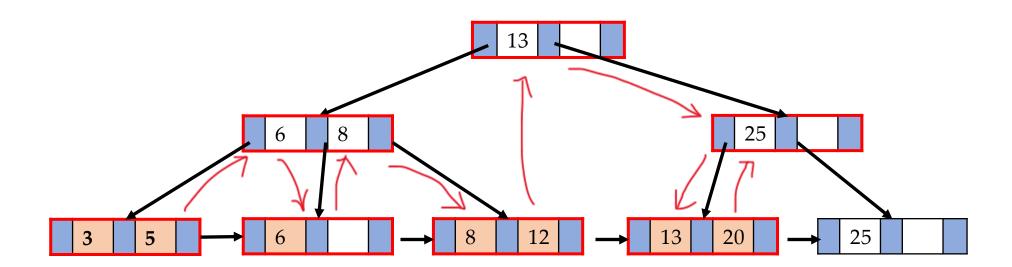


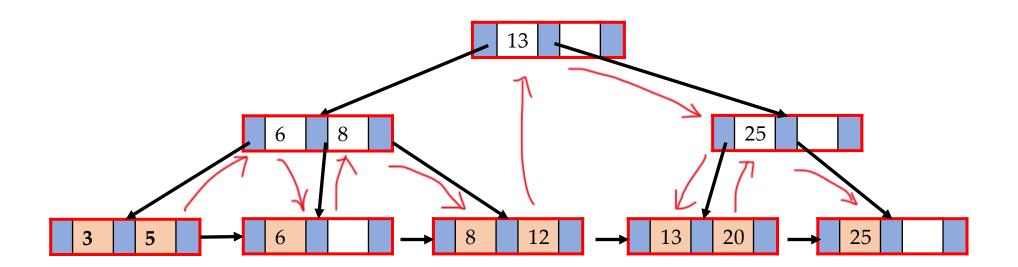




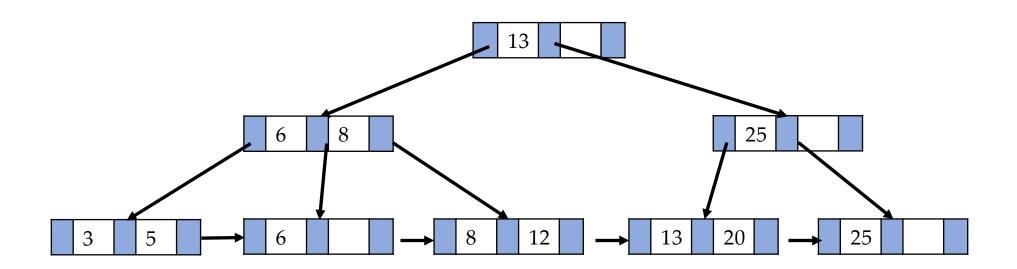




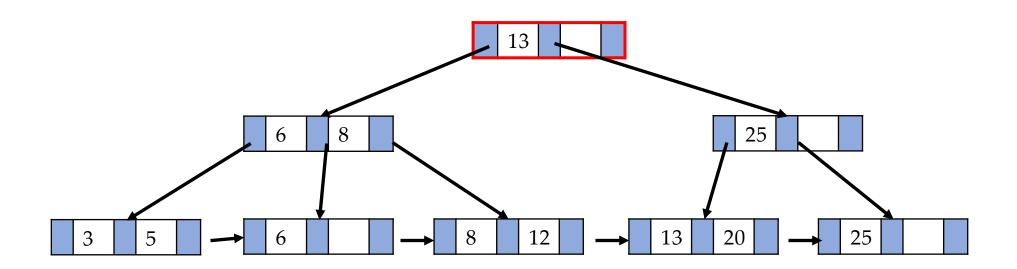




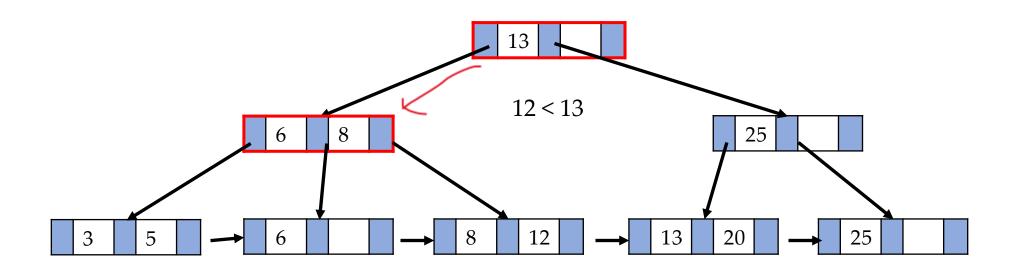
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 - We need to traverse the tree in the in-order fashion.
 - Stop traversing if one of the following three cases occur:
 - Key is found!
