

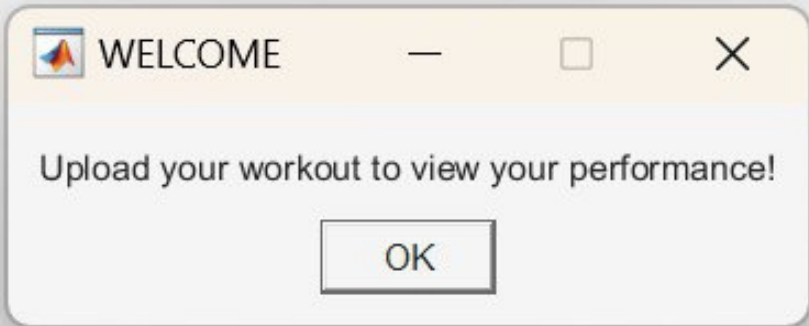
Fitness Tracker

Group: Make Mae Great Again

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Project Summary

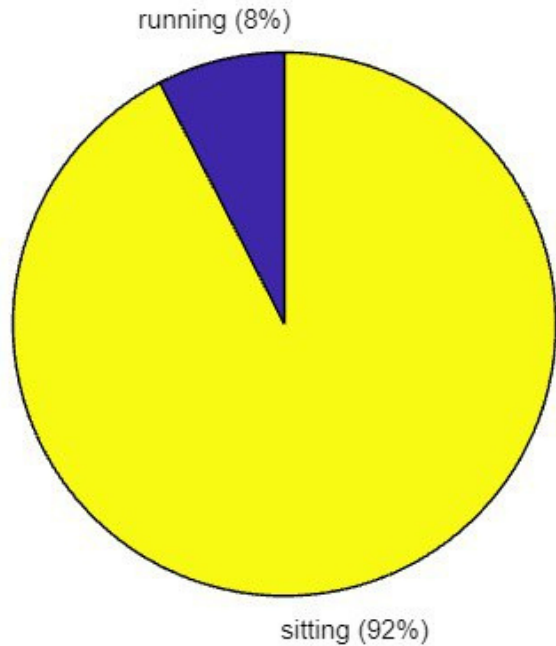
Data from the MATLAB mobile tracker is recorded, extracted, cleaned and studied. Analyses and machine learning are then conducted on the data to provide a better understanding and visualisation of information. Additional data such as moving speed and calories burnt are then derived using the necessary data.



5x6 timetable

	Timestamp
1	22-Mar-2024 15:28:04.573
2	22-Mar-2024 15:28:24.700
3	22-Mar-2024 15:28:44.869
4	22-Mar-2024 15:28:59.000
5	22-Mar-2024 15:29:00.000
6	22-Mar-2024 15:29:01.000
7	22-Mar-2024 15:29:02.000
	22-Mar-2024 15:29:03.000
	22-Mar-2024 15:29:04.000

```
distance = 658.7000  
time = 369  
averageSpeed = 1.8000
```



1

BASIC DATA INFORMATION

Preliminary Data Calculation

Initial calculations are made to give an overview of the exercise, including distance travelled, time taken and average speed

```
workout = "ExampleData.mat"  
load(workout)
```

