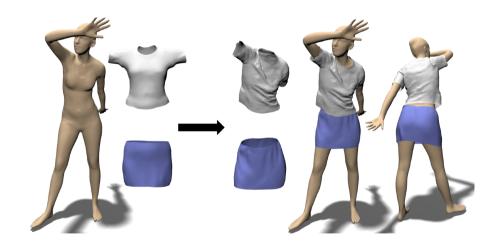
TailorNet: Predicting Clothing in 3D as a Function of Human Pose, Shape and Garment Style

Chaitanya Patel, Zhou Liao and Gerard Pons-Moll Max Planck Institute for Informatics

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Guray Ozgur University of Tübingen

Right to Clothing, a Human Right



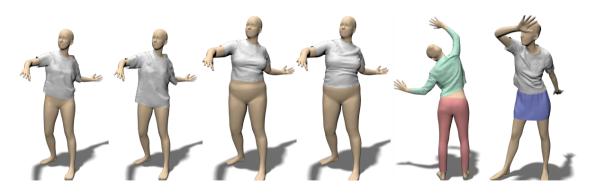
Previously: Physics Based Simulation

- ► Realistic look
- ► Good generalization
- ► Computationally expensive
- ► Complex to implement and to control
- ▶ Time-consuming

Previously: Earlier Data-Driven Methods

- ► A step forward to automate the process
- ► Do not jointly model style, pose and shape variation
- ▶ Over-smooth results
- ► Lack fine structure (wrinkles)

TailorNet

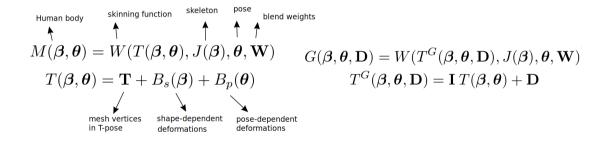


TailorNet: A model to estimate the clothing deformations with fine details from input body shape, body pose and garment style

TailorNet

- ► Simple
- ► Easy to deploy
- ► Fully differentiable
- ► Fine structures are preserved by learning not only low-frequency components but also high-frequency components

Garment Model Aligned with SMPL



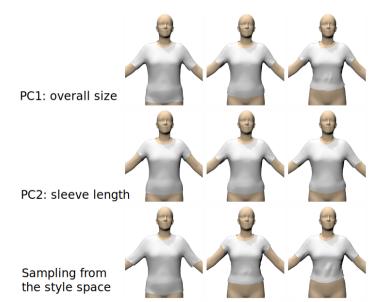
Un-posing Garment Deformation

$$\mathbf{D} = W^{-1}(\mathbf{G}, J(\boldsymbol{\beta}), \boldsymbol{\theta}, \mathbf{W}) - \mathbf{I} T(\boldsymbol{\beta}, \boldsymbol{\theta})$$

$$D(\boldsymbol{\beta}, \boldsymbol{\theta}, \boldsymbol{\gamma}) : \mathbb{R}^{|\boldsymbol{\theta}|} \times \mathbb{R}^{|\boldsymbol{\beta}|} \times \mathbb{R}^{|\boldsymbol{\gamma}|} \mapsto \mathbb{R}^{m \times 3}$$

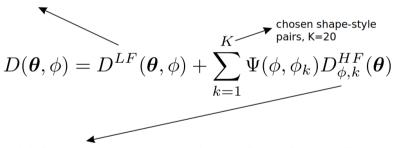
▶ **Learn** deformation **D** as a function of shape β , pose θ and style γ .

Generating Parametric Model of Style



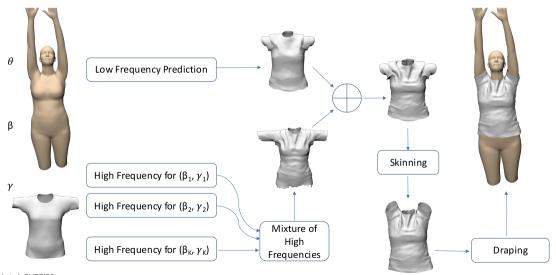
Tailoring

Low frequency component, single MLP, smooth but accurate



High frequency component, mixture of MLP, fine details

Tailoring



Model Evaluation





1000 times faster than PBS

Results of Single Style-Shape Model

| Style-shape | MLP | UV Decoder | Graph CNN |
|-------------|------|------------|-----------|
| Loose-fit | 14.5 | 15.9 | 16.1 |
| Tight-fit | 10.1 | 11.4 | 11.7 |

Results of TailorNet

| Split | Style-shape | Pose | Our | Our Mixture |
|-------|-------------|-------|----------|-------------|
| No. | set | set | Baseline | Model |
| 2 | train | test | 10.6 | 10.2 |
| 3 | test | train | 11.7 | 11.4 |
| 4 | test | test | 11.6 | 11.4 |

Limitations

- ► the pose dependent deformations produce intersections sometimes, vertices are pushed out in real time
- only quasi-statics of clothing not dynamics

Questions?