 - You encounter a Key greater than the search key.
 - You have reached the last key or leaf node of the tree.



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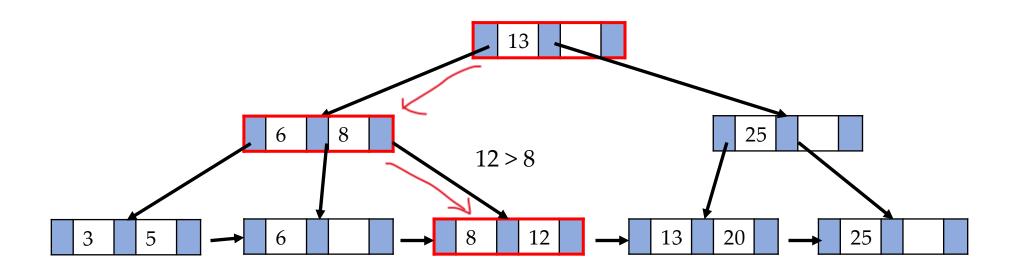


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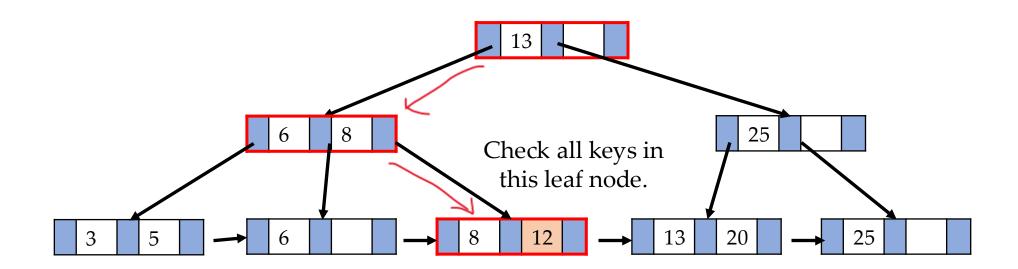
Searching data in B⁺-Tree

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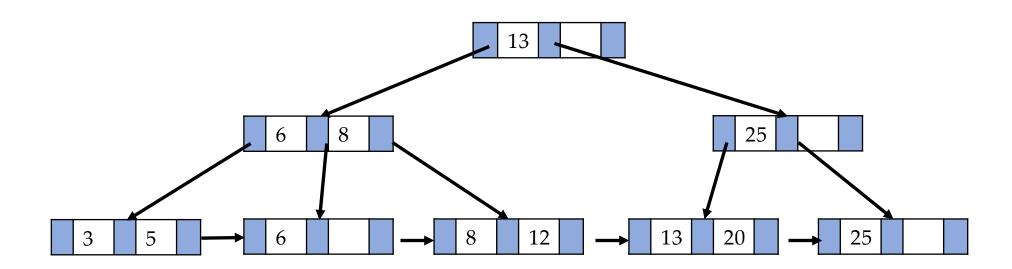