2

MACHINE LEARNING

Prediction of motion

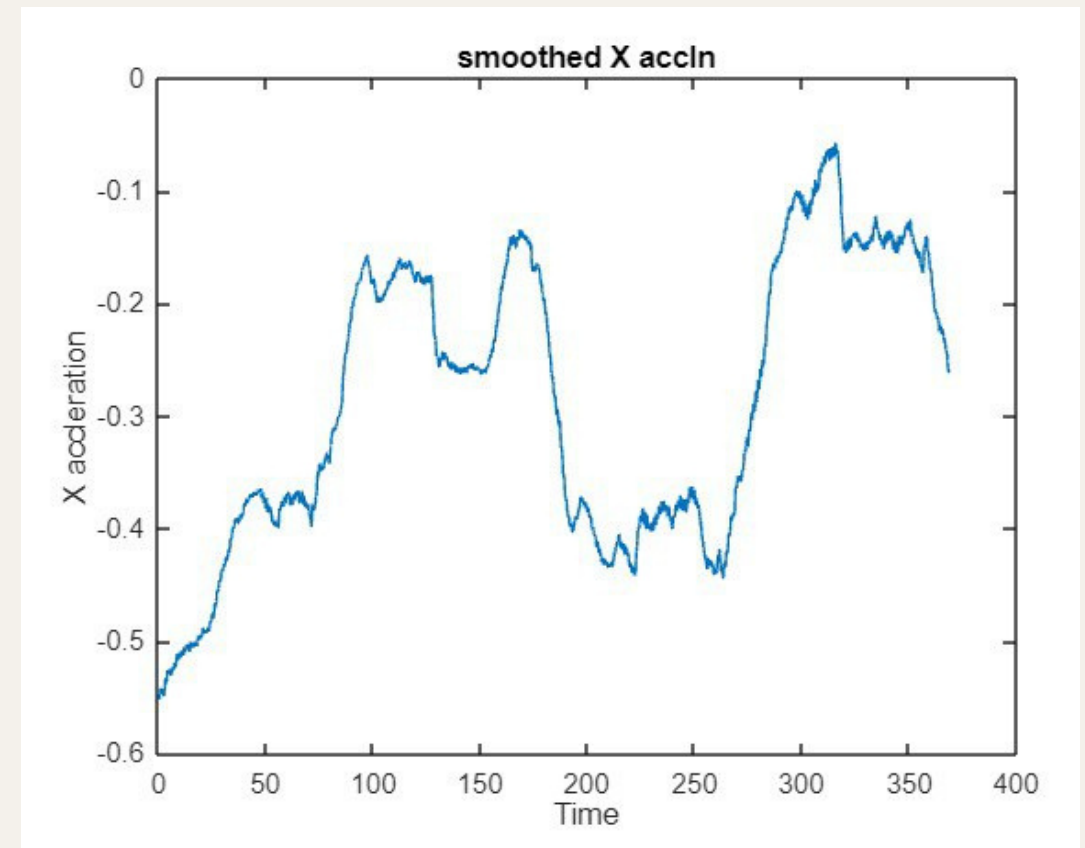
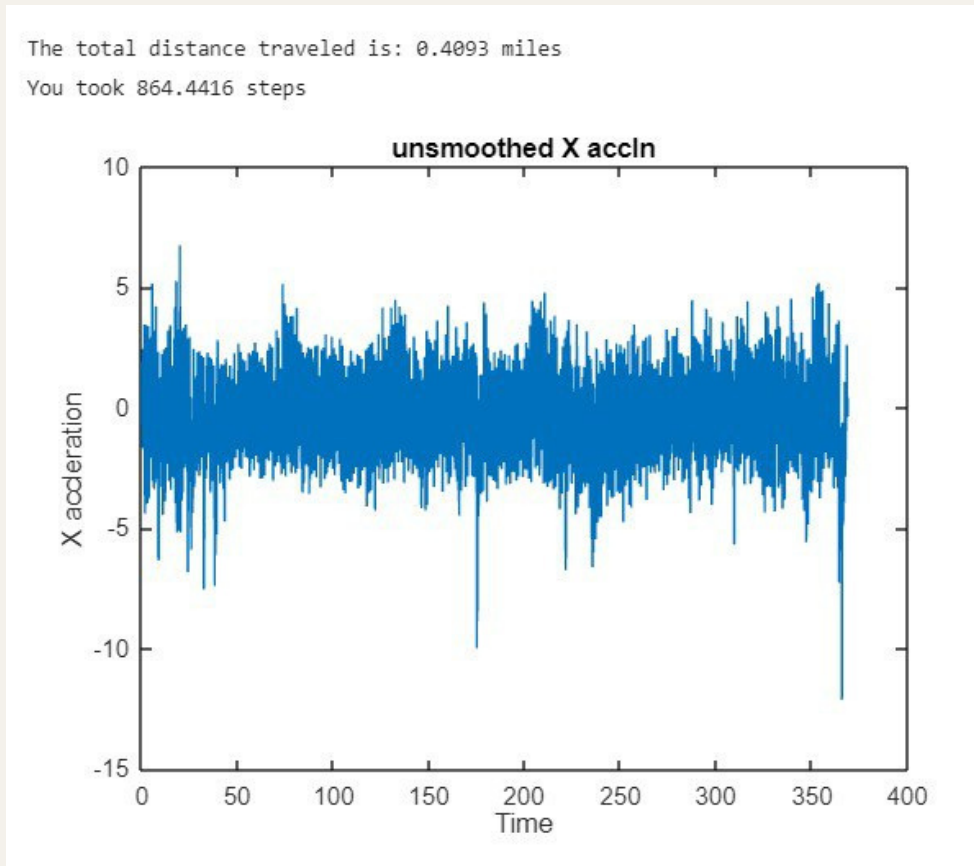
Machine learning is used to predict the motion of a person. The motion is classified into 3 categories, 'sitting', 'walking', 'running'.