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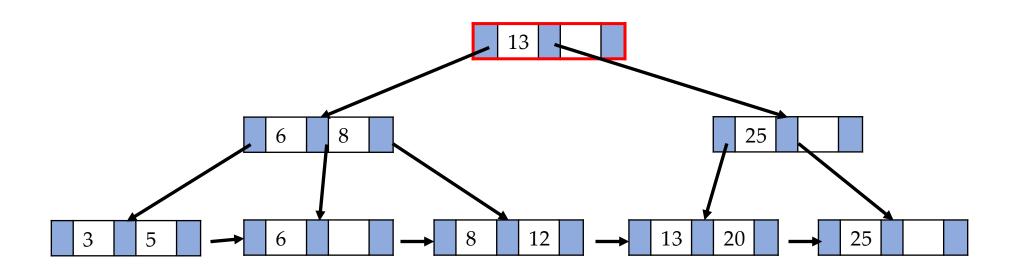
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- What we just did was a Point Query, where I wanted to search a specific item.
- Say we want to search a range of keys (Range Query) → Keys from 12 to 24.
 - We need to traverse the tree in the in-order fashion to reach the first key in the range, that is, first leaf node.
 - Then, perform linearly scan \rightarrow follow the leaf pointers till you hit the last key or a key greater than the range.

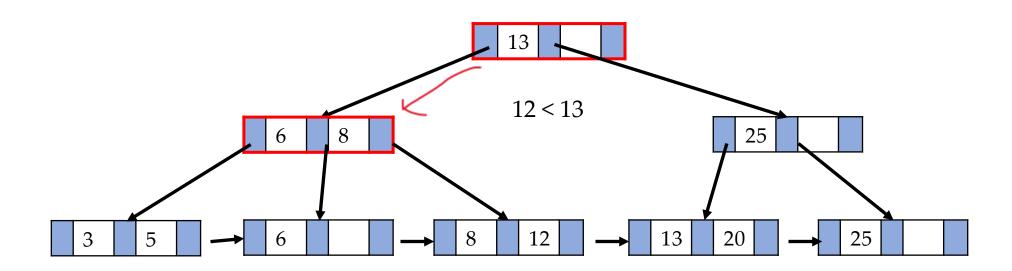


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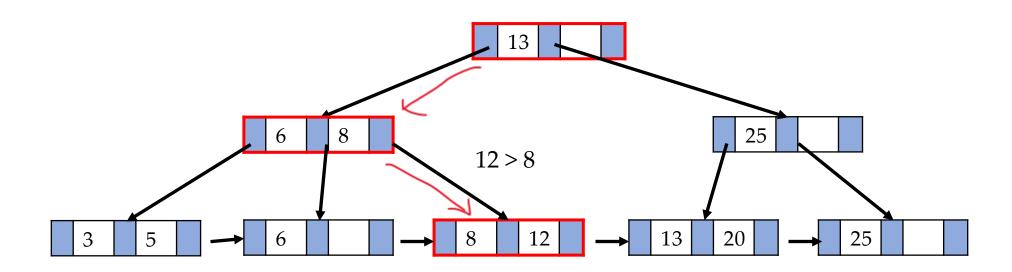


Searching data in B+-Tree

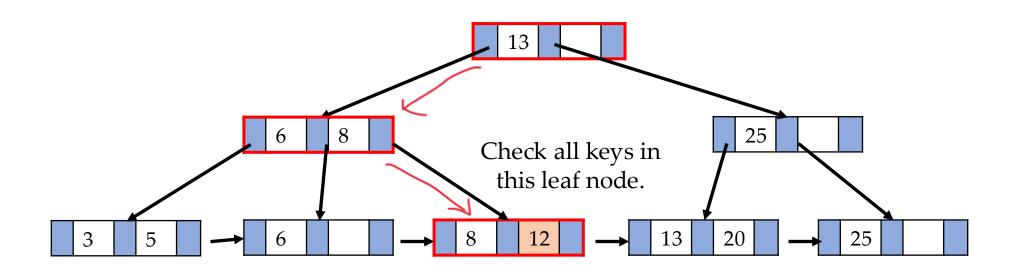
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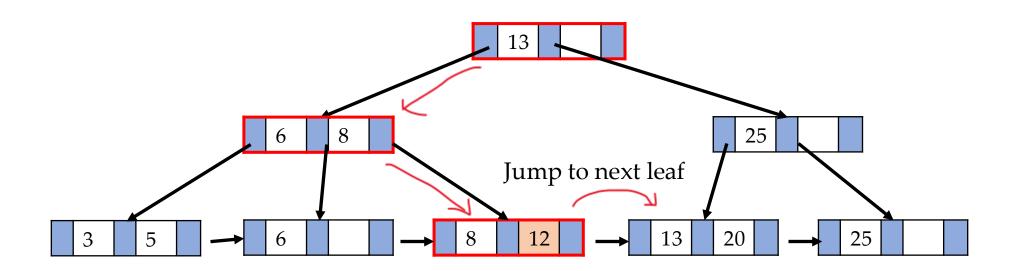
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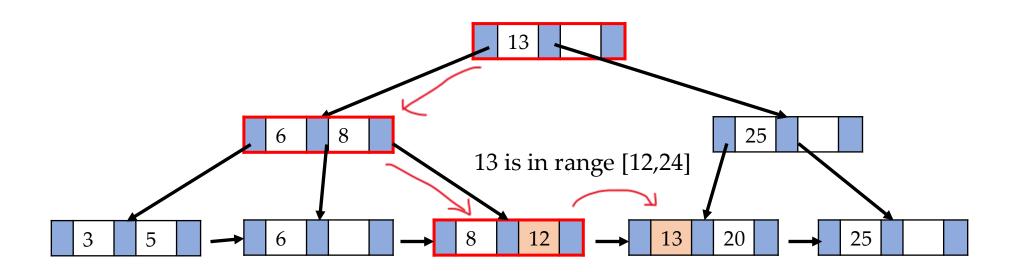
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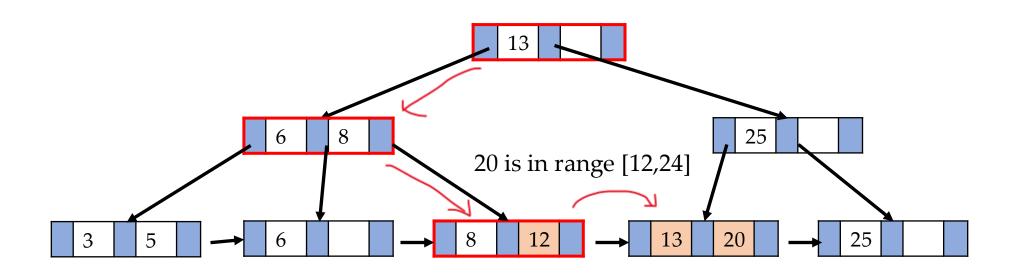
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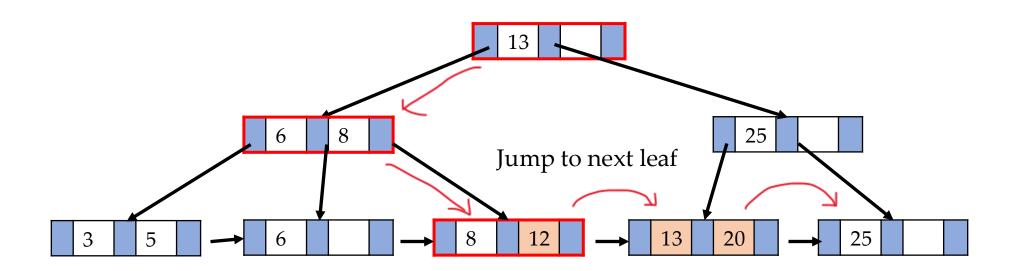
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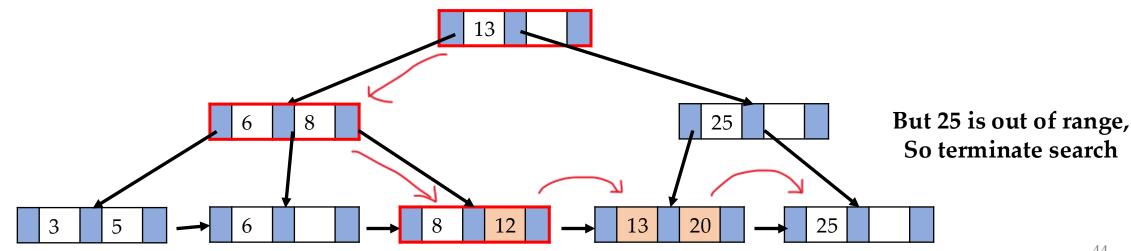
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Search Complexity of B+-Tree