3

DATA VISUALISATION

Acceleration

The instantaneous acceleration is visualised into a plot against time. The graph is then smoothed for clearer understanding. Although it is accurate in presenting the overall trend, the numeric value on the y-axis is scaled down as well, making this a limitation

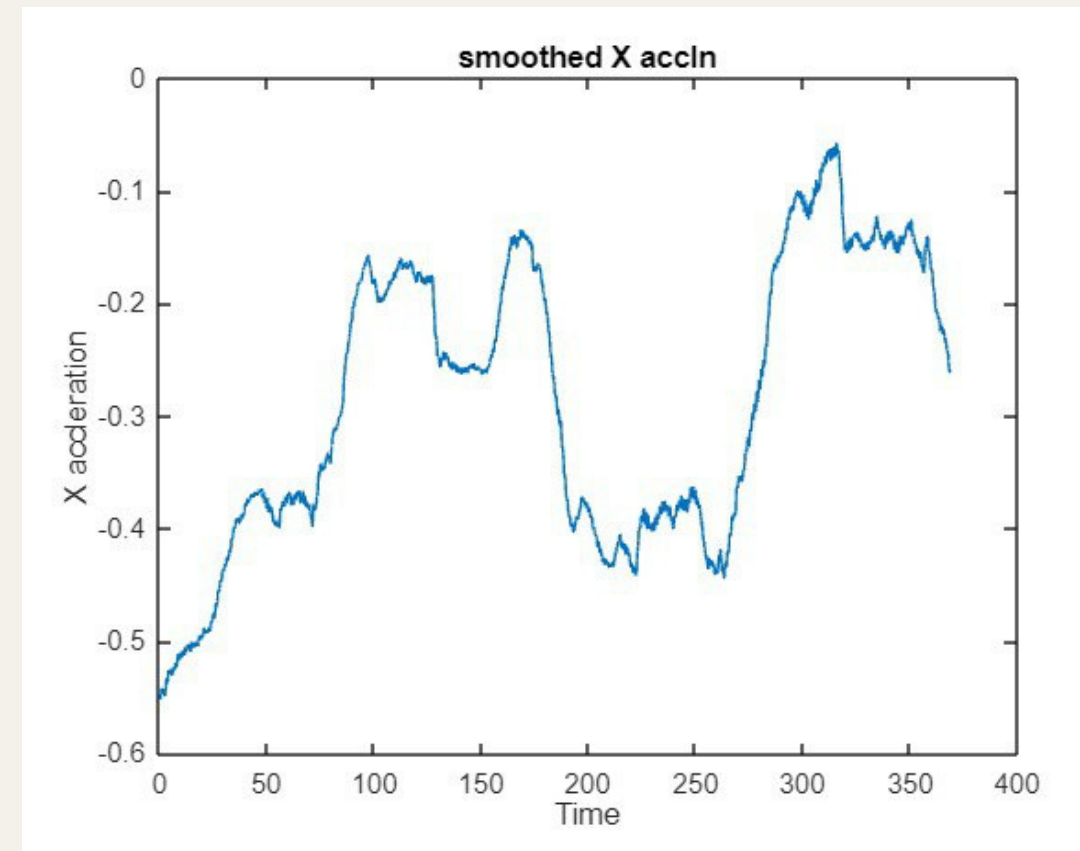
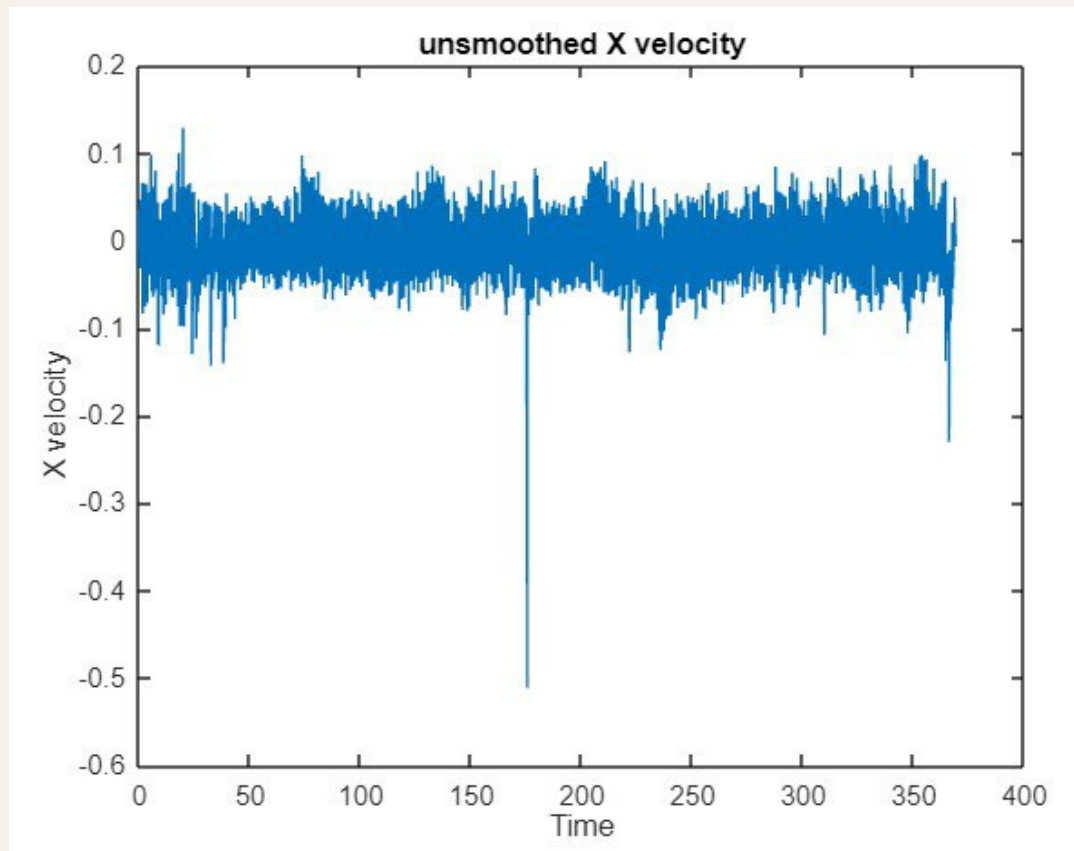


4

DATA VISUALISATION

Velocity

Velocity is calculated using Riemann sum method of integration using instantaneous acceleration and time data. A similar smoothing process is also carried out.



5

CALORIES DATA

Calculation of calories burnt

The code also calculates the amount of calories burnt based on weight data input by the user.

```
msgbox("Enter your weight (kg)")  
weight = 64
```

Metabolic Equivalent of Task (MET): 3



```
weight = 64
```

```
calorieBurn = 19.6800
```

6

POSITION MAP

Exercise path generated

Lastly, a position map is generated based on the coordinates recorded. It is then visualised.