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- If each node can have *n* search keys (pointers), and total N records in the tree,
 - $O(\log_{n/2} N)$ is the length of the path.
- Ex: If n = 100 and N = 1,000,000, only 4 nodes need to be accessed.
 - Only 4 blocks need to be read from disk.
- This is also an important **distinction between B**+-tree and **Binary trees**.
 - We can design B+-tree, where node size is large enough to be block size.
 - So one block fetch gives access to one node of the B+-tree.
- Notice that root is most frequently accessed.
 - Place it in your database buffer, which will save lookup cost.

Insertions and Deletions in B+-Tree

Insertions and Deletions in B⁺-Tree

- Insertions and Deletions are slightly more complex.
- You may need to **split a node** or **merge two nodes**.
- Split and merge operations can be avoided if there is a space, or you are not violating the B+-tree conditions.
- Remember; Give a value **n**, each internal node has:
 - **k** children
 - k-1 search keys
 - where, k is between $\lfloor n/2 \rfloor$ to n.
- Lets look at a live demonstration.

Insertions and Deletions in B+-Tree

30, 12, 56, 45, 18, 16, 10, 14, 8, 6, 90, 83, 67, 76, 49, 78,

56, 49, 67, 83, 78, 90, 18, 30, 76,

Insertions and Deletions Complexity

- If each node can have *n* search keys (pointers), and total N records in the tree,
 - $O(\log_{n/2} N)$ is the number of I/O operations needed.
- Notice that insertion and deletion complexity is still same as search!
- This is the worst case complexity, on average fewer I/O operations are required.

Can we use B+-tree for File organization?

- Till now, we used B+-tree for designing an index for our file.
- How about we use it to even organize our files.
- The leaf nodes of the B+-tree can store actual records.
- If each leaf has same size as the disk block, then one disk block I/O fetches necessary records.

Self Reading Task

• Difference between **B-tree** and **B**+-tree.

• Disadvantages of B-tree when compared to B+-tree?

Special Indices?

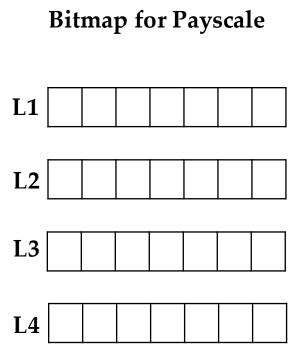
- Often, some attributes have only a small set of possible values.
 - Course with grades Pass or Fail.
 - Daily Attendance: Present or Absent
- For some attributes, we can create groups for their values.
 - Faculty Title: Assistant Prof., Associate Prof., Professor
 - Salary Payscale: L1 (<100); L2 (100 300); L3 (300 500); L4 (>500)

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- Constructing Bitmap indices is useful for such attributes.
- Each value is represented with the help of a bitmap.
 - Each record needs a sequential identifier.
 - The size of the bitmap is equal to number of records.
- One bitmap for each value!

- Assume that the following is our table:
 - We can construct bitmaps for Grade and Payscale.

ID	Name	Grade	Payscale
1	Voldemort	P	L1
2	Anakin	P	L2
3	Kang	F	L1
4	Gru	F	L2
5	Thanos	P	L4
6	Joker	F	L3
7	Jeoffrey	P	L1

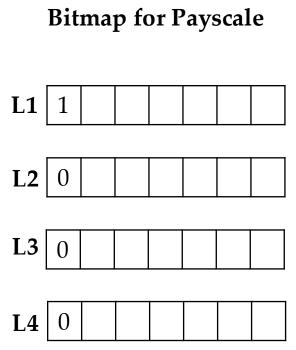
Bitmap for Grade P F



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P 1 F 0



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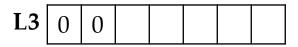
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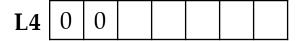
Bitmap for Grade







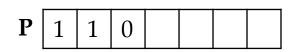




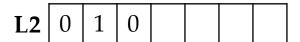
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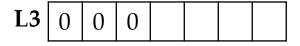
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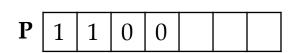


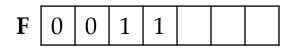


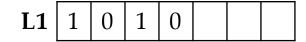
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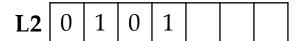
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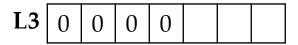
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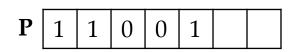


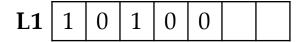


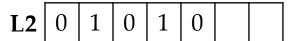
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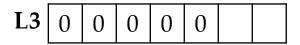
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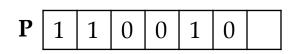


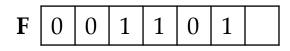


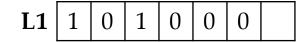
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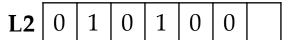
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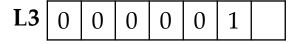
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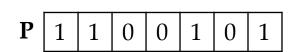


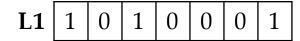


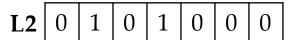
- Assume that the following is our table:
 - We can construct bitmaps for Grade and Payscale.

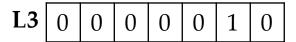
ID	Name	Grade	Payscale
1	Voldemort	P	L1
2	Anakin	P	L2
3	Kang	F	L1
4	Gru	F	L2
5	Thanos	P	L4
6	Joker	F	L3
7	Jeoffrey	P	L1

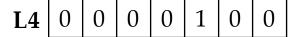
Bitmap for Grade











When are Bitmap Indices useful?

• Say we have the following query:

```
select * from cs_employees
where grade = 'P';
```

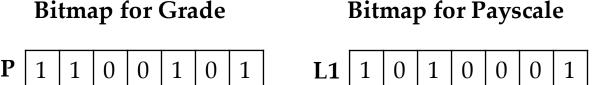
- Is Bitmap index useful for this query?
- Not much,
 - You will scan the bitmap index.
 - For every record where grade is equal to P, you will fetch it from the disk.
 - So, you did not have to fetch every record.
 - However, records are stored sequentially in blocks on the disk, so you may end up fetching a lot of blocks with not required blocks!

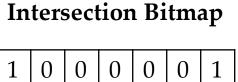
When are Bitmap Indices useful?

• Say we have another query:

```
select * from cs_employees
where grade = 'P' and payscale = 'L1';
```

- Is Bitmap index useful for this query?
- Significantly more,
 - We have bitmap indices on both grade and pay attributes.
 - So first, we will take an intersection of these bitmaps and then fetch!





So only two records are fetched!